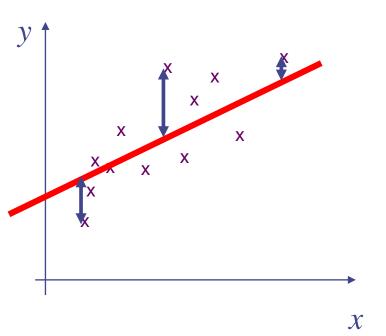
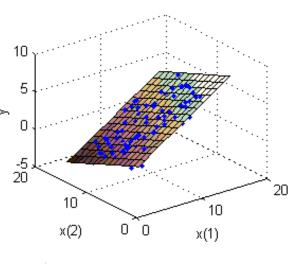
# Machine Learning 4771

Instructor: Itsik Pe'er

## Reminder: Regression

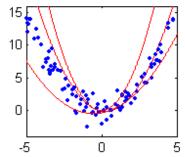


Multi-D Linear: matrix form



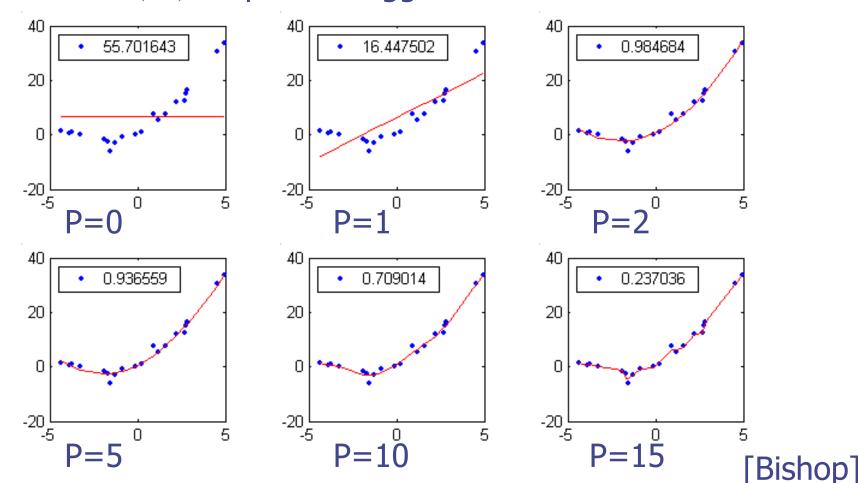
- 1D Linear:
  - Loss
  - Empirical risk
  - Least-squares

Polynomial



# Underfitting/Overfitting

- •Try varying P. Higher P fits a more complex function class
- •Observe  $R(\theta^*)$  drops with bigger P

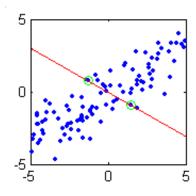


## Class 4

- Overfitting
- Additive models: Fourier
- Radial basis functions

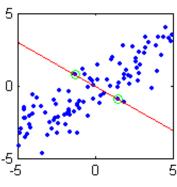
## **Evaluating The Regression**

- Unfair to use empirical to find best order P
- •High P (vs. N) can overfit, even linear case!
- •min  $R(\theta^*)$  not on training but on future data
- •Want model to *Generalize* to future data



# **Evaluating The Regression**

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True loss: 
$$R_{true}(\theta) = \int p(x,y) \frac{1}{2} (y - \theta^T x)^2 dx dy$$

One approach: split data into training / testing portion

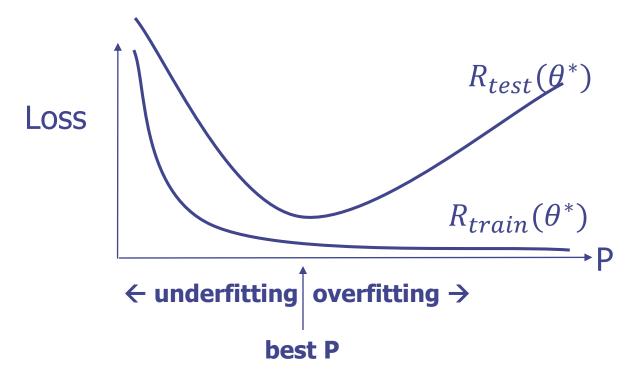
$$\{(x_1, y_1), \dots, (x_N, y_N)\} \qquad \{(x_{N+1}, y_{N+1}), \dots, (x_{N+M}, y_{N+M})\}$$

•Estimate  $\theta^*$  with training loss:  $R_{train}(\theta) = \frac{1}{2N} \sum_{i=1}^{N} (y_i - \theta^T x_i)^2$ 

•Evaluate P with testing loss:
$$R_{test}(\theta^*) = \frac{1}{2M} \sum_{i=N+1}^{N+M} (y_i - \theta^{*T} x_i)^2$$

#### Crossvalidation

- Try fitting with different polynomial order P
- •Select P which gives lowest  $R_{test}(\theta^*)$

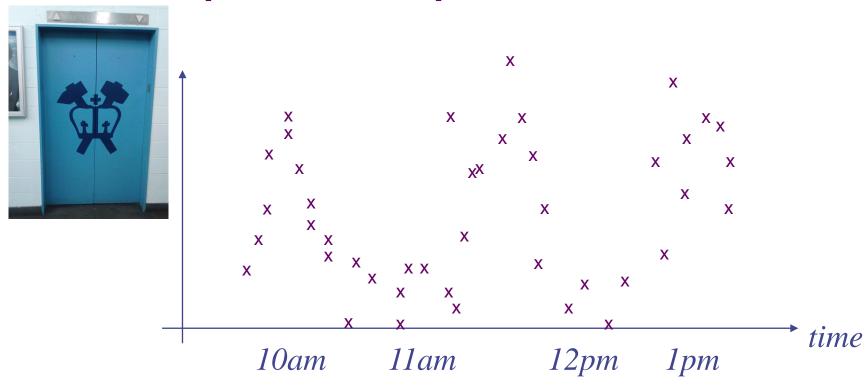


- •Think of P as a measure of the complexity of the model
- •Higher order polynomials are more flexible and complex

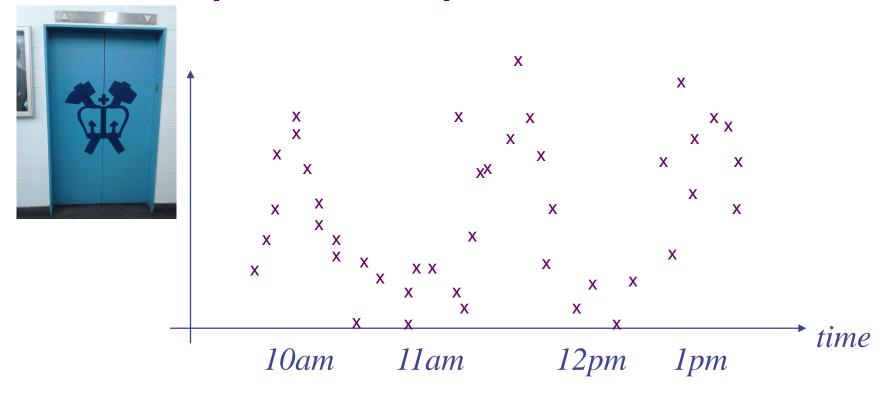
Itsik Pe'er, Columbia University



## Example: Temporal data



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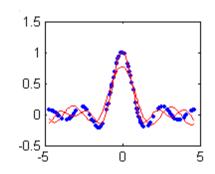


- Need to fit periodic behavior
- Cycle: 90min, daily, weekly, annual

## Sinusoidal Basis Functions

•General functions, not just polynomials:

$$f(x;\theta) = \sum_{p=1}^{r} \theta_p \phi_p(x) + \theta_0$$

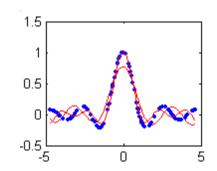


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- Regression adds linear combinations of the basis fn's

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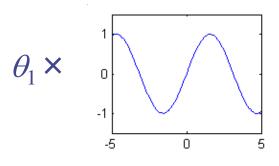
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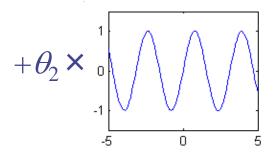


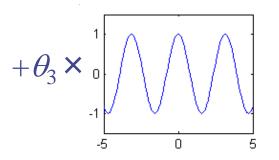
- These are generally called Additive Models
- Regression adds linear combinations of the basis fn's
- •For example: Fourier (sinusoidal) basis

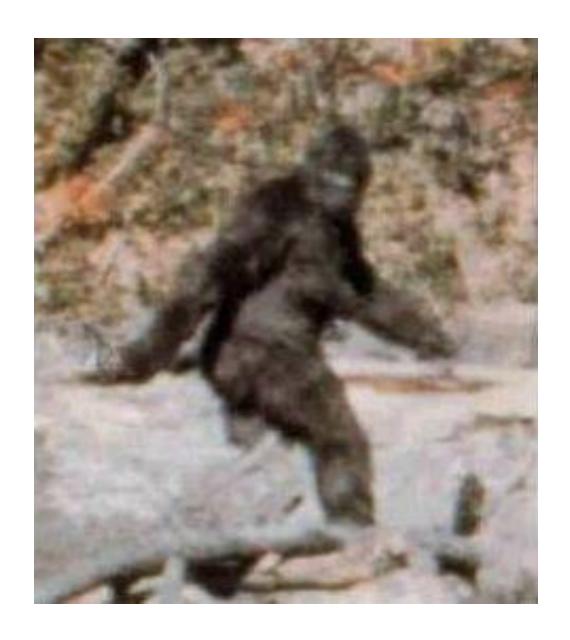
$$\phi_{2k}(x_i) = \sin(kx_i) \qquad \phi_{2k+1}(x_i) = \cos(kx_i)$$

Note, don't have to be a basis per se, usually subset









Patterson Gimlin

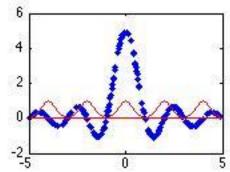
# Example: Bigfoot Sightings



# Radial Basis Functions (RBF)

Can act as prototypes of the data itself

$$f(\mathbf{x}; \theta) = \sum_{k=1}^{N} \theta_k \exp(-\frac{1}{\sigma^2} ||\mathbf{x} - \mathbf{x}_k||^2)^{\frac{1}{2-5}}$$

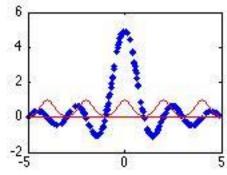


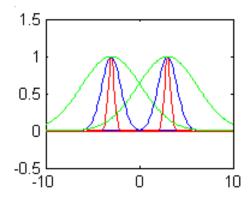
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•Parameter  $\sigma$  = standard deviation controls how wide bumps are

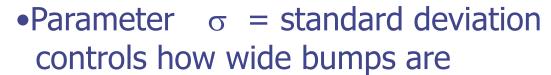




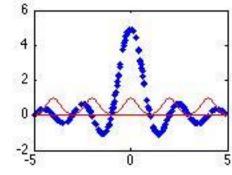
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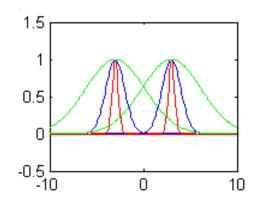
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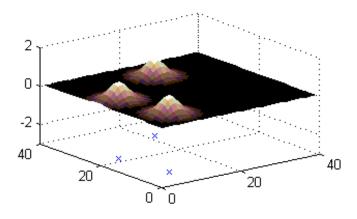
$$f(\mathbf{x}; \theta) = \sum_{k=1}^{N} \theta_k \exp(-\frac{1}{\sigma^2} ||\mathbf{x} - \mathbf{x}_k||^2)$$











- •Training point  $\rightarrow$  bump function  $f(x;\theta) = \sum_{k=1}^{N} \theta_k \exp(-\frac{1}{\sigma^2} ||x x_k||^2)$
- •Reuse solution from linear regression:  $\theta^* = (X^T X)^{-1} X^T y$
- •Can view the data instead as  $X_i$ , a big matrix of size  $N \times N$

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$$\mathbf{X} = \begin{bmatrix} \phi_1(x_1) & \phi_2(x_1) & \cdots & \phi_k(x_1) \\ \phi_1(x_2) & \phi_2(x_2) & \cdots & \phi_k(x_2) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_1(x_k) & \phi_2(x_k) & \cdots & \phi_k(x_k) \end{bmatrix}$$

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$$X = \begin{bmatrix} \exp(-\frac{1}{\sigma^2} \|x_1 - x_1\|^2) & \cdots & \exp(-\frac{1}{\sigma^2} \|x_1 - x_k\|^2) \\ \exp(-\frac{1}{\sigma^2} \|x_2 - x_1\|^2) & \cdots & \exp(-\frac{1}{\sigma^2} \|x_2 - x_k\|^2) \\ \vdots & \ddots & \vdots \\ \exp(-\frac{1}{\sigma^2} \|x_k - x_1\|^2) & \cdots & \exp(-\frac{1}{\sigma^2} \|x_k - x_k\|^2) \end{bmatrix}$$

•training point 
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•For RBFs, X is square and symmetric, so solution is just

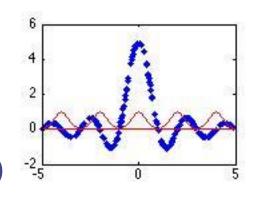
$$\theta^* = X^{-1} y$$

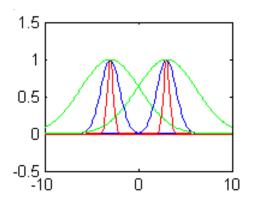
## Bump Width for RBF

Can act as prototypes of the data itself

$$f(\mathbf{x}; \theta) = \sum_{k=1}^{N} \theta_k \exp(-\frac{1}{\sigma^2} ||\mathbf{x} - \mathbf{x}_k||^2)$$

•Parameter  $\sigma$  = standard deviation controls how wide bumps are





What happens if too big/small?

How would we know that?

## **Evaluating Our Learned Function**

- •We minimized empirical risk to get  $\theta^*$
- •How well does  $f(x;\theta^*)$  perform on future data?
- •It should Generalize and have low True Risk:

$$R_{true}(\theta) = \int P(x, y) \frac{1}{2} (y - \theta^T x)^2 dx dy$$

- •Can't compute true risk, instead use Testing Empirical Risk
- •We randomly split data into training and testing portions

$$\{(x_1, y_1), \dots, (x_N, y_N)\}$$

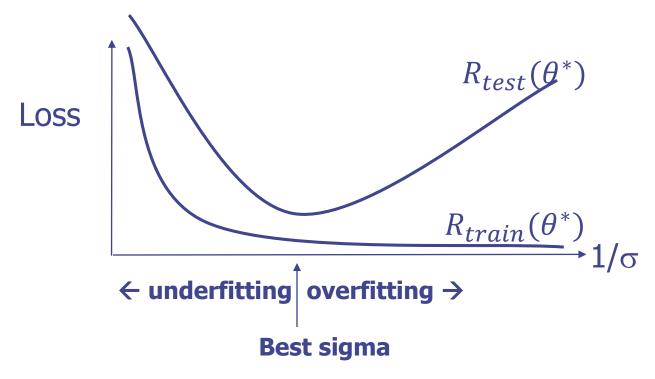
 $\{(x_{N+1}, y_{N+1}), \dots, (x_{N+M}, y_{N+M})\}$ 

•Find 
$$\theta^*$$
 with training data: 
$$R_{train}(\theta) = \frac{1}{2N} \sum_{i=1}^{N} (y_i - \theta^T x_i)^2$$
•Evaluate it with testing data: 
$$R_{train}(\theta) = \frac{1}{2M} \sum_{i=1}^{N+M} (y_i - \theta^T x_i)^2$$

$$R_{train}(\theta) = \frac{1}{2M} \sum_{i=N+1} (y_i - \theta^T x_i)$$

#### Crossvalidation

- Try fitting with different sigma radial basis function widths
- •Select sigma which gives lowest  $R_{test}(\theta^*)$



- •Think of sigma as a measure of the simplicity of the model
- Thinner RBFs are more flexible and complex

# Assuming $\theta$ is small

• Prior:  $Pr(\theta) \propto e^{-\frac{\lambda}{2} ||\theta||^2}$ 

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Posterior = Likelihood × Prior

# Assuming $\theta$ is small

- Prior:  $Pr(\theta) \propto e^{-\frac{\lambda}{2} ||\theta||^2}$
- $Pr(Data) = Pr(Data|\theta) \times Pr(\theta)$  $log Pr(Data) = l(\theta) + log Pr(\theta)$
- Posterior = Likelihood × Prior

$$\theta^* = \text{Max-aposteriori} = \operatorname{argmax}[l(\theta) + \log \Pr(\theta)]$$

- Empirical Risk Minimization gave overfitting & underfitting
- •We want to add a penalty for using too many theta values

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- We want to add a penalty for using too many theta values
- This gives us the Regularized Risk

$$R_{regularized}(\theta) = R_{empirical}(\theta) + Penalty(\theta)$$
$$= \frac{1}{N} \sum_{i=1}^{N} L(y_i, f(x_i; \theta)) + \frac{\lambda}{2} ||\theta||^2$$

Solution for Regularized Risk with Least Squares Loss:

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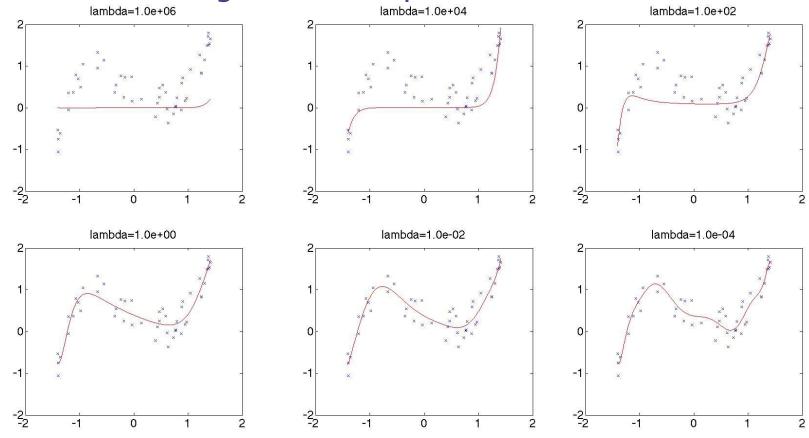
$$\nabla_{\theta} R_{regularized} = 0$$

$$\nabla_{\theta} \left( \frac{1}{2N} \| \mathbf{y} - \mathbf{X}\theta \| + \frac{\lambda}{2} \| \theta \|^2 \right) = 0$$

$$\frac{1}{2N} (-2\mathbf{X}^T \mathbf{y} + 2\mathbf{X}^T \mathbf{X}\theta) + \frac{\lambda}{2} (2\theta) = 0$$

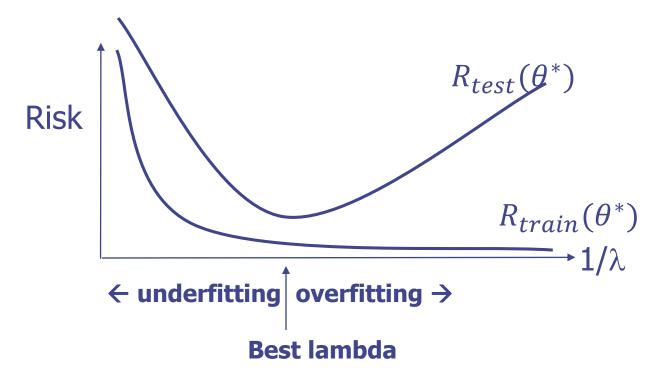
$$\theta^* = (\mathbf{X}^T \mathbf{X} + \lambda NI)^{-1} \mathbf{X}^T \mathbf{y}$$

- •Have D=16 features (or P=15 throughout)
- •Try minimizing  $R_{regularized}(\theta)$  to get  $\theta^*$  with different  $\lambda$
- •Note that  $\lambda = 0$  give back Empirical Risk Minimization



#### Crossvalidation

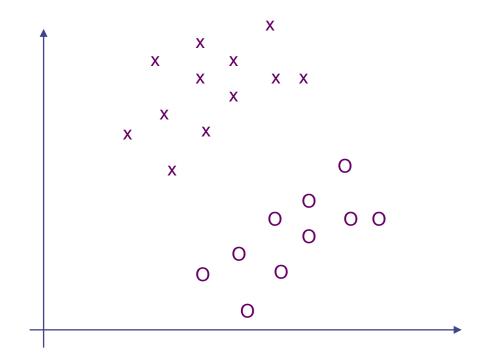
- Try fitting with different lambda regularization levels
- •Select lambda which gives lowest  $R_{test}(\theta^*)$



- Lambda measures simplicity of the model
- Models with low lambda are more flexible

## Class 5

- Classification
- Logistic Regression
- Gradient Descent



### Classification Problems

Determine student admission to Columbia based on GPA, prev. school rank, tests



### Classification Problems

- Determine student admission to Columbia based on GPA, prev. school rank, tests
- Decide malignant or benign tumors
  - based on size, density, speed of growth



# From Regression To Classification

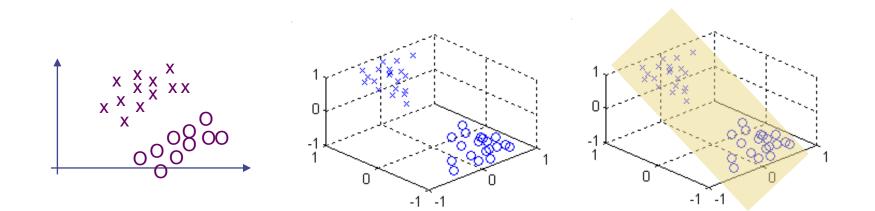
Classification is another important learning problem

Classification: 
$$X = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}, x \in \mathbb{R}^D, y \in \{0, 1\}$$

Regression:

$$X = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}, x \in \mathbb{R}^D, y \in \mathbb{R}^D$$

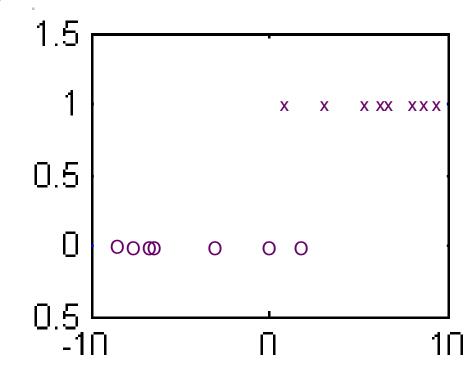
•Should we solve this as a least squares regression problem?



Given a classification problem with binary outputs

$$X = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}, x \in \mathbb{R}^D, y \in \{0, 1\}$$

$$f(\mathbf{x};\theta) = \frac{1}{1 + exp(-\theta\mathbf{x})}$$



#### Short hand for Linear Functions

•What happened to adding the intercept?

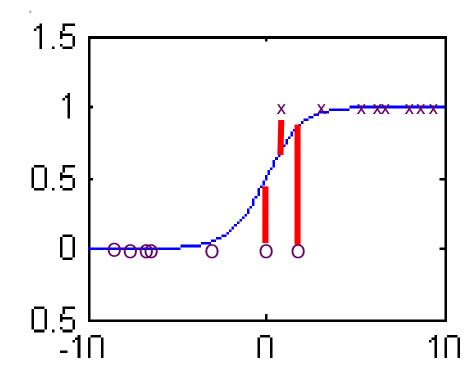
$$f(\mathbf{x}; \theta) = \theta^T \mathbf{x} + \theta_0$$

$$= \begin{bmatrix} \theta(1) \\ \theta(2) \\ \vdots \\ \theta(D) \end{bmatrix} \begin{bmatrix} \mathbf{x}(1) \\ \mathbf{x}(2) \\ \vdots \\ \mathbf{x}(D) \end{bmatrix} + \theta_0 = \begin{bmatrix} \theta_0 \\ \theta(1) \\ \theta(2) \\ \vdots \\ \theta(D) \end{bmatrix} \begin{bmatrix} 1 \\ \mathbf{x}(1) \\ \mathbf{x}(2) \\ \vdots \\ \mathbf{x}(D) \end{bmatrix} = \vec{\theta}^T \vec{\mathbf{x}}$$

Given a classification problem with binary outputs

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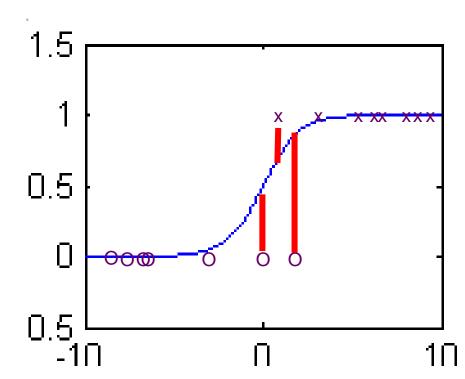
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$$X = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}, x \in \mathbb{R}^D, y \in \{0, 1\}$$

•Use this function and output 1 if f(x)>0.5 and 0 otherwise

$$f(\mathbf{x};\theta) = \frac{1}{1 + exp(-\theta\mathbf{x})}$$

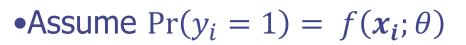
• Assume  $Pr(y = 1) = f(x; \theta)$ 

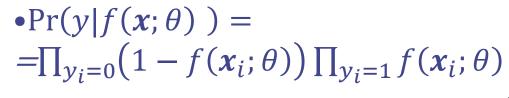


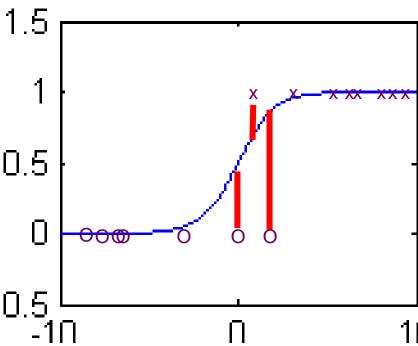
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$$f(\mathbf{x};\theta) = \frac{1}{1 + exp(-\theta\mathbf{x})}$$

•Instead of squared loss, use Logistic Loss (i.e. negative binomial likelihood)  $Loss_{log}(y, f(x; \theta)) = (y - 1) \log(1 - f(x; \theta)) - y \log(f(x; \theta))$ 

- •The resulting method is called Logistic Regression.
- Empirical Risk:

Given a classification problem with binary outputs

$$X = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}, x \in \mathbb{R}^D, y \in \{0, 1\}$$

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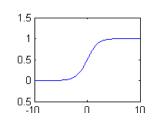
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- •Empirical Risk:

$$R_{emp}(\theta) = \frac{1}{N} \sum_{i=1}^{N} (y_i - 1) \log(1 - f(\mathbf{x_i}; \theta)) - y_i \log(f(\mathbf{x_i}; \theta))$$

•With empirical logistic risk has no closed form solution:

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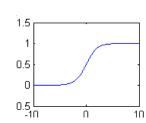
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$$\nabla_{\theta} R = \frac{1}{N} \sum_{i=1}^{N} \left( \frac{1 - y_i}{1 - f(x_i; \theta)} - \frac{y_i}{f(x_i; \theta)} \right) f'(x_i; \theta) = 0 \quad ??????$$
where
$$f(x; \theta) = \frac{1}{1 + exp(-\theta x)} = g(\theta^T x)$$

$$\lim_{t \to \infty} \frac{1}{1 + exp(-\theta x)} = g(\theta^T x)$$

$$f(\mathbf{x}; \theta) = \frac{1}{1 + exp(-\theta \mathbf{x})} = g(\theta^T \mathbf{x})$$

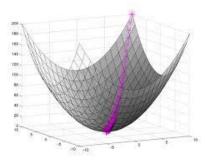
$$g(z) = \frac{1}{1 + exp(-z)} \qquad g'(z) = g(z)(1 - g(z))$$



$$g'(z) = g(z)(1 - g(z))$$

#### **Gradient Descent**

- •Useful when we can't get minimum solution in closed form
- Gradient points in direction of fastest increase
- •Take step in the opposite direction!



#### **Gradient Descent**

- •Useful when we can't get minimum solution in closed form
- Gradient points in direction of fastest increase
- Take step in the opposite direction!
- Gradient Descent Algorithm

choose scalar step size  $\eta$ , & tolerance  $\varepsilon$  initialize  $\theta^0 = \text{small random vector}$ 

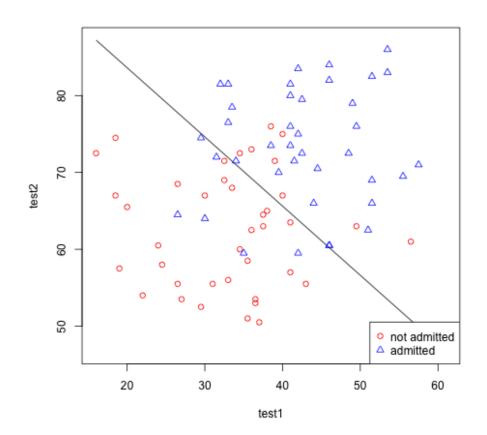
$$\theta^1 \leftarrow \theta^0 - \eta \nabla_{\theta} R_{emp}|_{\theta^0}$$
;  $t \leftarrow 1$ 

while  $\|\theta^t - \theta^{t-1}\| \ge \epsilon$  {

 $\theta^{t+1} \leftarrow \theta^t - \eta \nabla_{\theta} R_{emp}|_{\theta^0} ; t \leftarrow t+1$ 

•For appropriate  $\eta$ , this will converge to local minimum

- Logistic regression gives better classification performance
- •Its empirical risk is convex so gradient descent always converges to the same solution



# Summary

- Additive models
- Classification
- Logistic Regression
- Gradient Descent