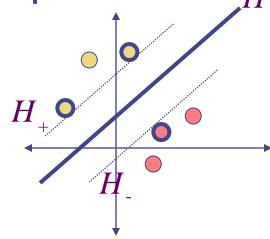
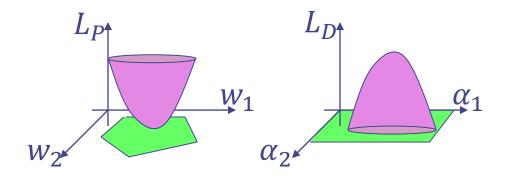
# Machine Learning 4771

Instructor: Itsik Pe'er

#### Reminder: SVM

- Linear classifier of separable points
- Maximizes margin
- QP + dual
- Has few support vectors





# Duality

# Duality

- Primal SVM problem  $L_P$ :

  minimize  $\frac{1}{2}||w||^2$  s.t.  $y_i(w^Tx_i+b)-1\geq 0$
- Lagrange multipliers  $\alpha_i$ :

$$\min_{w,b} \max_{\alpha \ge 0}^{\frac{1}{2}} ||w||^2 - \sum_{i} \alpha_i (y_i (w^T x_i + b) - 1)$$

- $w = \sum_i \alpha_i y_i x_i$ ; for  $\alpha_i > 0$ :  $w^T x_i + b = y_i$
- ♦ Dual:  $L_D = max \sum_i \alpha_i \frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j x_i^T x_j$ s.t.  $\sum_i \alpha_i y_i = 0$ ,  $\alpha_i \ge 0$
- $\bullet$  Classifier: $sign(\sum_i \alpha_i y_i x_i x + b)$

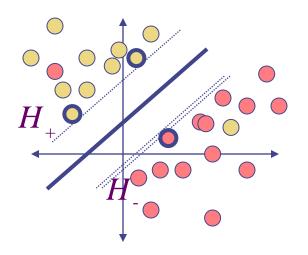
#### Class 9 – More SVMs

- Review
- Generalizations
  - Non-separable
  - Non-linear

#### Itsik Pe'er, Columbia University

# Non-Separable SVMs

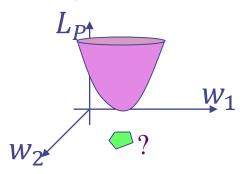
•What happens when non-separable?

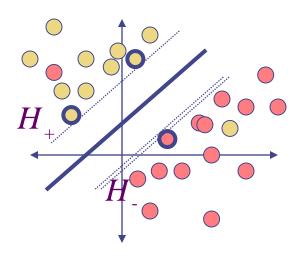


#### Itsik Pe'er, Columbia University

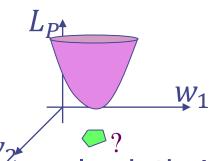
# Non-Separable SVMs

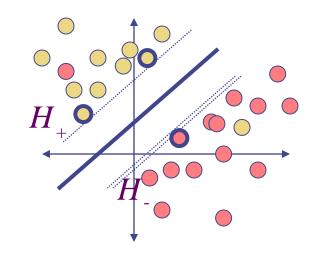
- •What happens when non-separable?
- There is no solution and convex hull shrinks to nothing



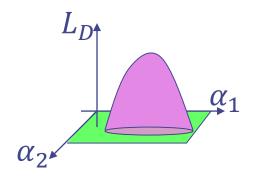


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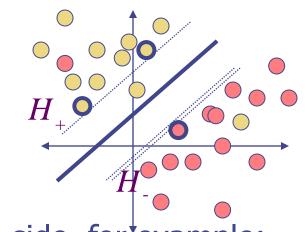




•Not all constraints can be resolved, their alphas go to  $\infty$   $L_D = \max \sum_i \alpha_i - \frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j x_i^T x_j$  subject to  $\sum_i \alpha_i y_i = 0$ ,  $\alpha_i \ge 0$ 



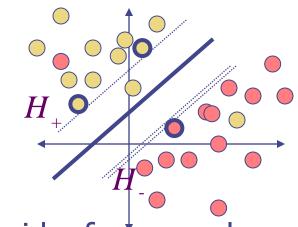
•Instead of perfectly classifying each point:  $y_i(w^Tx_i + b) \ge 1$  we "Relax" the problem with (positive) slack variables  $\xi$ 's



allow data to (sometimes) fall on wrong side, for texample:

$$(w^T x_i + b) \ge 1 - 0.03 \text{ if } y_i = +1$$

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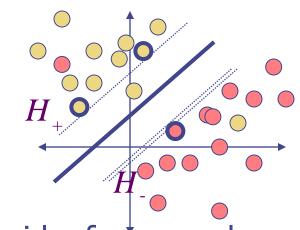


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•New constraints:  $w^T x_i + b \ge +1 - \xi_i$  if  $y_i = +1$  where  $\xi_i \ge 0$   $w^T x_i + b \le -1 + \xi_i$  if  $y_i = -1$  where  $\xi_i \ge 0$ 

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•But too much  $\xi$ 's means too much slack, so penalize them

$$L_p: \min \frac{1}{2} ||w||^2 + C \sum_{i} \xi_i \text{ subject to } y_i(w^T x_i + b) - 1 + \xi_i \ge 0$$

- This new problem is still convex, still qp()!
- •User chooses scalar C (or cross-validates) which controls how much slack  $\xi$  to use (how non-separable) and how robust to outliers or bad points on the wrong side

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Large margin On right side For 
$$\xi$$
 positivity 
$$L_p : \min \frac{1}{2} ||w||^2 + C \sum_i \xi_i - \sum_i \alpha_i \left( y_i (w^T x_i + b \,) - 1 + \xi_i \right) - \sum_i \beta_i \xi_i$$
 
$$\frac{\partial}{\partial w} L_p = \frac{\partial}{\partial b} L_p = \frac{\partial}{\partial \xi_i} L_$$

•This new problem is still convex, still qp()!

but  $\alpha_i \& \beta_i \ge 0 \Longrightarrow 0 \le \alpha_i \le C$ 

•User chooses scalar C (or cross-validates) which controls how much slack  $\xi$  to use (how non-separable) and how robust to outliers or bad points on the wrong side

Low slack On right side For 
$$\xi$$
 positivity 
$$L_p : \min \frac{1}{2} ||w||^2 + C \sum_i \xi_i - \sum_i \alpha_i (y_i(w^T x_i + b) - 1 + \xi_i) - \sum_i \beta_i \xi_i$$
 
$$\frac{\partial}{\partial w} L_p \ and \ \frac{\partial}{\partial b} L_p \ as \ before \dots$$
 
$$\frac{\partial}{\partial \xi_i} L_p = C - \alpha_i - \beta_i = 0 \quad \Rightarrow \alpha_i = C - \beta_i$$

$$\begin{split} L_p: \min \frac{1}{2} \left| |w| \right|^2 + C \sum_i \xi_i - \sum_i \alpha_i \left( y_i (w^T x_i + b \,) - 1 + \xi_i \right) - \sum_i \beta_i \xi_i \\ \frac{\partial}{\partial w} L_p \ and \frac{\partial}{\partial b} L_p \ as \ before \dots \\ \frac{\partial}{\partial \xi_i} L_p = C - \alpha_i - \beta_i = 0 \quad \Rightarrow \alpha_i = C - \beta_i \end{split}$$

•Can now write dual problem (to maximize):

but  $\alpha_i \& \beta_i \ge 0 \Longrightarrow 0 \le \alpha_i \le C$ 

 $L_D$ :

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but 
$$\alpha_i \& \beta_i \ge 0 \Longrightarrow 0 \le \alpha_i \le C$$

Can now write dual problem (to maximize):

$$L_{D}: \max \sum_{i} \alpha_{i} - \sum_{i,j} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{i}^{T} x_{j}$$

$$subject \ to \sum_{i} \alpha_{i} y_{i} = 0 \ \ and \ \alpha_{i} \in [0, C]$$

•Same dual as before but alphas can't grow beyond C

- •As we try to enforce a classification for a data point its KKT multiplier alpha keeps growing endlessly
- •Clamping alpha to stop growing at C makes SVM "give up" on those non-separable points

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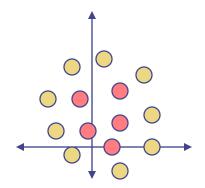
•The dual program is now:

 Solve as before with extra constraints that alphas positive AND

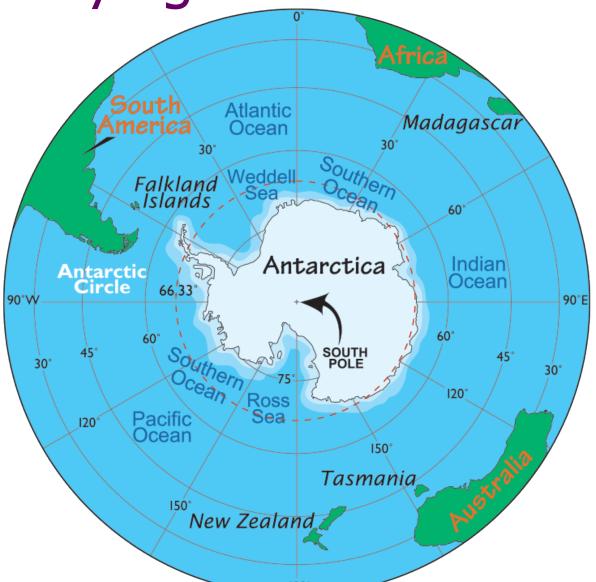


less than C... gives alphas... from alphas get  $w = \sum_i \alpha_i y_i x_i$ 

•What if the problem is not linear?



Classifying Antarctica

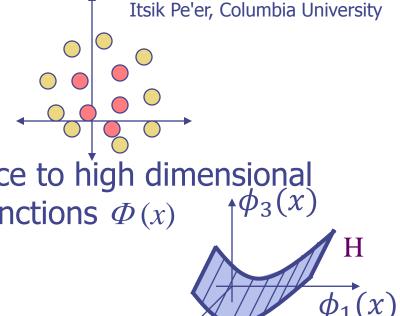


- •What if the problem is not linear?
- •We can use our old trick...



•For example, quadratic classifier:

$$x_i \to \phi(x_i) \ via \ \phi(\vec{x}) = \begin{bmatrix} \vec{x} \\ vec(\vec{x}\vec{x}^T) \end{bmatrix}$$



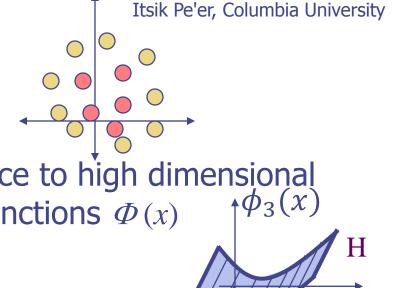
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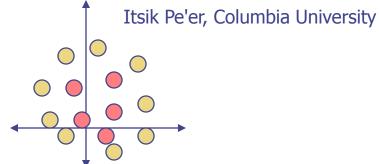
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•Call  $\phi$ 's feature vectors computed from original x inputs



•What if the problem is not linear?



- •Map d-dimensional x data from L-space to high dimensional H (Hilbert) feature-space via basis functions  $\Phi(x)$   $\uparrow^{\phi_3(x)}$
- •For example, quadratic classifier:

$$x_i \to \phi(x_i) \ via \ \phi(\vec{x}) = \begin{bmatrix} \vec{x} \\ vec(\vec{x}\vec{x}^T) \end{bmatrix}$$

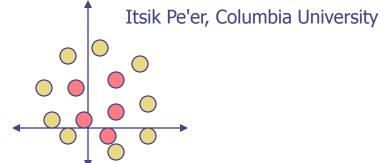
- •Call  $\phi$ 's feature vectors computed from original x inputs
- •Dual qp used to be:

$$L_D: \max \sum_i \alpha_i - \sum_{i,j} \alpha_i \alpha_j y_i y_j x_i^T x_j \ s.t. \alpha_i \ge 0 \ , \sum_i y_i \alpha_i = 0$$

•With linear classifier in original space:

$$f(x) = sign\left(\sum_{i} \alpha_{i} y_{i} x_{i}^{T} x + b\right)$$

•What if the problem is not linear?



 Map d-dimensional x data from L-space to high dimensional  $\phi_3(x)$ 

*H* (Hilbert) feature-space via basis functions  $\Phi(x)$ 

•For example, quadratic classifier:

$$x_i \to \phi(x_i) \ via \ \phi(\vec{x}) = \begin{bmatrix} \vec{x} \\ vec(\vec{x}\vec{x}^T) \end{bmatrix}$$



- •Replace all x's in the SVM equations with  $\phi$ 's
- •Now solve the following learning problem:

$$L_D: \max \sum_i \alpha_i - \sum_{i,j} \alpha_i \alpha_j y_i y_j \phi(x_i)^T \phi(x_j) \quad s.t. \alpha_i \ge 0 , \sum_i y_i \alpha_i = 0$$

•Which gives a nonlinear classifier in original space:

$$f(x) = sign\left(\sum_{i} \alpha_{i} y_{i} \phi(x_{i})^{T} \phi(x) + b\right)$$

# **Kernels** (see http://www.youtube.com/watch?v=3liCbRZPrZA)

•One important aspect of SVMs: all math involves only the *inner products* between the  $\phi$  features!

$$f(x) = sign\left(\sum_{i} \alpha_{i} y_{i} \phi(x_{i})^{T} \phi(x_{i}) + b\right)$$

- Replace all inner products with a general kernel function
- Mercer kernel: accepts 2 inputs and outputs a scalar via:

$$k(x,\tilde{x}) = \langle \phi(x), \phi(\tilde{x}) \rangle = \begin{cases} \phi(x)^T \phi(\tilde{x}) & \text{if } \phi \text{ is finite} \\ \int_t \phi(x,t) \phi(\tilde{x},t) dt & \text{otherwise} \end{cases}$$

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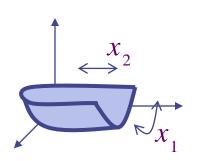
•Example: quadratic polynomial  $\phi(x) = \begin{bmatrix} x_1^2 & \sqrt{2}x_1x_2 & x_2^2 \end{bmatrix}$ 

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•Example: quadratic polynomial  $\phi(x) = |x_1^2| \sqrt{2}x_1x_2 - x_2^2|$ 



$$k(x, \tilde{x}) = \phi(x)^{T} \phi(\tilde{x})$$

$$= x_1^2 \tilde{x}_1^2 + 2x_1 x_2 \tilde{x}_1 \tilde{x}_2 + x_2^2 \tilde{x}_2^2$$

$$= (x_1 \tilde{x}_1 + x_2 \tilde{x}_2)^2$$

- •Sometimes, many  $\Phi(x)$  will produce the same k(x,x')
- •Sometimes k(x,x') computable but features huge or infinite!
- •Example: polynomials

  If explicit polynomial mapping, feature space  $\Phi(x)$  is huge

*d*-dimensional data, *p*-th order polynomial, 
$$dim(H) = \binom{d+p-1}{p}$$

images of size 16x16 with p=4 have dim(H)=183million

but can equivalently just use kernel: $k(x, y) = (x^T y)^p$  $k(x, \tilde{x}) =$ 

but can equivalently just use kernel: $k(x, y) = (x^T y)^p$ 

**Equivalent!** 

•Replace each  $x_i^T x_i \to k(x_i, x_i)$ , for example:

P-th Order Polynomial Kernel:  $k(x, \tilde{x}) = (x^T \tilde{x} + 1)^P$ 

RBF Kernel (infinite!):  $k(x, \tilde{x}) = \exp\left(-\frac{1}{2\sigma^2} ||x - \tilde{x}||^2\right)$ 

Sigmoid (hyperbolic tan) Kernel:  $k(x, \tilde{x}) = \tanh(\kappa x^T \tilde{x} - \delta)$ 

Using kernels we get generalized inner product SVM:

$$L_D: \max \sum_i \alpha_i - \sum_{i,j} \alpha_i \alpha_j y_i y_j \phi(x_i)^T \phi(x_j) \quad s.t. \ \alpha_i \in [0, C], \sum_i \alpha_i y_i = 0$$

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$$f(x) = sign\left(\sum_{i} \alpha_{i} y_{i} k(x_{i}, x) + b\right)$$

•Still qp solver, just use Gram matrix *K* (positive definite)

$$K_{i,j} = k(x_i, x_j)$$

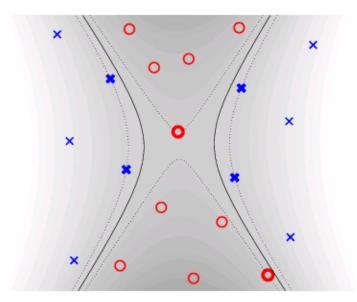
$$K = \begin{bmatrix} k(x_1, x_1) & k(x_2, x_1) & k(x_3, x_1) \\ k(x_1, x_2) & k(x_2, x_2) & k(x_3, x_2) \\ k(x_1, x_3) & k(x_2, x_3) & k(x_3, x_3) \end{bmatrix}$$

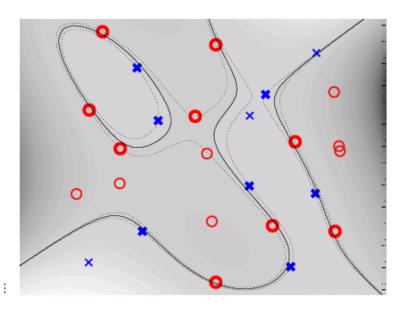
#### Kernelized SVMs

•Polynomial kernel:

- $k(x, \tilde{x}) = (x^T \tilde{x} + 1)^P$
- Polynomial Kernel

•Radial basis function kernel: 
$$k(x, \tilde{x}) = \exp\left(-\frac{1}{2\sigma^2}||x - \tilde{x}||^2\right)$$
  
Polynomial Kernel RBF kernel





•Least-squares, logistic-regression, perceptron: also kernelizable

# Summary

- Nonseparable SVM
- Kernels