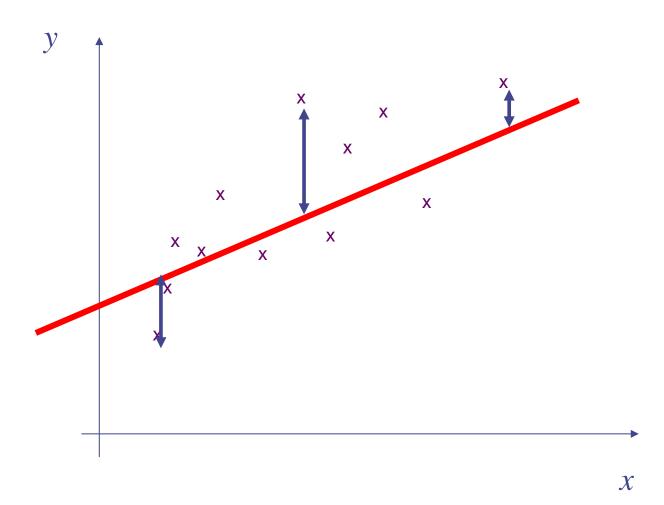
Machine Learning 4771

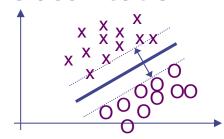
Instructor: Itsik Pe'er

Reminder: Gaussian Noise

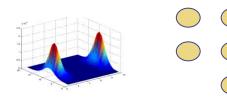


Regression

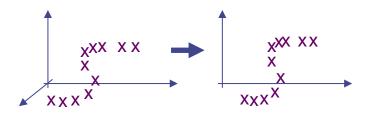
Classification

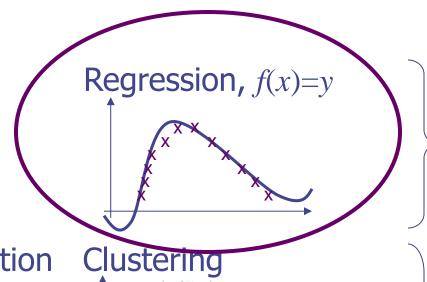


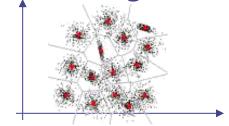




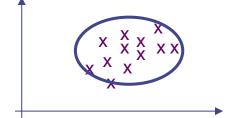
Feature Selection







Anomaly Detection



Supervised

Outline

- Regression
- Empirical Risk Minimization
- Least Squares
- Higher Order Polynomials
- Under-fitting / Over-fitting
- Cross-Validation

Start with training dataset

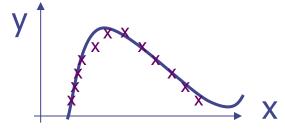
$$X = \{(x_1, y_1), (x_1, y_1), \dots, (x_N, y_N)\} \qquad x \in \mathbf{R}^D = \begin{bmatrix} x(1) \\ x(2) \\ \vdots \\ x(D) \end{bmatrix}, y \in \mathbf{R}$$

- •Have *N* (input, output) pairs
- •Find a function f(x) to predict y from xThat fits the training data well

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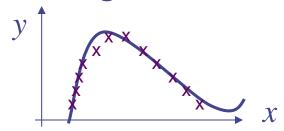


•Example: predict your grade y in ML x = [HW grades; quiz grades; midterm; final]

Start with training dataset

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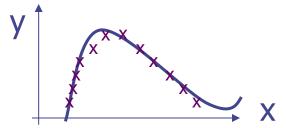
x = [HW grades; quiz grades; midterm; final]

x = [HW 1-4 grades; quiz 1 grade; midterm]

Start with training dataset

$$X = \{(x_1, y_1), (x_1, y_1), \dots, (x_N, y_N)\} \qquad x \in \mathbf{R}^D = \begin{bmatrix} x(1) \\ x(2) \\ \vdots \\ x(D) \end{bmatrix}, y \in \mathbf{R}$$

- Have N (input, output) pairs
- Find a function f(x) to predict y from x
 That fits the training data well



- •Example: predict the price of house in dollars y using x = [#rooms; latitude; longitude; ...]
- Need: a) Way to evaluate how good a fit we have
 b) Class of functions in which to search for f(x)

Empirical Risk Minimization

- •Idea: minimize 'loss' on the training data set
- •Empirical = use the training set to find the best fit
- Define a loss function of how good we fit a single point:

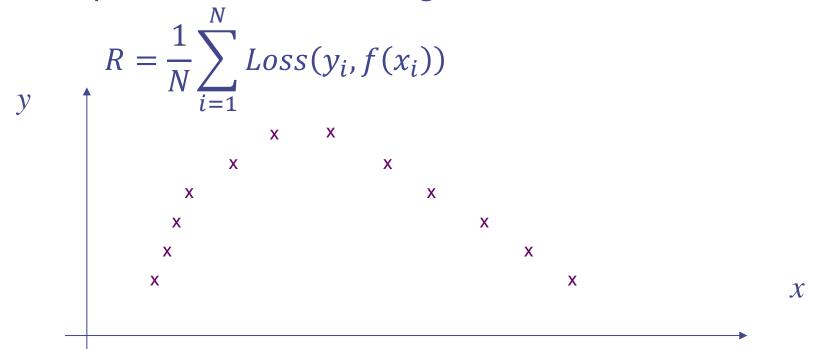
$$Loss(y, f(x)) = -\log Prob(y|f(x))$$

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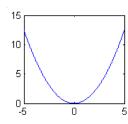
$$R = \frac{1}{N} \sum_{i=1}^{N} Loss(y_i, f(x_i))$$

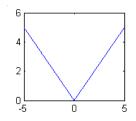
•Gaussian noise: squared error from y value 5

$$Loss(y_i, f(x_i)) = \frac{1}{2}(y_i - f(x_i))^2$$

Other possible loss: absolute error

$$Loss(y_i, f(x_i)) = |y_i - f(x_i)|$$





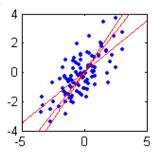
Linear Function Classes

•Linear is simplest class of functions to search over:

$$f(x;\theta) = \theta^T x + \theta_0 = \theta_0 + \sum_{d=1}^{\infty} \theta_d x(d)$$

•Start with x being 1-dimensional (D=1):

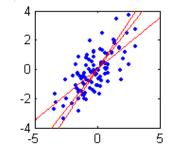
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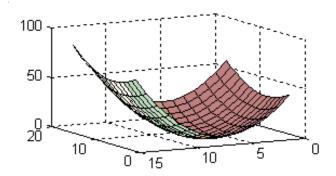
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•Start with x being 1-dimensional (D=1):

$$f(x;\theta) = \theta_1 x + \theta_0$$

•Plug in the above & minimize empirical risk over θ



$$R(\theta) = \frac{1}{2N} \sum_{i=1}^{N} (y_i - \theta_1 x_i - \theta_0)^2$$

•Note: minimum occurs when $R(\theta)$ gets flat (not always!)

•Note: when $R(\theta)$ is flat, gradient $\nabla_{\theta} R = 0$

Min by Gradient=0

- Gradient=0 means the partial derivatives are all 0
- Take partials of empirical risk:

$$R(\theta) = \frac{1}{2N} \sum_{i=1}^{N} (y_i - \theta_1 x_i - \theta_0)^2$$

$$\nabla_{\theta} R = \begin{bmatrix} \frac{\partial R}{\partial \theta_0} \\ \frac{\partial R}{\partial \theta_1} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

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$$\frac{\partial R}{\partial \theta_0} = \frac{1}{N} \sum_{i=1}^{N} (y_i - \theta_1 x_i - \theta_0)(-1) = 0$$

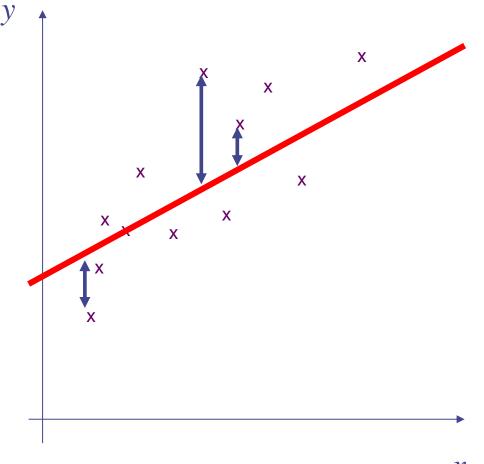
$$\frac{\partial R}{\partial \theta_1} = \frac{1}{N} \sum_{i=1}^{N} (y_i - \theta_1 x_i - \theta_0)(-x_i) = 0$$

$$\nabla_{\theta} R = \begin{bmatrix} \frac{\partial R}{\partial \theta_0} \\ \frac{\partial R}{\partial \theta_1} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Interpreting the equations

$$\frac{1}{N} \sum_{i=1}^{N} (y_i - \theta_1 x_i - \theta_0) = 0$$

$$\frac{1}{N} \sum_{i=1}^{N} x_i (y_i - \theta_1 x_i - \theta_0) = 0$$



Interpreting the equations

$$\frac{1}{N} \sum_{i=1}^{N} (y_i - \theta_1 x_i - \theta_0) = 0$$

$$\hat{E}(Err) = Avg(err_i) = \frac{1}{N} \sum_{i=1}^{N} err_i = 0$$

$$\frac{1}{N} \sum_{i=1}^{N} x_i (y_i - \theta_1 x_i - \theta_0) = 0$$

$$\hat{Cov}(X, Err) = \hat{E}(x_i err_i) = \frac{1}{N} \sum_{i=1}^{N} x_i err_i = 0$$

Solving Least Squares

$$\frac{1}{N} \sum_{i=1}^{N} (y_i - \theta_1 x_i - \theta_0) = 0$$

$$\frac{1}{N} \sum_{i=1}^{N} x_i (y_i - \theta_1 x_i - \theta_0) = 0$$

Solving Least Squares

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$$\frac{1}{N} \sum_{i=1}^{N} x_i (y_i - \theta_1 x_i - \theta_0) = 0$$

$$\theta_0 = \frac{1}{N} \sum_{i=1}^{N} y_i - \theta_1 \frac{1}{N} \sum_{i=1}^{N} x_i$$

$$\theta_1 \sum_{i=1}^{N} x_i^2 = \sum_{i=1}^{N} x_i y_i - \theta_0 \sum_{i=1}^{N} x_i$$

$$\theta_1 = \frac{\sum x_i y_i - \frac{1}{N} \sum y_i \sum x_i}{\sum x_i^2 - \frac{1}{N} \sum x_i \sum x_i}$$

- •More elegant/general to solve $\nabla_{\theta} R = 0$ with linear algebra
- Rewrite empirical risk in vector-matrix notation:

$$R(\theta) = \frac{1}{2N} \sum_{i=1}^{N} (y_i - \theta_1 x_i - \theta_0)^2$$

Can add more dimensions by adding columns to X matrix and rows to θ vector

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$$= \frac{1}{2N} \sum_{i=1}^{N} \left(y_i - \begin{bmatrix} 1 & x_i \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} \right)^2$$

$$= \frac{1}{2N} \left\| \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix} - \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} \right\|^2$$

$$= \frac{1}{2N} \| \mathbf{y} - \mathbf{X}\theta \|^2$$

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$$= \frac{1}{2N} \sum_{i=1}^{N} \left(y_i - [1 \quad x_i] \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} \right)^2$$

$$= \frac{1}{2N} \left\| \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix} - \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} \right\|^2$$

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- •More elegant/general to solve $\nabla_{\theta} R = 0$ with linear algebra
- •Rewrite empirical risk in vector-matrix notation:

$$R(\theta) = \frac{1}{2N} \sum_{i=1}^{N} (y_i - \theta_1 x_i(1) - \dots - \theta_D x_i(D) - \theta_0)^2$$

$$= \frac{1}{2N} \sum_{i=1}^{N} \left(y_i - \begin{bmatrix} 1 & x_i(1) \cdots & x_i(D) \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_D \end{bmatrix} \right)^2$$

$$= \frac{1}{2N} \left\| \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix} - \begin{bmatrix} 1 & x_1(1) \cdots & x_1(D) \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_N(1) \cdots & x_N(D) \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_D \end{bmatrix} \right\|^2$$
 Can add more dimensions by adding columns to X matrix and rows to θ vector
$$= \frac{1}{2N} \|\mathbf{y} - \mathbf{X}\theta\|^2$$

Can add more rows to θ vector

- More realistic dataset: many measurements
- Have N apartments each with D measurements
- •Each row of *X* is [#rooms; latitude; longitude,...]

$$\boldsymbol{X} = \begin{bmatrix} 1 & x_1(1) \cdots & x_1(D) \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_N(1) \cdots & x_N(D) \end{bmatrix}$$





785 Fifth Avenue #PH1718

Co-op, Lenox Hill

Listed by Corcoran

\$65,000,000

IN CONTRACT

7 beds 11 baths

•Solving gradient=0 $\nabla_{\theta} R = 0$

$$\nabla_{\theta} \left(\frac{1}{2N} \| \mathbf{y} - \mathbf{X}\theta \|^2 \right) = 0$$

•Solving gradient=0 $\nabla_{\theta} R = 0$

$$\nabla_{\theta} \left(\frac{1}{2N} || \mathbf{y} - \mathbf{X}\theta ||^{2} \right) = 0$$

$$\frac{1}{2N} \nabla_{\theta} \left((\mathbf{y} - \mathbf{X}\theta)^{T} (\mathbf{y} - \mathbf{X}\theta) \right) = 0$$

$$\frac{1}{2N} \nabla_{\theta} (y^{T}y - 2y^{T}X\theta + \theta^{T}X^{T}X\theta) = 0$$

$$\frac{1}{2N} (-2X^{T}y + 2X^{T}X\theta) = 0$$

$$X^{T}X\theta = X^{T}y$$

$$\theta^{*} = (X^{T}X)^{-1}X^{T}y$$

Solving gradient=0

$$X^T X \theta = X^T y$$
$$\theta^* = (X^T X)^{-1} X^T y$$

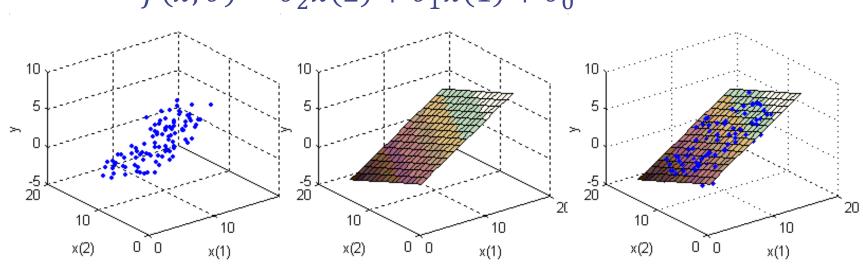
- •If the matrix X is skinny, the solution is probably unique
- •If *X* is fat (more dimensions than points) we get multiple solutions for theta which give zero error.
- •The pseudeoinverse (numpy.linalg.pinv(X)) returns the theta with zero error and which has the smallest norm.

$$min_{\theta} \|\theta\|^2$$
 such that $X\theta = y$

2D Linear Regression

•Once best θ^* is found, we can plug it into the function:

$$f(x;\theta) = \theta_2^* x(2) + \theta_1^* x(1) + \theta_0^*$$

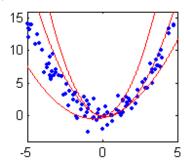


•What would a fat X look like?

Polynomial Function Classes

•Back to 1-dim x (D=1) BUT Nonlinear

•Polynomial:
$$f(x; \theta) = \sum_{p=0}^{P} \theta_p x^p$$

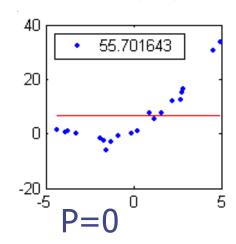


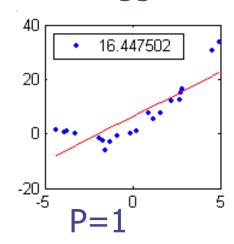
Polynomial Function Classes

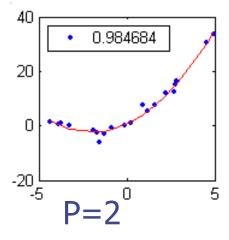
- Back to 1-dim x (D=1) BUT Nonlinear
- •Polynomial: $f(x; \theta) = \sum_{p}^{p} \theta_{p} x^{p}$
- •Writing Risk: $R(\theta) = \frac{1}{2N} \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix} \begin{bmatrix} 1 & x_1^1 \cdots & x_1^P \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_N^1 \cdots & x_N^P \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_D \end{bmatrix}^{\frac{5}{2}}$
- •Order-*P* polynomial regression fitting for 1D variable is same as *P*-dimensional linear regression!
- •Construct a multidim $X_i = [x_i^0 \ x_i^1 \ x_i^2 \ x_i^3]$ X-vector from x scalar
- •More generally any $X_i = [\phi_0(x_i) \quad \phi_1(x_i) \quad \phi_2(x_i) \quad \phi_3(x_i)]$

Underfitting/Overfitting

- •Try varying P. Higher P fits a more complex function class
- •Observe $R(\theta^*)$ drops with bigger P

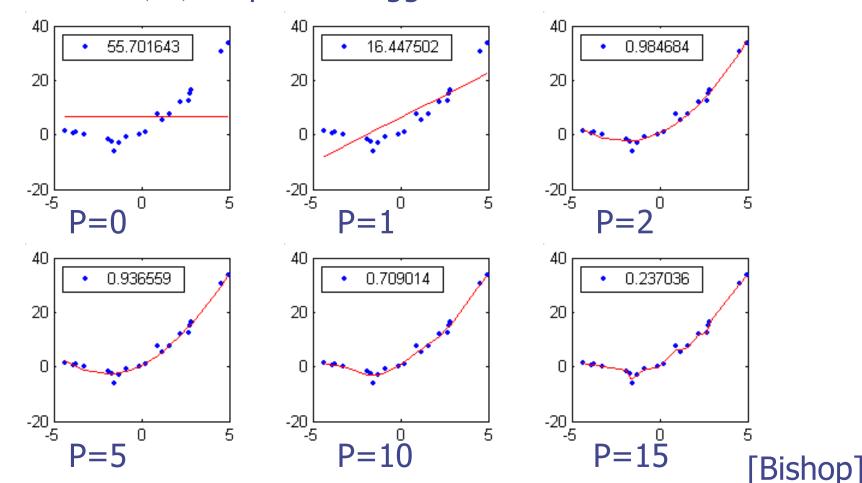






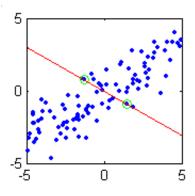
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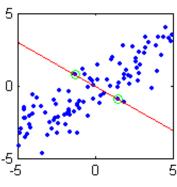
Evaluating The Regression

- Unfair to use empirical to find best order P
- •High P (vs. N) can overfit, even linear case!
- •min $R(\theta^*)$ not on training but on future data
- •Want model to *Generalize* to future data



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True loss:
$$R_{true}(\theta) = \int p(x,y) \frac{1}{2} (y - \theta^T x)^2 dx dy$$

One approach: split data into training / testing portion

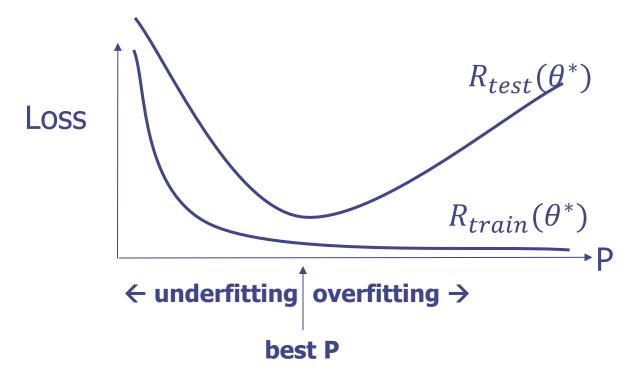
$$\{(x_1, y_1), \dots, (x_N, y_N)\} \qquad \{(x_{N+1}, y_{N+1}), \dots, (x_{N+M}, y_{N+M})\}$$

•Estimate θ^* with training loss: $R_{train}(\theta) = \frac{1}{2N} \sum_{i=1}^{N} (y_i - \theta^T x_i)^2$

•Evaluate P with testing loss:
$$R_{test}(\theta^*) = \frac{1}{2M} \sum_{i=N+1}^{N+M} (y_i - \theta^{*T} x_i)^2$$

Crossvalidation

- Try fitting with different polynomial order P
- •Select P which gives lowest $R_{test}(\theta^*)$



- •Think of P as a measure of the complexity of the model
- •Higher order polynomials are more flexible and complex

Summary

- Regression: approximating a function
- Minimizing loss function
- Least squares solution to linear regression
- Vector/matrix representation
- Hi-dimension, polynomial regression
- Overfit/underfit