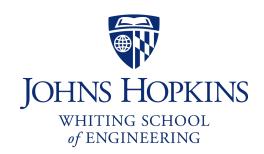
CS 318 Principles of Operating Systems

Fall 2017

Lecture 4: Scheduling

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Administrivia

Lab 0

- Due today
- "Lab 0 Unlimited Attempts" in Blackboard

Lab 1 released

- Due in two weeks
- Guoye will do a review session
- If you still don't have a group, hurry up and let us know soon

Office hours

Recap: Processes

The process is the OS abstraction for execution

- own view of machine

Process components

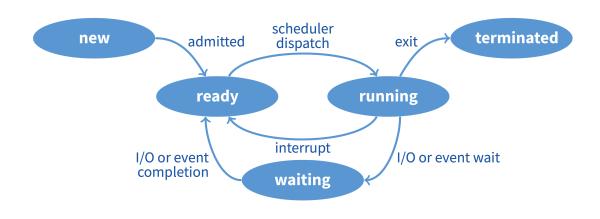
- address space, program counter, registers, open files, etc.
- kernel data structure: Process Control Block (PCB)

Process states and APIs

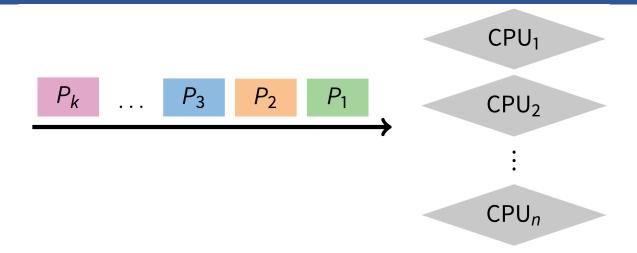
- state graph and queues
- process creation, deletion, waiting

Multiple processes

- overlapping I/O and CPU activities
- context switch



Scheduling Overview

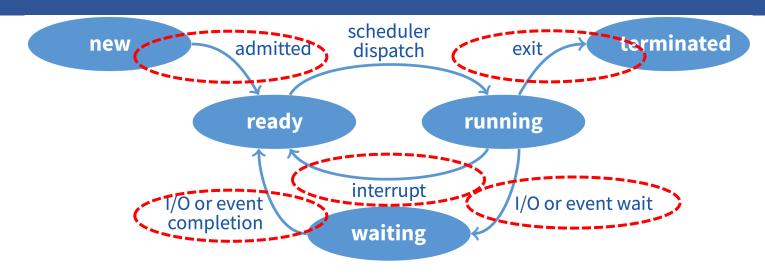


- The scheduling problem:
 - Have *K* jobs ready to run
 - Have $N \geq 1$ CPUs
- Policy: which jobs should we assign to which CPU(s), for how long?
 - we'll refer to schedulable entities as jobs could be processes, threads, people, etc.
- Mechanism: context switch, process state queues

Scheduling Overview

- 1. Goals of scheduling
- 2. Textbook scheduling
- 3. Priority scheduling
- 4. Advanced scheduling topics

When Do We Schedule CPU?



- Scheduling decisions may take place when a process:
 - 1. Switches from running to waiting state
 - 2. Switches from running to ready state
 - 3. Switches from new/waiting to ready
 - 4. Exits
- Non-preemptive schedules use 1 & 4 only
- Preemptive schedulers run at all four points

Scheduling Goals

Scheduling works at two levels in an operating system

- To determine the multiprogramming level # of jobs loaded into memory
 - Moving jobs to/from memory is often called swapping
- To decide what job to run next to guarantee "good service"
 - Good service could be one of many different criteria

Known as long-term and short-term scheduling decisions

- Long-term scheduling happens relatively infrequently
 - Significant overhead in swapping a process out to disk
- Short-term scheduling happens relatively frequently
 - Want to minimize the overhead of scheduling
 - Fast context switches, fast queue manipulation

Scheduling Criteria

- Why do we care?
 - What concrete goals should we have for a scheduling algorithm?

Scheduling Criteria

- Throughput # of processes that complete per unit time
 - Higher is better
- Turnaround time time for each process to complete
 - Lower is better
- Response time time from request to first response
 - i.e., time spent on ready queue (e.g., key press to echo, not launch to exit)
 - Lower is better
- Above criteria are affected by secondary criteria
 - **CPU utilization** fraction of time CPU doing productive work
 - Waiting time time each process waits in wait queue

Scheduling Goals

Scheduling algorithms can have many different goals:

- Job throughput (# jobs/time)
- Turnaround time (T_{finish} T_{start})
- Response time ($Avg(T_{readv})$: avg time spent on ready queue)
- CPU utilization (%CPU)
- Waiting time ($Avg(T_{wait})$: avg time spent on wait queues)

Batch systems

- Strive for job throughput, turnaround time (supercomputers)

Interactive systems

- Strive to minimize response time for interactive jobs (PC)

Scheduling "Non-goal": Starvation

- Starvation is when a process is prevented from making progress because some other process has the resource it requires
 - Resource could be the CPU, or a lock (recall readers/writers)
- Starvation usually a side effect of the sched. algorithm
 - A high priority process always prevents a low priority process from running
 - One thread always beats another when acquiring a lock
- Starvation can be a side effect of synchronization
 - Constant supply of readers always blocks out writers

Example: FCFS Scheduling

- Run jobs in order that they arrive
 - Called "First-come first-served" (FCFS)
 - E.g., Say P₁ needs 24 sec, while P₂ and P₃ need 3.
 - Say P₂, P₃ arrived immediately after P₁, get:



- Throughput: 3 jobs / 30 sec = 0.1 jobs/sec
- Turnaround Time: P₁: 24, P₂: 27, P₃: 30
 - Average TT: (24 + 27 + 30) / 3 = 27
- Can we do better?

FCFS Continued

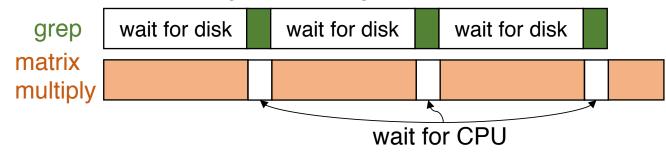
- Suppose we scheduled P₂, P₃, then P₁
 - Would get:



- Throughput: 3 jobs / 30 sec = 0.1 jobs/sec
- Turnaround Time: P₁: 30, P₂: 3, P₃: 6
 - Average TT: (30 + 3 + 6) / 3 = 13 much less than 27
- Lesson: scheduling algorithm can reduce TT
 - Minimizing waiting time can improve RT and TT
- Can a scheduling algorithm improve throughput?
 - Yes, if jobs require both computation and I/O

View CPU and I/O devices the same

- CPU is one of several devices needed by users' jobs
 - CPU runs compute jobs, Disk drive runs disk jobs, etc.
 - With network, part of job may run on remote CPU
- Scheduling 1-CPU system with n I/O devices like scheduling asymmetric (n+1)-CPU multiprocessor
 - Result: all I/O devices + CPU busy → (n + 1)-fold throughput gain!
- Example: disk-bound grep + CPU-bound matrix multiply
 - Overlap them just right? throughput will be almost doubled



FCFS Convoy Effect

The Convoy Effect, visualized

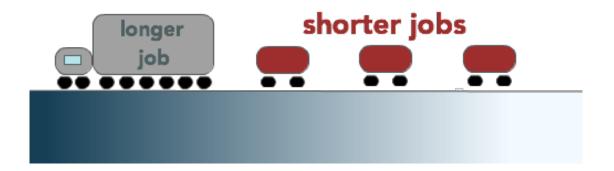


image source: http://web.cs.ucla.edu/classes/fall14/cs111/scribe/7a/convoy_effect.png

FCFS Convoy Effect



FCFS Convoy Effect

CPU-bound jobs will hold CPU until exit or I/O

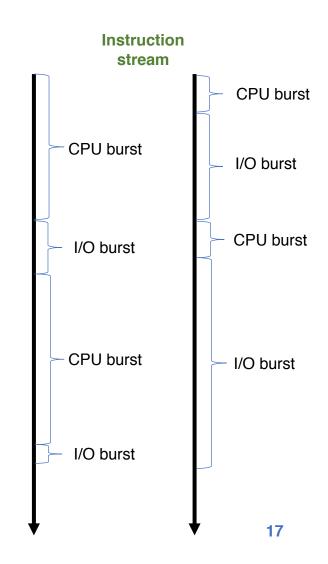
- Long periods where no I/O requests issued, and CPU held
- Result: poor I/O device utilization

Example: one CPU-bound job, many I/O bound

- CPU-bound job runs (I/O devices idle)
- Eventually, CPU-bound job blocks
- I/O-bound jobs run, but each quickly blocks on I/O
- CPU-bound job unblocks, runs again
- All I/O requests complete, but CPU-bound job still hogs CPU
- I/O devices sit idle since I/O-bound jobs can't issue next requests

Simple hack: run process whose I/O completed

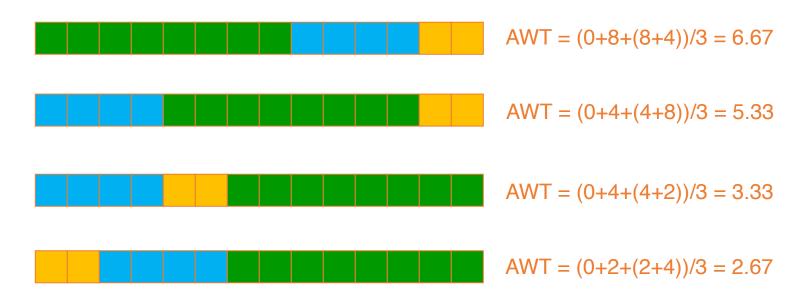
- What is a potential problem?
 - I/O-bound jobs can starve CPU-bound one



Shortest Job First (SJF)

Shortest Job First (SJF)

- Choose the job with the smallest expected CPU burst
 - Person with smallest number of items to buy
- Provably optimal minimum average waiting time (AWT)



Shortest Job First (SJF)

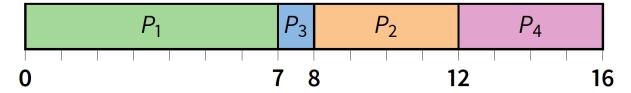
Two schemes

- Non-preemptive once CPU given to the process it cannot be preempted until completes its CPU burst
- Preemptive if a new process arrives with CPU burst length less than remaining time of current executing process, preempt
 - Known as the Shortest-Remaining-Time-First or SRTF

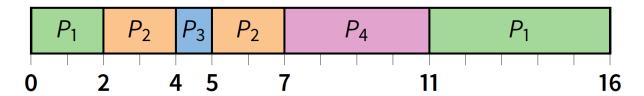
Examples

Process	Arrival Time	Burst Time
P_1	0	7
P_2	2	4
P_3	4	1
P_4	5	4

Non-preemptive



Preemptive



What is the AWT?

SJF Limitations

Problems

- Impossible to know size of CPU burst
 - Like choosing person in line without looking inside basket/cart
- How can you make a reasonable guess?
 - Estimate CPU burst length based on past
 - e.g., exponentially weighted average
- Doesn't always minimize average TT
 - Only minimizes waiting time
 - Example where turnaround time might be suboptimal?
- Can potentially lead to unfairness or starvation

Round Robin (RR)

 P_1 P_2 P_3 P_1 P_2 P_3

Solution to fairness and starvation

- Each job is given a time slice called a quantum
- Preempt job after duration of quantum
- When preempted, move to back of FIFO queue

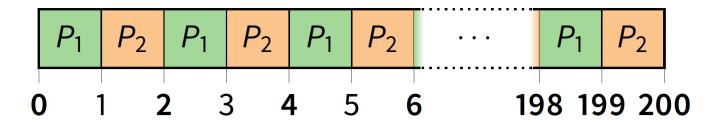
Advantages:

- Fair allocation of CPU across jobs
- Low average waiting time when job lengths vary
- Good for responsiveness if small number of jobs

Disadvantages?

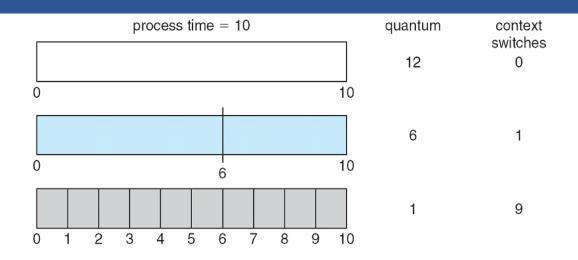
RR Disadvantages

- Context switches are frequent and need to be very fast
- Varying sized jobs are good ...what about same-sized jobs?
- Assume 2 jobs of time=100 each:



- Even if context switches were free...
 - What would average turnaround time be with RR?
 - How does that compare to FCFS?

Time Quantum



• How to pick quantum?

- Want much larger than context switch cost
- Majority of bursts should be less than quantum
- But not so large system reverts to FCFS
- Typical values: 1–100 msec

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Priority Scheduling

Priority Scheduling

- Associate a numeric priority with each process
 - E.g., smaller number means higher priority (Unix/BSD)
 - Or smaller number means lower priority (<u>Pintos</u>)
- Give CPU to the process with highest priority
 - Airline check-in for first class passengers
 - Can be done preemptively or non-preemptively
- Can implement SJF, priority = 1/(expected CPU burst)
- Problem: starvation low priority jobs can wait indefinitely

Solution?

- "Age" processes
 - Increase priority as a function of waiting time
 - Decrease priority as a function of CPU consumption

Combining Algorithms

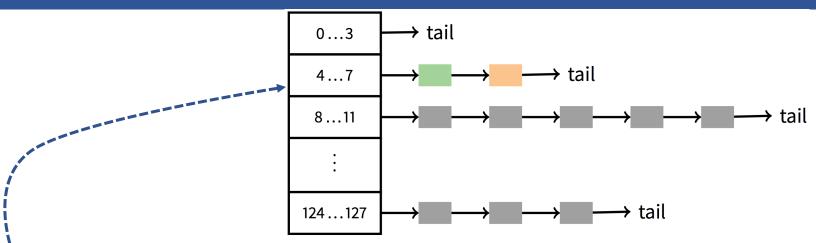
Scheduling algorithms can be combined

- Have multiple queues
- Use a different algorithm for each queue
- Move processes among queues

Example: Multiple-level feedback queues (MLFQ)

- Multiple queues representing different job types
 - Interactive, CPU-bound, batch, system, etc.
- Queues have priorities, jobs on same queue scheduled RR

MLFQ in BSD



- Every runnable process on one of 32 run queues
- ---- Kernel runs process on highest-priority non-empty queue
 - Round-robins among processes on same queue
- Process priorities dynamically computed
 - Processes moved between queues to reflect priority changes
- Idea: Favor interactive jobs that use less CPU

Process Priority

- p_nice user-settable weighting factor
- p_estcpu per-process estimated CPU usage
 - Incremented whenever timer interrupt found process running
 - Decayed every second while process runnable

$$p_estcpu \leftarrow \left(\frac{2 * load}{2 * load + 1}\right) * p_estcpu + p_nice$$

- Load is sampled average of length of run queue plus short-term sleep queue over last minute
- Run queue determined by p_usrpri/4

$$p_usrpri \leftarrow 50 + \left(\frac{p_estcpu}{4}\right) + 2 * p_nice$$

Sleeping Process Increases Priority

- p_estcpu not updated while asleep
 - Instead p_slptime keeps count of sleep time
- When process becomes runnable

$$p_estcpu \leftarrow \left(\frac{2 * load}{2 * load + 1}\right)^{p_slptime} * p_estcpu$$

- Approximates decay ignoring nice and past loads
- Description based on "The Design and Implementation of the 4.4BSD Operating System"

Pintos Notes

Same basic idea for second half of Lab 1

- But 64 priorities, not 128
- Higher numbers mean higher priority
- Okay to have only one run queue if you prefer (less efficient, but we won't deduct points for it)

Have to negate priority equation:

$$priority = 63 - \left(\frac{recent_cpu}{4}\right) - 2 * nice$$

Priority Inversion

Two tasks: H at high priority, L at low priority

- L acquires lock | for exclusive use of a shared resource R
- If H tries to acquire I, blocked until L release resource R
- M enters system at medium priority, preempts L
 - L unable to release R in time
 - H unable to run, despite having higher priority than M

A famous example: Mars PathFinder failure in 1997

 low-priority data gathering task and a medium-priority communications task prevented the critical bus management task from running

Priority Donation

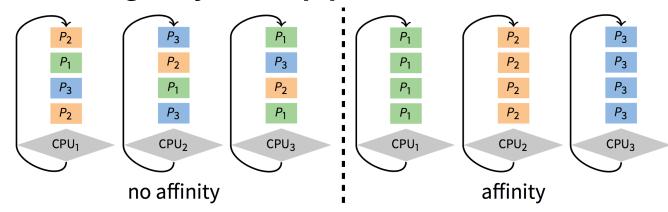
- Say higher number = higher priority (like Pintos)
- Example 1: L (prio 2), M (prio 4), H (prio 8)
 - L holds lock I
 - M waits on I, L's priority raised to $L_1 = \max(M; L) = 4$
 - Then H waits on I, L's priority raised to $max(H; L_1) = 8$
- Example 2: Same L,M,H as above
 - L holds lock I, M holds lock I₂
 - M waits on I, L's priority now $L_1 = 4$ (as before)
 - Then H waits on I_2 . M's priority goes to $M_1 = \max(H; M) = 8$, and L's priority raised to $\max(M_1; L_1) = 8$

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Multiprocessor Scheduling Issues

- Must decide on more than which processes to run
 - Must decide on which CPU to run which process
- Moving between CPUs has costs
 - More cache misses, depending on arch. more TLB misses too
- Affinity scheduling—try to keep process/thread on same CPU



- But also prevent load imbalances
- Do cost-benefit analysis when deciding to migrate...affinity can also be harmful, particularly when tail latency is critical

Multiprocessor Scheduling (cont)

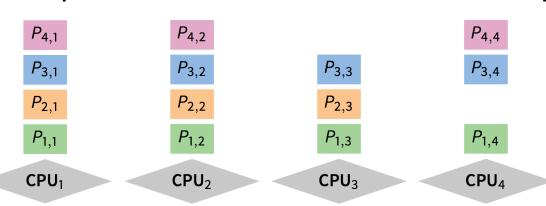
Want related processes/threads scheduled together

- Good if threads access same resources (e.g., cached files)
- Even more important if threads communicate often, otherwise must context switch to communicate

Gang scheduling—schedule all CPUs synchronously

- With synchronized quanta, easier to schedule related processes/threads

together



Real-time Scheduling

Two categories:

- Soft real time—miss deadline and CD will sound funny
- Hard real time—miss deadline and plane will crash

System must handle periodic and aperiodic events

- E.g., processes A, B, C must be scheduled every 100, 200, 500 msec, require 50, 30, 100 msec respectively
- Schedulable if $\sum \frac{cpu}{period} \le 1$

Variety of scheduling strategies

- E.g., first deadline first (works if schedulable, otherwise fails spectacularly)

Scheduling Summary

- Scheduling algorithm determines which process runs, quantum, priority...
- Many potential goals of scheduling algorithms
 - Utilization, throughput, wait time, response time, etc.
- Various algorithms to meet these goals
 - FCFS/FIFO, SJF, RR, Priority
- Can combine algorithms
 - Multiple-level feedback queues
- Advanced topics
 - affinity scheduling, gang scheduling, real-time scheduling

Next Time

Read Chapter 26, 27