1. Systolic architectures

- (a) Given an input vector $\mathbf{A}:[a_1, a_2, a_3, a_4, a_5, a_6, a_7]$ and weight vector $\mathbf{W}:[w_1, w_2, w_3]$, [15 pts] design systolic arrays of processing engines (PEs) for each of the design specifications listed below to perform 1D-convolution of input and weight vectors resulting in the output vector $\mathbf{Y}:[y_1, y_2, ...]$, where $y_n = w_1x_n + w_2x_{n+1} + w_3x_{n+2}$:
 - (1) Weights stationary in PEs; Inputs broadcasted; Outputs move systolically.
 - (2) Weights stationary in PEs; Inputs move systolically; Outputs evaluated through fan-in of partial sums from PEs.
 - (3) Weights stationary in PEs; Inputs and outputs move systolically in opposite direction.

Clearly indicate all the signals, appropriately timed, and consider PE as a black box that computes MAC.

- (b) Design a 2-D mesh of systolic PEs to carry out matrix-matrix multiplication between [20 pts] $A_{3\times3}$ and $W_{3\times3}$ matrices with output stationary dataflow. Clearly illustrate all the signals and timed dataflow and consider PE as a black box that computes MAC in one cycle.
 - (1) Calculate total cycles for the above operation.
 - (2) Consider mixed-precision operation where weights are quantized to 8 bits (Int), inputs quantized to 16 bits (half-float) and outputs are single precision floating-point. What is the suitable dataflow (input or weight or output stationarity) for area efficiency?
 - (3) Calculate the PE utilization to process above matrices when the dataflow is weight stationary and size of the PE array is 32 ×32.
- (c) Consider the following parameters of a CNN model (FastRCNN):

[25 pts]

Ow: The width of output feature map

Oh: The height of output feature map

kw: The width of filterkh: The height of filterC: The number of channels

F: The number of filters

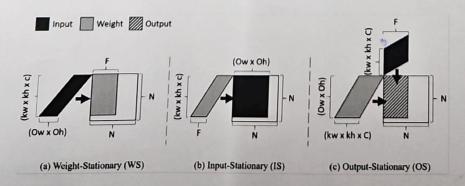


Figure 1: Execution workflow of three dataflows

Each layer of the model is parameterized as (Ow, Oh, kw, kh, C, F): layer L1(56, 56, 1, 1, 64, 256), layer L2(26, 26, 3, 3, 128, 128), layer L3(14, 14, 1, 1, 512, 1024). The size of systolic array is 128×128 .

- (1) Calculate the execution time of all three dataflows for all three layers on the systolic array (refer Fig. 1).
- (2) Can we opt for a single dataflow for all three layers on the systolic array?
- (3) Which of the dataflow policies (input or weight or output stationary) is the best for each of the three layers.

Design a multi-dataflow processing engine (PE) and datapath controller micro- [10 pts] architectures for the port mapping given below.

| | Weight-stationary | Input-stationary | Output-stationary |
|----------|-------------------|------------------|-------------------|
| preload | Weight | Input | X |
| Input_0 | X | X | Weight |
| Input 1 | PartialSum | PartialSum | X |
| Input 2 | Input | Weight | Input |
| Output 0 | X | X | Weight |
| Output 1 | PartialSum' | PartialSum' | X |
| Output_2 | Input | Weight | Input |

Figure 2: Port mapping in each dataflow

2. Model Compression

Consider the following Convolutional Neural Network (CNN) designed for CIFAR-10 classification (input image size: $32 \times 32 \times 3$):

- Conv1: 3×3 kernel, stride = 1, padding = 1, 32 output channels
- Conv2: 3×3 kernel, stride = 1, padding = 1, 64 output channels, followed by 2×2 max-pooling
- FC1: Fully connected layer with 512 hidden units
- FC2: Fully connected layer with 10 output units (for classification)

(a) Basics of CNNs

[10 pts]

- Compute the number of trainable parameters and MACs (Multiply-Accumulate operations) in each layer and total parameters in the network.
 - 2. Suppose the Conv2 is replaced by Conv2 (depthwise separable) depthwise 3×3 (stride = 1, padding =1) on the incoming channels, followed by a pointwise 1×1 to 64 output channels, then a 2×2 max-pool (stride 2). Compute the number of trainable parameters and MACs again.

(b) Pruning

[20 pts]

1. Suppose we do unstructured pruning to remove 50% of weights in Conv2. What is the MACs and number of parameters that need to be stored? Explain your answer.

- 2. Suppose we do 3x3 filter pruning of 50% of the filters on Conv2. What is the MACs and number of parameters that need to be stored? Explain your answer with appropriate examples of the Matrix multiplication that happens.
- (c) Discuss the pros and cons of Uniform/Linear Quantization vs Nonlinear/K-Means [20 pts] based quantization?