

### EECS 336, Problem 7.3

#### Question a:

Reduction to maximum flow:

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#### Algorithm 1 No Child Left Behind

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**Require:**  $n, m, M$

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1: function NOCHILDLEFTBEHIND( $m, n, M$ )
2:   Create vertices for each orphan and potential mentor, and add vertices
    $s, s', t, t'$ .
3:   for each potential mentor  $j$  do
4:     Connect  $j$  to  $t$  with capacity 1.
5:     if orphan  $i$  is in  $L_j$  then
6:       connect direct edge  $e = (i, j)$  with capacity 1.
7:     end if
8:   end for
9:   for each orphan  $i$  in the existing matching  $M$  do
10:    connect  $s'$  to  $i$  with capacity 1.
11:  end for
12:  connect  $t$  to  $s$  with capacity infinity (or a very large value).
13:  Connect  $s$  to  $t'$  with capacity = "the number of orphans in the existing
   matching  $M$ " (Denote as  $a$ ).
14:  Let  $G_0 =$  current graph
15:  for each orphan  $i$  that is not in the existing matching  $M$  do
16:    Let  $G' = G_0$ 
17:    on  $G'$ , connect  $s'$  to  $i$  with capacity 1.
18:     $c((s, t')) = a+1$ 
19:    connect  $s$  to all the orphans not in  $M$  except  $i$ 
20:    Taking  $s'$  as the source,  $t'$  as the sink, run Max-flow algorithm, max-
    flow =  $f^*$ .
21:    if  $f^* = c((s, t'))$  then
22:      Return True.
23:    end if
24:  end for
25:  Return False
26: end function
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#### RunTime:

Line 2 takes  $O(m+n+4) = O(m+n)$

Line 3-8 takes  $O(m + |L_i|)$

Line 9-13 takes  $O(n)$ .

Line 14 takes  $O(m+n+|L_i|)$ .

Line 15-25 can have at most  $n$  iterations, for each iteration, a max-flow takes  $O(n * (|L| + n + m + 2))$ . So totally it takes  $O(n^2 * (|L| + n + m))$ . (Note  $|L| \leq mn$ )  
Total Runtime  $O(n^2 * (|L| + n + m))$  or  $O(n^3 * m)$ .

#### Correctness of reduction:

The algorithm is actually created by two reductions. Here we will prove the correctness of both reductions individually.

**Reduction 1:**

We firstly add vertex  $s$  and  $t$  in addition to the  $n$  vertices for orphans and  $m$  vertices for mentors. Then the orphans and mentors are connected with capacity 1 based on  $L$ . We also connect all mentors to  $t$  with capacity 1. When we connect  $s$  to the orphans, 1) if orphan  $i$  is in  $M$ , then connect  $s$  to  $i$  by assigning both the lower and upper bounds as 1. 2) if orphan  $i$  is not in  $M$ , then connect  $s$  to  $i$  with capacity 1. 3) For testing if an orphan not in  $M$  can be matched with a mentor, we do iteration on all orphans  $i$  not in  $M$  individually, remove  $(s, i)$  and add  $(s', i)$  with capacity 1. Meanwhile add 1 to  $(s, t')$ . By following this process, we reduce our matching problem to a max-flow problem with lower bound (demand). The process here is identical to the reduction from bipartite matching to max-flow. And if there is a feasible solution to this network, this added orphan can be the one newly included.

**Reduction 2:**

Since the lower bounded capacity cannot be solved by max-flow algorithm, we have to convert (reduce) it further to a problem solvable by max-flow. We did the following steps:

- 1) Remove all edges with capacity  $[1,1]$ .
- 2) Add edge  $(s', i)$  to all  $i$ 's in  $M$  with capacity 1, add  $s$  to  $t'$  edge with capacity equal to the total number of existing matched orphans and add an infinity capacity edge  $(t, s)$  to compensate the lower bound requirement.

If the max flow on  $(s, t')$  equals to the number of edges with capacity  $[1,1]$  in Reduction1, then we call it a saturating flow. Then we show a feasible solution in Reduction 1 is equivalent to a saturating flow in Reduction 2. Let the lower bound on the edges in Reduction 1 be  $d(u, v)$ , then step 1) and 2) are actually doing:

$$f'(u, v) = f(u, v) - d(u, v)$$

$$f'(s', v) = \sum_{v \in V} d(u, v)$$

$$f'(u, t') = \sum_{w \in V} d(u, w)$$

$$f'(t, s) = |f|$$

$$\text{Since } f(e) \geq d(e), f'(e) \geq 0$$

$$\text{Since } f(e) \leq c(e), f'(e) \leq c'(e)$$

And also  $\sum_{u \in V'} f'(u, v) = \sum_{w \in V} f'(v, w)$ , so  $f'$  is a legal  $(s', t')$  flow. The reduction is to reduce the flow by the lower bound and add the same amount to  $t'$ . The equivalency implies that for any saturated  $(s', t')$  flow  $f'$ , the function  $f = f'|_E + d$  is a feasible flow  $(s, t)$  in  $G$ .

**Question b:** No. Since we are testing if individual orphan that is not in  $M$  can be added to form a larger matching in each iteration, it is not guaranteed that other untested orphan cannot be matched. Therefore, it is not necessary to be a maximum matching.