

Announcements:

- midterm next tuesday, in class.

Reading: 6.0-6.3

Last time:

- Polynomial Multiplication
- Fast Fourier Transform

Today:

- Dynamic Programming
- Weighted interval scheduling

Dynamic Programming

“divide problem into small number of sub-problems and **memoize** solution to avoid redundant computation”

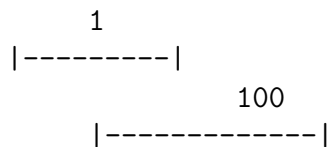
Example: Weighted Interval Scheduling

input:

- n jobs $J = \{1, \dots, n\}$
- s_i = start time of job i
- f_i = finish time of job i
- v_i = value of job i

output: Schedule $S \subseteq J$ of compatible jobs with maximum total value.

Recall Greedy: “earliest finish time”



Idea: job i is either in $\text{OPT}(J)$ or not.

1. let J' = jobs compatible with i in J .
2. let V = value of OPT if “ $i \in \text{OPT}(J)$ ”.

$$= v_i + \text{OPT}(J')$$

3. let $V' = \text{value of OPT if } i \notin \text{OPT}(j)$

$$= \text{OPT}(J \setminus \{i\}).$$

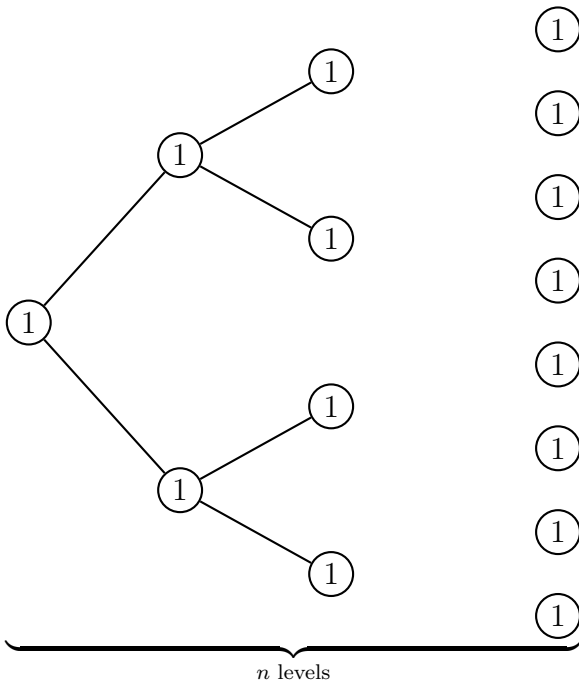
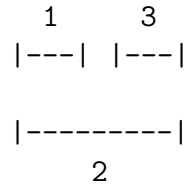
4. return $\text{OPT}(J) = \max(V, V')$.

Note: subproblems: schedule J' and $J \setminus \{i\}$.

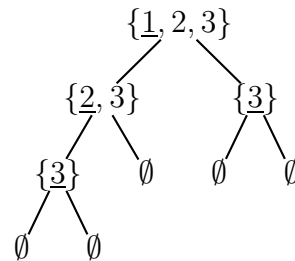
Recurrence: $T(n) = 2T(n-1) + 1$

Challenge 1: redundant computation

Example:



$$T(n) = O(2^n)$$



Note: $\text{OPT}(\{3\})$ called twice!

Solution: memoize

“when computing the value of a subproblem save the answer to avoid computing it again”

Result: runtime = # of subproblems \times cost to combine.

Challenge 2: could have too many subproblems.
(could be exponential!)

Solution: require “succinct description” of subproblems.

Idea: for interval scheduling, process jobs in order of start time so subproblems suffixes of order.

- sort jobs by increasing start time, $s_1 \leq s_2 \leq \dots \leq s_n$.
- let $\text{next}[i]$ denote job with earliest start time after i finishes. (if none, set $\text{next}[i] = n + 1$)
- subproblems when processing job 1:
 - $J' = \{\text{next}[i], \text{next}[i] + 1, \dots, n\}$
 - $J \setminus \{i\} = \{2, 3, \dots, n\}$
- suffix $\{j, \dots, n\}$ is succinctly described by “ j ”.

Algorithm: Weighted Interval Scheduling:

1. sort jobs by increasing start time.
2. initialize array $\text{next}[i]$.
3. initialize $\text{memo}[i] = \emptyset$ for all i .
4. initialize $\text{memo}[n + 1] = 0$.
5. compute $\text{OPT}(1)$.

Subroutine: $\text{OPT}(i)$

1. if $\text{memo}[i] \neq \emptyset$, return $\text{memo}[i]$.
2. $\text{memo}[i] \leftarrow \max(v_i + \text{OPT}(\text{next}[i]), \text{OPT}(i + 1))$.
3. return $\text{memo}(i)$.

Correctness

“ $\text{OPT}(i)$ ” is correct (by induction on i)

Runtime Analysis

- n subproblems
- constant time to combine
- initialization: sorting & precomputing next array

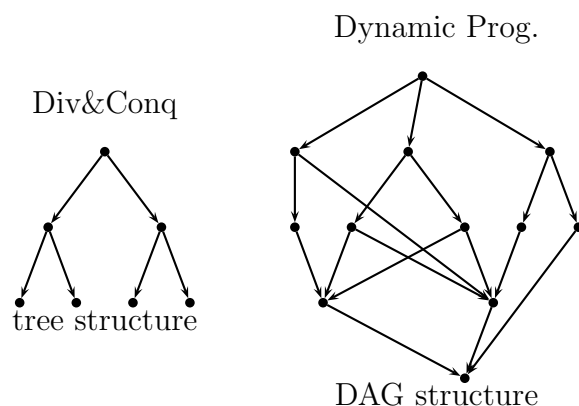
Runtime: $O(n) + \text{initialization} = O(n \log n)$

Key Ideas of Dynamic Programming Finding Optimal Schedule

Subproblems must be:

1. succinct
(only a polynomial number of them)
2. efficiently combinable.
3. partially ordered (avoid infinite loops),
e.g.,
 - process elements “once and for all”
 - “measure of progress/size”.

Comparison to Divide and Conquer



Iterative DPs

“fill in memoization table from bottom to top”

Algorithm: iterative weighted interval scheduling

1. $\text{memo}[n + 1] = 0$.
2. for $i = n$ down to 1.
 - $\text{memo}[i] = \max(v_i + \text{memo}[\text{next}(i)], \text{memo}[i + 1])$.

“traverse memoization table to find schedule”

Algorithm: schedule

```

i = 1
while i < n
    if memo[i + 1] < vi + memo[next(i)]
        schedule i; i ← next(i).
    else
        i ← i + 1.
endif
endwhile
    
```

Suggested Approach

- I. identify subproblem in english

$\text{OPT}(i)$ = “optimal schedule of $\{i, \dots, n\}$ (sorted by increasing start time)”

- II. specify subproblem recurrence

$\text{OPT}(i) = \max(\text{OPT}(i + 1), v_i + \text{OPT}(\text{next}(i)))$

- III. identify base case

$\text{OPT}(n + 1) = 0$

- IV. write iterative DP.