

# VECTOR FIELDS

## 1. VECTOR FIELDS

Reference: Varadarajan 1974, p.5

Let  $X(x \mapsto X_x)$  be any assignment such that  $X_x \in T_x(M)$  for all  $x \in M$ . Then for any function  $f \in C^\infty(M)$ , the function  $Xf : x \mapsto X_x(\mathbf{f}_x)$  is well defined on  $M$ ,  $\mathbf{f}_x$  being the germ at  $x$  defined by  $f$ .

We say that  $X$  is a **vector field** on  $M$  if  $Xf \in C^\infty(M)$  for all  $f \in C^\infty(M)$ . A vector field  $X$  is said to be **real** if  $X_x \in T_x(M)$  for all  $x \in M$ .

Then  $X$  is real if and only if  $Xf$  is real for all real  $f \in C^\infty(M)$ .

Given a vector field  $X$ , the mapping  $f \mapsto Xf$  is a derivation of the algebra  $C^\infty(M)$ ; i.e., for all  $f$  and  $g \in C^\infty(M)$ ,

$$X(fg) = f \cdot Xg + g \cdot Xf.$$

This correspondence between vector fields and derivations is one to one and maps the set of all vector fields onto the set of all derivations of  $C^\infty(M)$ .

**Notation:** Denote by  $\mathfrak{T}(M)$  the set of all vector fields on  $M$ .

If  $X \in \mathfrak{T}(M)$  and  $f \in C^\infty(M)$ , then  $fX : x \mapsto f(x)X_x$  is also a vector field. In this way,  $\mathfrak{T}(M)$  becomes a module over  $C^\infty(M)$ . We make in general no distinction between a vector field and the corresponding derivation of  $C^\infty(M)$ .

We now define a Lie algebra structure. Let  $X$  and  $Y$  be two vector fields. Then  $X \circ Y - Y \circ X$  is an endomorphism of  $C^\infty(M)$  which is easily verified to be an endomorphism. The associated vector field is denoted by  $[X, Y]$  and is called the **Lie bracket** of  $X$  with  $Y$ . The map

$$(X, Y) \mapsto [X, Y]$$

is bilinear and possesses the following easily verified properties:

(Lie algebra axioms).

## 2. DEFINITION

If  $M$  is a smooth manifold with or without boundary, a **vector field on  $M$**  is a section of the map  $\pi : TM \rightarrow M$ . More concretely, a vector field is a continuous map  $X : M \rightarrow TM$ , usually written  $p \mapsto X_p$ , with the property that

$$\pi \circ X = \text{Id}_M,$$

or equivalently,  $X_p \in T_p M$  for each  $p \in M$ . (We write the value of  $X$  at  $p$  as  $X_p$  instead of  $X(p)$  to be consistent with our notation for elements of the tangent bundle. You should visualize a vector field on  $M$  in the same way as you visualize vector fields in Euclidean space: as an arrow attached to each point of  $M$ , chosen to be tangent to  $M$  and to vary continuously from point to point.

3. VECTOR FIELDS AS DERIVATIONS OF  $C^\infty(M)$ 

An essential property of vector fields is that they define operators on the space of smooth real-valued functions. If  $X \in \mathfrak{X}(M)$  and  $f$  is a smooth real-valued function defined on an open subset  $U \subseteq M$ , we obtain a new function  $Xf : U \rightarrow \mathbb{R}$ , defined by

$$(Xf)(p) = X_p f.$$

A smooth vector field  $X$  defines a map from  $C^\infty(M)$  to itself by  $f \mapsto Xf$ . This map is clearly linear over  $\mathbb{R}$ . Moreover, the product rule for tangent vectors translates into the following product rule for vector fields:

$$X(fg) = fXg + gXf,$$

as you can easily check by evaluating both sides at an arbitrary point  $p \in M$ . In general, a map  $X : C^\infty(M) \rightarrow C^\infty(M)$  is called a **derivation** if it is linear over  $\mathbb{R}$  and satisfies

$$X(fg) = fXg + gXf$$

for all  $f, g \in C^\infty(M)$ .

The next proposition shows that derivations of  $C^\infty(M)$  can be identified with smooth vector fields.

**Proposition 3.1.** *Let  $M$  be a smooth manifold. A map  $D : C^\infty(M) \rightarrow C^\infty(M)$  is a derivation if and only if it is of the form  $Df = Xf$  for some smooth vector field  $X \in \mathfrak{X}(M)$ .*

See Lee, Proposition 8.15.

Because of this result, we sometimes *identify* smooth vector fields on  $M$  with derivations of  $C^\infty(M)$ , using the same letter for both the vector field (thought of as a smooth map from  $M$  to  $TM$ ) and the derivation (thought of as a linear map from  $C^\infty(M)$  to itself).

## 4. LIE BRACKETS

In this section we introduce an important way of combining two smooth vector fields to obtain another vector field.

Let  $X$  and  $Y$  be smooth vector fields on a smooth manifold  $M$ . Given a smooth function  $f : M \rightarrow \mathbb{R}$ , we can apply  $X$  to  $f$  and obtain another smooth function  $Xf$ . In turn, we can apply  $Y$  to this function, and obtain yet another smooth function  $YXf = Y(Xf)$ . The operation  $f \mapsto YXf$ , however, does not in general satisfy the product rule and thus cannot be a vector field.

We can also apply the same two vector fields in the opposite order, obtaining a (usually different) function  $XYf$ . Applying both of these operators to  $f$  and subtracting, we obtain an operator  $[X, Y] : C^\infty(M) \rightarrow C^\infty(M)$ , called the **Lie bracket** of  $X$  and  $Y$ , defined by

$$[X, Y]f = XYf - YXf.$$

The key fact is that this operator *is* a vector field.

**Lemma.** The Lie bracket of any pair of smooth vector fields is a smooth vector field.