YUZHOU ZHOU

M.S. Candidate, Wuhan University; Website: yuzhoulidar.com Email: yuzhou3d@gmail.com; Tel: (+86)188-3272-2876

OVERVIEW

Third-year M.S. Student in Photogrammetry and Remote Sensing, Graduating in June, 2022 State Key Laboratory of Information Engineering (LIESMARS), Wuhan University, China Research interests: point cloud processing, 3D deep learning, transportation scene understanding Currently working on: 3D instance segmentation, image and point cloud fusion, weakly-supervised learning

EDUCATION

M.S. in Photogrammetry and Remote Sensing

Sep. 2019 - Jun.2022

State Key Lab of Information Engineering in SMARS(LIESMARS), Wuhan University Advised by Prof. Bisheng Yang and Dr. Zhen Dong

Wuhan, China

Awarded National Scholarship for Postgraduates (Top 2%, Ranking 1/300)

B.E. in Geodesy and Geomatics Engineering

Sep. 2015 - Jun.2019

School of Geodesy and Geomatics, Wuhan University

Wuhan, China

GPA: 3.88/4.00 (Ranking 2/302)

Awarded *Outstanding Student Scholarship* (Top 1%), Outstanding Graduate of Wuhan University (Top 5%)

PUBLICATION

Highway Alignments Extraction and 3D Modeling from Airborne Laser Scanning Point Clouds

- Yuzhou Zhou, Ronggang Huang, Tengping Jiang, Zhen Dong, Bisheng Yang
- International Journal of Applied Earth Observation and Geoinformation (IF: 5.933)
- Key words: Point cloud segmentation, highway feature extraction, energy function.
- Presented in the invited talk in GeoScience Cafe, Wuhan University

Street-view Imagery Guided Street Furniture Inventory from Mobile Laser Scanning Point Clouds [Under Review]

- Yuzhou Zhou, Xu Han, Bo Yang, Zhen Dong, Bisheng Yang
- ISPRS Journal of Photogrammetry and Remote Sensing (IF: 8.979)
- Key words: Instance segmentation, image-point fusion, HD map, 3D transportation analysis.
- Presented in the invited talk on Forum on Intelligent Connected Future and Intelligent Transportation, Shanghai Jiao Tong University (SJTU)

Evaluation of Tunnel Excavation Combining Terrestrial Laser Scanning Point Clouds and Design Models

- Yuzhou Zhou, Zhen Dong, Peiling Tong, Bisheng Yang
- The International Archives of Photogrammetry, Remote Sensing and Spatial Information Sciences (EI)
- Key words: Tunnel 3D modeling, model comparison, feature point extraction and completion.
- Presented (video) on ISPRS Congress 2021 in Nice, France

Bilevel Convolutional Neural Networks for 3D Semantic Segmentation Using Large-scale LiDAR Point Clouds in Complex Environments

- Tengping Jiang, Bisheng Yang, Yuzhou Zhou, Runsong Zhu, Zongtian Hu, Zhen Dong
- Geomatics and Information Science of Wuhan University (EI)
- Key words: Point cloud semantic segmentation, bilevel neural network.

Automated Semantics and Topology Representation of Residential-building Space using Floor-plan Raster Maps [Under Review]

- Bisheng Yang, Tengping Jiang, Weitong Wu, Yuzhou Zhou, Lei Dai
- IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing (IF: 3.784)
- Key words: Indoor mapping, point cloud based 3D modeling.

CONTEST

ChinaLiDAR 2020 First Prize (Ranking 1st)

• Point Cloud Semantic Segmentation Contest of the China LiDAR Conference 2020 (ChinaLiDAR 2020)

INTERNSHIP

LiDAR-Based HD Map Creation and Parsing for V2X Applications

Jun. 2020 - Sep. 2020

Algorithm Engineer for Localization and HD Mapping in Hesai Technology

Shanghai, China

• Automated OpenDRIVE HD map creation, roadside LiDAR object detection, V2X applications.

Point Cloud Processing Software Development

Jul. 2019 - Aug. 2019

Software Engineer in Sichuan Department of Transportation (DOT)

Chengdu, China

• Highway point cloud semantic segmentation software development based on CloudCompare.

GIS Software Development

Jul. 2018 - Sep. 2018

 $Software\ Engineer\ in\ GIS\ Group,\ Department\ of\ System\ Architecture,\ JD(Jingdong)\ Logistics \qquad Beijing,\ China$

• Geo-coding and Geo-fencing API development.

PROGRAMMING AND ENGLISH SKILLS

- Experience in C/C++(with PCL, OpenCV, Ceres-Solver, CGAL, etc.), Python(with TensorFlow, PyTorch, etc.), MATLAB, CloudCompare Plugins Development.
- TOEFL (Sep. 2021): 105 (S24, R30, L27, W24).