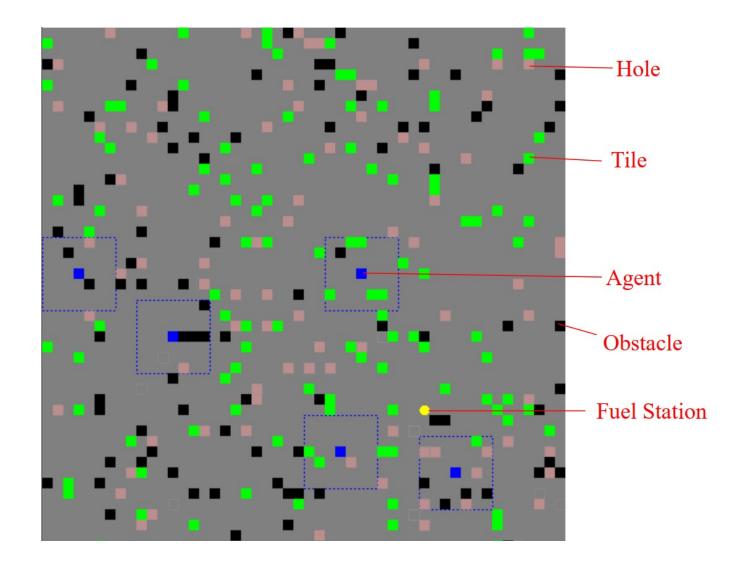
Build Intelligent Agents for Tileworld Environment

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AI6125: Multi-agent System

Tileworld

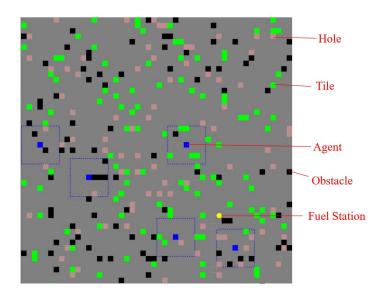




Tileworld

Agent:

- Move up/down/left/right, consume one fuel
- Pickup tile (can carry 3 tiles at most)
- Drop, i.e. put tile in the hole \rightarrow get 1 reward
- Refuel from fuel station due to limited fuel
- Has limited visibility



Obstacles/tiles/holes appear randomly and exist for a certain period

Fuel station has a fixed position that is randomly generated at the beginning. This position is unknown to agents.



Dbjective: get as many rewards as possible within a preset steps of simulation.

In every step, an agent goes through the cycle: Sense-Communicate (optional)-Plan-Act



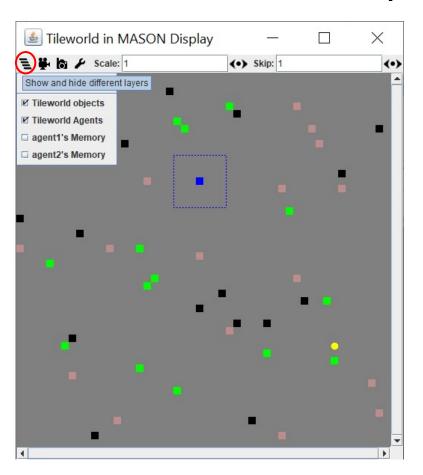
▶ Three modules to be implemented:

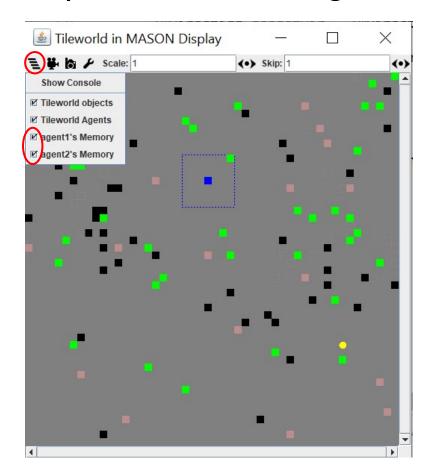
- Planning module: after sensing/communication, the agent's memory is updated. The agent plans its action accordingly.
- Memory module (optional): agents store environmental information in their memory. By default, we use TWAgentWorkingMemory module. You may extend "TWAgentWorkingMemory" class and implement your own module.
- Communication module (optional): in every step, each agent can broadcast a message encoded by "Message" class. You can extend "Message" class and use your own design to encode information.



Memory is critical for planning

Use GUI to check memory for implementation/debug







- To implement your own agent, you should
 - Extend "TWAgent" class

Create your own planner/message/memory

 Override "communicate()", "think()" and "act()" methods in "TWAgent" class

- →

 # tileworld.agent
 - AgentInspector.java
 - Message.java
 - > A SimpleTWAgent.java
 - > If TWAction.java
 - 🛂 TWAgent.java
 - > TWAgentPercept.java
 - > II TWAgentPortrayal.java
 - > 🕖 TWAgentSensor.java
 - > I TWAgentWorkingMemory.java
 - > I TWThought.java
- → # tileworld.environment
- > # tileworld.exceptions
- → # tileworld.planners
 - AstarPathGenerator.java
 - DefaultTWPlanner.java
 - I TWPath.java
 - TWPathGenerator.java
 - I TWPathStep.java
 - > II TWPlanner.java



You should NOT

Override other methods of "TWAgent" class

Modify "environment" package of the simulator

 Call "increaseReward()" method of "TWEnvironment" class in any methods other than the "putTileInHole()" method of "TWAgent" class



Assessment

- Report (maximum 2000 words and 8 pages including images/plots)
- ▶ Team based 15~20 minute presentation
- Competition
 - Each team has 3~4 agents
 - Your agent class will be used in "TWEnvironment" class:

```
//Now we create some agents
Int2D pos = this.generateRandomLocation();
createAgent(new SimpleTWAgent("agent1", pos.getX(), pos.getY(), this, Parameters.defaultFuelLevel));
pos = this.generateRandomLocation();
createAgent(new SimpleTWAgent("agent2", pos.getX(), pos.getY(), this, Parameters.defaultFuelLevel));
```



Competition

• Configuration One:

- Environment Size: 50×50 cells
- Average Object Creation Rate: NormalDistribution(μ =0.2, σ =0.05)
- Lifetime: 100

• Configuration Two:

- Environment Size: 80×80 cells
- Average Object Creation Rate: NormalDistribution(μ =2, σ =0.5)
- Lifetime: 30

• Configuration Three:

- Environment Size: ?×? cells
- Average Object Creation Rate: $?(\mu=?, \sigma=?)$
- Lifetime: ?
- ▶ Each experiment runs 5000 steps
- Each agent has 500 fuel at the beginning
- ▶ Ten experiments for each configuration (average reward)

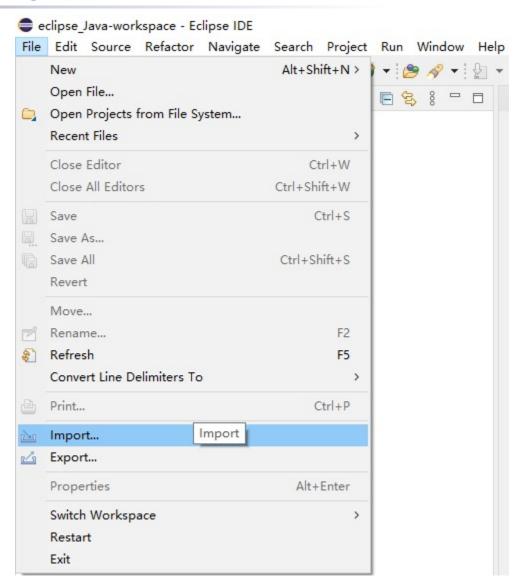


Installation of Tileworld

- Read group-project.pdf file in NTULearn for more details
- Download source file (Tileworld.zip) from NTULearn
- Install Java JDK and the JDK version should be 1.8
 - https://www.oracle.com/java/technologies/javase/javase8u211-later-archive-downloads.html
- ▶ Install the Java3D library (version 1.5)
 - Library file link: https://www.oracle.com/java/technologies/javase/java-3d.html
 - Installation guide: https://download.java.net/media/java3d/builds/release/1.5.1/README-download.html
- Download the MASON_I4.jar file from NTULearn and use it as an external library for compiling and running
- Download Eclipse IDE <u>for Java Developers</u> from: https://www.eclipse.org/downloads/packages/release/2021-06/r

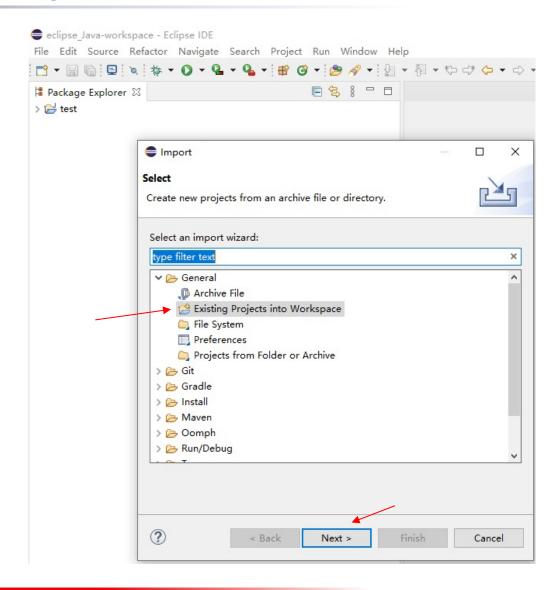


Import Project



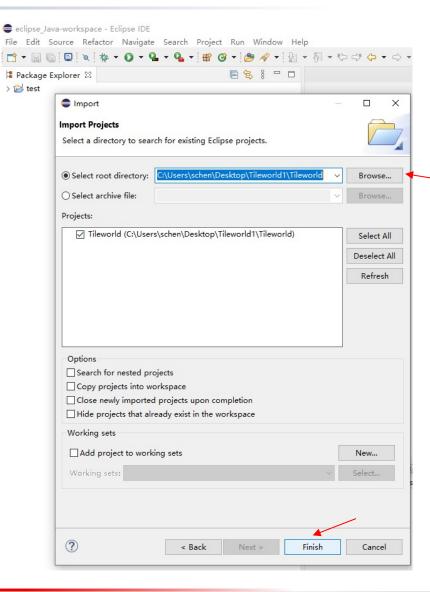


Import Project

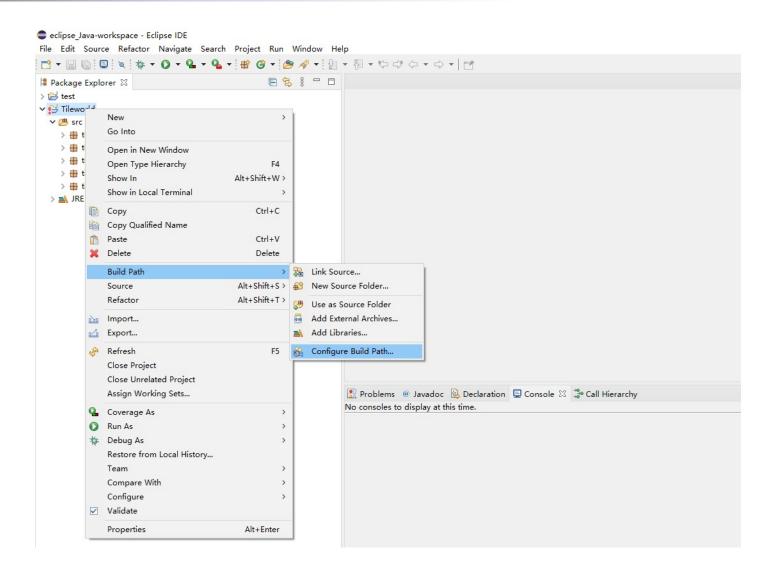




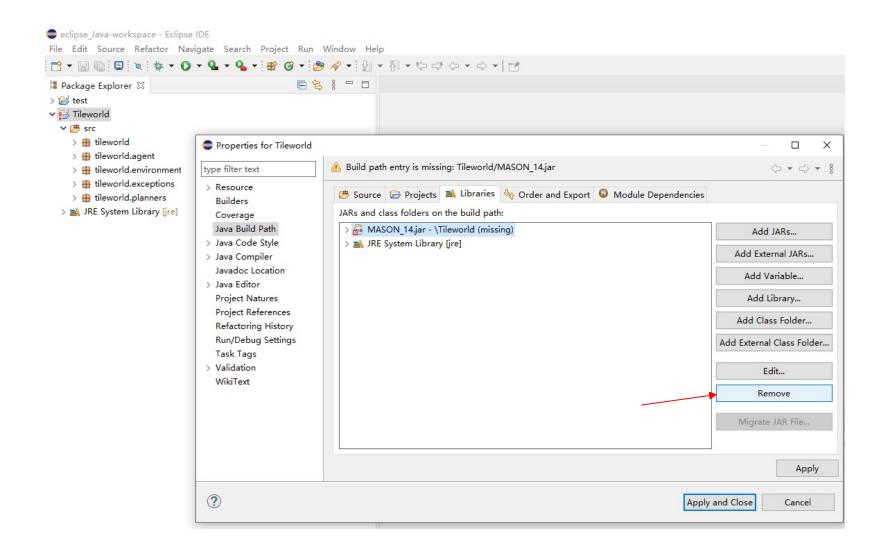
Import Project



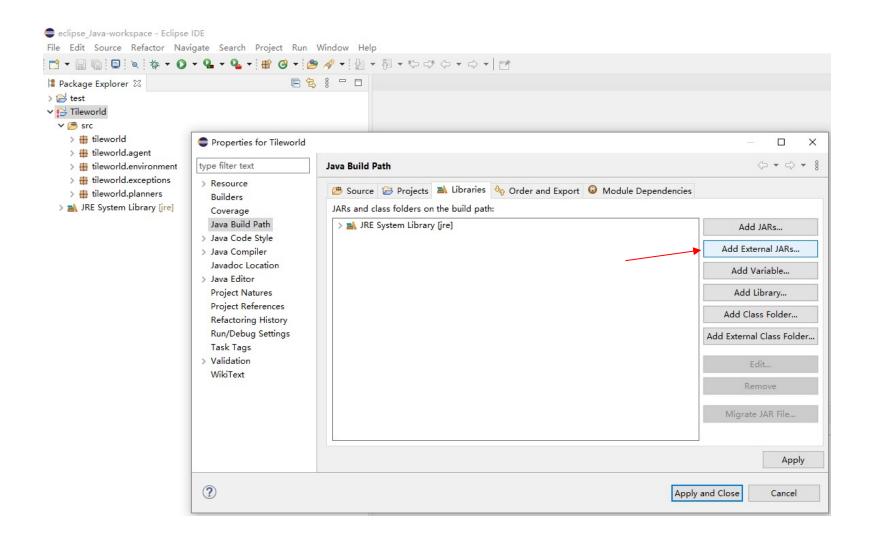




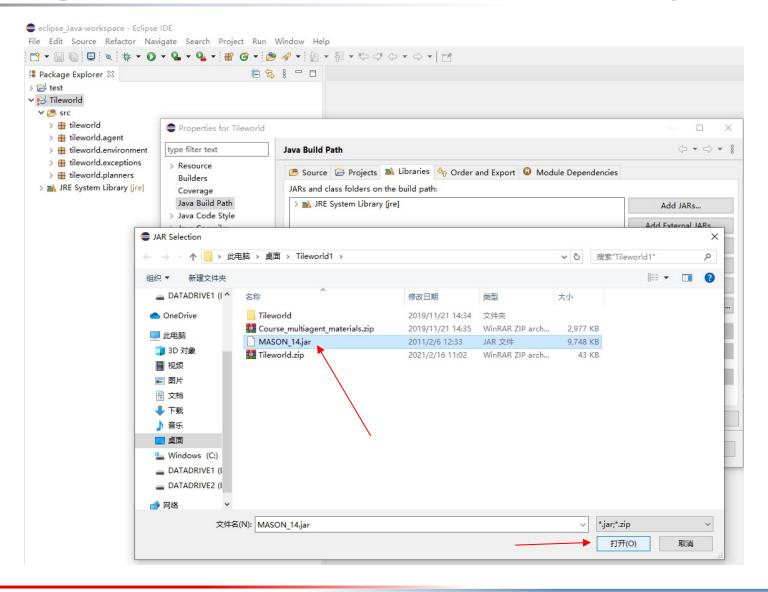




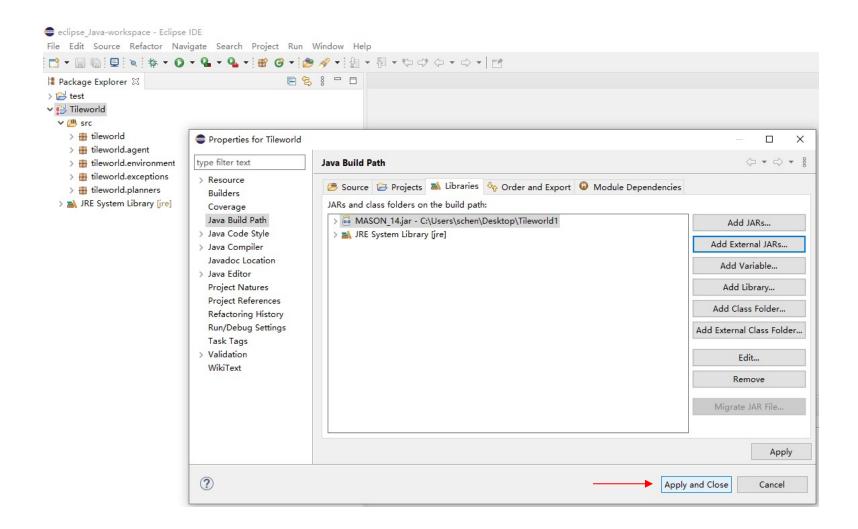














Run Experiment

