# 6.1: Game Theory – Multi-Agent Interaction

Al6125: Multi-Agent System

Assoc Prof Zhang Jie

## Topics in this Module

- This module focuses on the issue of reaching agreement among self-interested agents
- 5.1. Multiagent Interaction
  - Basic concepts on multiagent encounters; how to model agents' decision making, how cooperation can be facilitated
- 5.2. Allocating Scarce Recourses
  - Auctions
- 5.3. Making Group Decisions (if time permits)
  - Social choice, or voting

## 5.1: MULTIAGENT INTERACTION

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#### Utilities and Preferences

- Assume we have just two agents:  $Ag = \{i, j\}$
- Agents are assumed to be self-interested: they have preferences over how the environment is
- Assume  $\Omega = \{\omega_1, \, \omega_2, \, \ldots\}$  is the set of "outcomes" that agents have preferences over
- We capture preferences by utility functions:

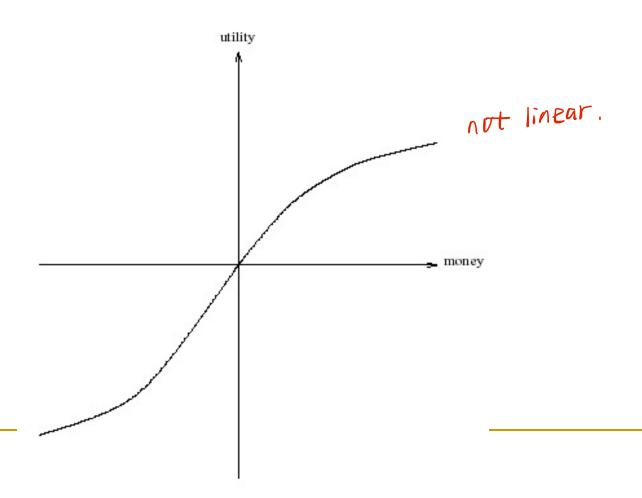
$$u_i = \Omega \to \Re$$
  
$$u_i = \Omega \to \Re$$

Utility functions lead to preference orderings over outcomes:

$$\omega \ge_i \omega'$$
 means  $u_i(\omega) \ge u_i(\omega')$   
 $\omega \not \ge \omega'$  means  $u_i(\omega) > u_i(\omega')$ 

## What is Utility?

- Utility is not money (but it is a useful analogy)
- Typical relationship between utility & money:



## Multiagent Encounters

- We need a model of the environment in which these agents will act...
  - floor agents simultaneously choose an action to perform, and as a result of the actions they select, an outcome in  $\Omega$  will result
  - the actual outcome depends on the combination of actions
  - assume each agent has just two possible actions that it can perform, C ("cooperate") and D ("defect")
- Environment behavior given by state transformer function:

$$au$$
:  $\underbrace{\mathit{Ac}}_{i}$  ×  $\underbrace{\mathit{Ac}}_{j}$   $\to \Omega$  agent  $i$ 's action agent  $j$ 's action

## Multiagent Encounters

Here is a state transformer function:

$$\tau(D,D)=\omega_1 \quad \tau(D,C)=\omega_2 \quad \tau(C,D)=\omega_3 \quad \tau(C,C)=\omega_4$$

(This environment is sensitive to actions of both agents.)

Here is another:

$$\tau(D,D) = \omega_1 \quad \tau(D,C) = \omega_1 \quad \tau(C,D) = \omega_1 \quad \tau(C,C) = \omega_1$$

(Neither agent has any influence in this environment.)

And here is another:

$$\tau(D,D) = \omega_1 \quad \tau(D,C) = \omega_2 \quad \tau(C,D) = \omega_1 \quad \tau(C,C) = \omega_2$$

(This environment is controlled by j.)

#### Rational Action

Suppose we have the case where both agents can influence the outcome, and they have utility functions

as follows:  $u_i(\omega_1)=1 \quad u_i(\omega_2)=1 \quad u_i(\omega_3)=4 \quad u_i(\omega_4)=4$  where 1 ,  $u_j(\omega_1)=1 \quad u_j(\omega_2)=4 \quad u_j(\omega_3)=1 \quad u_j(\omega_4)=4$ 

With a bit of abuse of notation:

$$u_i(D,D) = 1$$
  $u_i(D,C) = 1$   $u_i(C,D) = 4$   $u_i(C,C) = 4$ 

Then agent i's preferences are:

$$C, C \succeq_i C, D \succ_i D, C \succeq_i D, D$$

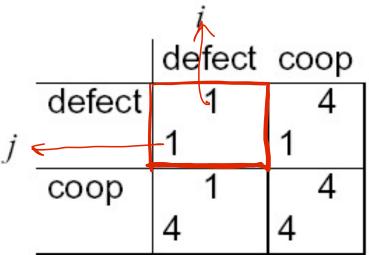
C" is the *rational choice* for i.

(Because *i* prefers all outcomes that arise through *C* over all outcomes that arise through *D*.)

## Payoff Matrices

We can characterize the previous scenario in a

payoff matrix:



- Agent i is the column player
- Agent j is the row player

## Solution Concepts

- How will a rational agent behave in any given scenario?
- Answered in solution concepts:
  - dominant strategy;
  - Nash equilibrium strategy;
  - Pareto optimal strategies;
  - strategies that maximise social welfare.

## Dominant Strategies

## i.j 都c为 dominant strategy.

- Given any particular strategy (either C or D) of agent i, there will be a number of possible outcomes
- We say s<sub>1</sub> dominates s<sub>2</sub> if every outcome possible by i playing s<sub>1</sub> is preferred over every outcome possible by i playing s<sub>2</sub>
- A rational agent will never play a dominated strategy
- So in deciding what to do, we can delete dominated strategies
- Unfortunately, there isn't always a unique undominated strategy

## Nash Equilibrium

- In general, we will say that two strategies  $s_1$  and  $s_2$  are in Nash equilibrium if:
  - under the assumption that agent i plays  $s_1$ , agent j can do no better than play  $s_2$ ; and
  - under the assumption that agent j plays  $s_2$ , agent i can do no better than play  $s_1$ .
- Neither agent has any incentive to deviate from a Nash equilibrium
- Unfortunately:
  - 1. Not every interaction scenario has a Nash equilibrium
  - Some interaction scenarios have more than one Nash equilibrium

## Matching Pennies

- Players i and j simultaneously choose the face of a coin, either "heads" or "tails".
- If they show the same face, then i wins, while if they show different faces, then j wins.
- The Payoff Matrix:

	i heads	i tails
j heads	1	-1
	-1	1
<i>j</i> tails	-1	1
j talis	1	-1

## Mixed Strategies for Matching Pennies

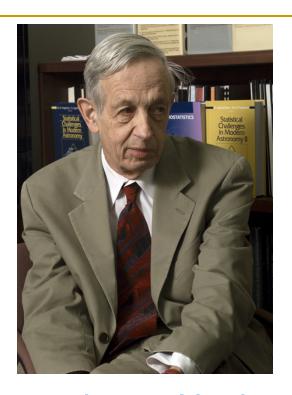
- NO pair of strategies forms a pure strategy NE: whatever pair of strategies is chosen, somebody will wish they had done something else.
- The solution is to allow mixed strategies:
  - play "heads" with probability 0.5
  - play "tails" with probability 0.5.
- This is a NE strategy.

## Mixed Strategies

- A mixed strategy has the form
  - play 1 with probability p<sub>1</sub>
  - play 2 with probability p<sub>2</sub>
  - **—** . . .
  - play k with probability  $p_k$ . such that  $p_1 + p_2 + ... + p_k = 1$ .
- Nash proved that every finite game has a Nash equilibrium in mixed strategies.

#### Nash's Theorem

John Forbes Nash



- Nash proved that every finite game has a Nash equilibrium in mixed strategies. (Unlike the case for pure strategies.)
- So this result overcomes the lack of solutions; but there still may be more than one Nash equilibrium...

## Pareto Optimality

- An outcome is said to be Pareto optimal (or Pareto efficient) if there is no other outcome that makes one agent better off without making another agent worse off.
- If an outcome is Pareto optimal, then at least one agent will be reluctant to move away from it (because this agent will be worse off).
- If an outcome  $\omega$  is not Pareto optimal, then there is another outcome  $\omega$  that makes everyone as happy, if not happier, than  $\omega$ .
- "Reasonable" agents would agree to move to  $\omega$ ' in this case. (Even if I don't directly benefit from  $\omega$ ', you can benefit without me suffering.)

## Social Welfare

• The social welfare of an outcome  $\omega$  is the sum of the utilities that each agent gets from  $\omega$ :

$$\sum_{i \in Ag} u_i(\omega)$$

- Think of it as the "total amount of money in the system".
- As a solution concept, may be appropriate when the whole system (all agents) has a single owner (then overall benefit of the system is important, not individuals).

### Competitive and Zero-Sum Interactions

- Where preferences of agents are diametrically opposed we have strictly competitive scenarios
- Zero-sum encounters are those where utilities sum to zero:

$$u_i(\omega) + u_j(\omega) = 0$$
 for all  $\omega \in \Omega$ 

- Zero sum implies strictly competitive
- The best outcome for me is the worst for you!
- Zero sum encounters in real life are very rare ... but people tend to act in many scenarios as if they were zero sum

- Two men are collectively charged with a crime and held in separate cells, with no way of meeting or communicating. They are told that:
  - if one confesses and the other does not, the confessor will be freed, and the other will be jailed for three years
  - if both confess, then each will be jailed for two years
- Both prisoners know that if neither confesses, then they will each be jailed for one year

Payoff matrix for prisoner's dilemma:

		i	
		defect	coop
	defect	2	1
j		2	4
	coop	4	3
		1	3

- Top left: If both defect, then both get punishment for mutual defection
- Top right: If i cooperates and j defects, i gets sucker's payoff of 1, while j gets 4
- Bottom left: If j cooperates and i defects, j gets sucker's payoff of 1, while i gets 4
- Bottom right: Reward for mutual cooperation

- The individual rational action is defect
  This guarantees a payoff of no worse than 2, whereas cooperating guarantees a payoff of at most 1
- So defection is the best response to all possible strategies: both agents defect, and get payoff = 2
- But intuition says this is not the best outcome: Surely they should both cooperate and each get payoff of 3!
  - D is a dominant strategy
  - (D;D) is the only Nash equilibrium.
  - All outcomes except (D;D) are Pareto optimal.
  - □ (C;C) maximises social welfare.

- This apparent paradox is the fundamental problem of multi-agent interactions.
   It appears to imply that cooperation will not occur in
  - societies of self-interested agents.
- Real world examples:
  - nuclear arms reduction ("why don't I keep mine. . . ")
- The prisoner's dilemma is ubiquitous.
- Can we recover cooperation?

## Arguments for Recovering Cooperation

- Conclusions that some have drawn from this analysis:
  - the game theory notion of rational action is wrong!
  - somehow the dilemma is being formulated wrongly
- Arguments to recover cooperation:
  - We are not all Machiavelli!
  - The other prisoner is my twin!
  - Program equilibria and mediators
  - The shadow of the future...

## Program Equilibria

The strategy you really want to play in the prisoner's dilemma is:

I'll cooperate if he will.

- Program equilibria provide one way of enabling this.
- Each agent submits a program strategy to a mediator which jointly executes the strategies. Crucially, strategies can be conditioned on the strategies of the others.

## Program Equilibria

Consider the following program:

```
IF HisProgram == ThisProgram THEN
        DO(C);
ELSE
        DO(D);
END-IF.
Here == is textual comparison.
```

- The best response to this program is to submit the same program, giving an outcome of (C;C)!
- You can't get the sucker's payoff by submitting this program.

#### The Iterated Prisoner's Dilemma

- One answer: play the game more than once
- If you know you will be meeting your opponent again, then the incentive to defect appears to evaporate
- Cooperation is the rational choice in the infinititely repeated prisoner's dilemma (Hurrah!)

#### Backwards Induction

- But...suppose you both know that you will play the game exactly n times
  On round n 1, you have an incentive to defect, to gain that extra bit of payoff...
  But this makes round n 2 the last "real", and so you have an incentive to defect there, too.
  This is the backwards induction problem.
- Playing the prisoner's dilemma with a fixed, finite, pre-determined, commonly known number of rounds, defection is the best strategy

#### Axelrod's Tournament

- Suppose you play iterated prisoner's dilemma against a range of opponents...
   What strategy should you choose, so as to maximize your overall payoff?
- Axelrod (1984) investigated this problem, with a computer tournament for programs playing the prisoner's dilemma

## Strategies in Axelrod's Tournament

#### ALLD:

"Always defect" — the *hawk* strategy;

#### TIT-FOR-TAT:

- 1. On round u = 0, cooperate
- 2. On round u > 0, do what your opponent did on round u 1

#### TESTER:

 On 1st round, defect. If the opponent retaliated, then play TIT-FOR-TAT. Otherwise intersperse cooperation and defection.

#### JOSS:

As TIT-FOR-TAT, except periodically defect

## Recipes for Success in Axelrod's Tournament

- Axelrod suggests the following rules for succeeding in his tournament:
  - Don't be envious:Don't play as if it were zero sum!
  - Be nice:
     Start by cooperating, and reciprocate cooperation
  - Retaliate appropriately:
     Always punish defection immediately, but use "measured" force don't overdo it
  - Don't hold grudges:
     Always reciprocate cooperation immediately

#### Game of Chicken

Consider another type of encounter — the game of chicken:

		defect	coop
	defect	1	2
j	2	1	4
	coop	4	3
		2	3

- Difference to prisoner's dilemma:
  Mutual defection is most feared outcome.
- There is no dominant strategy (in our sense).
- Strategy pairs (C;D)) and (D;C)) are Nash equilibriums.
- All outcomes except (D;D) are Pareto optimal.
- All outcomes except (D;D) maximise social welfare.