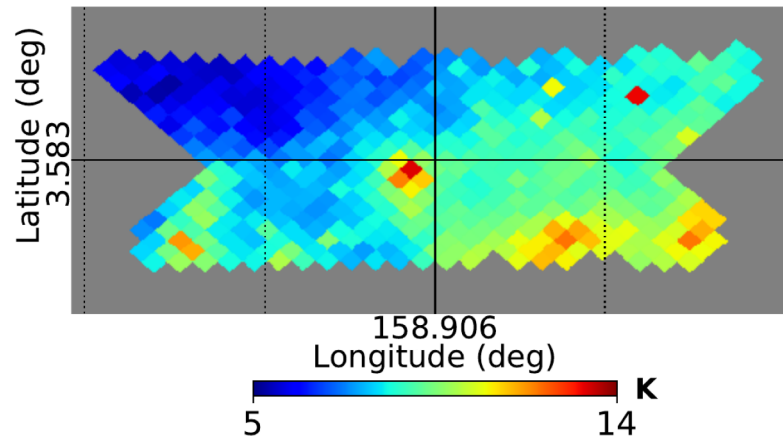
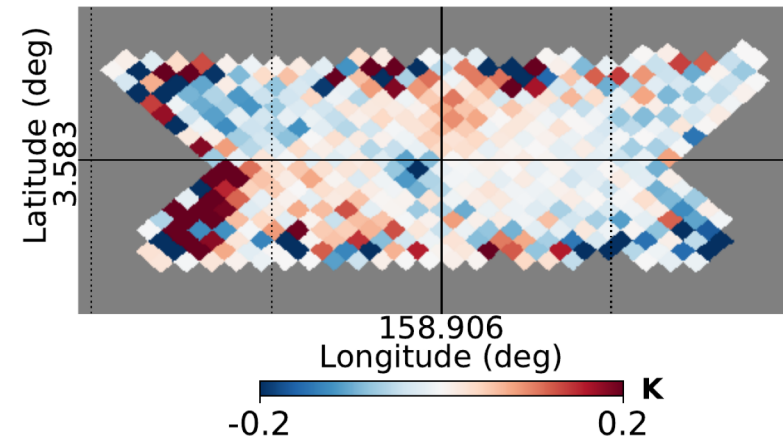


Latitude

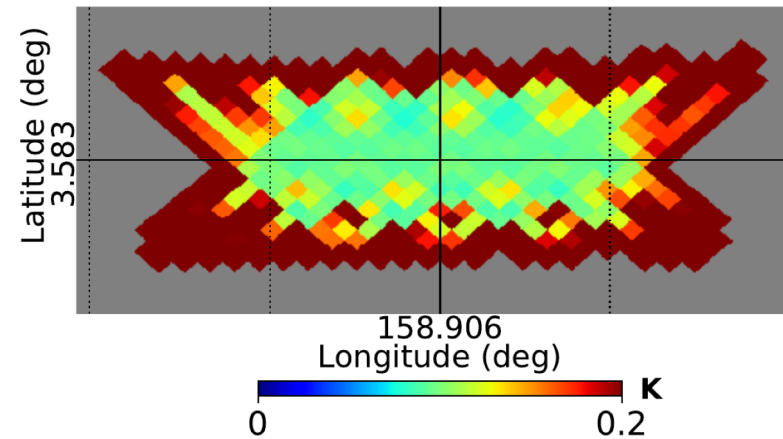
HighPass Wiener Filter



Residual



Uncertainty



Z-score

