

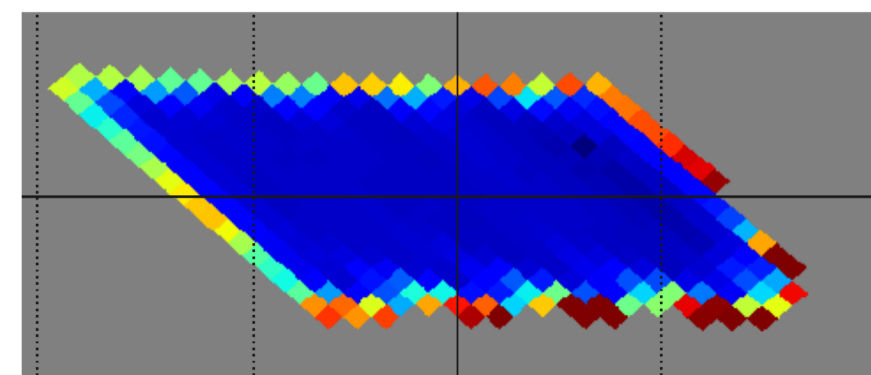
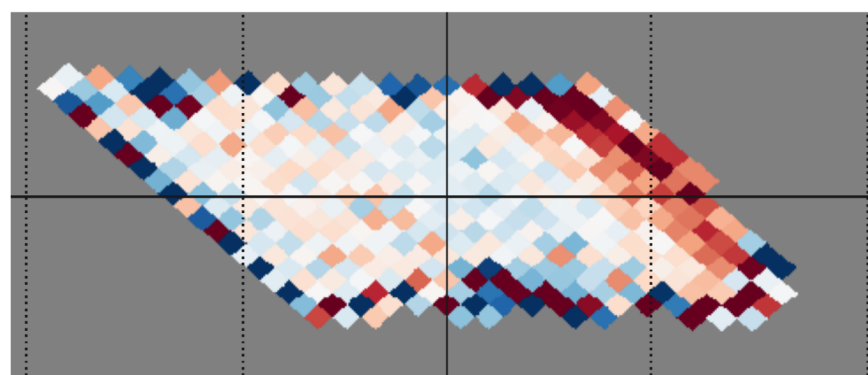
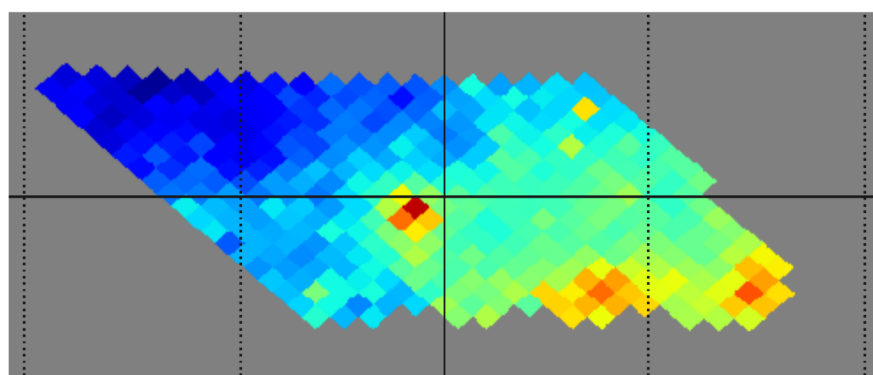
Estimated maps

Residual maps

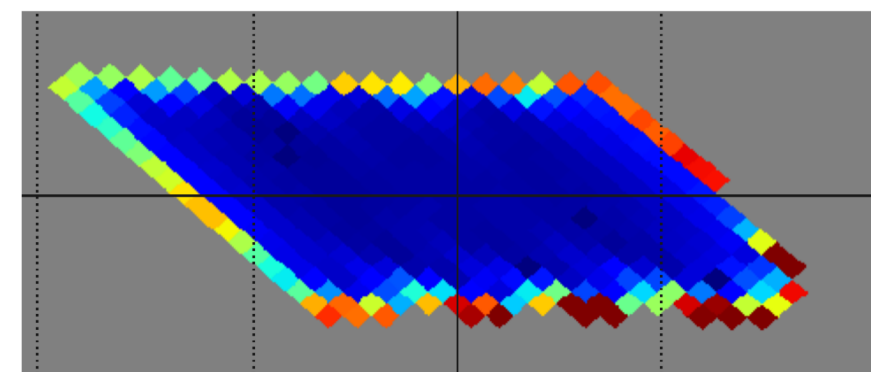
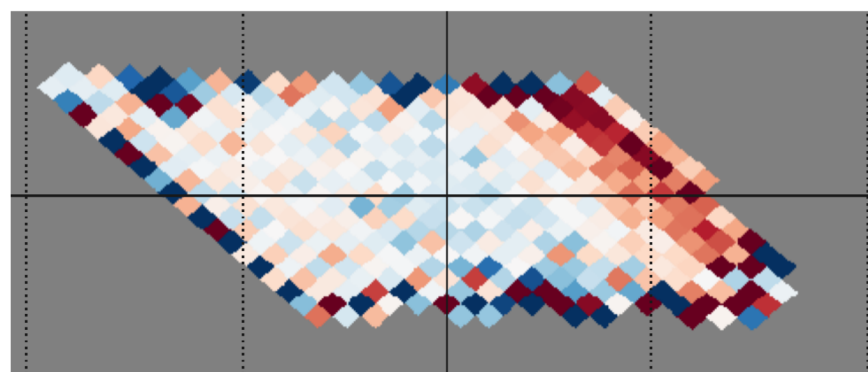
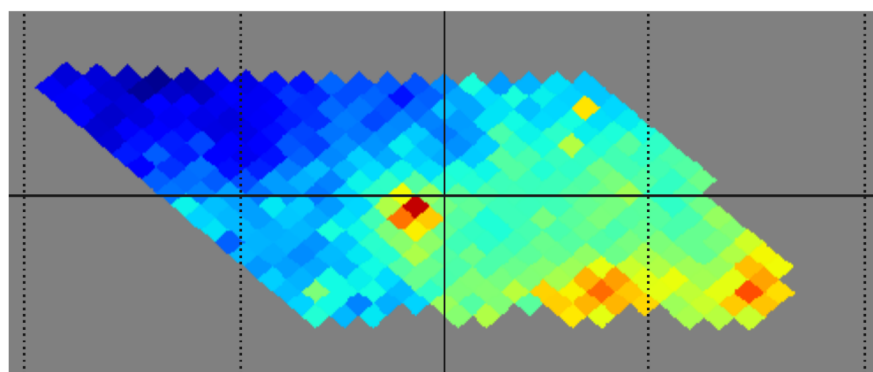
Uncertainty maps

1xTOD
1 CalSrc

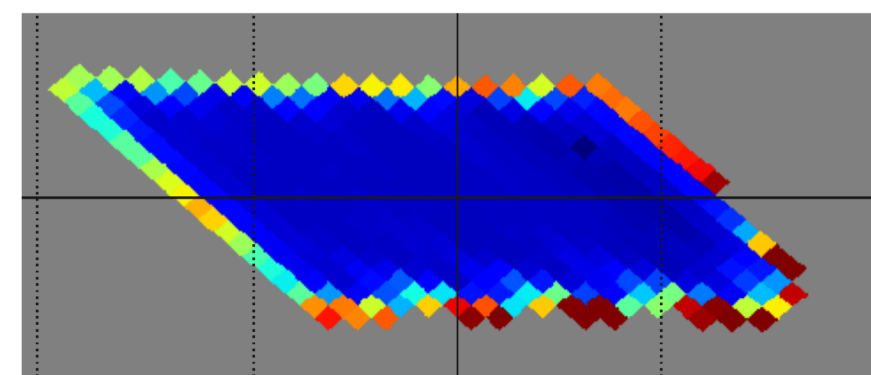
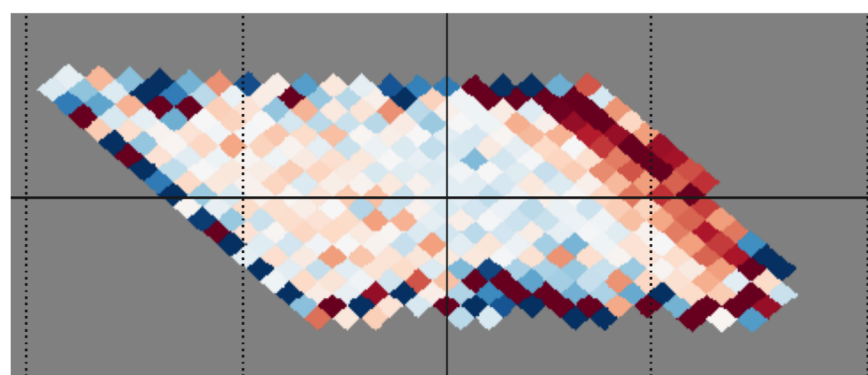
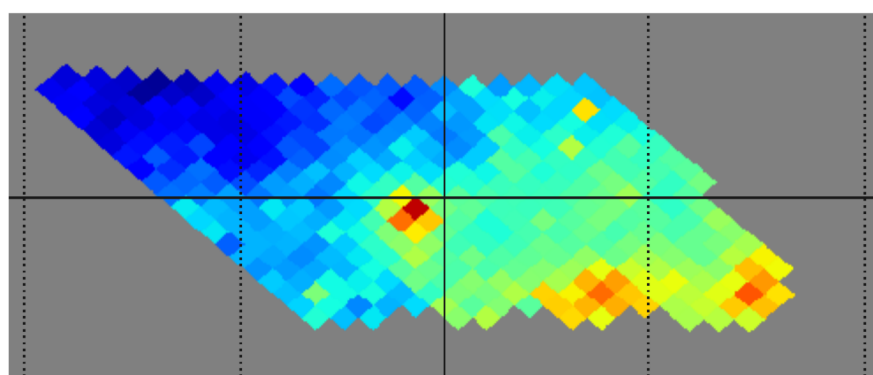
Latitude

1xTOD
5 CalSrc

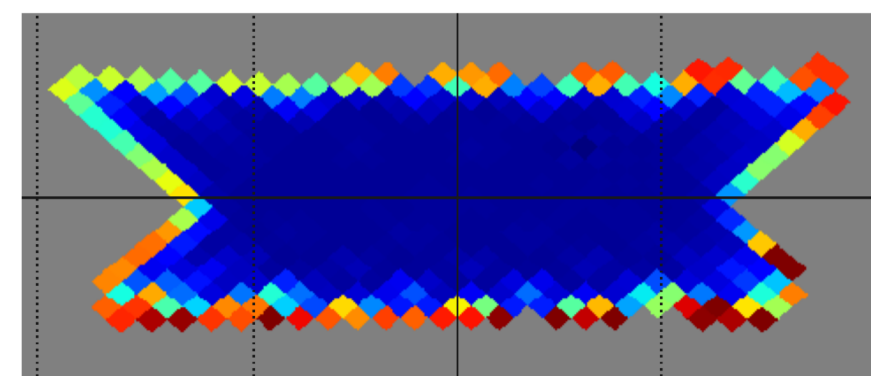
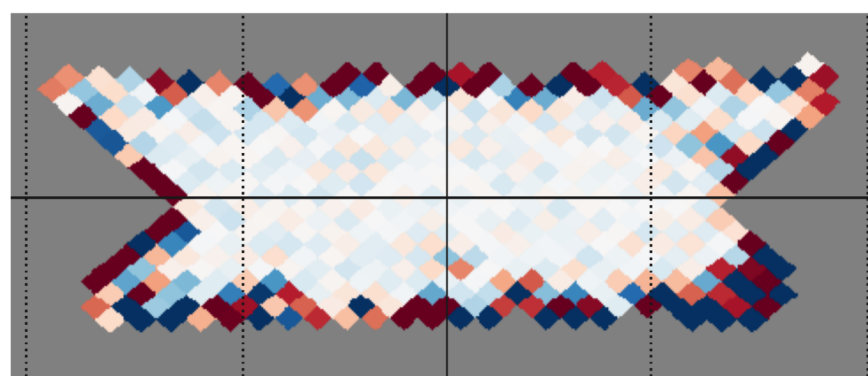
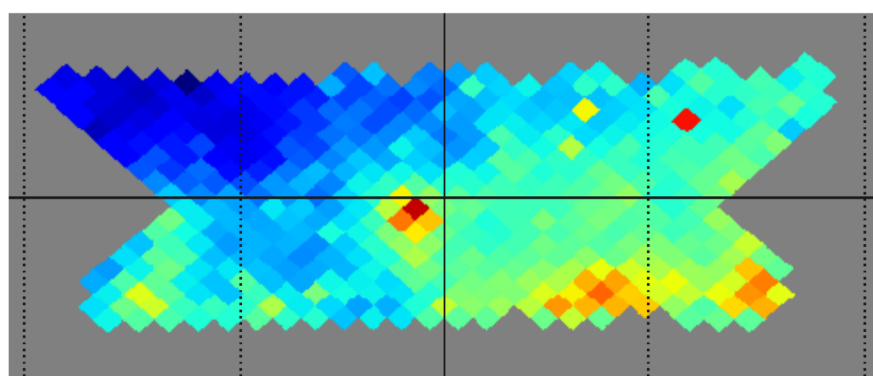
Latitude

1xTOD
5 CalSrc + 1/f prior

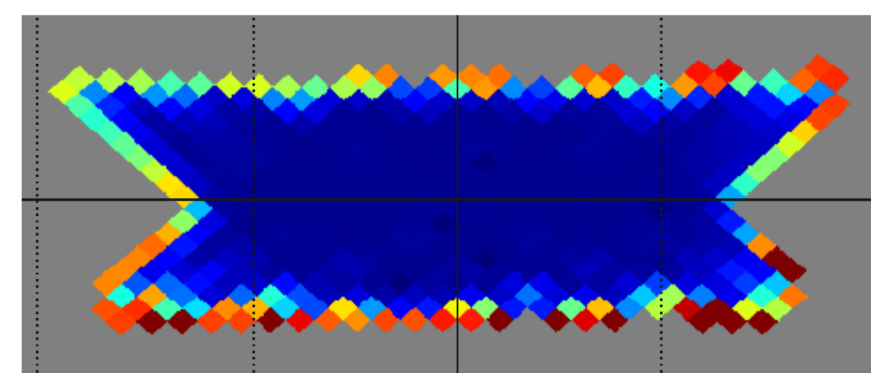
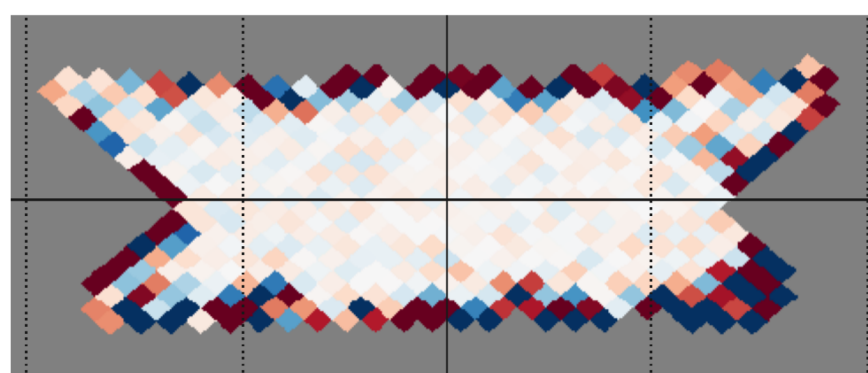
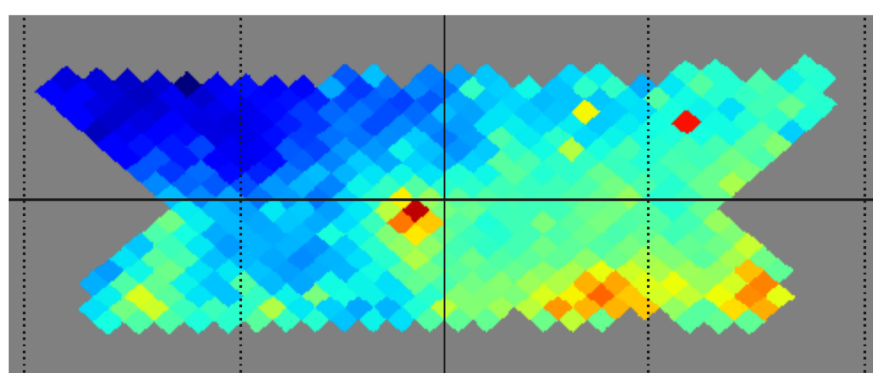
Latitude

2xTOD
1 CalSrc

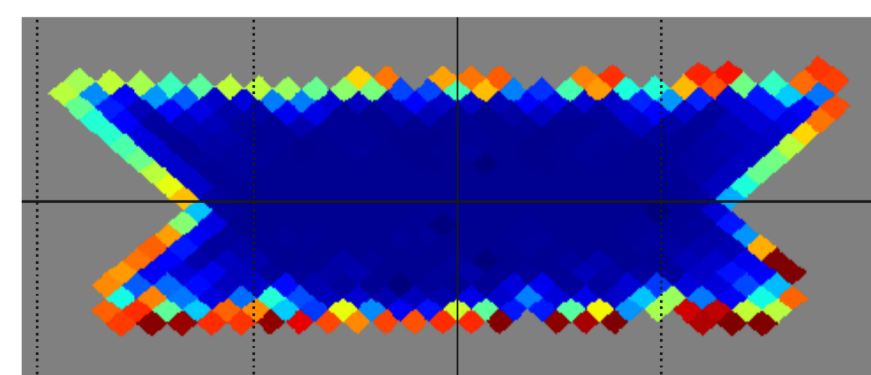
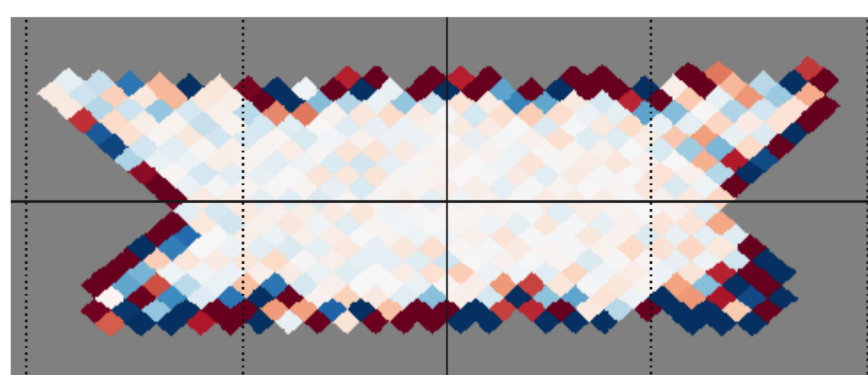
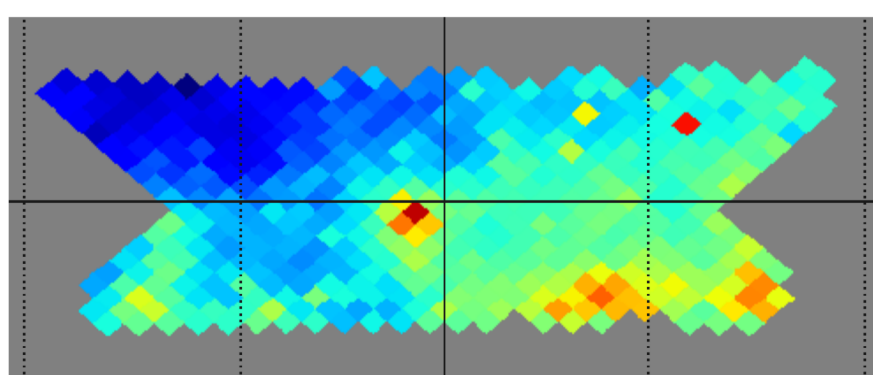
Latitude

2xTOD
5 CalSrc

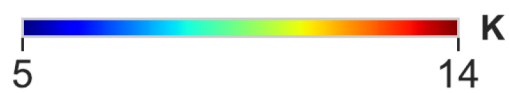
Latitude

2xTOD
5 CalSrc + 1/f prior

Latitude



Longitude



Longitude



Longitude

