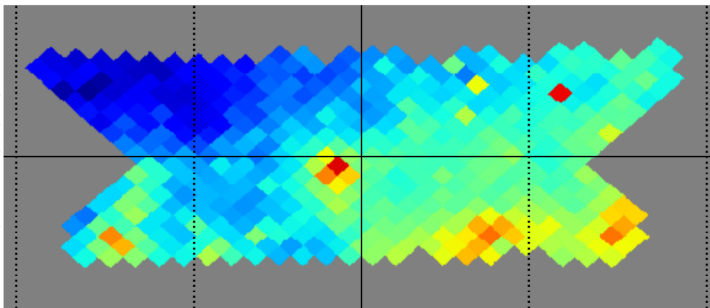


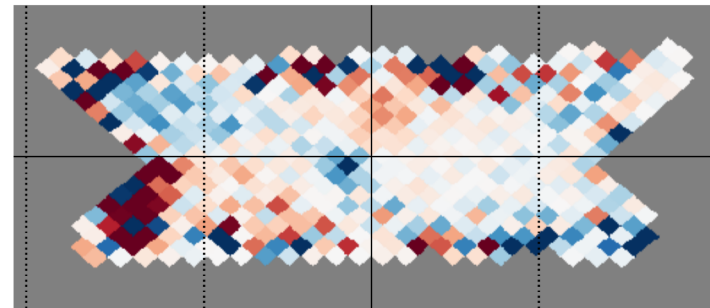
HighPass Wiener Filter



Longitude



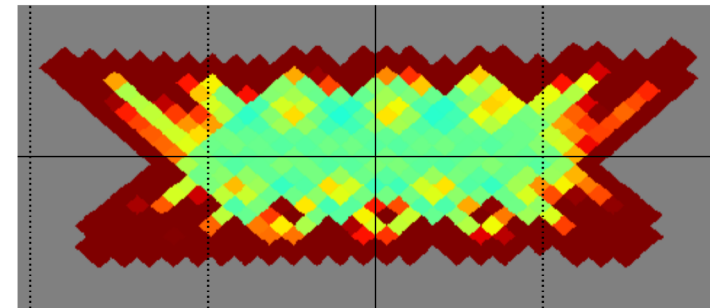
Residual



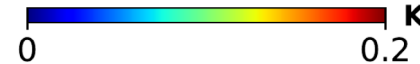
Longitude



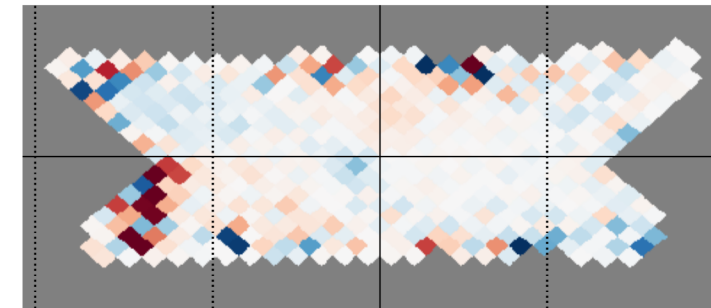
Uncertainty



Longitude



Z-score



Longitude

