Components of CNNs

MPCS 53111

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1 Symbolic differentiation

Suppose we have a list of objects S, each object of S has two methods forward() and backward(), and S is always kept in the topological order of the computation graph of our neural networks. S has 3 operations:

```
function Add(S, Object o):
      S \leftarrow S \cup \{o\}
end function
function Forward(S):
       for each o \in S:
01.
02.
          o.forward()
03.
       end for
end function
function Backward(S):
       for each o \in S in the reversed order:
01.
02.
          o.backward()
       end for
03.
end function
```

The generic of constructing a neural network, training and testing can described in a high-level language as follows:

procedure Neural Network Scheme():

01. Construction 02. Initialize the computation graph as empty $S \leftarrow \emptyset$ 03. Add all the layers we want to S in the bottom-up order 04. Training 05. for each training example x (or a batch of training examples): S.forward() 06. 07. S.backward()08. Gradient Descent Algorithm 09. end for

```
10. Testing
11. for each testing example x:
12. S.forward()
13. Return the prediction for example x
14. end for
end procedure
```

2 Convolution Forward and Backward

Read the another document that published before!

3 Padding Forward and Backward

Padding Forward: Read the another document that published before!

Padding Backward:

```
 \begin{array}{ll} \textbf{function} \ \operatorname{Backward}(\mathcal{L}'.\delta \in \Re^{B \times H' \times W' \times D}, \ w \in \mathbb{N}_{odd}, \ h \in \mathbb{N}_{odd}) \\ 01. \quad \mathcal{L}.\delta[:,:,:,:] \leftarrow \mathcal{L}.\delta[:,:,:] + \mathcal{L}'.\delta[:,\lfloor h/2 \rfloor : H + \lfloor h/2 \rfloor, \lfloor w/2 \rfloor : W + \lfloor w/2 \rfloor,:] \\ \textbf{end function} \end{array}
```

4 Max-Pooling Forward and Backward

Max-Pooling Forward: Read the another document that published before!

Max-Pooling Backward:

```
function Backward(\mathcal{L}'.\delta \in \Re^{B \times H' \times W' \times D}, w \in \mathbb{N}, h \in \mathbb{N})
01. for each x = 0 \to H' - 1:
02. for each y = 0 \to W' - 1:
03. (u, v) \leftarrow \mathbf{max\text{-index}} \ (\mathcal{L}[:, x * h : (x + 1) * h, y * w, (y + 1) * w, :])
06. \mathcal{L}.\delta[:, u, v, :] \leftarrow \mathcal{L}.\delta[:, u, v, :] + \mathcal{L}'.\delta[:, x, y, :]
07. end for
08. end for
end function
```

5 Average-Pooling Forward and Backward

Average-Pooling Forward: Read the another document that published before!

Average-Pooling Backward:

```
function Average-Pooling(\mathcal{L}'.\delta \in \Re^{B \times H' \times W' \times D}, w \in \mathbb{N}, h \in \mathbb{N})
             for each x = 0 \rightarrow H' - 1:
01.
02.
                  for each y = 0 \rightarrow W' - 1:
                        \mathcal{X} \leftarrow x * h : (x+1) * h
03.
                        \mathcal{Y} \leftarrow y * w : (y+1) * w
04.
                        \mathcal{L}.\delta[:,\mathcal{X},\mathcal{Y},:] \leftarrow \mathcal{L}.\delta[:,\mathcal{X},\mathcal{Y},:] + \frac{1}{w \cdot h} \mathcal{L}'.\delta[:,x,y,:]
05.
                  end for
06.
07.
             end for
end function
```

6 Hinge Loss

```
function Forward (Target y, Prediction \hat{y})
01. return max(0, 1 - y \cdot \hat{y})
end function

function Backward (Target y, Prediction \hat{y})
01. if y \cdot \hat{y} > 1:
02. \hat{y} \cdot \delta \leftarrow 0
03. else:
04. \hat{y} \cdot \delta \leftarrow -y
05. end if
end function
```