

# LAB4 postlab

; ECE-222 Lab ... Winter 2013 term  
; Lab 4 code

```

        THUMB
        ; Declare THUMB instruction set
        AREA My_code, CODE, READONLY
        EXPORT __MAIN
        ; Label __MAIN is used externally
        EXPORT EINT3_IRQHandler
without this the interrupt routine will not be found

```

ENTRY

\_\_MAIN

; The following lines are similar to previous labs.  
; They just turn off all LEDs

```

        LDR            R10, =LED_BASE_ADR
        ; R10 is a pointer to the base address for the LEDs
        MOV            R3, #0xB0000000
three LEDs on port 1

```

```

        STR            R3, [R10, #0x20]
        MOV            R3, #0x0000007C
        STR            R3, [R10, #0x40]
LEDs on port 2
; Turn off five

```

```

        MOV            R0, #0X0
initial all registers which we need
        MOV            R4, #0X0
        MOV            R7, #0X0
        MOV            R8, #0X0
        MOV            R12, #0X0

```

```

        LDR            R3, =ISERO
        MOV            R2, #0x00200000
bit ,active the port---1
;21th
        STR            R2, [R3]
        LDR            R3, =IO2IntEnf
        MOV            R2, #0x00000400
active the port ---1
;10th bit,
        STR            R2, [R3]

```

; This line is very important in your main program  
; Initializes R11 to a 16-bit non-zero value and NOTHING else can write to R11 !!

```

        MOV            R11, #0xABCD
Init the random number generator with a non-zero number
LOOP    BL            RNG

```

```

        MOV            R6, R11
; we do not change the random number but use another register to save
it.

```

```

        LSL            R6, #16 ; clear garbage bits
        LSR            R6, #16
        MOV            R9, #3
        MUL            R6, R6, R9

```

```

MOV          R9, #1000                ;5-
25s delay
UDIV         R6,R6,R9                ; get value
from 0-200
ADD          R6, #50; 50-250, 0.1s → 5s-25s
LOOP2        BL          DISPLAY_NUM
MOV          R0,#10
BL          DELAY
SUBS         R6, #10                ;R6 counter
decrease every 1 s
CMP          R6, #0
BGT          LOOP2
MOV          R9, #0                ;flag for ISR
B           FLASH                ;R6 less or equal
to 0

FLASH        MOV          R11, #0    ;
STR          R11, [R10,#0x54]
STR          R11, [R10,#0x34] ; flsh
MOV          R0,#1
CMP          R9, #0 ; when ISR in this
subroutine, we need it come back
BNE          LOOP2
BL          DELAY
MOV          R11, #0x0000007C
STR          R11, [R10,#0x54]
MOV          R11, #0xB0000000
STR          R11, [R10,#0x34]
MOV          R0,#1
CMP          R9, #0 ; check it again
BNE          LOOP2
BL          DELAY
B           FLASH

;
; Your main program can appear here
;

```

```

DISPLAY_NUM  STMFD        R13!,{R3-R5, R14} ;display R3
MOV          R3, R6
MOV          R4, #0
; two initial register we need to use
MOV          R5, #0
BFI          R5,R3,#0, #5
;Replace the bits from 0th to 4th(5 bits) in R5 by R3, which using the bits
in R3 from 0th to the 4th(5 bits). R9 contains the counter value
RBIT        R5,R5                ;
reverse the bits for fitting the LED
LSR          R5,#25
;when we reverse, the last 5 significant bits become the most 5
significant bits, so we should shift right 25 to get bit 2th to 6th.
LSR          R3,#5
; need rest 3 bits
STR          R5, [R10,#0x54]
; port 2.2-2.6

```

```

MOV R5,#0
; reuse R5 again
BFI R5,R3, #0,#1 ;
we first take 1 bits, 30th bits we do need it but we have to show it
LSL R3, #1
; get 0 in
ADD R3, R3,R5
; put the rest three bits in the R5
BFI R5,R3,#0,#4
; Replace the bits from 0th to 3th(4 bits) in R5 by R3, which using the bits
in R3 from 0th to the 3th(4 bits).
RBIT R5,R5
;reverse
STR R5,[R10,#0x34]
; show the value

LDMFD R13!,{R3-R5, R15}
;-----
; Subroutine RNG ... Generates a pseudo-Random Number in R11
;-----
; R11 holds a random number as per the Linear feedback shift register (Fibonacci)
on Wikipedia
; R11 MUST be initialized to a non-zero 16-bit value at the start of the program
; R11 can be read anywhere in the code but must only be written to by this
subroutine
RNG STMFD R13!,{R1-R3, R14} ; Random Number
Generator

AND R1, R11, #0x8000
AND R2, R11, #0x2000
LSL R2, #2
EOR R3, R1, R2
AND R1, R11, #0x1000
LSL R1, #3
EOR R3, R3, R1
AND R1, R11, #0x0400
LSL R1, #5
EOR R3, R3, R1 ;

The new bit to go into the LSB is present
LSR R3, #15
LSL R11, #1
ORR R11, R11, R3
LDMFD R13!,{R1-R3, R15}
;-----
; Subroutine DELAY ... Causes a delay of 1ms * R0 times
;-----
; aim for better than 10% accuracy
DELAY STMFD R13!,{R2,R4,R10, R14}
DELAY1 MOV R4, #0x0084 ; 0.1s counter
MOV R10, #1000
MUL R4,R4,R10

```

```

DELAY_LOOP      SUBS      R4, #1          ; two inserted for loops,
satisfies the 0.1ms *R0
                  BNE      DELAY_LOOP

```

```

delay2          SUBS      R0, #1
                  BNE      DELAY1
                  B         exitDelay
exitDelay        LDMFD     R13!,{R2,R4,R10, R15}

```

```

; The Interrupt Service Routine MUST be in the startup file for simulation
; to work correctly. Add it where there is the label "EINT3_IRQHandler
;
;
;-----
;

```

```

; Interrupt Service Routine (ISR) for EINT3_IRQHandler
;-----
;

```

```

; This ISR handles the interrupt triggered when the INT0 push-button is pressed
; with the assumption that the interrupt activation is done in the main program
EINT3_IRQHandler

```

```

                  STMFD     R13!,{R1-R4, R14}

                  LDR       R7, =IO2INTCLR
                  MOV       R8, #0x00000400
                  STR       R8, [R7]

                  MOV       R11, #0xABCD
                  AND       R1, R11, #0x8000
                  AND       R2, R11, #0x2000
                  LSL       R2, #2
                  EOR       R3, R1, R2
                  AND       R1, R11, #0x1000
                  LSL       R1, #3
                  EOR       R3, R3, R1
                  AND       R1, R11, #0x0400
                  LSL       R1, #5
                  EOR       R3, R3, R1          ;

The new bit to go into the LSB is present
                  LSR       R3, #15
                  LSL       R11, #1
                  ORR       R11, R11, R3

                  MOV       R6, R11
; we do not change the random number but use another register to save
it.

                  LSL       R6, #16
                  LSR       R6, #16
                  MOV       R9, #3
                  MUL       R6, R6, R9          ;
                  MOV       R9, #1000          ;5-

25s delay
                  ADD       R6, #50
                  UDIV      R6,R6,R9          ; random
number R6

```

```

MOV                                R9, #1 ; flag to check where
and how to come back

LDMFD                              R13!,{R1-R4, R15}
; *-----
;
; Below is a list of useful registers with their respective memory addresses.
; *-----
;
LED_BASE_ADR      EQU    0x2009c000      ; Base address of the memory
that controls the LEDs
PINSEL3           EQU    0x4002C00C      ; Pin Select Register 3
for P1[31:16]
PINSEL4           EQU    0x4002C010      ; Pin Select Register 4
for P2[15:0]
FIO1DIR           EQU          0x2009C020      ; Fast Input
Output Direction Register for Port 1
FIO2DIR           EQU          0x2009C040      ; Fast Input
Output Direction Register for Port 2
FIO1SET           EQU          0x2009C038      ; Fast Input
Output Set Register for Port 1
FIO2SET           EQU          0x2009C058      ; Fast Input
Output Set Register for Port 2
FIO1CLR           EQU          0x2009C03C      ; Fast Input
Output Clear Register for Port 1
FIO2CLR           EQU          0x2009C05C      ; Fast Input
Output Clear Register for Port 2
IO2IntEnf         EQU          0x400280B4      ; GPIO Interrupt Enable
for port 2 Falling Edge
ISERO             EQU          0xE000E100      ; Interrupt Set-Enable
Register 0
IO2INTCLR         EQU          0x400280AC      ; Interrupt Port 2 Clear
Register

ALIGN

END

```

# Lab-4 Submission form

Class: 001 <input type="checkbox"/>	201 <input type="checkbox"/>	202 <input checked="" type="checkbox"/>	203 <input type="checkbox"/>	Demo date: <u>Nov 18, 2016</u>
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		Weight	Grade	Comment
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Lab-demo	Questions	40	40	
Part-III	Code quality	10		
Lab report	Code comments	10		
Penalty for using flash memory for code development (LPC 1768 only)		-20		
Late show up for demo		-10		
Total		100		