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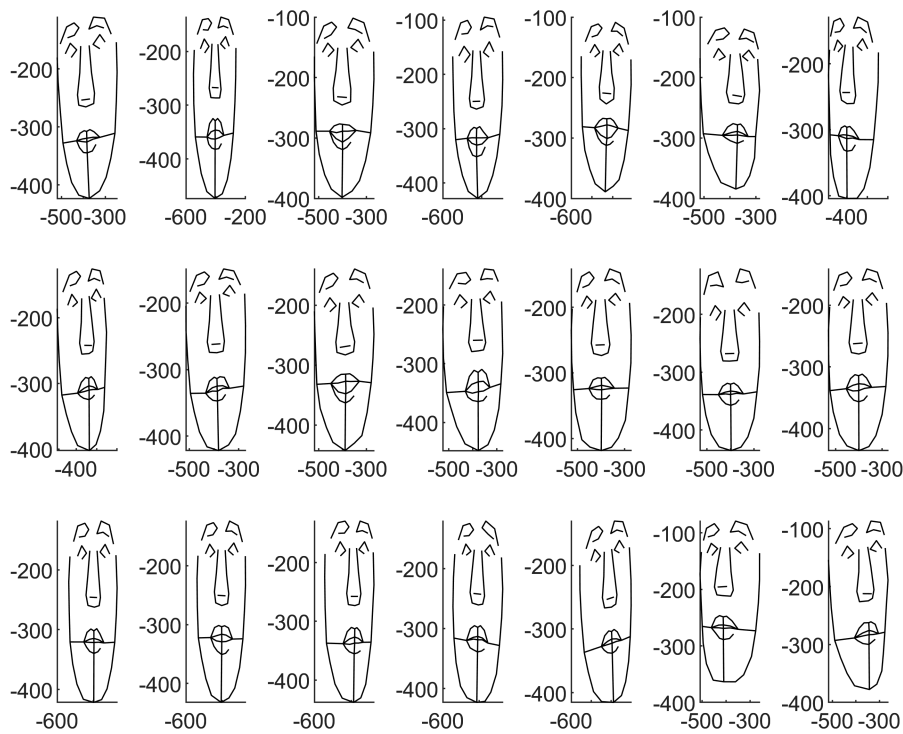
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## Problem 1

```
% Load all data points
allFiles = dir('code/dat/107*.pts');
N = length(allFiles);
for i=1:N
    [X(:,:,i),Y(:,:,i),ptSets(:, :, i)] = readPoints( strcat('code/dat/',allFiles(i).name ) );
end
```

## Original Set of Faces

```
figure()
for j = 1:N
    subplot(3,7,j)
    drawFaceParts( -ptSets(:, :, j), 'k-' )
end
```



## Aligning Faces

```

for iter = 1:500
    if iter == 1
        mu = ptSets(:,:,1);
    else
        [aligned(:,:,1), pars,E(1)] = getAlignedPts(ptSets(:,:,1),mu);
        mu = aligned(:,:,1);
    end
    for i = 1:N
        [aligned(:,:,i), pars,E(i)] = getAlignedPts(mu,ptSets(:,:,i));
    end
    mu = mean(aligned,3);
    energy(iter) = mean(E);
end

```

## Energy Calculations

```

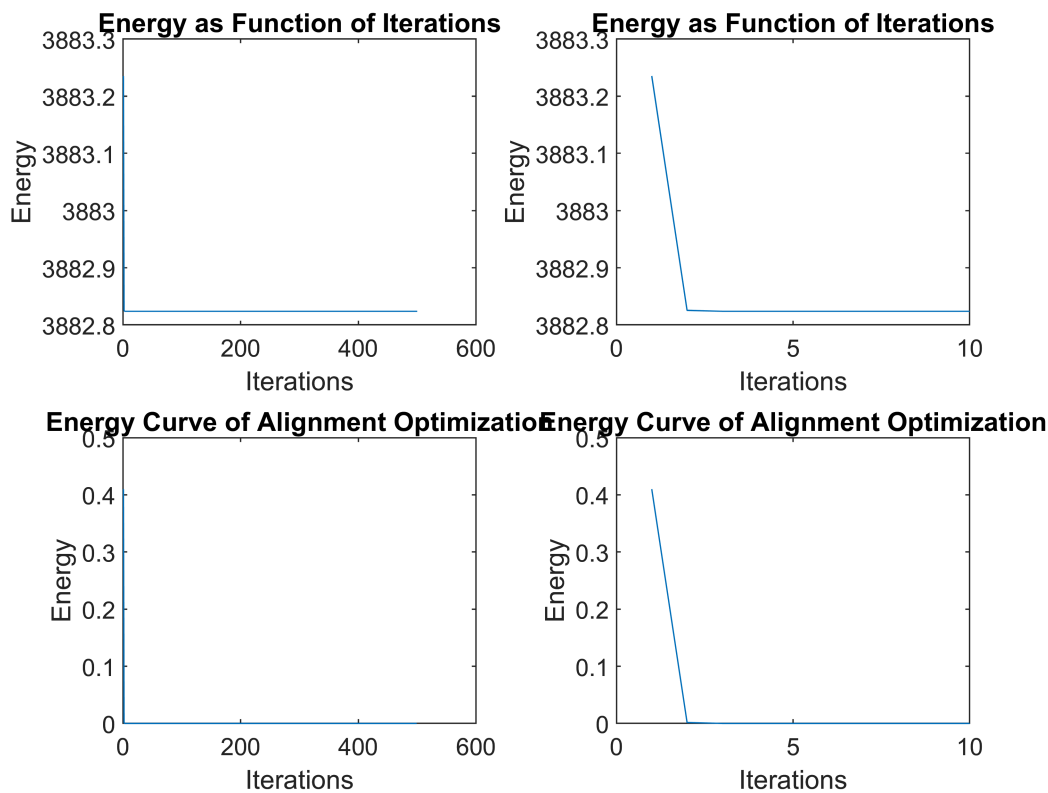
figure()
subplot(2,2,1)
plot(energy)
title('Energy as Function of Iterations')
ylabel('Energy')
xlabel('Iterations')
subplot(2,2,2)

```

```

plot(energy(1:10))
title('Energy as Function of Iterations')
ylabel('Energy')
xlabel('Iterations')
subplot(2,2,3)
plot(abs(diff(energy)))
title('Energy Curve of Alignment Optimization')
ylabel('Energy')
xlabel('Iterations')
subplot(2,2,4)
e = abs(diff(energy));
plot(e(1:10))
title('Energy Curve of Alignment Optimization')
ylabel('Energy')
xlabel('Iterations')

```

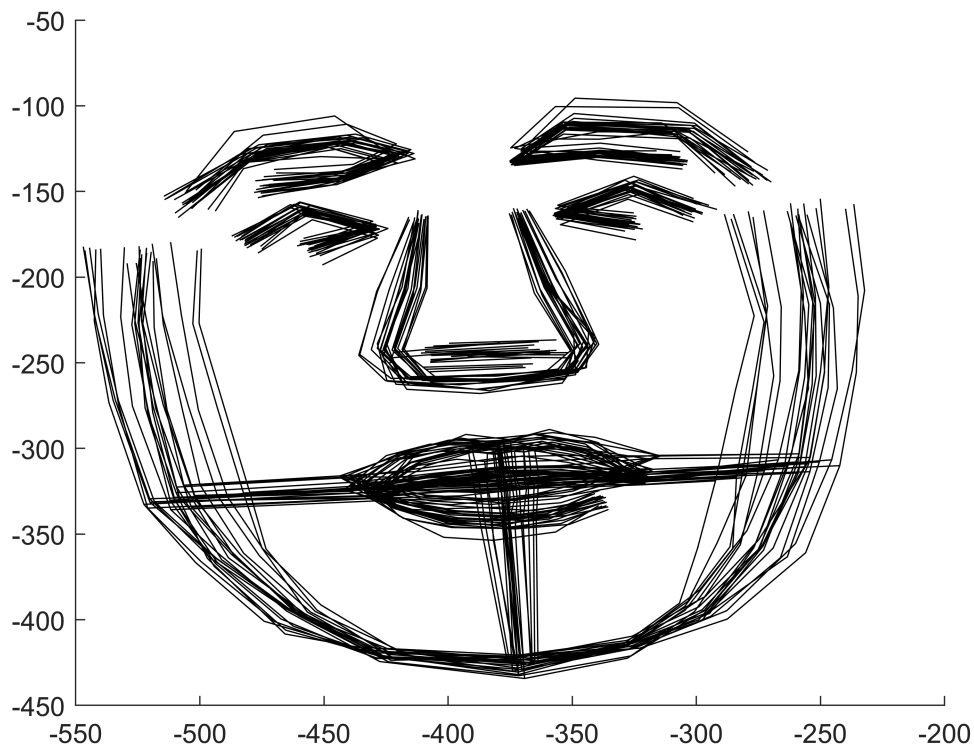


## Aligned Faces

```

figure()
for j = 1:N
    drawFaceParts( -aligned(:, :, j), 'k-' )
    hold on
end

```



## Problem 2

```
% Reformating the shape of the point sets to be a vector on n points of
% the ith shape in the set
for i = 1:N
    P(:,i) = reshape(aligned(:,:,i),1,136);
end
% Taking the mean across points N = 136 eqn 7 Cootes
muP = mean(P,2);
% Calculating the deviation from mean across points N = 136 eqn. 8 (Cootes)
dP = P-muP;
% Calculate 2n x 2n Covariance Matrix eqn. 9 (Cootes)
S = zeros(136,136,21);
for i = 1:N
    S(:,:,i) = dP(:,i)*dP(:,i)';
end
Smu = mean(S,3);
```

$$Sp_k = \lambda_k p_k$$

The eigenvector with the most variation explains the most significant modes of variation in the variables. Using the PCA function of Matlab, the largest eigenvectors were found.

```
[coeff,score,latent,explained] =pca(Smu);
```

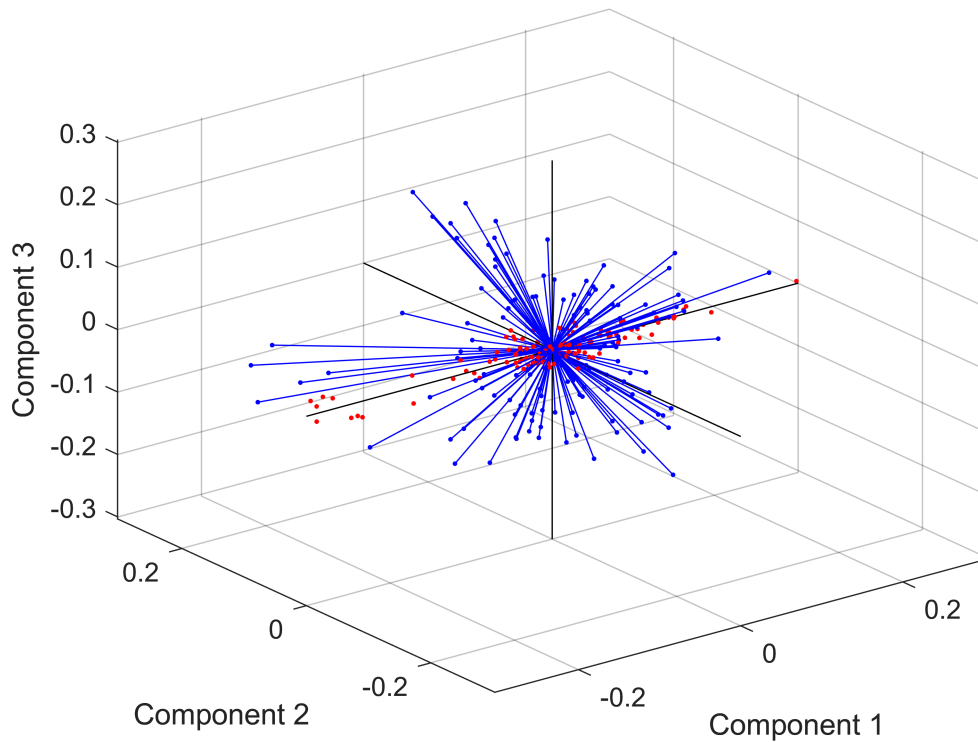
Warning: Columns of X are linearly dependent to within machine precision.

Using only the first 20 components to compute TSQUARED.

```
score(1:3)
```

```
ans = 1×3  
-661.1122 -566.3378 -600.7431
```

```
figure()  
biplot(coeff(:,1:3), 'scores', score(:,1:3))
```



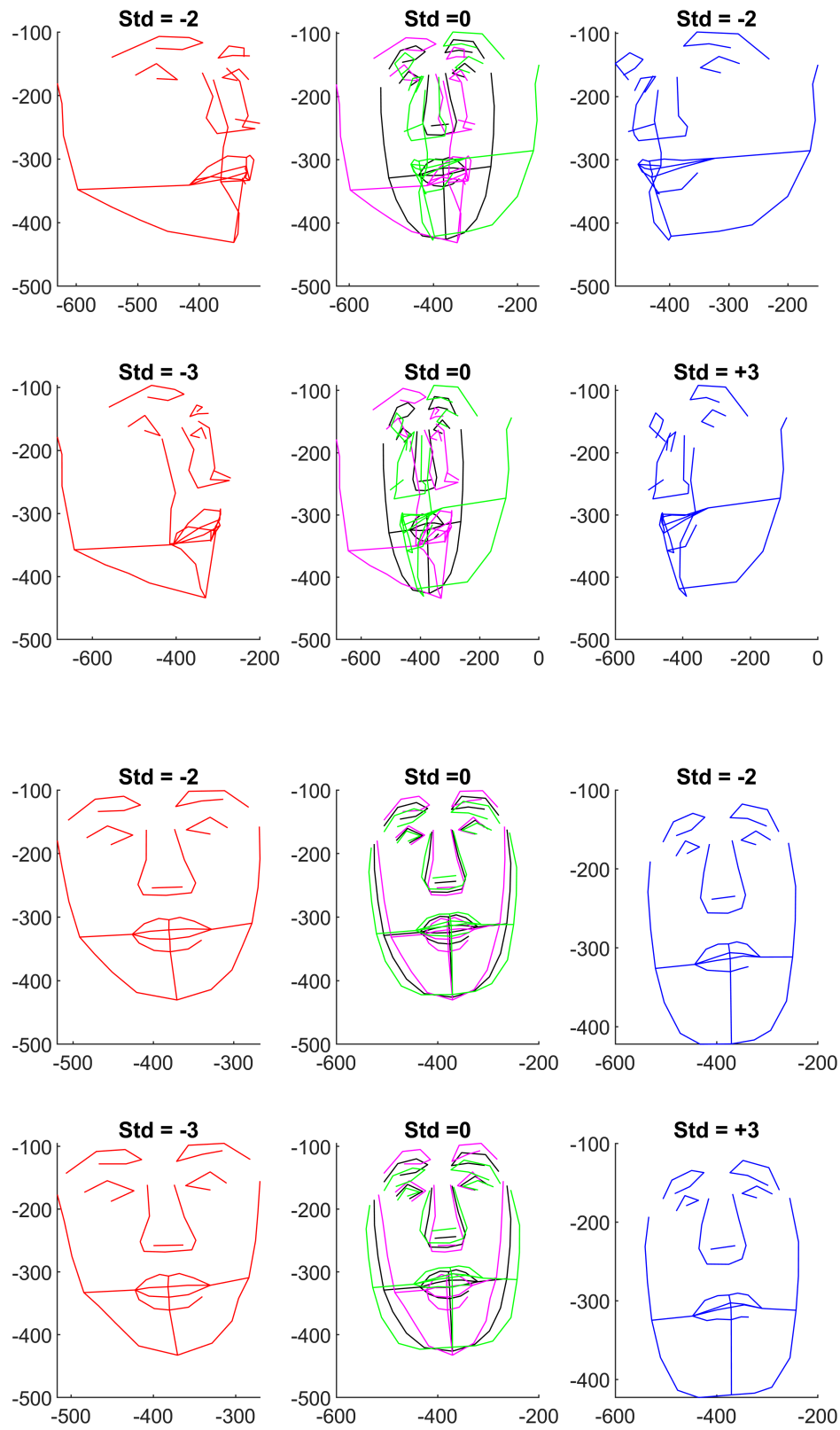
```
covarianceMatrix = cov(Smu);  
[V,D] = eig(covarianceMatrix);  
[bs,ind]=maxk(diag(D),3)
```

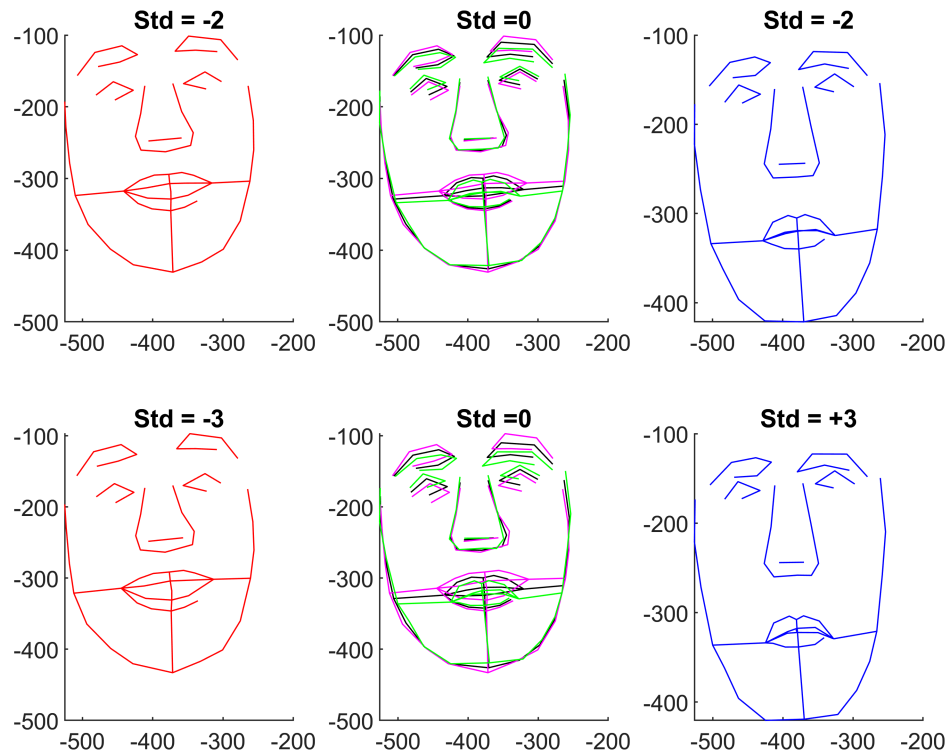
```
bs = 3×1  
104 ×  
4.3277  
0.1508  
0.0460  
ind = 3×1  
136  
135  
134
```

```
maxEigV = V(:,ind);
```

```
for i = 1:3  
    eigFaces(maxEigV(:,i),bs(i),muP);
```

end





The differences between the faces occur especially when the deviation is at  $\pm 3$  and mostly for the largest eigenvector, which would be sensible because it explains the most variation.

We are operating within the bounds of  $-3 \sqrt{\lambda_k} \leq b_k \leq 3 \sqrt{\lambda_k}$ .

```
function eigFaces(eig,bk,muP)
    bmin = -3.*sqrt(abs(bk)');
    xmin = muP + eig*bmin;
    xminr = reshape(xmin,68,2);

    bmin = -2.*sqrt(abs(bk)');
    xmin = muP + eig*bmin;
    xmin2r = reshape(xmin,68,2);

    bmax = 2.*sqrt(abs(bk)');
    xmax = muP + eig*bmax;
    xmax2r = reshape(xmax,68,2);

    bmax = 3.*sqrt(abs(bk)');
    xmax = muP + eig*bmax;
    xmaxr = reshape(xmax,68,2);

    xmu = reshape(muP,68,2);

    figure()
    subplot(2,3,1)
```

```

        drawFaceParts( -xmin2r, 'r-' )
        title('Std = -2')
subplot(2,3,2)
        drawFaceParts( -xmu, 'k-' )
        title('Std = 0')
        hold on
        drawFaceParts( -xmin2r, 'm-' )
        drawFaceParts( -xmax2r, 'g-' )
subplot(2,3,3)
        drawFaceParts( -xmax2r, 'b-' )
        title('Std = -2')
subplot(2,3,4)
        drawFaceParts( -xminr, 'r-' )
        title('Std = -3')
subplot(2,3,5)
        drawFaceParts( -xmu, 'k-' )
        title('Std = 0')
        hold on
        drawFaceParts( -xminr, 'm-' )
        drawFaceParts( -xmaxr, 'g-' )
subplot(2,3,6)
        drawFaceParts( -xmaxr, 'b-' )
        title('Std = +3')
end

```