## Subproblem

$$\min_{F,\Omega,\theta,\lambda^{k},\lambda^{-}} \sum_{v \in V} c_{v} F_{v} + \Omega$$
 (9) 
$$\max_{x,\xi^{+},\xi^{-}} \sum_{a=(v,w) \in A} (F_{v} - F_{w} + t_{w}) x_{a} + q_{a}^{+} \cdot u_{w} - q_{a}^{-} \cdot u_{w}$$
 s.t. 
$$2 \geq \sum_{a \in (v,w)} (F_{v} - F_{w} + t_{w}) x_{a}^{k} + F_{w}^{k}$$
 s.t. 
$$\sum_{a \in (v,w) \in A} x_{a} - \sum_{a \in (v,v) \in A} x_{a} \leq d_{v}^{+}$$
  $\forall v \in V \setminus \{v_{0}\}$  
$$+ \sum_{v \in V} (\lambda_{v}^{k+} + \lambda_{v}^{k-})$$
  $\forall 1 \leq k \leq K$  
$$- \sum_{a \in (v,v) \in A} x_{a} + \sum_{a \in (v,v) \in A} x_{a} \leq d_{v}^{-}$$
  $\forall v \in V \setminus \{v_{0}\}$  
$$- \sum_{a \in (v,v) \in A} x_{a} + \sum_{a \in (v,v) \in A} x_{a} \leq d_{v}^{-}$$
  $\forall v \in V \setminus \{v_{0}\}$  
$$- \sum_{a \in (v,v) \in A} x_{a} + \sum_{a \in (v,v) \in A} x_{a} \leq d_{v}^{-}$$
 
$$\forall v \in V \setminus \{v_{0}\}$$
 
$$- \sum_{a \in (v,v) \in A} x_{a} + \sum_{a \in (v,v) \in A} x_{a} \leq d_{v}^{-}$$
 
$$\forall v \in V \setminus \{v_{0}\}$$
 
$$- \sum_{a \in (v,v) \in A} x_{a} + \sum_{a \in (v,v) \in A} x_{a} \leq d_{v}^{-}$$
 
$$\forall v \in V \setminus \{v_{0}\}$$
 
$$- \sum_{a \in (v,v) \in A} x_{a} + \sum_{a \in (v,v) \in A} x_{a} \leq d_{v}^{-}$$
 
$$\forall v \in V \setminus \{v_{0}\}$$
 
$$- \sum_{a \in (v,v) \in A} x_{a} + \sum_{a \in (v,v) \in A} x_{a} \leq d_{v}^{-}$$
 
$$\forall v \in V \setminus \{v_{0}\}$$
 
$$- \sum_{a \in (v,v) \in A} x_{a} + \sum_{a \in (v,v) \in A} x_{a} \leq d_{v}^{-}$$
 
$$\forall v \in V \setminus \{v_{0}\}$$
 
$$x_{a} \geq 0$$
 
$$\forall a \in A$$
 
$$x_{a} \geq 0$$
 
$$x_{a} \geq 0$$
 
$$x_{a} \leq x_{a}$$
 
$$x_{$$

Algorithm 1 Exact algorithm for the  $\Gamma$ -robust two-stage project scheduling problem

**Input:** Graph G = (V, A), uncertainty parameter  $\Gamma \in \mathbb{N}_{\leq |V|}$ , execution times  $(t_v)_{v \in V}$ , uncertainties  $(u_v)_{v \in V}$ , costs per time unit  $(c_v)_{v \in V}$ , costs per time unit for finishing earlier than scheduled  $(d_v^-)_{v \in V}$ , costs per time unit for finishing later than scheduled  $(d_v^+)_{v \in V}$ , initial vertex set  $\hat{X} \subset \tilde{X}$ , sufficiently large constant M

**Output:** the costs for the  $\Gamma$ -robust two-stage problem and the finish times for all tasks  $(F_v)_{v \in V}$ 

- 1: while true do
- 2:  $schedule\_obj, F^*, \Omega^*$  optimal solution of (9) with constraints only for  $\hat{X}$
- 3:  $subproblem_obj, x^* = optimal solution of (10)$
- 4: **if**  $subproblem_obj > \Omega$  **then**
- 5:  $\tilde{X} = \tilde{X} \cup \{x\}$
- 6: else
- 7: break;
- 8: end if
- 9: end while
- 10: **return**  $schedule\_obj, (F_v)_{v \in V}$

## McCormick Heuristic

```
\begin{split} \min_{\substack{F,\mu^{+},\theta,a^{\pm}\\ \beta^{\pm},\lambda^{\pm},\phi^{\pm}}} \sum_{v\in V\setminus\{v_{0}\}} \left(d_{v}^{-}\mu_{v}^{-} + d_{v}^{+}\mu_{v}^{+}\right) + \sum_{v\in V} \left(c_{v}\cdot F_{v} + \phi_{v}^{+} + \phi_{v}^{-}\right) \\ &+ \Gamma\theta + M\cdot \sum_{a\in A} \left(\lambda_{a}^{+} + \lambda_{a}^{-}\right) \\ \text{s.t. } \mu_{w}^{+} - \mu_{w}^{-} - \alpha_{a}^{+} - \alpha_{a}^{-} + \lambda_{a}^{+} + \lambda_{a}^{-} \geq -F_{w} + t_{w} \quad \forall a = (v_{0},w) \in A \\ \mu_{w}^{+} - \mu_{v}^{+} - \mu_{w}^{-} + \mu_{v}^{-} - \alpha_{a}^{+} - \alpha_{a}^{-} + \lambda_{a}^{+} + \lambda_{a}^{-} \qquad \forall a = (v,w) \in A \\ &\geq F_{v} - F_{w} + t_{w} \qquad v \neq v_{0} \\ \theta - M\cdot \sum_{a=(\cdot,v)\in A} (\beta_{a}^{+} - \lambda_{a}^{+}) + \phi_{v}^{+} \geq 0 \qquad \forall v \in V \\ \theta - M\cdot \sum_{a=(\cdot,v)\in A} (\beta_{a}^{-} - \lambda_{a}^{-}) + \phi_{v}^{-} \geq 0 \qquad \forall v \in V \\ \theta - M\cdot \sum_{a=(\cdot,v)\in A} (\beta_{a}^{-} - \lambda_{a}^{-}) + \phi_{v}^{-} \geq 0 \qquad \forall v \in V \\ \alpha_{a}^{+} + \beta_{a}^{+} - \lambda_{a}^{+} \geq u_{w} \qquad \forall a = (v,w) \in A \\ \alpha_{a}^{-} + \beta_{a}^{-} - \lambda_{a}^{-} \geq -u_{w} \qquad \forall a = (v,w) \in A \\ F, \mu^{+}, \mu^{-}, \theta, \alpha^{+}, \alpha^{-}, \beta^{+}, \beta^{-}, \lambda^{+}, \lambda^{-}, \phi^{+}, \phi^{-} \geq 0 \end{cases} \tag{11} \end{split}
```

Algorithm 2 Adaptive McCormick heuristic for the  $\Gamma$ -robust two-stage project scheduling problem

**Input:** Graph G = (V, A), uncertainty parameter  $\Gamma \in \mathbb{N}_{\leq |V|}$ , execution times  $(t_v)_{v \in V}$ , uncertainties  $(u_v)_{v \in V}$ , costs per time unit  $(c_v)_{v \in V}$ , costs per time unit for finishing earlier than scheduled  $(d_v^-)_{v \in V}$ , costs per time unit for finishing later than scheduled  $(d_v^+)_{v \in V}$ 

**Output:** the costs for the  $\Gamma$ -robust two-stage problem and the finish times for all tasks  $(F_v)_{v \in V}$ 

- 1: step =  $-\frac{1}{2}$
- $2: M_{\text{opt}} = M$
- 3:  $cost_{opt}$ ,  $F_{opt}$  optimal solution of McCormick heuristic with  $M = M_{opt}$
- 4: **while** step  $\geq 0.01$  **and** number iterations  $\leq 30$  **do**
- 5:  $M_{\text{temp}} = M_{\text{opt}} \cdot (1 + \text{step})$
- 6:  $cost_{temp}$ ,  $F_{temp}$  optimal solution of McCormick heuristic with  $M = M_{temp}$
- 7: **if**  $cost_{temp} < cost_{opt}$  **then**
- 8:  $M_{\text{opt}}, \text{cost}_{\text{opt}}, F_{\text{opt}} = M_{\text{temp}}, \text{cost}_{\text{temp}}, F_{\text{temp}}$
- 9: else
- 10:  $step = -\frac{1}{2} \cdot step$
- 11: end if
- 12: end while
- 13: **return**  $cost_{opt}$ ,  $F_{opt}$

## Iterative Recovery Heuristic

## Algorithm 3 Iterative Recovery Heuristic

**Input:** Graph G = (V, A), uncertainty parameter  $\Gamma \in \mathbb{N}_{\leq |V|}$ , execution times  $(t_v)_{v \in V}$ , uncertainties  $(u_v)_{v \in V}$ , costs per time unit  $(c_v)_{v \in V}$ , costs per time unit for finishing earlier than scheduled  $(d_v^-)_{v \in V}$ , costs per time unit for finishing later than scheduled  $(d_v^+)_{v \in V}$ 

**Output:** the costs for the  $\Gamma$ -robust two-stage problem and the finish times for all tasks  $(F_v)_{v \in V}$ 

- 1: F solution of the deterministic project scheduling problem G, t
- 2:  $\xi$ , y optimal solution of the second stage problem for schedule F with cost obj
- 3: **while** number iterations  $\leq 30$  **do**
- 4:  $\tilde{F}$  with  $\tilde{F}_v = F_v + 1$  if  $y_v > 0$  and  $\tilde{F}_v = F_v 1$  if  $y_v < 0$
- 5:  $\tilde{\xi}, \tilde{y}$  optimal solution of the second stage problem for schedule  $\tilde{F}$  with cost  $\tilde{\text{obj}}$
- 6: **if**  $\tilde{\text{obj}}/\text{obj} > 1 10^{-5}$  **then**
- 7:  $F, \xi, y, \text{obj} = \tilde{F}, \tilde{\xi}, \tilde{y}, \text{obj}$
- 8: else
- 9: break
- 10: end if
- 11: end while
- 12: return obj, F