

# Libevent 简介

Libevent 是一款事件驱动的网络开发包，由于采用 C 语言开发体积小巧，跨平台，速度极快。大量开源项目使用了 Libevent 比如谷歌的浏览器和分布式的高速缓存系统 memcached。libevent 支持 kqueue, select, poll, epoll, iocp。内部事件机制完全独立于公开事件 API，libevent 支持跨平台可以在 Linux, \*BSD, MacOSX, Solaris, Windows 等平台上编译。

学习条件：具有一定的 C/C++ 基础，熟悉 Linux

## 环境搭建

### ☑ 配置 zlib 库

```
# 1. 解压zlib 1.2.11
tar xvf zlib-1.2.11.tar.gz
# 2. 编译
cd zlib-1.2.11/
./configure
make
make install
```

### ☑ 配置 openssl 库

```
# 1. 解压openssl-1.1.1.tar.gz
tar xvf openssl-1.1.1.tar.gz
# 2. 编译
cd openssl-1.1.1/
./configure
make
make install
```

### ☑ 配置 libevent 环境

```
# 1. 解压libevent 2.1.8
unzip libevent-master.zip
# 2. 编译
cd libevent-master/
./autogen.sh
./configure
make
make install
# 3. 将动态库来连接到 /usr/lib 下或者执行以下 ldconfig
sudo ln -s /usr/local/lib/libevent-2.2.so.1 /usr/lib/libevent-2.2.so.1
```

## 实战实例

## 创建 event\_base

仅仅实现创建上下文

```
/**
 * 创建event base
 * */

#include <event2/event.h>
#include <iostream>
using namespace std;
int main()
{
    std::cout << "test libevent!\n";
    //创建libevent的上下文
    event_base * base = event_base_new();
    if (base)
    {
        cout << "event_base_new success!" << endl;
    }
    return 0;
}
```

## 创建 test\_server

test\_server 中说明了如何使用 libevent 创建一个 socket 监听

evconntlistener\_new\_bind 一个接口完成了 socket 的创建，绑定和监听。

```
/**
 * 创建event base
 * */

#include <event2/event.h>
#include <iostream>
#include <signal.h>
#include <event2/listener.h>
#include <string.h>
#include "event_interface.h"

using namespace std;

/**
    A callback that we invoke when a listener has a new connection.

    @param listener The evconntlistener
    @param fd The new file descriptor
    @param addr The source address of the connection
    @param socklen The length of addr

```

```

    @param user_arg the pointer passed to evconnlistener_new()
    */
void listen_cb(struct evconnlistener * evConnListener, evutil_socket_t
evUtilSockFd, struct sockaddr * sockAddr, int socklen, void *data)
{
    cout << "listen cb is called" << endl;
}

int main(int argc, char *argv[])
{
    //1. 忽略管道信号,发送数据给已关闭的socket
    //一些socket程序莫名宕掉的原因
    if(signal(SIGPIPE, SIG_IGN) == SIG_ERR)
    {
        cout << "signal pipe signal" << endl;
    }

    std::cout << "test libevent!\n";
    //创建libevent的上下文
    event_base * base = event_base_new();
    if (!base)
    {
        cout << "event_base_new failed." << endl;
        return -1;
    }
    else
    {
        cout << "event_base_new success!" << endl;
    }

    //监听端口
    //socket, bind, listen
    sockaddr_in sockIn;
    memset(&sockIn, 0, sizeof(sockIn));
    sockIn.sin_family = AF_INET;
    sockIn.sin_port = htons(SERVER_PORT);
    /* 地址没有指定因为对sockIn进行了memset, 地址赋值为0代表着可以为任意可以用的地址 */

    struct evconnlistener *pEvListener = evconnlistener_new_bind(base, /*
libevent的上下文 */
        listen_cb, /* 接收到连接的回调 */
        base, /* 回调函数参数 */
        LEV_OPT_REUSEABLE|LEV_OPT_CLOSE_ON_FREE, /* 地址重用,
evconnlistener关闭同时关闭socket */
        10, /* 连接队列的大小, 对应的listen函数 */
        (sockaddr *)&sockIn, /* 绑定地址和端口 */
        sizeof(sockIn)
    );

    //事件分发处理
    if(base)
        event_base_dispatch(base);

    if(pEvListener)
        evconnlistener_free(pEvListener);

    if(base)
        event_base_free(base);
}

```

```
    return 0;
}
```

## 创建 test\_conf

test\_conf 主要是实现了，测试当前系统中支持的方法类型和事件特征的支持情况。

```
support methods
epoll
poll
select
```

```
EV_FEATURE_ET events are supported.
EV_FEATURE_01 events are supported.
EV_FEATURE_FDS events are not supports.
EV_FEATURE_EARLY_CLOSE events are supported.
event base new with config sucess
```

```
#include <event2/event.h>
#include <event2/thread.h>
#include <event2/listener.h>
#include <signal.h>
#include <iostream>
#include <string.h>
#include "event_interface.h"

using namespace std;

int main()
{
    //忽略管道信号，发送数据给已关闭的socket
    if (signal(SIGPIPE, SIG_IGN) == SIG_ERR)
        return 1;

    //创建配置上下文
    event_config *config = event_config_new();
    //显示支持的网路模式
    const char **methods = event_get_supported_methods();
    cout << "support methods " << endl;
    for(int i = 0; methods[i] != NULL; i++)
    {
        cout << methods[i] << endl;
    }
    //设置特征，确认特征时候生效
    //这个features在linux中设置没有效果，因为linux中本来就是支持ET模式的，边缘触发模式
    // 设置了EV_FEATURE_FDS其他特征嗯就无法设置
    //也就是所支持了EV_FEATURE_FDS 其他的特征都是无法支持的
    int ret =
    event_config_require_features(config, EV_FEATURE_ET|EV_FEATURE_EARLY_CLOSE);
    if(OK != ret)
```

```

{
    cerr << "event config require features failed." << endl;
    return ERROR;
}
//初始化libevent上下文
event_base *base = event_base_new_with_config(config);

//config一旦配置好就不需要在使用了
event_config_free(config);

if(!base)
{
    cerr << "event base new with config failed!" << endl;
    //首次失败就创建一个base取默认值, 若是再次失败就返回失败
    base = event_base_new();
    if(!base)
    {
        cerr << "event base new failed." << endl;
        return ERROR;
    }
}
else
{
    //确认特征那些生效
    int f = event_base_get_features(base);
    if(f&EV_FEATURE_ET)
    {
        cout << "EV_FEATURE_ET events are supported." << endl;
    }
    else
    {
        cout << "EV_FEATURE_ET events are not supports." << endl;
    }

    if(f&EV_FEATURE_01)
    {
        cout << "EV_FEATURE_01 events are supported." << endl;
    }
    else
    {
        cout << "EV_FEATURE_01 events are not supports." << endl;
    }

    if(f&EV_FEATURE_FDS)
    {
        cout << "EV_FEATURE_FDS events are supported." << endl;
    }
    else
    {
        cout << "EV_FEATURE_FDS events are not supports." << endl;
    }

    if(f&EV_FEATURE_EARLY_CLOSE)
    {
        cout << "EV_FEATURE_EARLY_CLOSE events are supported." << endl;
    }
    else
    {

```

```
        cout << "EV_FEATURE_EARLY_CLOSE events are not supports." << endl;
    }
    cout << "event base new with config sucess" << endl;
    event_base_free(base);
}

return 0;
}
```

