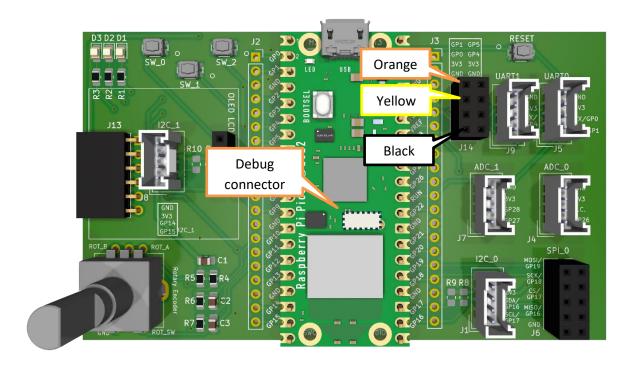
## PicoProbe wiring

## **General instructions**

Connect JST-JST cable to connector marked with **D** on the PicoProbe and the other end to the debug connector next to the WiFi module.

Connect JST-Male cable to connector marked with **U** on the PicoProbe and connect the loose ends: Orange to GP1, Yellow to GP0 and Black to Ground.



Make following changes to CMakeLists.txt in you project:

Add:

```
set(PICO BOARD pico w)
```

after the first **include** in CMakeLists.txt. This line has nothing to do with the debugger but it tells the build system that we are building for PicoW which enables use of wireless module libraries if needed.

 Change the lines that define where stdio is routed to: pico\_enable\_stdio\_usb(\${PROJECT\_NAME} 0) pico\_enable\_stdio\_uart(\${PROJECT\_NAME} 1)

With these changes stdio is routed to UARTO. The UART connection through PicoProbe is not affected by Pico reset so you won't miss any output when the Pico resets.