

# AWR1843 Secondary Bootloader Design Guide

This document is a guide to the Secondary Bootloader application for AWR1843 device.

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# 1 Introduction

In automotive applications, CAN is the only available external interface to the XWR1843 device and hence any update to the application binaries residing in the SFLASH need to be received over CAN. The secondary bootloader primarily is responsible for supporting the following functionality:

- 1. Provides the capability of updating application binaries in the SFLASH by receiving the binaries over CAN
- 2. Loads the application to run on the device. The SBL is never updated once deployed in the field. This ensures that even in case of power outages during the update of the application there is no impact to the availability of the device. On the subsequent power cycle, the SBL again is loaded by the primary (ROM) bootloader to allow for an update to the application.

Secondary bootloader application aims at providing a reference for an application which can fulfill this requirement.

The following Nomenclature is used throughout this document.

Primary Bootloader or PBL	The ROM bootloader
Secondary Bootloader or SBL	This application
Application Meta-Image or User Application	The user's application Meta-Image that will be loaded over CAN interface

# 1.1 Design Scheme

The application has following two parts:

Can Downloader: Update a new or existing application Meta-Image in SFLASH



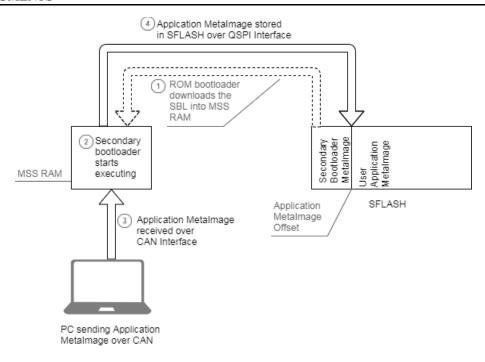


Figure 1: Can Downloader

 Flash Downloader: Download the existing application Meta-Image from FLASH into the RAMs of all subsystems



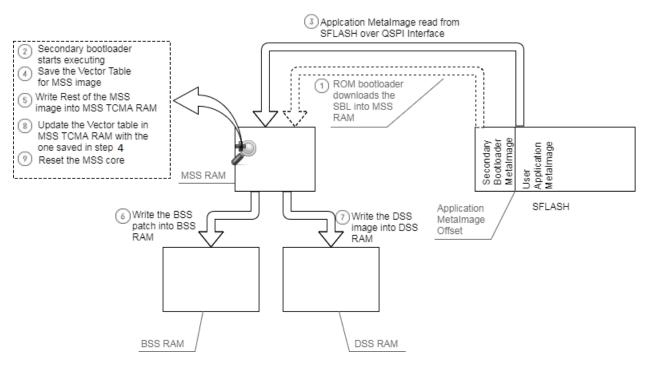


Figure 2: Flash Downloader



# 2 Application Design Flow

The idea behind this approach is that the Meta-Image (without the BSS patch and DSS image) for the secondary bootloader application will be flashed once over UART. From there on, following each Cold/Warm reset, this application will be loaded from the SFLASH into the MSS RAM by the primary bootloader, which then will allow the user to do either of the following based on the user input over UART:

- Flash the Application Meta-Image at a fixed offset (from the Secondary bootloader image) in the SFLASH.
- Load the Application Meta-Image present at a fixed offset (from the Secondary bootloader image) to the following memories:
  - MSS TCMA, TCMB
  - BSS TCMA, TCMB
  - DSS L2, L3 memories

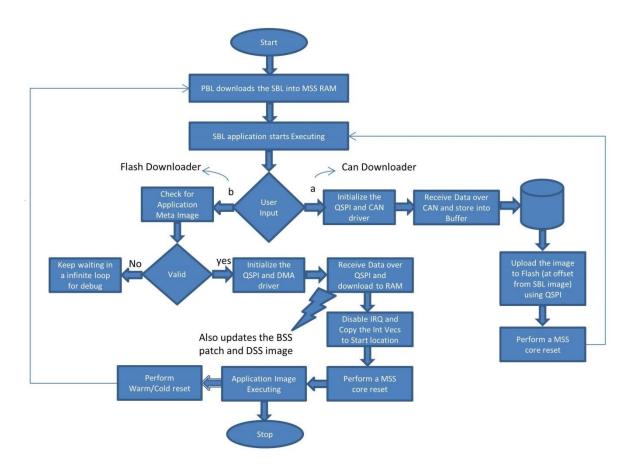


Figure 3: SBL Design Flow



# 3 Decision Analysis and Resolution (DAR)

#### 3.1 TCMA vs TCMB

Whether to execute the Secondary Bootloader code from TCMA or TCMB.

### TCMA advantages over TCMB

As the primary bootloader already load the code into the TCMA, no additional effort is required in the SBL application code. Thus, the execution time will be relatively less and the SBL code would be simpler.

# TCMB advantages over TCMA

If the SBL code is executing from the TCMA, the user application code has to be loaded at an offset larger or equal to the SBL code size. The available TCMA memory available for the user application will be reduced. Whereas, executing the code from TCMB allows the user application code to use the whole of TCMA memory. Also, the TCMB memory is initialized by the application startup code ensuring there would be no reduction in the TCMB memory for user application.

#### Decision

Apart from the startup code responsible for copying the code into the TCMB memory, the SBL code will be kept in TCMB memory.



# 4 Detailed Flow

The Secondary Bootloader application code is divided into various phases. The functioning and relevance of each phases is explained in the following subsections.

### 4.1 Pre Initialization

As most of the code would be executing from the MSS TCMB memory, it needs to be copied from TCMA to TCMB as part of the pre initialization routine. The following variables are defined in the linker command file which will be used to copy the code.

```
extern uint32_t _libRunAddr, _libLoadStart, _libLoadEnd;
extern uint32_t _constRunAddr, _constLoadStart, _constLoadEnd;
extern uint32_t _startupRunAddr, _startupLoadStart, _startupLoadEnd;
```

# 4.2 MPU Configuration

The following Memory sections will be relevant for this application. The MPU setting of each of these sections is also specified.

MSS TCMA: Read, Write and Executable

MSS TCMB : Read, Write and Executable

BSS TCMA: Read, Write and Executable

BSS TCMB : Read and Write

DSS L1:

DSS L2:

### 4.3 PinMux

The following peripherals are used for this application. Hence the pin muxing for these peripherals is required.

CAN : CAN-Tx and CAN-Rx

QSPI: CLK, CS, D0(IN/OUT), D1(IN), D2(IN), D3(IN)

• UART : UART-Tx, UART-Rx

# 4.4 User Input

The UART is initialized with following configuration:



Baudrate: 115200

Data: 8 bit

Parity : None

Stop bit: 1 bit

Flow control: None

User can choose from one of the following option:

a. Update Meta Image via CAN(FD)

b. Download existing Meta Image from Flash

### 4.5 Can Downloader

The following steps are performed in this phase:

- Initialize QSPI Flash interface.
- Initialize CAN interface with following configuration:
  - 1 Mbps as nominal bit-rate

Propagation segment: 8

Phase segment1: 6

Phase segment2:5

Sync jump: 1

BRP:2

Nominal Bit rate = (40)/(((8+6+5)+1)\*BRP) = 1Mhz

5 Mbps as data bit-rate

Propagation segment: 2

Phase segment1: 2

Phase Segment2: 3

Sync jump: 1

BRP:1

Data Bit rate = (40)/(((2+2+3)+1)\*BRP) = 5Mhz



- Create an Rx object with DATA\_MSG\_ID
- Create an Rx object with TERMINATE\_MSG\_ID
- Erase the SFLASH for ERASE\_SIZE\_KB at an offset of METAIMAGE\_OFFSET
- Wait to receive a CAN message in a loop
  - o If the received message ID is DATA\_MSG\_ID, write it to the SFLASH
  - If the received message ID is TERMINATE\_MSG\_ID, break out of the loop
- Close the QSPI Flash interface

### 4.6 Flash Downloader

The following steps are performed in this phase:

- Initialize the DMA
- Initialize QSPI Flash interface
- Parse the Application Meta-Image present in the SFLASH
- Load each Sub-System image in their respective RAMs
  - o If no Error: Close the QSPI Flash interface
  - If Error: wait in an infinite loop for debug

#### 4.7 Soft Reset

Reset the MSS core



# 5 Configurable options

Only the following options should be configured as per the requirement (in main.c):

0x29E

The CAN message ID for the receiving the Meta-Image.

0x19E

The CAN message ID for the notifying the end of CAN transmission.

(300 \* 1024)

The user application Meta-Image offset from the start of flash memory. This value shall be larger than the size of SBL Meta-Image.

(1024)

This is the size of flash memory that needs to be cleared before flashing the application Meta-Image. This value shall be larger than the size of the application Meta-Image.



# 6 Usage

# 6.1 Pre requisites

- **ECO's:** As this application receives the image over CAN interface, the ECOs for enabling the CAN-FD interface on the EVM are required. Below are the ECOs
  - Mount 0 ohms on R11 and R12
  - Remove R6 and R4
- Setup: The setup required for this application is shown below.

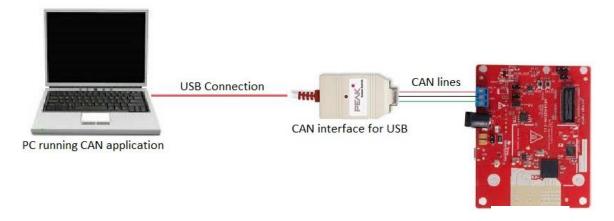


Figure 4: Can downloader Setup

PC based CAN application: For the CAN downloader part of the application, where
the Application Meta-Image will be updated at an offset in the SFlash, a PC based
application is required. This PC based application will communicate with the device
over USB-to-CAN dongle. The purpose of this application is to send the Meta-Image
over CAN in chunks of 64 bytes each. For more information on this application refer
to PC based CAN application.

# 6.2 Running the application

The Meta-Image for SBL application will be created automatically along with the out file upon compiling this application. Note that this image will contain only the MSS binary (no BSS or DSS binary). This Meta-Image needs to be flashed once using the conventional method (uniflash). From this point onwards, this image will reside in the SFLASH as the primary Meta-Image (until a new image is flashed using the uniflash) and will be loaded each time after a cold or warm reset. Follow the below steps to run the application

 Find the COM port which shows as "XDS110 Class Application/User UART" under device manager.



 Connect to the COM port found in previous step (using any serial terminal application like Teraterm, Hyperterminal etc.) and configure this port with following configuration.

Baudrate: 115200

Data: 8 bit

Parity: None

Stop bit: 1 bit

Flow control: None

- Restart the device by pressing the "SW2" on the EVM. The following prompt will appear on the serial terminal console. Refer to the below figure.
- Hit "Enter" on the console. The application will start erasing the portion of SLFASH, where the user application Meta-Image will reside. After the Erase has completed the application will ask the user to start the PC based CAN application. Refer to below figure.

Figure 5: SBL Input Prompt



 Hit "space bar" on the console. The SBL will wait for the CAN messages to update the flash.

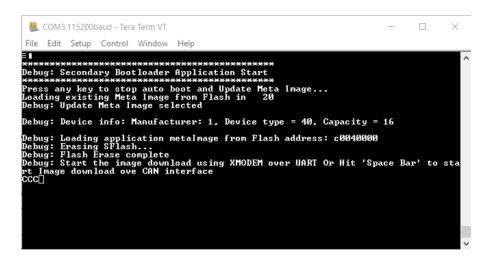


Figure 6: Can Downloader Start

- This application uses PCAN (Peak) USB-CAN adaptor to download firmware to device. To use this application with Peak PCAN adaptor follow these steps:
  - Copy PCANBasic.dll to 'C:\windows\SysWOW64' directory(Download from <u>PCAN-Basic API</u>)
  - Open the command prompt in the directory where the "CAN\_Metaimage\_Flasher.exe" is located
  - Run the PC based CAN CLI based application. Open the CLI in Windows PC and run below command

```
CAN_Metaimage_Flasher.exe <Metalmage_path_name> <MetalMage_path_name> => path and name of the Metalmage
```

 Once the PC application has sent the complete Meta-Image over the CAN, the console will show the total number of bytes transferred. This can be used to ensure that the complete image has been transferred. The application will restart and the input prompt will show up again. Refer to the below figure.



Figure 7: Can Downloader Finish

• If there is no error is the application Meta-Image, the application will start executing automatically. Refer to the below figure.



Figure 8: Flash Downloader



# 7 PC based CAN application

A PC based CAN application based on the Peak System USB to CAN Dongle is already provided. For other similar dongles, the application has to be ported. The General flow of the application is explained in the below flow diagram

