# Ai Lab

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## part\_1

## 贝叶斯网络手写数字识别

#### 实验原理

数字识别贝叶斯网络主要采用了像素值作为特征值来进行预测图片所对应的数字

在 fit 函数中,需要完成对先验概率和条件概率的计算,其中, labels\_prior 为先验概率,

```
def fit(self, pixels, labels):
    n_samples = len(labels)
# Calculate prior probability
labels_counts = np.bincount(labels, minlength=self.n_labels)
self.labels_prior = labels_counts / n_samples

# Calculate conditional probability
for pixel in range(self.n_pixels):
    for value in range(self.n_values):
        for label in range(self.n_labels):
            pixel_value_mask = (pixels[:, pixel] == value)
            label_pixel_mask = (labels == label)
            count = np.sum(pixel_value_mask & label_pixel_mask)
            self.pixels_cond_label[pixel, value, label] = count / labels_counts[label]
```

然后通过遍历每一个数字每个像素的值来计算对应的条件概率

在 predict 函数中, 首先获取待处理图片的像素值, 然后根据学习的概率来预测最高可能性的值。

```
def predict(self, pixels):
    n_samples = len(pixels)
    labels_pred = np.zeros(n_samples, dtype=np.int8)

for i in range(n_samples):
    probabilities = np.zeros(self.n_labels)
    for label in range(self.n_labels):
        label_prob = self.labels_prior[label]
        for pixel in range(self.n_pixels):
            pixel_value = pixels[i, pixel]
            pixel_prob = self.pixels_cond_label[pixel, pixel_value, label]
            label_prob *= pixel_prob
            probabilities[label] = label_prob

labels_pred[i] = np.argmax(probabilities)

return labels_pred
```

准确率是84.38%

C:\ProgramData\Anaconda3\python.exe F:\Desktop\exp2\src\_exp2\_ai2023sp\_ustc\part\_1\src\Bayesian-network.py
test score: 0.8438

## 利用K-means实现图片压缩

#### 实验原理

利用KMeans算法将图像的每一个像素(R, G, B)作为数据点并对所有点进行聚类。完成聚类之后,将所有数据点的值替换成其聚类中心的值,这样仅需保留几个聚类中心的数据点值以及其他点的类别索引,从而达到压缩图片的目的。

在 assign\_points 函数中,我们需要计算每个点和中心点的距离并把它们分配给最近的中心点,因此,我们可以使用如下方法进行 计算

```
for i in range(n_samples):
    distances = np.linalg.norm(points[i] - centers, axis=1)
    labels[i] = np.argmin(distances)
```

在 update\_centers 函数中, 我们需要根据新的数据点来更新中心点

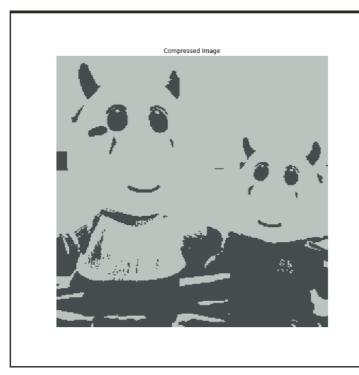
```
for k in range(self.k):
    cluster_points = points[labels == k]
    if len(cluster_points) > 0:
        centers[k] = np.mean(cluster_points, axis=0)
```

在 fit 函数中,通过迭代更新中心直到收敛或者达到最大迭代次数来执行,可以用np.allclose来检查收敛性

```
centers = self.initialize_centers(points)
for _ in range(self.max_iter):
    labels = self.assign_points(centers, points)
    new_centers = self.update_centers(centers, labels, points)
    if np.allclose(centers, new_centers):
        break
    ceters = new_centers
```

在 compress 函数中, 我们需要将像素值替换为对应的附近聚类中心值。可以用如下方式实现

```
points = img.reshape((-1, img.shape[-1]))
    centers = self.fit(points)
    labels = self.assign_points(centers, points)
    compressed_points = centers[labels.astype(int)]
    compressed_img = compressed_points.reshape(img.shape)
```





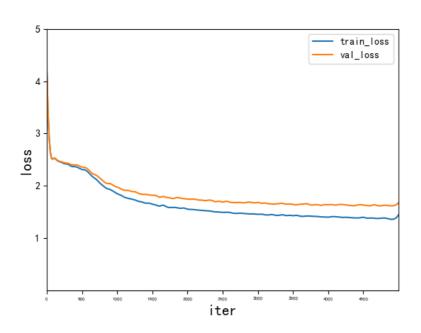






part\_2

## 误差曲线如下所示:



### 输入:

To be or not to be: that is the

结果(为什么会这样呜呜呜):

To be or not to be: that is the shamest of the stand.

#### Citizens:

I would you the say the same of your souls and the seast That the shall be the shall be the seast of the state.

#### Second Citizen:

I will the shall be the shall be the shall be the shall That the that the to the stand of the world, And the to the to the stand the father of the That the that the the stand of the world to the stand The to the that the to the to the to the to thee.

The would the the shame of the world to the stand the seat of the seat That the the  $\ensuremath{\mathsf{t}}$