1. Out put images q1_Superpixels.png and q1_result.png are shown in Figure 1 and 2 correspondingly. This super-pixel covers a part of two yellow peppers of the lower middle of the input image.



Figure 1: Superpixels of Question 1

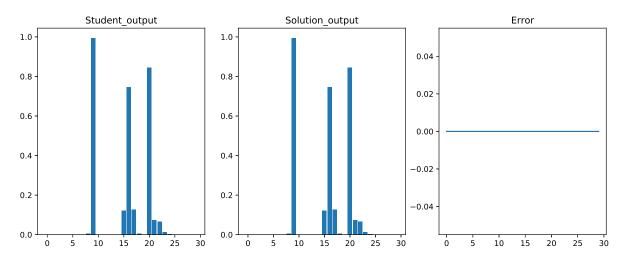


Figure 2: Results of Question 1

2. (a) Out put images q2_Superpixels.png and q2_result.png are shown in Figure 3 and 4 correspondingly.

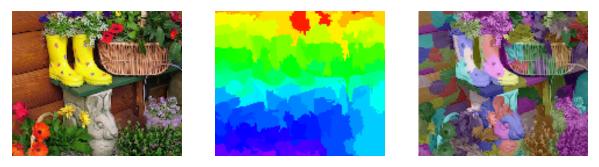


Figure 3: Superpixels of Question 2

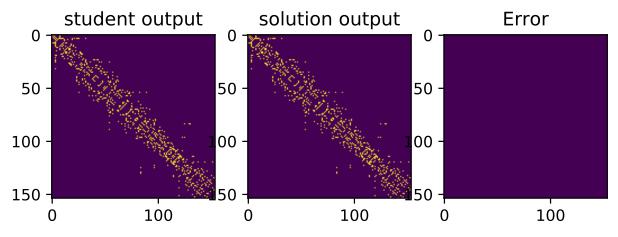


Figure 4: Results of Question 2

- (b) We find the average node degree is 5.33766 for the adjacency matrix in this problem.
- (c) The adjacency graph is not perfectly banded diagonal matrix because superpixels in images have various sizes. We can see that some superpixels are cover a lot of space along the y direction, while narrow along x direction. In this way, it is able to adjunct to some superpixel, whose centroid is far from its centroid. Moreover, some superpixel are relatively small and only adjunct to four superpixels around it.
- 3. (a) Out put images q3_Superpixels.png and q3_result.png are shown in Figure 5 and 6 correspondingly.

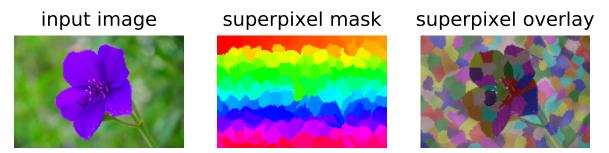


Figure 5: Superpixels of Question 3

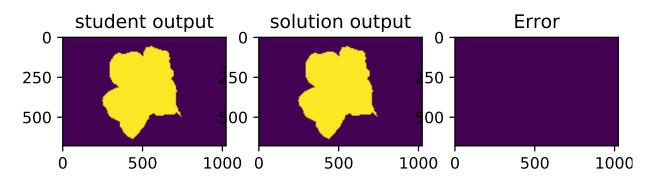


Figure 6: Results of Question 3

(b) We have shown Adjacency matrix and capacity image in the figure 7. We know that adjacency matrix is an unweighted bidirected graph, and capacity matrix is an weighted bidirected graph. Capacity image has two extra nodes, source and sink than the adjacency matrix. All edges in adjacency matrix are preserved in capacity matrix, and source and sink are connected to all nodes besides each other.

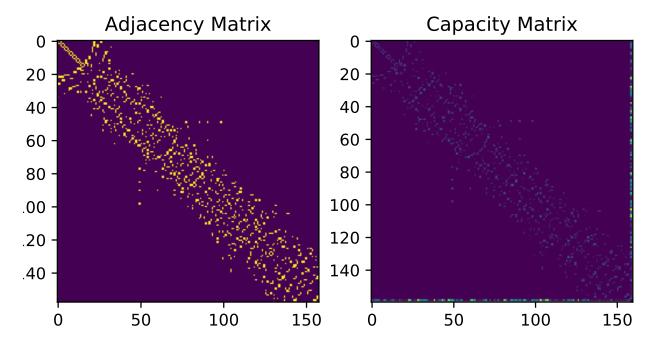


Figure 7: Capacity Image of Question 3

(c)

4. (a) Flower segmentation is shown in Figure 8 and 9.

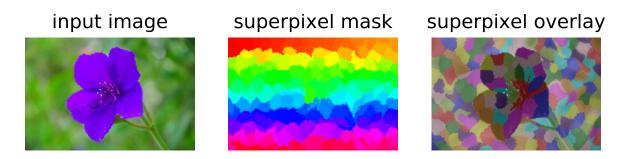


Figure 8: Superpixels of Question 4a

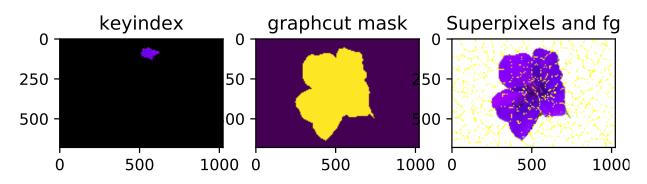


Figure 9: Results of Question 4a

Appendix

Q1:

```
def histvec(img, mask, b):
       , , ,
      Function to find the color histogram of the image.
3
4
      Args:
5
       ____
6
      img: input image
      mask: Super pixel mask. Each pixel location will have the
          superpixel label corresponding to it
      b: number of bins in the histogram
      Return:
10
       -----
11
      hist_vector: 1-D vector having the histogram of all three
12
          channels appended
       , , ,
14
       img_in_SP = img[mask,:].astype(dtype=np.int64)
15
       total_location = img_in_SP.shape[0]
16
17
      hist\_vector = np.zeros(3*b)
18
      ub\_unit = 256.0/b
19
       '''loop through all bins'''
21
      for i in range(b):
22
           ub_cur = ((i+1)*ub_unit)
23
           '''loop through rgb channels'''
24
           for j in range(3):
25
               cur_idx = np.argwhere(img_in_SP[:,j]<=ub_cur)</pre>
26
               hist_vector[j*b+i]+=len(cur_idx)
27
               img_in_SP[cur_idx,j] = 300
       '', Normalize Histogram'',
30
      hist_vector=hist_vector/total_location
31
      return hist_vector
32
```

Q2:

```
def seg_neighbor(svMap):
      , , ,
      Function to find adjacency matrix
3
4
      ----
5
      svMap: Super pixel mask. Each pixel location will have the
6
          superpixel label corresponding to it.
      Return:
      _____
      Bmap: a binary adjacency matrix NxN (N being the number of
10
          superpixels in svMap).
      , , ,
11
      segmentList = np.unique(svMap)
12
      segmentNum = segmentList.shape[0]
13
      # FILL IN THE CODE HERE to calculate the adjacency
14
      Bmap = np.zeros([segmentNum, segmentNum])
15
      height, width = svMap.shape
16
      for i in range(height):
17
           for j in range(width):
18
               '', check eight connectivity'',
19
               y_u = min(i+1, height-1)
20
               x_u = min(j+1, width-1)
21
               x_1 = max(j-1, 0)
22
               ''' check lower'''
               if svMap[i,j] != svMap[y_u,j]:
24
                   Bmap[svMap[i,j],svMap[y_u,j]] = 1
25
                   Bmap[svMap[y_u,j],svMap[i,j]] = 1
26
               ''' check left'''
27
               if svMap[i,j] != svMap[i,x_u]:
28
                   Bmap[svMap[i,j],svMap[i,x_u]] = 1
                   Bmap[svMap[i,x_u],svMap[i,j]] = 1
30
               ''' check lower left'''
31
               if svMap[i,j] != svMap[y_u,x_u]:
32
                   Bmap[svMap[i,j],svMap[y_u,x_u]] = 1
33
                   Bmap[svMap[y_u,x_u],svMap[i,j]] = 1
34
               ''' check lower right'''
35
               if svMap[i,j] != svMap[y_u,x_l]:
36
                   Bmap[svMap[i,j],svMap[y_u,x_l]] = 1
37
                   Bmap[svMap[y_u,x_l],svMap[i,j]] = 1
38
      return Bmap
39
```

Q3: