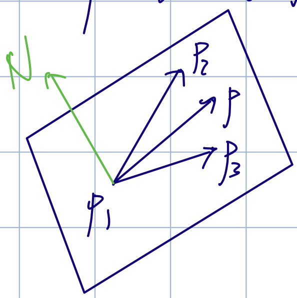
Lecture 3 plane

3 points to form a plane



(1) $\det(\overrightarrow{P_1P_2}, \overrightarrow{P_1P_3}, \overrightarrow{P_1P}) = 0$ $\quad \det(\vec{a}, \vec{b}, \vec{c}) = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$

(2) $N = \overrightarrow{P_1P_3} \times \overrightarrow{P_1P_2}$ 解 $\overrightarrow{P_1P} \cdot \vec{N} = 0$

$Ax + By + Cz = D$ $\quad (A, B, C)$ 即为 normal vector $\vec{N}$

若 $Ax=b$ 中 $\det(A)=0$，则 $\vec{N_1}, \vec{N_2}, \vec{N_3}$ are coplanar

找出一个特解 x_p

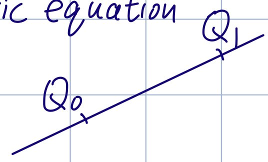
$x = x_p + c\vec{n}$

Lecture 5 Equation of line

1. intersection of 2 planes

2. trajectory of a moving point parametric equation

ex. line through $Q_0=(-1,2,2)$ $Q_1=(1,3,-1)$



l: $\overrightarrow{Q_0Q(t)} = t\,\overrightarrow{Q_0Q_1} = t\,\langle 2,1,-3\rangle$

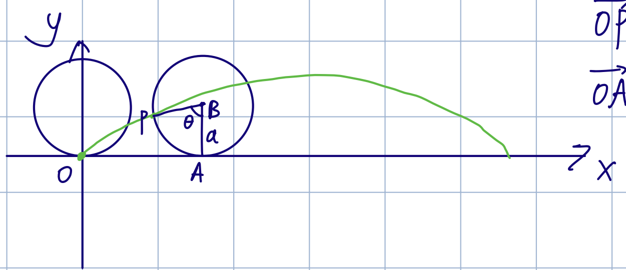
$$\begin{cases} x(t) = -1+2t \\ y(t) = 2+t \\ z(t) = 2-3t \end{cases} \qquad Q(t) = Q_0 + t\,\overrightarrow{Q_0Q_1}$$

Application:

Intersection with plane? ex. $x+2y+4z=7$ line through $(-1,2,2),(1,3,-1)$

the plane divide the space into 2 part: $x+2y+4z>7$ and $x+2y+4z<7$ opposite side

$x(t)+2y(t)+4z(t) = -8t+11 = 7$ $t=\frac{1}{2}$ intersection point: $(0,\frac{5}{2},\frac{1}{2})$



$\overrightarrow{OP} = \overrightarrow{OA} + \overrightarrow{AB} + \overrightarrow{BP}$

$\overrightarrow{OA} = \langle a\theta, 0\rangle$ $\overrightarrow{AB} = \langle 0, a\rangle$ $\overrightarrow{BP} = \langle -a\sin\theta, -a\cos\theta\rangle$

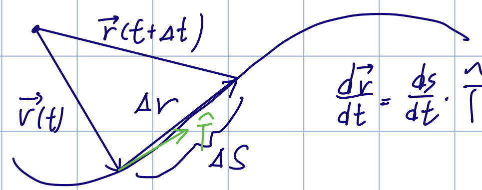
$\overrightarrow{OP} = \langle \underbrace{a\theta - a\sin\theta}_{=x(\theta)}, \underbrace{a - a\cos\theta}_{=y(\theta)}\rangle$

velocity ex $\vec{r}(t) = \langle t-\sin t, 1-\cos t\rangle$

$\vec{v} = d\vec{r}/dt = \langle \frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt}\rangle = \langle 1-\cos t, \sin t\rangle$ speed $= |\vec{v}|$

unit tangent vector $\hat{T} = \frac{\vec{v}}{|\vec{v}|}$

$\vec{v} = \frac{d\vec{r}}{dt} = \frac{d\vec{r}}{ds}\cdot\frac{ds}{dt} = |\vec{v}|$, $\therefore \frac{d\vec{r}}{ds} = \hat{T}$



$\frac{d\vec{r}}{dt} = \frac{ds}{dt}\cdot\hat{T}$

Velocity has $\begin{cases} \text{direction, tangent to traj}, \hat{T} \\ \text{length: speed}, \frac{ds}{dt} \end{cases}$

Lecture 6 Partial derivative

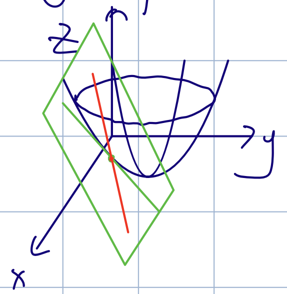
$f = f(x,y)$ $\quad \left.\frac{\partial f}{\partial x}\right|_{x_0,y_0} = \lim_{\Delta x \to 0} \frac{f(x_0+\Delta x, y_0) - f(x_0, y_0)}{\Delta x}$

$\frac{\partial f}{\partial x} = \lim_{\Delta x \to 0} \frac{f(x+\Delta x, y) - f(x)}{\Delta x} = f_x \quad \frac{\partial f}{\partial y} = \lim_{\Delta y \to 0} \frac{f(x, y+\Delta y) - f(x,y)}{\Delta y} = f_y$

Approximation:

If we change $x \to x+\Delta x$, $y \to y+\Delta y$, $z = f(x,y)$ then $\Delta z \approx f_x \Delta x + f_y \Delta y$

Tangent plane



$L_1 = \begin{cases} z = z_0 + a(x-x_0) \\ y = y_0 \end{cases} \quad \frac{\partial f}{\partial x}(x_0,y_0) = a$

$L_2 = \begin{cases} z = z_0 + b(y-y_0) \\ x = x_0 \end{cases} \quad \frac{\partial f}{\partial y}(x_0,y_0) = b$

plane: $z = z_0 + a(x-x_0) + b(y-y_0)$

Application. Optimization problems

At a local min or max: $\frac{\partial f}{\partial x}(x_0,y_0) = \frac{\partial f}{\partial y}(x_0,y_0) = 0$ tangent plane is horizental

Def: (x_0,y_0) is a critical point if $f_x(x_0,y_0) = 0$ and $f_y(x_0,y_0) = 0$

ex: $f(x,y) = x^2 - 2xy + 3y^2 + 2x - 2y$

$\begin{cases} f_x = 2x - 2y + 2 = 0 \\ f_y = -2x + 6y - 2 = 0 \end{cases} \Leftrightarrow \begin{cases} x = -1 \\ y = 0 \end{cases}$ critical point $(x,y) = (-1,0)$

Lecture 8 second derivative

critical point $\begin{cases} \text{local max} \\ \text{local min} \\ \text{saddle} \end{cases}$ global max/min: either critical point or boundary

ex. $w = ax^2+bxy+cy^2$

$w = \frac{1}{4a}\left[4a^2\left(x+\frac{b}{2a}y\right)^2+(4ac-b^2)y^2\right]$

3 cases: (1) $4ac-b^2<0 \Rightarrow$ saddle point

(2) $4ac-b^2=0$ $\quad w=x^2$

(3) $4ac-b^2>0$ $\quad$ if $a>0$, minimum; if $a<0$, maximum

In general: look at second derivative

$\frac{\partial^2 f}{\partial x^2} = f_{xx} \quad f_{xy} = \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x} = f_{yx} \quad \frac{\partial^2 f}{\partial y^2} = f_{yy}$

second derivative test

At a critical point (x_0,y_0) at f

let $A = f_{xx}(x_0,y_0)$, $B = f_{xy}(x_0,y_0)$ $\quad C = f_{yy}(x_0,y_0)$

If $AC-B^2>0$ and $A>0$, $f(x_0,y_0)$ is a local minimum

If $AC-B^2>0$ and $A<0$, local maximum

If $AC-B^2<0$ saddle

If $AC-B^2=0$ can't conclude

proof: quadraic approximation

$\Delta f = \underbrace{f_x}_{=0}\cdot(x-x_0)+\underbrace{f_y}_{=0}(y-y_0)+\frac{1}{2}f_{xx}(x-x_0)^2+f_{xy}(x-x_0)(y-y_0)+\frac{1}{2}f_{yy}(y-y_0)^2$

$= \frac{1}{2}f_{xx}(x_0,y_0)(x-x_0)^2+f_{xy}(x_0,y_0)(x-x_0)(y-y_0)+f_{yy}(x_0,y_0)(y-y_0)^2$

In degenerate case, depends on higher derivative

Lecture 9 Least Square

$y = \hat{a}x + \hat{b}$

deviation for each point: $y_i - (ax_i + b)$

Minimise $D(a,b) = \sum_{i=1}^{n} [y_i - (ax_i + b)]^2 = \sum_{i=1}^{n} [y_i^2 + (ax_i + b)^2 - 2y_i(ax_i + b)]$

$$\frac{\partial D}{\partial a} = \sum_{i=1}^{n} \left[2(ax_i + b)\cdot x_i - 2x_i y_i\right] = 0 \Leftrightarrow a\sum x_i^2 + b\sum x_i = \sum x_i y_i$$

$$\frac{\partial D}{\partial b} = \sum_{i=1}^{n} \left[2(ax_i + b) - 2y_i\right] = 0 \Leftrightarrow a\sum x_i + nb = \sum y_i$$

solve for (a,b)

$$\begin{cases} \hat{a} = \dfrac{n\sum x_i y_i - \sum x_i \sum y_i}{n\sum x_i^2 - (\sum x_i)^2} \\ \hat{b} = \dfrac{\sum y_i \sum x_i^2 - \sum x_i \sum x_i y_i}{n\sum x_i^2 - (\sum x_i)^2} = \dfrac{\sum y_i - a\sum x_i}{n} \end{cases}$$

Lecture 11 Differential

Total differential

$f(x,y,z)$ $df = f_x dx + f_y dy + f_z dz = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz$

Important: df is NOT Δf

can do ① encode how change on x, y, z affect f

② placeholder for small variation $\Delta x, \Delta y, \Delta z$

to get approximation formula $\Delta f \approx f_x \Delta x + f_y \Delta y + f_z \Delta z$

③ divide by something like dt to get a rate of change when $x(t), y(t), z(t)$

$$\frac{df}{dt} = f_x \frac{dx}{dt} + f_y \frac{dy}{dt} + f_z \frac{dz}{dt}$$

ex, $w = x^2 y + z$, $x = t$, $y = e^t$ $z = \sin t$

$$\frac{dw}{dt} = 2xy \cdot \frac{dx}{dt} + x^2 \cdot \frac{dy}{dt} + 1 \cdot \frac{dz}{dt}$$

$$= 2te^t + t^2 e^t + \cos t = (t^2 + 2t)e^t + \cos t$$

Prove chain rule with more variables

$w = f(x,y)$ $x = x(u,v)$ $y = y(u,v)$

$w = f(x(u,v), y(u,v))$, what about $\frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}$

$$dw = f_x dx + f_y dy = f_x (x_u du + x_v dv) + f_y (y_u du + y_v \cdot dv)$$

$$= \underbrace{(f_x x_u + f_y y_u)}_{\text{has to be } \frac{\partial w}{\partial u}} du + \underbrace{(f_x x_v + f_y y_v)}_{\text{has to be } \frac{\partial w}{\partial v}} dv$$

$$\frac{\partial f}{\partial u} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial u} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial u}$$

$$\frac{\partial f}{\partial v} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial u} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial u}$$

Lecture 12 Gradient

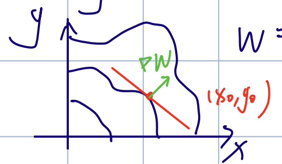
$w = f(x, y, z)$

$\nabla w = \langle w_x, w_y, w_z \rangle$ gradient of w at some point (x, y, z)

$\frac{d\vec{r}}{dt} = \langle \frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \rangle$

$\frac{dw}{dt} = \nabla w \cdot \frac{d\vec{r}}{dt}$

Theory: $\nabla w \perp$ level surface $\{w = \text{constant}\}$



$w = f(x, y)$

沿 ∇w 方向函数值变化最快

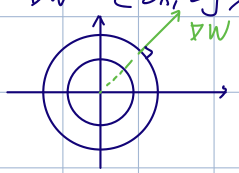
ex1. $w = a_1 x + a_2 y + a_3 z$

$\nabla w = \langle a_1, a_2, a_3 \rangle$

level surface: $a_1 x + a_2 y + a_3 z = c$ plane with normal vector ∇w

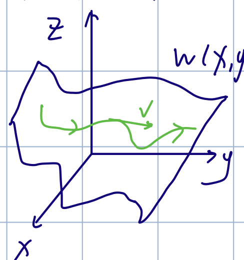
ex2. $w = x^2 + y^2$ level curve $w = c$ is a circle $x^2 + y^2 = c$

$\nabla w = \langle 2x, 2y \rangle$



∇w always points at higher value of a function

Proof: Take a curve $\vec{r} = \vec{r}(t)$ that stays on the level $w = c$



$w(x, y, z) = c$ Take a motion on the surface $w(x, y, z) = c$

$v = \frac{d\vec{r}}{dt}$ is tangent to the plane $w(x, y, z) = c$

By chain rule: $\frac{dw}{dt} = \nabla w \cdot \frac{d\vec{r}}{dt} = \nabla w \cdot \vec{v} = 0$ because $w(t) = c = \text{constant}$

So $\nabla w \perp \vec{v}$, This is true for any motion on $w = c$

$\vec{v}$ can be any vector tangent to the surface

so ∇w is prependicular to the tangent plance to the level

Application: find the tangent plane to surface $x^2+y^2-z^2=4$ at $(2,1,1)$?

Level set $w=4$ when $w=x^2+y^2-z^2$

gradient $\nabla w = \langle 2x, 2y, -2z\rangle = \langle 4,2,-2\rangle$, which is the normal vector to the plane $4(x-2)+2(y-1)-2(z-1)=0 \iff 4x+2y-2z=8$

Another way: $dw = 2x\,dx + 2y\,dy - 2z\,dz = 4\,dx + 2\,dy - 2\,dz$ at $(2,1,1)$

$\Delta w \approx 4\Delta x + 2\Delta y - 2\Delta z$

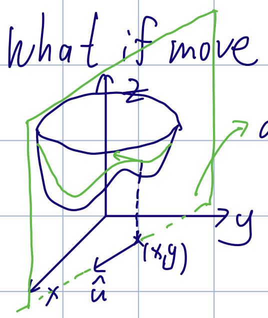
when $\Delta w = 0$ its tangent plane: $4\Delta x + 2\Delta y - 2\Delta z = 0$

$4(x-2)+2(y-1)-2(z-1)=0$

Directional derivatives

$w = w(x,y) \rightsquigarrow$ know $\frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}$

What if move in direction of $\hat{u}$ = unit vector



$\rightarrow$ a straight line trajectory $\vec{r}(s)$, $\frac{d\vec{r}}{ds} = \hat{u}$

$\frac{dw}{ds} = \nabla w \cdot \frac{d\vec{r}}{ds} = \nabla w \cdot \hat{u}$

Def: If $\hat{u} = \langle a,b\rangle$ (unit vector)

$$\begin{cases} x(s) = x_0 + a s \\ y(s) = y_0 + b s \end{cases}$$

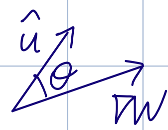
$\boxed{\left.\frac{dw}{ds}\right|_{\hat{u}}} = \nabla w \cdot \hat{u}$ components of ∇w in direction of $\hat{u}$

Directional derivative

Geometric view: slice the graph by the plane of the unit vector, slope $= \left.\frac{dw}{ds}\right|_{\hat{u}}$

$$\left.\frac{dw}{ds}\right|_{\hat{u}} = \nabla w \cdot \hat{u} = |\nabla w| \cdot \underbrace{|\hat{u}|}_{=1} \cdot \cos\theta$$

$$= |\nabla w| \cdot \cos\theta$$



$\Rightarrow$ be maximal when $\cos\theta = 1 \Rightarrow \hat{u} = \text{dir}(\nabla w)$

Conclusion: $\nabla w =$ dir of fatest increase of w

$|\nabla w| = \left.\frac{dw}{ds}\right|_{\hat{u} = \text{dir}(\nabla w)}$

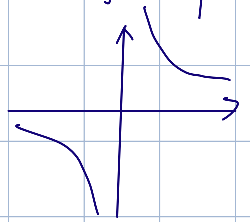
minimal when $\cos\theta = -1$ $\quad \hat{u} = \text{dir}(\nabla w)$

when $\left.\frac{dw}{ds}\right|_{\hat{u}} = 0$ $\quad \cos\theta = 0$ $\quad \theta = 90^\circ$ $\quad \hat{u} \perp \nabla w \Leftrightarrow \hat{u}$ tangent to level

Lecture 13 Lagrange multipliers

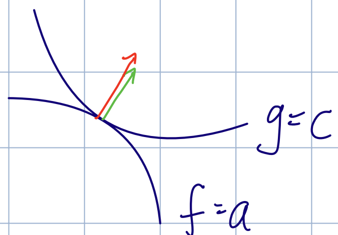
min/max a function $f(x,y,z)$ where x,y,z are not independent, $g(x,y,z)=c$

ex: find point cloest to origin on $xy=3$



Minimize $f(x,y)=x^2+y^2$ subject to constraint $\overset{g(x,y)}{xy}=3$

Observe: at minimum, level curve of f is tangent to $g=3$



When $f(x,y)$'s level curve is tangent to $g(x,y)$'s level curve, normal vectors parallel

$\nabla f \parallel \nabla g$ so $\nabla f = \lambda \nabla g$

$$\Rightarrow \begin{cases} f_x = \lambda g_x \\ f_y = \lambda g_y \\ xy = 3 \end{cases}$$

f_x, f_y equations: from $\nabla f = \lambda \nabla g$

$xy=3$: from the constraint

Why is this method valid?

At constraint min/max, in any direction along $g=c$, the rate of change of f must be 0

For any $\hat{u}$ tangent to $g=c$, we must have $\frac{df}{ds}\big|_{\hat{u}}=0$

$\nabla f \cdot \hat{u} = 0$, so any such $\hat{u}$ is $\perp \nabla f$, so $\nabla f \perp$ level set of g

Know $\nabla g \perp$ level set of g, so $\nabla f \parallel \nabla g$

WARNING: method don't tell whether it's maximum or minimum (or a saddle)

CAN'T use second derivative test

Lecture 14 Non-independent variables

$f(x,y,z)$ where $g(x,y,z)=c$

then $z=z(x,y)$ $\frac{\partial z}{\partial x}$? $\frac{\partial z}{\partial y}$?

ex $x^2+yz+z^3=8$ at $(2,3,1)$

Take differential: $2x\,dx+z\,dy+(y+3z^2)dz=0$

at $(2,3,1)$ $4dx+dy+6dz=0$

If we view $z=z(x,y)$ $dz=-\frac{1}{6}(4dx+dy)$

$\frac{\partial z}{\partial x}=-\frac{2}{3}/1=-\frac{2}{3}$ $\quad$ $\frac{\partial z}{\partial y}=-\frac{1}{6}/1=-\frac{1}{6}$

(y constant $dy=0$) $\quad$ (x constant $dx=0$)

In general:

$g(x,y,z)=c$ then $dg=g_x\,dx+g_y\,dy+g_z\,dz=0$

Solve for dz: $dz=-\frac{g_x}{g_z}dx-\frac{g_y}{g_z}dy$

so for $\frac{\partial z}{\partial x}$, set $dy=0$ $dz=-\frac{g_x}{g_z}dx$ $\quad$ $\frac{\partial z}{\partial x}=\frac{-g_x}{g_z}$

ex. $f(x,y)=x+y$ $\quad$ $\frac{\partial f}{\partial x}=1$

$x=u$ $y=u+v$, then $f=2u+v$ $\quad$ $\frac{\partial f}{\partial u}=2$

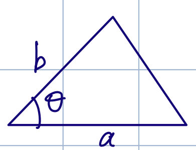
$x=u$, but $\frac{\partial f}{\partial x}\neq\frac{\partial f}{\partial u}$, because $\frac{\partial f}{\partial x}$ means keeping y constant, $\frac{\partial f}{\partial u}$ means keeping v constant

Need clearer Notations

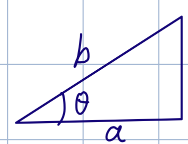
$\left(\frac{\partial f}{\partial x}\right)_y$ = keep y constant $\qquad$ so $\underbrace{\left(\frac{\partial f}{\partial x}\right)_y}_{1}\neq\underbrace{\left(\frac{\partial f}{\partial x}\right)_v}_{2}=\underbrace{\left(\frac{\partial f}{\partial u}\right)_v}_{2}$

$\left(\frac{\partial f}{\partial u}\right)_v$ = keep v constant

ex. area of a triangle



$A=\frac{1}{2}ab\sin\theta$ $\qquad$ Assume it's a right triangle



$a=b\cos\theta$ constraint

Rate of A respect to θ

(1) treat a,b,θ as independent $\frac{\partial A}{\partial\theta}=\left(\frac{\partial A}{\partial\theta}\right)_{a,b}=\frac{1}{2}ab\cos\theta$ $\quad$ loss the constraint

(2) keep a constant $b=b(a,\theta)$ $\left(=\frac{a}{\cos\theta}\right)$ to keep right angle $\left(\frac{\partial A}{\partial\theta}\right)_a$

(3) keep b constant, $a=a(b,\theta)$ $\quad$ $\left(\frac{\partial A}{\partial\theta}\right)_b$

Compute $\left(\frac{\partial A}{\partial \theta}\right)_a$

Method 0: solve for b then substitute

$$= \frac{\partial}{\partial \theta}\left(\frac{1}{2} a \cdot \frac{a}{\cos\theta} \cdot \sin\theta\right) = \frac{1}{2} a^2 \sec^2\theta$$

2 systematic methods

Method 1: differentials

keep a fixed: $da = 0$

constraint $a = b\cos\theta$ $\quad da = \cos\theta\, db - b\sin\theta\, d\theta = 0$

$db = b\tan\theta\, d\theta$ (To find when θ change, how b change)

function $A = \frac{1}{2} ab\sin\theta$

$$dA = \frac{1}{2} b\sin\theta \underbrace{da}_{=0} + \frac{1}{2} a\sin\theta \underbrace{db}_{\text{substitute}} + \frac{1}{2} ab\cos\theta\, d\theta$$

$\sin\theta\tan\theta + \cos\theta = \sec\theta$

$$= \frac{1}{2} a\sin\theta \cdot b\tan\theta\, d\theta + \frac{1}{2} ab\cos\theta\, d\theta = \left(\frac{1}{2} ab\sin\theta\tan\theta + \frac{1}{2} ab\cos\theta\right) d\theta = \frac{1}{2} ab\sec\theta\, d\theta$$

so $\left(\frac{\partial A}{\partial \theta}\right)_a = \frac{1}{2} ab\sec\theta$

Summary: (1) write dA in terms of $da, db, d\theta$

(2) set $da = 0$

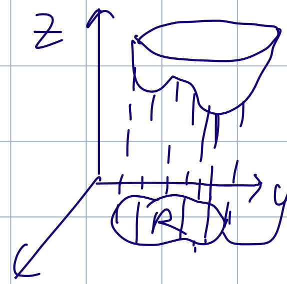
(3) differentiate constraint $\Rightarrow$ solve for db in terms of $d\theta$

plug in

Method 2: Chain Rule $\left(\frac{\partial}{\partial \theta}\right)_a$ in formula for A

$$\left(\frac{\partial A}{\partial \theta}\right)_a = A_\theta \underbrace{\left(\frac{\partial \theta}{\partial \theta}\right)_a}_{1} + A_a \underbrace{\left(\frac{\partial a}{\partial \theta}\right)_a}_{0} + A_b \underbrace{\left(\frac{\partial b}{\partial \theta}\right)_a}_{\text{use constraint}}$$

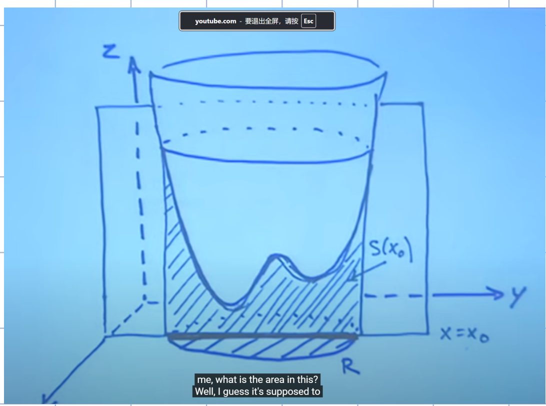
Lecture 15 Double integral



one-variable Integral: area of graph

Double integral: volumn below the graph

over a region R is xy plane $\iint_R f(x,y)\,dA$



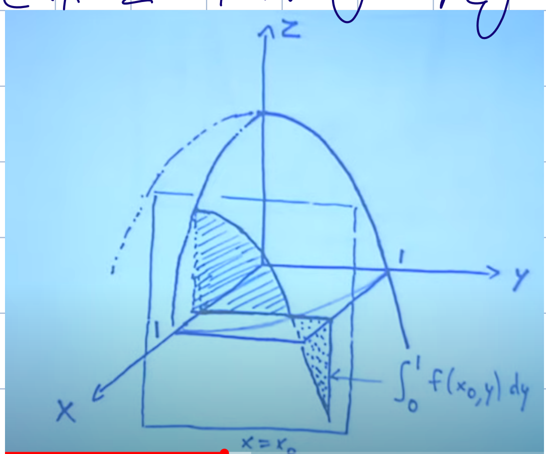
move a plane from one axis, take slices

add all the $A\cdot dx$ $\quad V=\int_{x_{min}}^{x_{max}} S(x)\,dx$

For given x, $S(x)=\int_{y_{min}(x)}^{y_{max}(x)} f(x,y)\,dy$

$$\iint_R f(x,y)\,dA=\int_{x_{min}}^{x_{max}}\left[\int_{y_{min}(x)}^{y_{max}(x)} f(x,y)\,dy\right]dx$$

ex1. $z=1-x^2-y^2$ region $0\le x\le 1$ $\quad 0\le y\le 1$



$$\int_0^1\int_0^1 (1-x^2-y^2)\,dy\,dx$$
$$=\int_0^1 \left[(1-x^2)y-\frac{1}{3}y^3\right]_0^1 dx$$
$$=\int_0^1\left(\frac{2}{3}-x^2\right)dx$$
$$=\left(\frac{2}{3}x-\frac{1}{3}x^3\right)\Big|_0^1$$
$$=\frac{1}{3}$$

$dA=dy\,dx$

ex2: Integral in such R

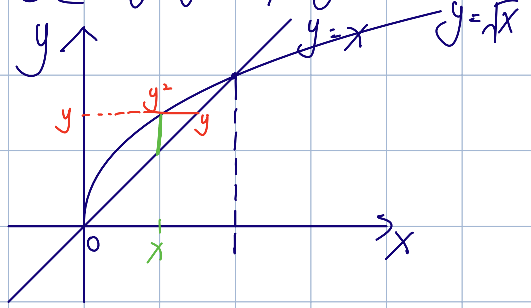
$$\int_0^1\int_0^{\sqrt{1-x^2}}(1-x^2-y^2)\,dy\,dx=\int_0^1\left[(1-x^2)\sqrt{1-x^2}-\frac{1}{3}(1-x^2)\sqrt{1-x^2}\right]dx$$
$$=\int_0^1\frac{2}{3}(1-x^2)^{\frac{3}{2}}dx=\frac{2}{3}\int_0^{\pi/2}\cos^4\theta\,d\theta$$
$$=\frac{2}{3}\cdot\frac{3}{16}\pi=\frac{1}{8}\pi$$

Easier in Polar coordinates

Exchanging order

ex1. $\int_0^1\int_0^2 dx\,dy = \int_0^2\int_0^1 dy\,dx$

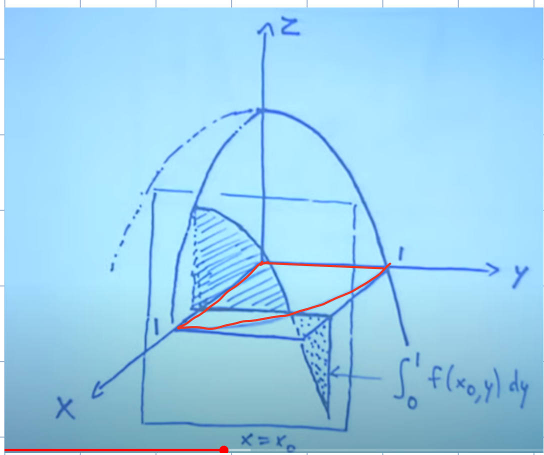
ex2. $\int_0^1\int_x^{\sqrt{x}} \frac{e^y}{y}\,dy\,dx$



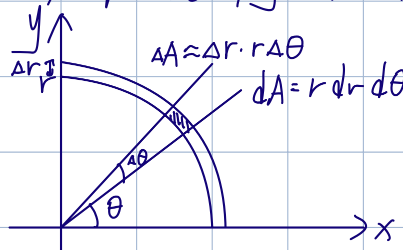
$$\int_0^1\int_x^{\sqrt{x}} \frac{e^y}{y}\,dy\,dx$$
$$= \int_0^1\int_{y^2}^{y} \frac{e^y}{y}\,dx\,dy = \int_0^1 (1-y)e^y\,dy$$
$$= \left[(2-y)e^y\right]_0^1$$
$$= e-2$$

$$\bar{x} = \frac{1}{Mass}\iint x f(\theta, r)\,dy\,dx$$
$$\bar{y} = \frac{1}{Mass}\iint y f(\theta, r)\,dy\,dx$$

Lecture 17 Polar Coordinates



$x = r\cos\theta\ ,\ y = r\sin\theta$

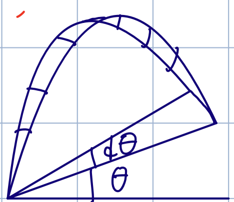


$$\frac{1}{2}\Delta\theta\left((r+\Delta r)^2 - r^2\right) = \Delta\theta\, r\, dr$$

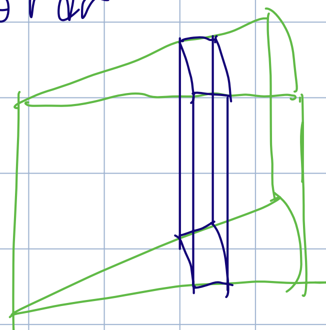
$$\int_0^{\frac{\pi}{2}}\int_0^1 f(\theta,r)\, r\,dr\,d\theta = \int_0^{\pi/2}\int_0^1 (1-r^2)\, r\,dr\,d\theta = \int_0^{\pi/2}\left(\frac{1}{2}r - \frac{1}{4}r^4\right)\Big|_0^1 d\theta = \int_0^{\pi/2}\frac{1}{4}\,d\theta = \frac{\pi}{8}$$

???

?



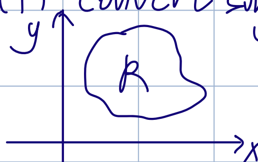
$$\underbrace{\underbrace{\iint f(\theta,r)\,dr}_{\text{面积}A}\cdot r\,d\theta\cdot\frac{1}{2}}_{\text{体积}dV}$$



$$\iint \underbrace{\underbrace{f(\theta,r)\,dr}_{S}\ \frac{1}{2}r\,d\theta}_{dV}$$

Application

(1) convert single integral to double integral

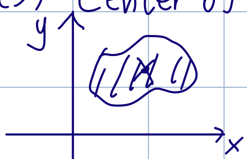


$\text{Area} = \iint 1\cdot dA$

(2) Average value of f = $\bar{f} = \frac{1}{\text{Area}(R)}\iint_R f\,dA$

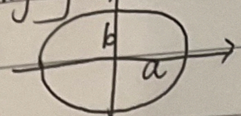
weighted average of f with density δ : $\bar{f} = \frac{1}{\text{Mass}(R)}\iint_R f\delta\,dA$

(3) Center of mass of a (planar) object (with density δ)



$(\bar{x},\bar{y})$ $\quad \bar{x} = \frac{1}{\text{Mass}}\iint x\delta\,dA,\ \bar{y} = \frac{1}{\text{Mass}}\iint y\delta\,dA$

changing variables in $\iint$

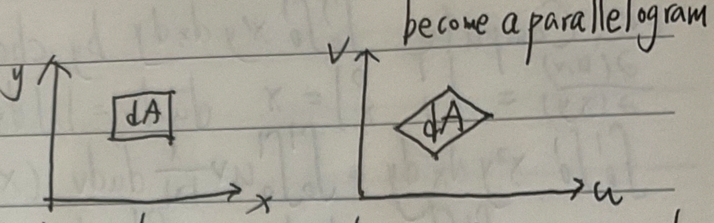
ex1.  $\left(\frac{x}{a}\right)^2+\left(\frac{y}{b}\right)^2=1$

$$\iint_{\left(\frac{x}{a}\right)^2+\left(\frac{y}{b}\right)^2\le 1} dx\,dy = ab\iint_{u^2+v^2\le 1} du\,dv = \pi ab$$

set $\frac{x}{a}=u$ $\frac{y}{b}=v$

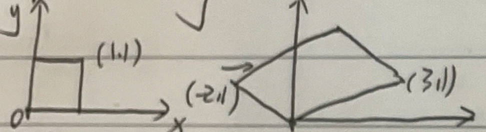
In general: finding scaling factor between $dx\,dy \leftrightarrow du\,dv$

$$\begin{cases} u=3x-2y \\ v=x+y \end{cases}$$



$dA=dx\,dy$ and $dA'=dv\,du$

The scaling factor here doesn't depend ~~cho~~ on cohce of rectangle



$A'=\left|\begin{matrix}3 & 1\\ -2 & 1\end{matrix}\right|=5$

so $dA'=5dA$ $du\,dv=5dx\,dy$

$\iint f(x,y)\,dx\,dy=\iint g(u,v)\frac{1}{5}du\,dv$, bound also needs change

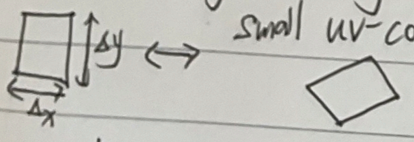
↑ Only for linear transformation

General case: $u=u(x,y)$ $v=v(x,y)$

$\Delta u \approx \cancel{du} \; u_x\cdot\Delta x+u_y\cdot\Delta y$

$\Delta v \approx \quad v_x\cdot\Delta x+v_y\cdot\Delta y$

Small rectangle in x-y coordinates



$A'=\left|\begin{matrix}u_x & v_x\\ u_y & v_y\end{matrix}\right|$

can be seen as linear transformation, which changing scaler depends on u_x, u_y, v_x, v_y (x_0,y_0)

$dA'=\left|\begin{matrix}u_x & v_x\\ u_y & v_y\end{matrix}\right|dA$ or $dA'=\left|\begin{matrix}u_x & u_y\\ v_x & v_y\end{matrix}\right|dA$

Jacobian : $J = \frac{\partial(u,v)}{\partial(x,y)} = \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix}$

$du\,dv = |J|\,dx\,dy = \left\| \begin{matrix} u_x & u_y \\ v_x & v_y \end{matrix} \right\| dx\,dy$

ex1. Polar coordinate

$x = r\cos\theta \quad y = r\sin\theta$

$\frac{\partial(x,y)}{\cancel{\partial(u,v)}\,\partial(r,\theta)} = \begin{vmatrix} x_r & x_\theta \\ y_r & y_\theta \end{vmatrix} = \begin{vmatrix} \cos\theta & -r\sin\theta \\ \sin\theta & r\cos\theta \end{vmatrix} = r$

$dx\,dy = |r|\,dr\,d\theta = r\,dr\,d\theta$

ex2. Compute $\int_0^1\int_0^1 x^2y\,dx\,dy$ by changing to $u = x \quad v = xy$

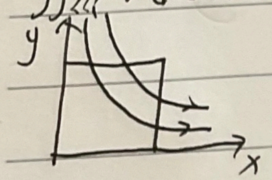
$\frac{\partial(u,v)}{\partial(x,y)} = \begin{vmatrix} 1 & 0 \\ y & x \end{vmatrix} = x \quad du\,dv = |x|\,dx\,dy = x\,dx\,dy$

$\int_0^1\int_0^1 x^2y\,dx\,dy = \int_0^1\int_0^1 uv\frac{1}{|x|}\,du\,dv \quad (\times)$

$= \int_0^1\int_0^1 v\,du\,dv = \int_0^1 v\,dv = \frac{1}{2} \quad (\times)$

For bounds

$\iint_{???} v\,du\,dv$ or $dv\,du$?



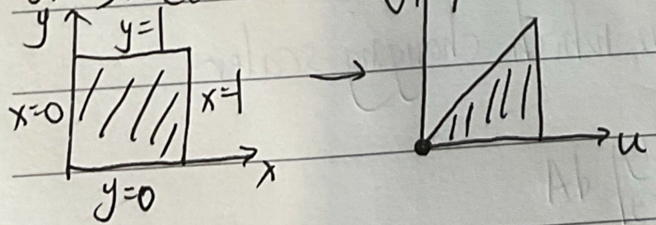
$\iint \underbrace{v\,du}_{\substack{u \text{ change}, V \text{ constant} \\ xy = C}}\,dv$

when V is constant, find scope of u

$y=1 \quad V = x, \; u = v \quad \int_v^1 v\,du$

$= \int_0^1\int_v^1 v\,du\,dv$

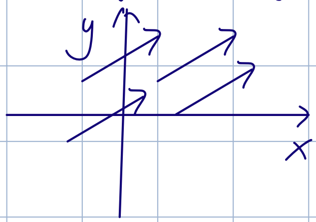
or switch to u-v picture

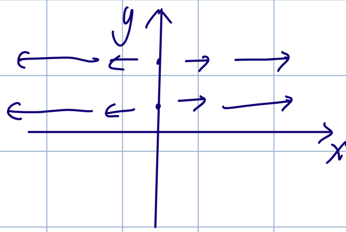


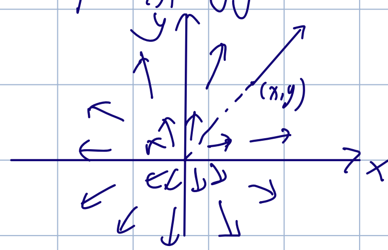
Lecture 19 Vector fields

$\vec{F} = M\vec{i} + N\vec{j}$, M, N are functions of x, y

ex: $\vec{F} = 2\vec{i} + \vec{j}$ $\quad\quad$ $\vec{F} = x\vec{i}$ $\quad\quad$ $\vec{F} = x\vec{i} + y\vec{j}$

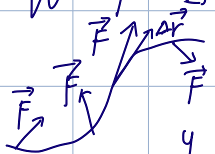






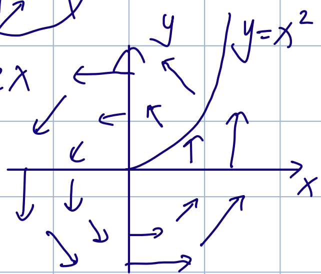
line integra

$W = \vec{F} \cdot \Delta\vec{r}$ $\quad$ Along a trajectory C $\quad$ $\vec{F} = M\hat{i} + N\hat{j}$



$$W = \int_C \vec{F} \cdot d\vec{r} = \int_{t_1}^{t_2} \vec{F} \cdot \frac{d\vec{r}}{dt} \cdot dt = \int_C M dx + N dy$$

ex



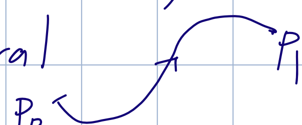
$\vec{F} = -y\vec{i} + x\hat{j}$

C: $x = t$
$\quad y = t^2$ $\quad (0 \le t \le 1)$

$$\int_C \vec{F} \cdot d\vec{r} = \int_0^1 (-y, x) \cdot (1, 2t)\, dt$$
$$= \int_0^1 (-t^2, t) \cdot (1, 2t)\, dt$$
$$= \int_0^1 t^2 dt = \frac{1}{3}$$

Special case, when $\vec{F}$ is gradient of a function $f(x,y)$

Fundamental theorem of Calculus for line integral



$$\int_C \nabla f \cdot d\vec{r} = f(P_1) - f(P_0)$$

proof: $\int_C \nabla f \cdot d\vec{r} = \int_C f_x dx + f_y dy = \int_C df = f(P_1) - f(P_0)$

proof: $\int_C \nabla f \cdot d\vec{r} = \int_C f_x dx + f_y dy$ $\quad$ C: $x = x(t)$ $\; y = y(t)$

$$= \int_C \left(f_x \frac{dx}{dt} + f_y \cdot \frac{dy}{dt}\right) dt = \int_{t_0}^{t_1} \frac{df}{dt}\, dt = f(x(t), y(t)) \Big|_{t_0}^{t_1} = f(P_1) - f(P_0)$$

Only works if $\vec{F}$ is a gradient field

(1) Path-independence $\quad \int_{C_1} \nabla f\, d\vec{r} = \int_{C_2} \nabla f\, d\vec{r}$ if C_1 and C_2 have same start/end points

$\Leftrightarrow$ (2) $\vec{F}$ is a gradient field

$\Leftrightarrow$ (3) $M dx + N dy$ is an exact differential (can be expressed in df)

Lecture 21 Exact differential

if $\vec{F} = \nabla f$, $M = f_x$ $N = f_y$, then $f_{xy} = f_{yx} \Rightarrow M_y = N_x$

Then: if $\vec{F} = \langle M, N \rangle$ defined, differentiable everywhere
and $M_y = N_x$, then $\vec{F}$ is a gradient field

ex. $\vec{F} = -y\hat{i} + x\hat{j}$

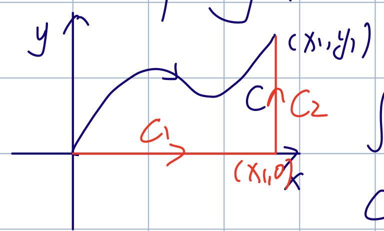
$\frac{\partial M}{\partial y} = -1$ $\frac{\partial N}{\partial x} = 1$ are not the same, not a gradient field

ex. $\vec{F} = (4x^2 + axy)\hat{i} + (3y^2 + 4x^2)\hat{j}$

$\frac{\partial M}{\partial y} = ax = \frac{\partial N}{\partial x} = 8x$ $a = 8$

Then, how do we find the potential (only if $M_y = N_x$)

(1) Computing line integral



$\int_C \vec{F} d\vec{r} = f(x_1, y_1) - \underbrace{f(0,0)}$ choose a constant

$\int_C \vec{F} d\vec{r} = (4x^2 + 8xy)dx + (3y^2 + 4x^2)dy$

C_1: $y = 0$ $dy = 0$ $\int_{C_1} \vec{F} d\vec{r} = \int_0^{x_1} 4x^2 dx = \frac{4}{3}x_1^3$

C_2: $y: 0 \to y_1$ $x = x_1$ $dx = 0$ $\int_{C_2} \vec{F} d\vec{r} = \int_0^{y_1} (3y^2 + 4x_1^2)dy = y_1^3 + 4x_1^2 y$

$f(x_1, y_1) = \frac{4}{3}x_1^3 + y_1^3 + 4x_1^2 y_1 + C$ $f(x,y) = \frac{4}{3}x^3 + y^3 + 4x^2 y + C$

(2) Antiderivatives

Want to solve $\begin{cases} f_x = 4x^2 + 8xy & ① \\ f_y = 3y^2 + 4x^2 & ② \end{cases}$

①: $f = \frac{4}{3}x^3 + 4x^2 y + g(y)$

$\Rightarrow f_y = 4x^2 + g'(y)$ $\xrightarrow{\text{match with ②}}$ $g'(y) = 3y^2$ $g(y) = y^3 + C$

$f = \frac{4}{3}x^3 + 4x^2 y + y^3 + C$

$\vec{F}$ is a consecutive field, the $\oint_C \vec{F} d\vec{r} = 0$

Definition $\text{curl}(\vec{F}) = N_x - M_y$ and $N_x = M_y \Leftrightarrow \text{curl}(\vec{F}) = 0$

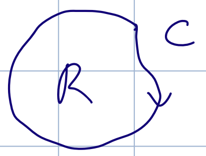
For a velocity field, curl measures rotation component of motion

ex. $\vec{F} = \langle -y, x \rangle$ $\text{curl}(\vec{F}) = \frac{\partial}{\partial x}(x) - \frac{\partial}{\partial y}(-y) = 2$

curl measures $(2\times)$ angular velocity of rotation component of velocity field

in a force field, curl measure $\frac{\text{torque}}{\text{moment of inertia}} = \frac{d}{dt}(\text{angular velocity})$

Lecture 22 Green Theorem



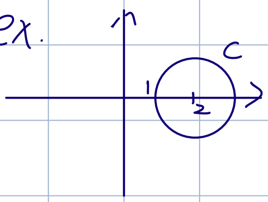
If C is a closed curve enclosing a region R, counterclockwise

$\vec{F}$ vector field defined and differentiable in R

Then $\oint_C \vec{F}\,d\vec{r} = \iint_R \mathrm{curl}(\vec{F})\,dA$

$\oint_C M\,dx + N\,dy = \iint_R (N_x - M_y)\,dA$

ex.



$\oint_C y e^{-x}dx + (\frac{1}{2}x^2 - e^{-x})dy$

$= \iint_R (x + e^{-x} - e^{-x})\,dA$

$= 2\pi$

Proof: Special case: $\mathrm{curl}(\vec{F}) = 0$

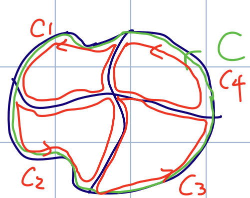
$\oint_C \vec{F}\,d\vec{r} = \iint_R \mathrm{curl}(\vec{F})\,dA = 0$ if $\mathrm{curl}(\vec{F}) = 0$

Proof: $\oint_C M\,dx + N\,dy = \iint_R (N_x - M_y)\,dA$

Observe: first improve $\oint_C M\,dx = \iint -M_y\,dA$ (special case when $N=0$)

Similarly: $\oint_C N\,dy = \iint N_x\,dA$ ($M=0$)

Observe 2: decompose R into simple regions



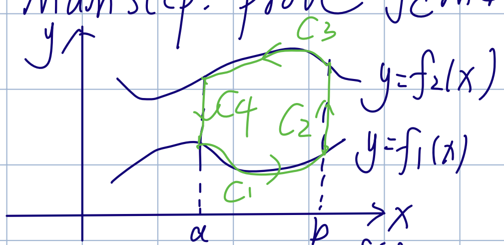
$\oint_C M\,dx + N\,dy = \sum_{i=1}^{n} \oint_{C_i} M\,dx + N\,dy$

$\iint_R (N_x - M_y)\,dA = \sum_{i=1}^{n} \iint_{r_i} (N_x - M_y)\,dy$

(go twice along boundary, cancelled out)

Cut R into pieces that for $a \le x \le b$, $f_1(x) \le y \le f_2(x)$

Main step: prove $\oint_C M\,dx = \iint_R -M_y\,dx$ if R vertically simple



$\int_{C_1} M\,dx = \int_a^b M(x, f_1(x))\,dx$ $\quad \int_{C_3} M\,dx = \int_b^a M(x, f_2(x))\,dx$

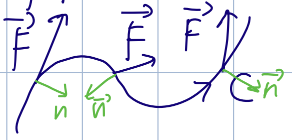
$\int_{C_2} M\,dx = \int_{C_4} M\,dx = 0$

$\int_C M\,dx = \int_a^b M(x, f_1(x))\,dx - \int_a^b M(x, f_2(x))\,dx$

$\iint -M_y\,dA = -\int_a^b \int_{f_1(x)}^{f_2(x)} \frac{\partial M}{\partial y}\,dy\,dx = -\int_a^b [M(x, f_2(x)) - M(x, f_1(x))]\,dx = \int_a^b [M(x, f_1(x)) - M(x_1, f_2(x))]\,dx$

Lecture 23 Flux

Flux: another line integral : $\int_C \vec{F}\cdot\hat{n}\cdot ds$



$\vec{n}$ lies right to the curve

Flux: $\int_C \vec{F}\,\vec{n}\,ds$ measure normal component of $\vec{F}$

Interpretation: For $\vec{F}$ a velocity field, Flux measure how much fluid passes throught C

Calculation: $d\vec{r} = \hat{T}\,ds = \langle dx, dy\rangle$

$\hat{n}$ is $\hat{T}$ rotate $90°$ clockwise: $\hat{n}\,ds = \langle dy, -dx\rangle$

if $\vec{F} = \langle P, Q\rangle$ $\int_C \vec{F}\cdot\hat{n}\,ds = \int_C \langle P,Q\rangle\cdot\langle dy, -dx\rangle = \int_C -Q\,dx + P\,dy$

Green Theorem for flux

If C encloses a region R counterclockwise and $\vec{F} = \langle P, Q\rangle$ defined in R

then $\oint_C \vec{F}\,\hat{n}\,ds = \iint_R \operatorname{div}\vec{F}\,dA$ (divergence of $\vec{F}$)

$\operatorname{div}\langle P, Q\rangle = P_x + Q_y$

$\oint_C \underbrace{-Q}_{M}\,dx + \underbrace{P}_{N}\,dy = \iint_R (\underbrace{P_x}_{N_x} + \underbrace{Q_y}_{-M_y})\,dA$ the same as Green Theorem

ex. $\vec{F} = x\hat{i} + y\hat{j}$ C = circle of $r = a$

$\operatorname{div}\vec{F} = \frac{\partial}{\partial y}(y) + \frac{\partial}{\partial x}(x) = 2$

$\oint_C \vec{F}\,\hat{n}\,ds = \iint_R 2\,dA = 2\pi a^2$

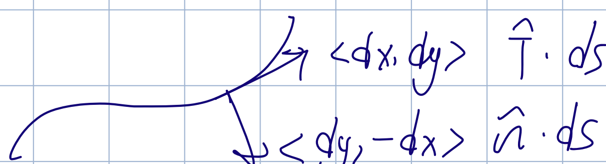
Interpretation

(1) how much the flow is "expanding"

(2) the source rate = amount of fluid added to the system per unit time and area

line integral: $\int_C \vec{F}\,d\vec{r} = \int_C M\,dx + N\,dy$

line integral Flux: $\int_C \vec{F}\cdot\hat{n}\cdot ds = \int_C -Q\,dx + P\,dy$



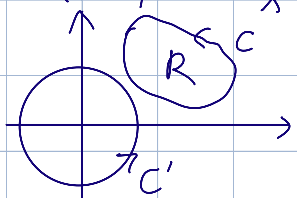
$\operatorname{curl} F = N_x - M_y$ $\oint_C \vec{F}\,d\vec{r} = \iint_R (N_x - M_y)\,dA$

$\operatorname{div} F = P_x + Q_y$ $\oint_C \vec{F}\cdot\hat{n}\cdot ds = \iint_R (P_x + Q_y)\,dA$

More validity of Green's Theorem

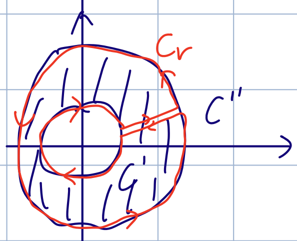
Only work if $\vec{F}$ (and derivative) defined everywhere

ex. $\vec{F} = \frac{-y\hat{i} + x\hat{j}}{x^2+y^2}$ For not $x=y=0$, $\text{curl}\,\vec{F} = 0$



$\oint_C \vec{F}\,d\vec{r} = \iint_R \text{curl}\,\vec{F}\,dA = 0$

$\oint_{C'} \vec{F}\,d\vec{r} = ?$ can't use Green theorem directly

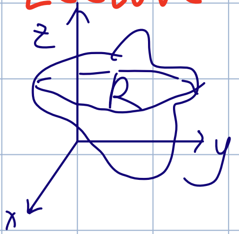


$\oint_{C''} \vec{F}\,d\vec{r} - \oint_{C'} \vec{F}\,d\vec{r} = \iint_R \text{curl}\,\vec{F}\,dA$

take line integral for Cr to prove

If $\text{curl}\,\vec{F} = 0$ and domain where $\vec{F}$ defined is simply connected, $\vec{F}$ is conservative and is a gradient

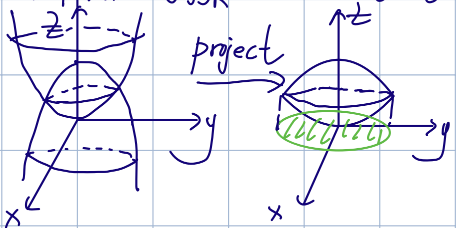
Lecture 25 Triple Integrals



$$\iiint_R f(x,y,z)\,dz\,dy\,dx$$

ex. region between $z=x^2+y^2$, $z=4-x^2-y^2$

volumn $= \iiint_R 1\,dV = \int\int\int_{x^2+y^2}^{4-x^2-y^2} dz\,dy\,dx$ find wherever $z_{bottom} < z_{top}$ $x^2+y^2 \le 4-x^2-y^2$; $x^2+y^2 \le 2$



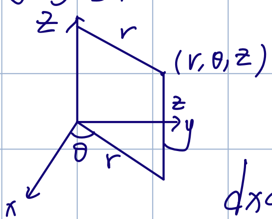
$$= \int_{-\sqrt{2}}^{\sqrt{2}}\int_{-\sqrt{2-x^2}}^{\sqrt{2-x^2}}\int_{x^2+y^2}^{4-x^2-y^2} dz\,dy\,dx$$

$$= \int_{-\sqrt{2}}^{\sqrt{2}}\int_{-\sqrt{2-x^2}}^{\sqrt{2-x^2}} (4-2x^2-2y^2)\,dy\,dx$$

switch to polar coordinate

Better: Polar coordinates

$$\int_0^{2\pi}\int_0^{\sqrt{2}}\int_{r^2}^{4-r^2} dz\cdot r\,dr\,d\theta$$ cylindrical coordinate



$x = r\cos\theta$

$y = r\sin\theta$

$dx\,dy\,dz = dV = r\,dr\,d\theta\,dz$

Average value of $f(x,y,z)$ in x, y, z

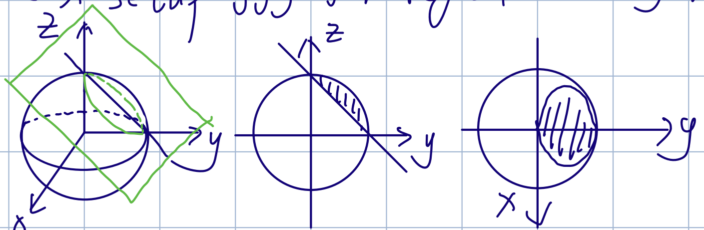
$\bar{f} = \frac{1}{Vol(R)}\iiint_R f\,dV$ or with weighted $\bar{f} = \frac{1}{Mass(R)}\iiint_R f\delta\,dV$

Center of Mass $(\bar{x},\bar{y},\bar{z})$, $\bar{x} = \frac{1}{Mass}\iiint x\delta\,dV$ $\bar{y} = \frac{1}{Mass}\iiint_R y\delta\,dV$ $\bar{z} = \frac{1}{Mass}\iiint_R z\delta\,dz$

Moments of inertia

$I = \iiint_R (\text{distance to the axis})^2\delta\,dV$ ex. $I_z = \iiint_R r^2\delta\,dV$

ex3. setup $\iiint$ for region $z > 1-y$ inside unit ball

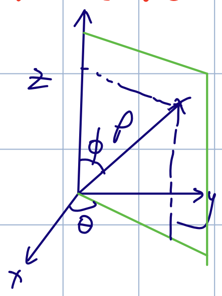


$$= \int_0^1 \int_{-\sqrt{2y-2y^2}}^{\sqrt{2y-2y^2}} \int_{1-y}^{\sqrt{1-x^2-y^2}} dz\,dx\,dy$$

$(1-y) < \sqrt{1-x^2-y^2}$

$(1-y)^2 < 1-x^2-y^2$

Lecture 26 Spherical coordinate

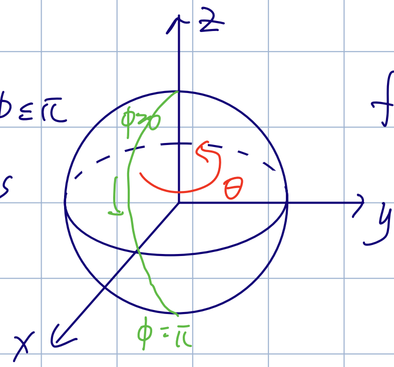


ϕ : go down from z-axis $\quad 0 \le \phi \le \pi$

θ : counterclockwise from x-axis

$z = \rho\cos\phi \qquad \rho = \sqrt{r^2+z^2} = \sqrt{x^2+y^2+z^2}$

$r = \rho\sin\phi \;;\; x = \rho\sin\phi\cos\theta \;;\; y = \rho\sin\phi\sin\theta$

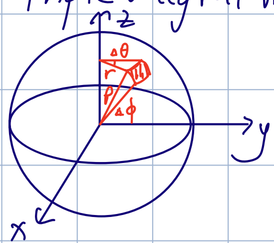


fix $\rho = a$

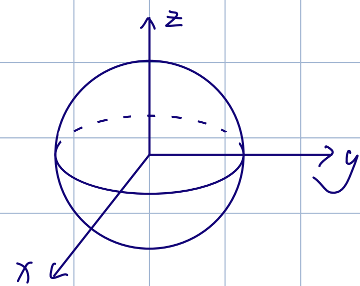
$\phi \leftrightarrow$ latitude

θ : longitude

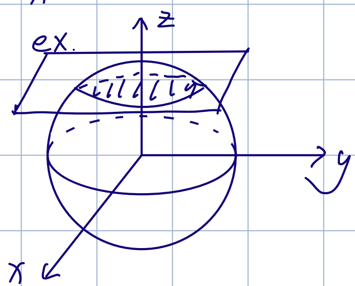
Triple integral in spherical coordinate



$$dV = \rho\, d\phi\; r\, d\theta\; d\rho$$
$$= \rho\, \rho\sin\phi\, d\rho\, d\phi\, d\theta$$
$$= \rho^2 \sin\phi\, d\rho\, d\phi\, d\theta$$



ex.

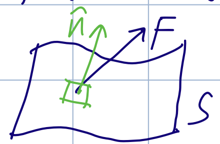


$$= \int_0^{2\pi}\int_0^{\pi/4}\int_{\frac{\sqrt{2}}{2}\sec\phi}^{1} \left(1-\frac{\sqrt{2}}{2}\sec(\theta)\right)\rho^2\sin\phi\, d\rho\, d\phi\, d\theta$$
$$= \frac{2\pi}{3} - \frac{5\pi}{6\sqrt{2}}$$

Lecture 27 Flux in space

flux through a surface; surface integral

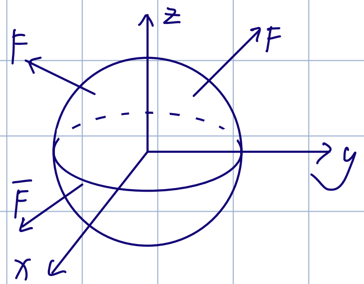
$\vec F$ vector field, S a surface



2 choices for $\hat n$ (orientation)

Flux $= \iint_S \vec F\cdot\hat n\, dS$ Notation $d\vec S = \hat n\, dS$

ex1. Flux of $\vec F = \langle x,y,z\rangle$ through sphere of a centered at O



$\hat n = \frac{1}{a}\langle x,y,z\rangle$

$\vec F\cdot\hat n = |\vec F| = a$

$\iint_S \vec F\hat n\, dS = \iint_S a\, dS = 4\pi a^3$

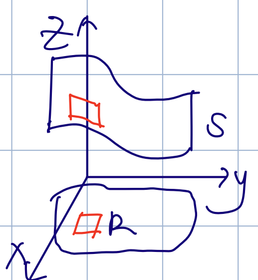
ex2. Same sphere $\vec H = z\hat k$

$\vec H\cdot\vec n = \langle 0,0,z\rangle\cdot\langle x,y,z\rangle\cdot\frac{1}{a} = \frac{z^2}{a}$

$\iint_S \vec F\cdot\vec n\, dS = \iint_S \frac{z^2}{a}\, dS$

$dS = \rho^2\sin\phi\, d\phi\, d\theta = a^2\sin\phi\, d\phi\, d\theta$ $z = a\cos\phi$

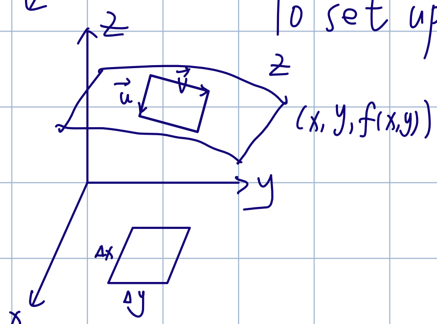
$\iint_S \frac{z^2}{a}\, dS = \int_0^{2\pi}\int_0^{\pi}\frac{a^2\cos^2\phi}{a}\cdot a^2\sin\phi\, d\phi\, d\theta = \frac{4}{3}\pi a^3$



graph $z = f(x,y)$

$\hat n\, dS = \pm\underbrace{\langle -f_x, -f_y, 1\rangle}_{\text{Not }\hat n}\underbrace{dx\,dy}_{\text{Not }dS}$ simplifies magically!

To set up bounds on $\iint \cdots dx\,dy$, look at shadow on x-y plane



$\pm\vec u\times\vec v = \Delta S\cdot\hat n$

$\vec u$: from $(x,y,f(x,y))$ to $(x+\Delta x, y, \overset{\approx f(x,y)+\Delta x\cdot f_x}{f(x+\Delta x, y)})$

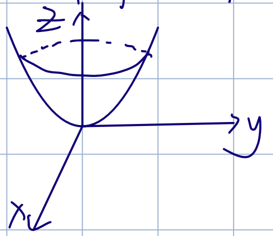
$\vec u = \langle \Delta x, 0, f_x\Delta x\rangle$ $\vec v = \langle 0, \Delta y, f_y\Delta y\rangle$

$= \langle 1, 0, f_x\rangle\Delta x$ $= \langle 0, 1, f_y\rangle\Delta y$

$\hat n\Delta S = \vec u\times\vec v = \begin{vmatrix} i & j & k\\ 1 & 0 & f_x\\ 0 & 1 & f_y\end{vmatrix}\Delta x\Delta y = \langle -f_x, -f_y, 1\rangle\Delta x\Delta y$

$\hat n\, dS = \pm\langle -f_x, -f_y, 1\rangle\, dx\, dy$

ex. $\vec{F} = z\hat{k}$, $z = x^2 + y^2$ above the unit circle



$$= \iint \langle 0, 0, z \rangle \cdot \langle -2x, -2y, 1 \rangle \, dy\, dx$$

choose the unit vector upward

$$= \int_{-1}^{1} \int_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} x^2 + y^2 \, dy\, dx$$

get rid of z

$$= \int_0^{2\pi} \int_0^1 r^2 \cdot r\, dr\, d\theta = \int_0^{2\pi} \frac{1}{4} \, d\theta = \frac{\pi}{2}$$

More generally: given parametric description of S

$$S: \begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases}$$

$\langle x, y, z \rangle = \vec{r} = \vec{r}(u, v)$

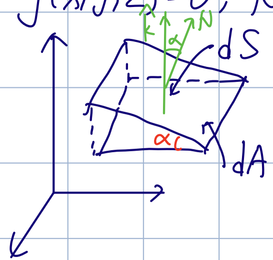
Sides: $\frac{\partial \vec{r}}{\partial u} \cdot \Delta u = \langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \rangle \Delta u$ and $\frac{\partial \vec{r}}{\partial v} \Delta v$

$$\hat{n} \Delta S = \left(\frac{\partial \vec{r}}{\partial u} \cdot \Delta u\right) \times \left(\frac{\partial \vec{r}}{\partial v} \Delta v\right) = \left(\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v}\right) du\, dv$$

$$\hat{n}\, dS = \pm \left(\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v}\right) du\, dv$$

If we know a normal vector $\vec{N}$ (not necessarily unit)

$g(x, y, z) = 0$, $\vec{N} = \nabla g$



$dA = dS \cos\alpha$

$\cos\alpha = \frac{\vec{N} \cdot \hat{k}}{|\vec{N}| |\hat{k}|}$

$dS = \frac{|\vec{N}|}{\vec{N} \cdot \hat{k}} dA$

$$\hat{n}\, d\hat{S} = \frac{|\vec{N}| \cdot \vec{n}}{\vec{N} \cdot \hat{k}} dA = \pm \frac{\vec{N}}{\vec{N} \cdot k} dA$$

$$\hat{n}\, dS = \pm \frac{\vec{N}}{\vec{N} \cdot \hat{k}} \cdot dx\, dy$$

$$n\, dS = \pm \frac{\vec{N}}{\vec{N} \cdot \hat{k}} dx\, dy$$

ex. $z - f(x, y) = 0$

$g = z - f(x, y) = 0 \quad \nabla g = \langle -f_x, -f_y, 1 \rangle$

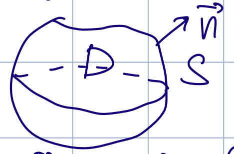
$$\pm \frac{\vec{N}}{\vec{N} \cdot \hat{k}} dx\, dy = \pm \langle -f_x, -f_y, 1 \rangle \, dx\, dy$$

The more general case, if $g(x, y, z) = 0$ can't be solved as $z = f(x, y)$

use $\hat{n}\, dS = \pm \frac{\vec{N}}{\vec{N} \cdot \hat{k}} dx\, dy$, $\vec{N} = \nabla g$

Divergence Theorem (Gauss Theorem)

If S is a closed surface enclosing a space called D



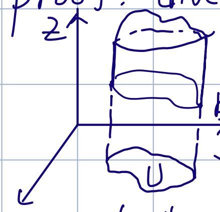
$\hat n$ needs to be outward, and $\vec F$ is defined and differentiable in D

$\oiint_S \vec F\cdot d\vec S = \iiint_D \operatorname{div}\vec F\, dV$, where $\operatorname{div}(P\hat i+Q\hat j+R\hat k)=P_x+Q_y+R_z$

∇ notation ∇ "del" $= \langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\rangle$

$\nabla\cdot\vec F = \langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\rangle\cdot\langle P,Q,R\rangle = \frac{\partial P}{\partial x}+\frac{\partial Q}{\partial y}+\frac{\partial P}{\partial z}$

proof: divergence theorem $\Leftrightarrow \oiint_S\langle 0,0,R\rangle\cdot\hat n\,dS=\iiint_D R_z\,dV$, sum up x, y, z components



top $z=z_2(x,y)$

bottom $z=z_1(x,y)$

vertically simple

$\iiint_D R_z\,dV = \iint_U\left(\int_{z_1(x,y)}^{z_2(x,y)} R_z\,dz\right)dy\,dx = \iint_U \left[R(x,y,z_2(x,y))-R(x,y,z_1(x,y))\right]dy\,dx$

$\oiint_{S=\text{bottom}+\text{top}+\text{sides}}\langle 0,0,R\rangle\cdot\hat n\,dS$

Top: $\hat n\,dS = \langle -\frac{\partial z_2}{\partial x}, -\frac{\partial z_2}{\partial y}, 1\rangle\,dx\,dy$ $\quad \iint_{top}\langle 0,0,R\rangle\hat n\,dS = \iint_{top} R\,dx\,dy = \iint R(x,y,z_2(x,y))\,dx\,dy$

Bottom: $\hat n\,dS = -\langle -\frac{\partial z_1}{\partial x}, -\frac{\partial z_2}{\partial y}, 1\rangle\,dx\,dy$ $\quad \iint_{bottom} -R\,dx\,dy = \iint -R(x,y,z_1(x,y))\,dy\,dx$

Sides are vertical, $\langle 0,0,R\rangle$ is tangent to sides. Flux through sides $= 0$

Diffusion Equation = Heat Equation (immobile)

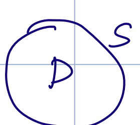
u = concentration $= u(x,y,z,t)$

$\frac{\partial u}{\partial t} = k\nabla^2 u = k\left(\frac{\partial^2 u}{\partial x^2}+\frac{\partial^2 u}{\partial y^2}+\frac{\partial^2 u}{\partial z^2}\right)$

$\vec F$ = flow of smoke, smoke flows from high concentration to low

so $\vec F$ directed along $-\nabla u$ $\quad \vec F = -k\nabla u$

(2) Relate $\vec F$ and $\frac{\partial u}{\partial t}$



Flux out of D through S

$\oiint_S \vec F\hat n\,dS$ = amount of smoke pass in per unit time $= -\frac{d}{dt}\left(\iiint_D u\,dV\right)$ (smoke we are losing)

$=$

$\iiint_D \operatorname{div}\vec F\,dV = -\frac{d}{dt}\iiint_D u\,dV = -\iiint_D \frac{\partial u}{\partial t}\,dV \Rightarrow \operatorname{div}\vec F = -\frac{\partial u}{\partial t}$

$\Rightarrow \frac{\partial u}{\partial t} = -\operatorname{div}\vec F = -\operatorname{div}(-k\nabla u) = k\nabla^2 u$

Lecture 29 Line integral

$\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k}$ $\quad d\vec{r} = \langle dx, dy, dz \rangle$

Work $= \int_C \vec{F}\, d\vec{r} = \int_C P\,dx + Q\,dy + R\,dz$

parametrize C

ex. $\vec{F} = \langle yz, xz, xy \rangle$ $\quad C: x = t^3, y = t^2, z = t, \ 0 \le t \le 1$

$\int_C \vec{F}\, d\vec{r} = \int_0^1 (t^3 \cdot 3t^2 + t^4 \cdot 2t + t^5)\,dt = 1$

In Fact, $\vec{F}$ is conservative $\vec{F} = \langle x, y, z \rangle$

$\vec{F}$ is conservative $\iff P_y = Q_x \quad P_z = R_x \quad Q_z = R_y \iff P\,dx + Q\,dy + R\,dz = df$

① Line integrals

② Antiderivatives

$f_x = 2xy \quad f_y = x^2 + z^3 \quad f_z = 3yz^2 - 4z^3$

$f = x^2y + g(y, z)$

$f_y = x^2 + g_y = x^2 + z^3 \quad g_y = z^3 \quad g = z^3y + h(z)$

$f_z = 3yz^2 - 4z^3 = 3yz^2 + h_z \quad h_z = -4z^3 \quad h = -z^4 + C$

$f = x^2y + z^3y - z^4 + C$

Lecture 30 Stoke's theorem

curl in 3D

if $\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k}$ $\text{curl } \vec{F} = (R_y - Q_z)\hat{i} + (P_z - R_x)\hat{j} + (Q_x - P_y)\hat{k}$

If $\vec{F}$ is defined on a simply-conn region, $\vec{F}$ is consercutive $\Leftrightarrow$ curl $\vec{F} = 0$

$\nabla = \langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \rangle$

$\nabla f = \langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \rangle$

$\nabla \cdot \langle P, Q, R \rangle = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$

$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ P & Q & R \end{vmatrix} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}\right)i - \left(\frac{\partial R}{\partial x} - \frac{\partial P}{\partial z}\right)j + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right)k = \text{curl } \vec{F}$

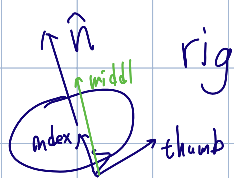
curl measure the rotation component in a velocity field

STOKES' THM

$\oint_C \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot \hat{n}\, dS$ if C closed curve S = any curve bounded by C

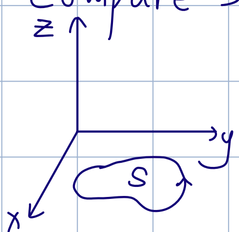
calculate the flux of $\nabla \times \vec{F}$ (curl is a vector field also)

Orientation: need C and S to be compatible



right hand rule

Compare Stokes with Green

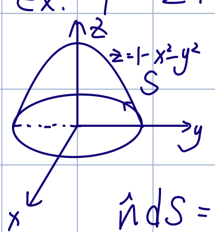


$\oint_C \vec{F} \cdot d\vec{r} = \oint_C P\,dx + Q\,dy$

Stokes: $= \iint_S (\nabla \times \vec{F}) \hat{k}\, dS$ $(\nabla \times \vec{F})\hat{k}$ = z components of curl $\vec{F}$

$= \iint_S (Q_x - P_y)\, dx\, dy$

ex. $\vec{F} = z\hat{i} + x\hat{j} + y\hat{k}$ arount unit circle counterclockwise



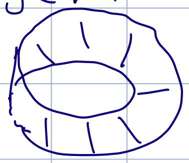
$\oint_C z\,dx + x\,dy + y\,dz = \int_0^{2\pi} 0 + \cos t \cdot (\cos t\, dt) + 0 = \int_0^{2\pi} \cos^2 t\, dt = \pi$

$\iint_S (\nabla \times \vec{F}) \hat{n}\, dS$ $\nabla \times \vec{F} = \begin{vmatrix} i & j & k \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ z & x & y \end{vmatrix} = \langle 1, 1, 1 \rangle$

$\hat{n}\, dS = \langle -f_x, -f_y, 1 \rangle dx\,dy = \langle 2x, 2y, 1 \rangle dx\,dy$

$\iint_S \langle 1,1,1 \rangle \langle 2x, 2y, 1 \rangle dx\,dy = \iint (2x + 2y + 1)\, dx\,dy = \pi$

$\oint_C \vec{F}\, d\vec{r} = \iint_S (\text{curl}\,\vec{F})\,\hat{n}\, dS$



Flux can't be defined

div $(\nabla \times \vec{F}) = 0$ always

$\vec{F} = \langle P, Q, R \rangle$

div $(\nabla \times \vec{F}) = (R_y - Q_z)_x + (P_z - R_x)_y + (Q_x - P_y)_z = 0$

In space, curl $\vec{F} = \nabla \times \vec{F}$ is a consecutive vector field