CV Final Project

Group 25

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Image Enhancement

Motivation

Introduce problem

Results

Qualitative and Quantitative Result

Method

Briefs and Algorithms

Discussion

The effect of modification

Motivation

Goal

- Enhance low-light images automatically
- Prevent over enhancing a normal light image

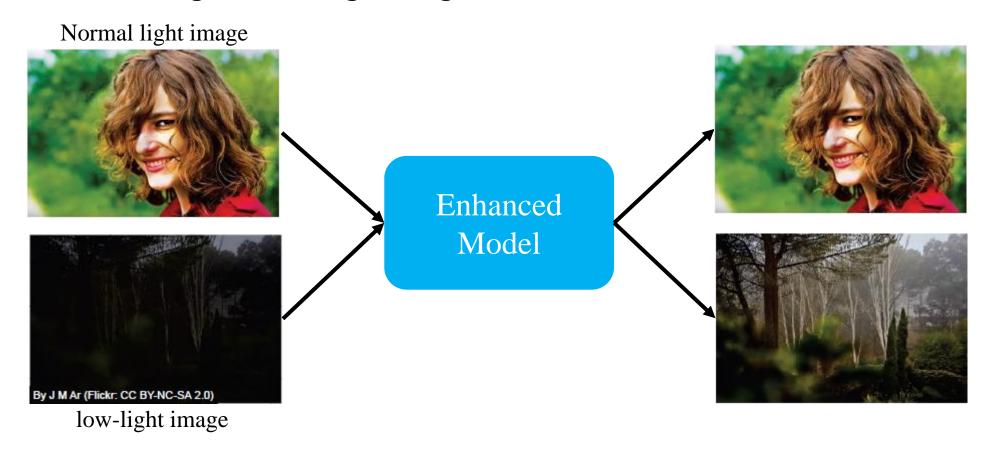


Fig. 1. An illustrate example for the image enhancement.

Motivation

Based on Zero-DCE [1]

Two problems

• The color will tend to become white

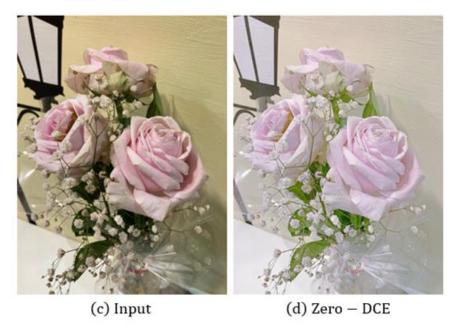


Fig. 2. The result that the color tend to be white

Over enhancement

Fig. 3. Result that is over enhancement.

(b) Zero - DCE

(a) Input

Purpose

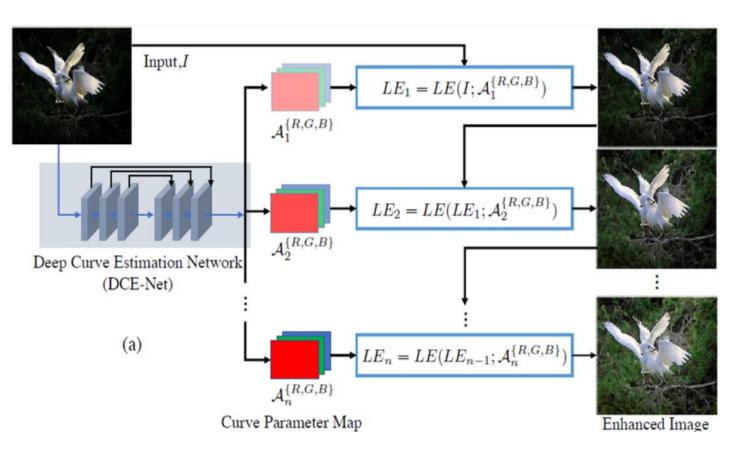
- Our Work: modified the paper Zero-DCE
- To avoid the color of the image becomes white and over enhancement

[1] C. Guo et al. Zero – reference deep curve estimation for low – light image enhancement. In CVPR, 2020.

Method

1. Zero-DCE

- Formulate light enhancement as a task of image-specific curve estimation
- A lightweight deep network, DCE-Net



• Use a Quadratic function (degree=2):

$$LE(I(X); \alpha) = I(x) + \alpha I(x)(1 - I(x))$$

• Learned the curve parameter $\alpha \in [-1, 1]$

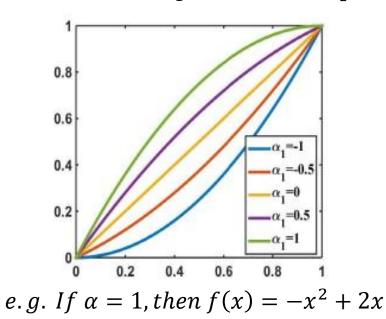


Fig. 4. The Zero-DCE architecture.

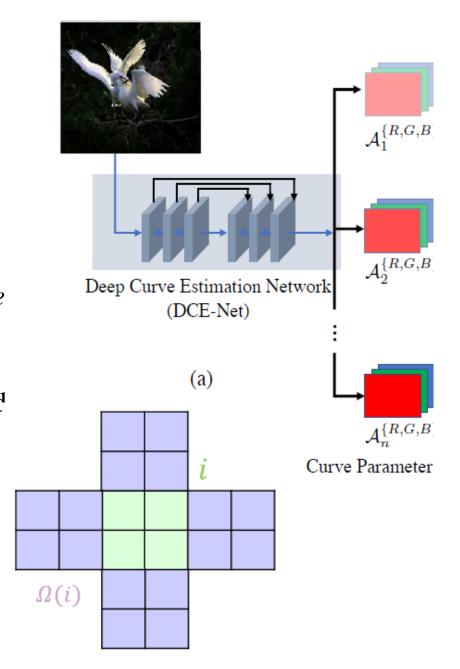
Proposed Method

DCE-Net

- Input: a low light image
- Output: 8 parameter maps

Spatial Consistency Loss

- Preserving the difference of neighboring regions between the input image and its enhanced version
- *Y*, *I*: Average intensity value of local region in the enhanced version and input image, respectively
- $\mathcal{L}_{spa} = \frac{1}{K} \sum_{i=1}^{K} \sum_{j \in \Omega(i)} (\left| Y_i Y_j \right| \left| I_i I_j \right|)$



Proposed Method

Exposure Control Loss

- Restrain under-/over-exposed regions
- *Y*: Average intensity value of local region in the enhanced image
- E: well-exposedness level
- $\mathcal{L}_{exp} = \frac{1}{M} \sum_{k=1}^{M} |Y_k E|$

Color Constancy Loss

- Gray-World color constancy hypothesis : color in each sensor channel averages to gray over the entire image.
- Correct the potential color deviations in the enhanced image
- $\mathcal{L}_{col} = \sum_{\forall (p,q) \in \varepsilon} |J^p J^p|, \varepsilon = \{(R,G), (R,B), (G,B)\}$

Proposed Method

Illumination Smoothness Loss

- Preserve the monotonicity relations between neighboring pixels
- *Y*: Average intensity value of local region in the enhanced image
- *E* : Well-exposedness level
- $\mathcal{L}_{tv_{\mathcal{A}}} = \frac{1}{N} \sum_{n=1}^{N} \sum_{c \in \xi} (|\nabla_{x} \mathcal{A}_{n}^{c}| + |\nabla_{y} \mathcal{A}_{n}^{c}|), \xi \in \{R, G, B\}$



(a) Input



(b) Zero-DCE



(c) w/o L_{spa}



(d) w/o L_{exp}



(e) w/o L_{col}



(f) w/o L_{tv_A}

Method

2. Modification

• Iterative:

- o output only 3 parameter maps
- o the output of the previous iteration is an input of the next iteration

Stop Mechanism:

 \circ mean of an image, $\mu(I)$, should be less than or equal to 0.6

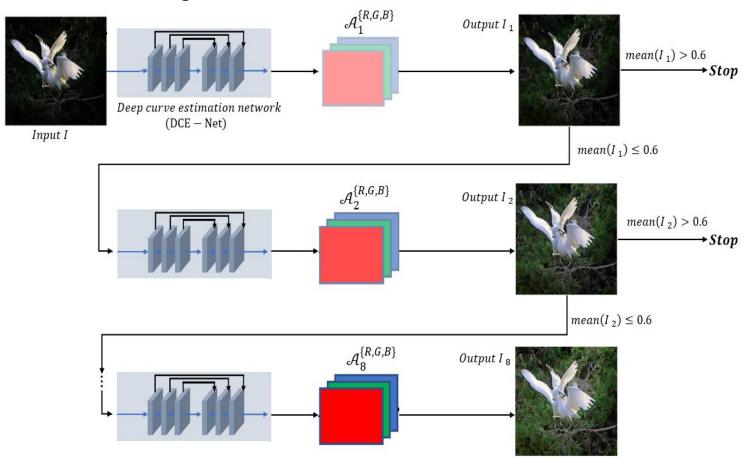


Fig. 4. The Zero-DCE++ architecture.

$Gray = (R_{avg} + R_{avg} + R_{avg})/3$

 $R' = \frac{Gray}{R_{avg}} R$

 $G' = \frac{Gray}{G_{avg}} G$

 $B' = \frac{Gray}{B_{avg}} B$

2. Modification

Weighted Color Constancy Loss: (inspired by [2])

$$L_{wcol} = \sum_{\forall (p,q) \in \varepsilon} (S \odot J^p - S \odot J^q)^2, \varepsilon = \{(R,G), (G,B), (B,R)\}$$

- S is the segmentation map,
- O denotes the element-wise product.



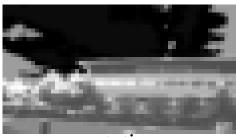
input



Gray world



[2]



segmentation map

- Color Consistency Loss:
 - \circ Transform the input image I (RGB color space) to enhanced image I' (YCbCr color space)
 - $L_{ccl} = \frac{1}{HW} \sum_{c \in \xi} (I^c I'^c)^2$, $\xi = \{Cb, Cr\}$, where HW is the number of pixels.

Results

Datasets

- Our dataset: Lucy
- VV, MEF, LOL, LIME, FiveK, DICM

Evaluation metric

• NIMA

Results (normal)



1.a. Input



1.b. Zero-DCE



1 1



1.c. Iterative Zero-DCE++ 1.d. Iterative Zero-DCE++ w/ stop



1.e. Weighted color constancy loss



1.f. Weighted color constancy loss (stop)



1.g. Color consistency loss



1.h. Color consistency loss (stop)

Results (normal)



2.a. Input



2.b. Zero-DCE



2.c. Iterative Zero-DCE++



2.d. Iterative Zero-DCE++ w/ stop



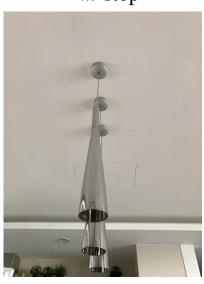
2.e. Weighted color constancy loss



2.f. Weighted color constancy loss (stop)



2.g. Color consistency loss



2.h. Color consistency loss (stop)



3.a. Input



3.b. Zero-DCE



3.c. Iterative Zero-DCE++



3.d. Iterative Zero-DCE++ w/ stop



3.e. Weighted color constancy loss



3.f. Color consistency loss



4.a. Input



4.d. Iterative Zero-DCE++ w/ stop



4.b. Zero-DCE



4.e. Weighted color constancy loss



4.c. Iterative Zero-DCE++



4.f. Color consistency loss



5.a. Input



5.d. Iterative Zero-DCE++ w/ stop



5.b. Zero-DCE



5.e. Weighted color constancy loss



5.c. Iterative Zero-DCE++



5.f. Color consistency loss



6.a. Input



6.d. Iterative Zero-DCE++ w/ stop



6.b. Zero-DCE



6.e. Weighted color constancy loss



6.c. Iterative Zero-DCE++



6.f. Color consistency loss



7.a. Input



7.d. Iterative Zero-DCE++ w/ stop



7.b. Zero-DCE



7.e. Weighted color constancy loss



7.c. Iterative Zero-DCE++



7.f. Color consistency loss

Results (low light)



8.a. Input



8.b. Zero-DCE



8.e. Weighted color constancy loss



8.c. Iterative Zero-DCE++



8.d. Iterative Zero-DCE++ w/ stop



8.f. Color consistency loss

Results (extremely dark)



9.a. Input



9.d. Iterative Zero-DCE++ w/ stop



9.b. Zero-DCE



9.e. Weighted color constancy loss



9.c. Iterative Zero-DCE++



9.f. Color consistency loss

Results (extremely dark) • Visual results



10.a. Input



10.b. Zero-DCE



10.c. Iterative Zero-DCE++



10.d. Iterative Zero-DCE++ w/ stop

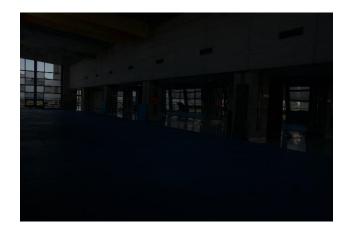


10.e. Weighted color constancy loss



10.f. Color consistency loss

Results (extremely dark) • Visual results



11.a. Input



11.d. Iterative Zero-DCE++ w/ stop



11.b. Zero-DCE



11.e. Weighted color constancy loss



11.c. Iterative Zero-DCE++



11.f. Color consistency loss

• Quantitative results

	Lucy	VV	MEF	LOL	LIME	FiveK	DICM
Zero-DCE	4.725	4.579	4.618	4.755	4.549	4.141	4.382
Iterative Zero-DCE++	4.747	4.564	4.433	3.962	4.635	4.242	4.485
Iterative Zero-DCE++ w/ stop	4.741	4.564	4.333	3.962	4.634	4.239	4.481
Iterative Zero-DCE++ w/ weighted color constancy loss	4.762	4.544	4.644	4.251	4.725	4.389	4.477
Iterative Zero-DCE++ w/ color consistency loss	4.762	4.544	4.644	4.251	4.725	4.389	4.477

NIMA[†]

Discussion

Normal-light images.

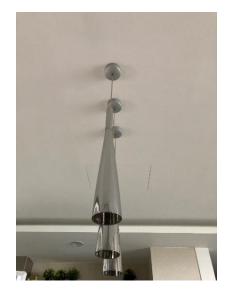
- Hope that our model will not enhance a normal image too much.
- Observing Fig 1.f, 2.f:
 - o **color consistency loss:** only enhance its brightness and remain the color.
 - Stop mechanism: avoids color deviation.



1.a. Input



1.f. Color consistency loss



2.a. Input

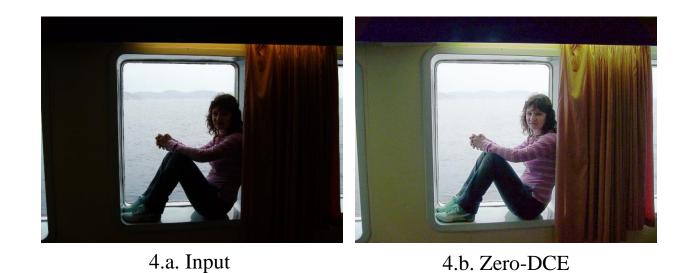


2.f. Color consistency loss

Work plan

Low-Light images.

- The brightness should be increased and the color should be remained.
- Observing Fig 4 ~8: Zero-DCE enhance the brightness significantly.
- With color consistency loss: closer to the color its of corresponding input image.



color may change a little bit



4.f. Color consistency loss

closer to the color its of corresponding input image

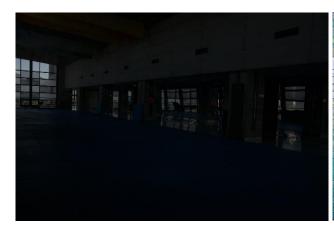
Discussion

Extreme Dark images.

- Increasing the brightness is the most important part.
- Color consistency is less important.
- Fig. 9~11: Zero-DCE can enhance the brightness of image much more than the other methods.









9.a. Input

9.b. Zero-DCE

11.a. Input

11.b. Zero-DCE

Noise is amplified.

Work assignment plan between team

- We finish and discuss all the works together.
- Each member focus on different part:

郭家瑋:Code, 江梓豪: Report, 范氏和兒: PPT file