

A Recursive Strategy for Symbolic Execution Expressed in Coq

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Abstract. Prior work has proposed the use of symbolic execution for the security validation of a processor design. The approach uses a recursive search strategy that is designed to counter the exponential path growth inherent in multi-cycle processor execution. In this work, we examine the search strategy in order to prove its correctness. We formulate an abstract model of symbolic execution with the recursive search strategy in Coq, and we find that the strategy as proposed is not guaranteed to be sound—that is, the search may find a symbolic path for which no concrete path from the processor’s initial state to the given error state exists. We tighten one of the requirements of the search strategy and then prove the modified strategy correct.

1 Introduction

Researchers have recently begun exploring the use of software-style symbolic execution for the verification of hardware designs [17,14]. Symbolic execution has a proven track record in the software community as a bug-finding tool [5,6,12] and as an aid in formal verification [9,10]. However, bringing these benefits to bear on hardware designs has been a challenge—the complexity of the search space of relatively simple hardware designs more closely resembles that of large, continuously interactive software systems than that of the stand-alone software programs that are the classic targets of symbolic execution. In response to this challenge a recent paper proposed a recursive search strategy for symbolic execution [23]. Zhang et al. showed the strategy to be practical [22], but the soundness of the approach has not been demonstrated. A proof of correctness is needed.

In this paper we prove that a recursive search strategy for the symbolic execution of hardware designs is sound: a list of constraints returned by a successful search defines a set of concrete input sequences, each of which will take the processor from its initial reset state to an error state.

Our goal is to validate the search strategy itself rather than any one implementation of it. Therefore we decouple our model of symbolic execution from the particular programming language to be symbolically executed. We formalize an abstract model of symbolic execution in Gallina, the specification language of the Coq proof assistant [21]; the structure of the model is built around the three fundamental properties of symbolic execution as first laid out by King in 1976 [13]. This has the advantage of providing soundness guarantees for the recursive search strategy when implemented by any symbolic execution engine which abides by the three King properties.

The symbolic exploration of a program produces a rooted, binary tree. The root node represents the entry point of the program, and each path from root to a leaf node represents one possible path of the execution through the program. Although the mechanics are similar, the symbolic exploration of a hardware design differs from this model conceptually: The tree produced by the symbolic exploration of a hardware design represents the state transitions possible in a single clock cycle from a given state (the root node). A sequence of state transitions, for example from the hardware’s initial, reset state to an error state is represented by a sequence of trees. The set of all possible n transitions from a given state requires a tree (of depth n) of trees.

The strategy proposed by Zhang and Sturton tackles this search complexity with a recursive search. First the n^{th} tree in the desired sequence of trees is found, then the $n - 1^{\text{st}}$ tree, and so on, until the first tree in the sequence, whose root node starts at the reset state, is found.¹ The strategy lays out three properties that, if satisfied at each iteration of the search, are sufficient to ensure the final sequence of paths through trees represents a possible, multi-cycle sequence of state transitions from the hardware’s initial state to the desired (error) state.

¹ The problem is undecidable in the general case, and Zhang et al. introduce a set of heuristics to make it work in practice [22].

The bulk of our proof is a proof by induction over the sequence of trees to show that the trees are correctly stitched together. In the base case we show that symbolic execution, as defined by King, implies the correct *concretization* of a path through a single symbolic execution tree as defined by Zhang and Sturton. In the inductive step we show that a path through a sequence of trees stitched together according to the Zhang and Sturton requirements will yield a correct concretization of a path through the sequence of trees. Finally, we prove that the sequence begins in a reset state and ends in the desired error state.

We find that the recursive search strategy as originally proposed is not sound—that is, the search may find a symbolic path for which no concrete path from the processor’s initial state to the given error state exists. We tighten one of the three requirements of the strategy and then prove the modified strategy is sound.

We present two contributions of this work:

- An abstract model of symbolic execution expressed in the Coq framework. This model can form the starting point for building a provably correct implementation of a symbolic execution engine for a particular language. We make our model available online at <https://github.com/AlyssaByrnes/recursive-strategy-symbolic-execution-proof>.
- We verify the soundness of the recursive search strategy for symbolic execution. We find and fix a flaw in the original formulation of the strategy. The recursive search strategy was originally developed for the verification of hardware designs; however, any symbolic execution engine that implements the proven strategy will be assured the same guarantee of soundness.

2 Prior Work

Symbolic execution was first formally defined by King in 1976 [13] and has been widely adopted by the software engineering and software security communities. (See Schwartz et al. [20] for a recent survey.)

Symbolic execution has since shown practical value through implementations. Anand et al. introduced a tool JPF-SE that works as an extension of the Java PathFinder model checker to allow for symbolic execution of Java programs [2]. Păsăreanu et al. later introduced the tool Symbolic PathFinder that also utilizes Java Path Finder to symbolically execute Java bytecode [19]. Noller et al. recently released a tool that utilizes Java PathFinder to perform “shadow symbolic execution” on Java bytecode [18].

2.1 Use of Symbolic Execution in Hardware

In addition to the paper by Zhang and Sturton that lays out the three-part strategy we prove here [23], there are a handful of papers that examine the use of symbolic execution in hardware. In a subsequent paper, Zhang et al. [23] make use of their recursive strategy to find new security vulnerabilities in processor designs. Their work demonstrates that the strategy is useful in practice.

Prior work first explored the use of software-style symbolic execution for hardware designs. The STAR tool combines symbolic and concrete simulation of hardware designs to provide high statement and branch coverage [14]; PATH-SYMEX uses forward symbolic execution applied to an ANSI-C model of the hardware design [17]. Both tools use a forward search strategy and have limits on how deep or broadly they can search.

2.2 Formalization of Symbolic Execution

Some work has been done to formalize symbolic execution. Arusoiaie et al. provide a formal framework for a symbolic execution tool that is language-independent [3,4,15]. However, they don’t provide a formal representation of King’s branching properties [13] nor do they formally verify their tool or its outputs.

2.3 Backward Search Strategies in Symbolic Execution

A backward search strategy for symbolic execution of software has been studied [16,7,11,8]. There the approach is to search backward through function call chains from a goal line of code to the program’s entry point. The strategy is hindered by complications that arise in software, such as floating point calculations and external method calls. To the best of our knowledge, the strategy has not been formalized in the software community, nor its validity proven.

3 Background

We provide a brief review of symbolic execution and describe the key features of a hardware design that necessitate a new approach for symbolic execution. We explain the recursive strategy for symbolic execution and provide some background on the Coq proof assistant.

3.1 Symbolic Execution

In symbolic execution formal parameters to a program's entry point are assigned symbolic values. The program is then simulated by a symbolic execution engine that uses the symbolic values in place of concrete literals. As execution continues the resulting symbolic expressions propagate throughout the program's state.

In addition to the symbolic state, the symbolic execution engine keeps track of the *path condition* (pc) for the current path of execution. When execution begins the path condition is initialized to TRUE. At each conditional branch the condition c is evaluated. If $pc \rightarrow c$ is valid, the **then** branch is taken and the path constraint is updated, $pc := pc \wedge c$. If $pc \rightarrow \neg c$ is valid, the **else** branch is taken and the path constraint is updated, $pc := pc \wedge \neg c$. If neither $pc \rightarrow c$ nor $pc \rightarrow \neg c$ hold, then both branches are possible. Execution forks and both branches are explored in turn with the path condition updated appropriately for each branch.

All the paths explored through the program form a logical tree t . The root represents the program's entry point and each node of the tree represents a line of code in the program. Associated with each node is the (partially) symbolic state of the program and the path condition at that point of execution. A path in the tree from root to leaf represents a path of execution through the program.

Figure 1 demonstrates the idea. Given the code in Figure 1a, **reset** and **count** are initialized with the symbolic values r_0 and c_0 , respectively, and after symbolically executing lines 1, 3, and 4 **count** may be set to the symbolic expression $c_0 + 1$ as shown in Figure 1c. The path condition for the path through lines 1, 3, 4, 5, 6 is also shown. When execution reaches the **ERROR** at line 6 the path condition is $pc := r_0 = 0 \wedge c_0 + 1 > 3$. This expression can then be solved using a standard, off-the-shelf SMT solver to find a satisfying solution, say $r_0 := 0$ and $c_0 := 3$. Substituting these values for **reset** and **count**, respectively and executing the code concretely would cause execution to follow the same path as was followed symbolically. Figure 1b illustrates the tree of path conditions generated by the complete symbolic execution of the code fragment.

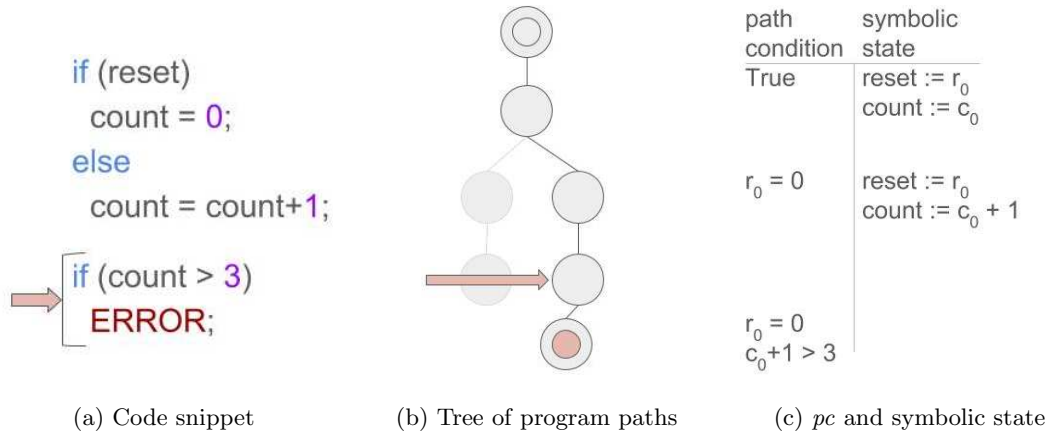


Fig. 1: Symbolic Execution

3.2 Register Transfer Level Hardware Designs

For their recursive strategy, Zhang et al. are targeting the symbolic execution of a synchronous hardware design described at the register transfer level (RTL) of abstraction. The RTL specifies the stateful registers in the design and the combinational logic connecting those registers. A complete

simulation of the design corresponds to a single clock cycle; the symbolic execution of the design produces a tree where the root node represents the design in a given state and each leaf node represents a possible next-state of the design at the next clock cycle. The hardware design differs from software code in that it is not meant to be executed sequentially, rather it describes a design in which all transitions happen simultaneously. When run in simulation—during which it must be executed sequentially—an order of execution is imposed and temporary variables may be introduced in order to achieve the correct next state. The same strategy is used during symbolic execution and therefore, the root and leaf nodes of the resulting symbolic execution tree correspond to valid states of the hardware design, but intermediate nodes of the tree do not and are largely ignored.

The symbolic execution tree represents an exploration of the design for a single clock cycle. But it is often desirable to find states that arise only after many steps of execution. Because of this the complexity of the search space quickly becomes untenable. To explore a design for two clock cycles would require first producing the symbolic execution tree of the design when started at the initial, reset state, and then, for each leaf in that tree, a new symbolic execution of the design, this time starting at the state described by the leaf node. It is to counter this complexity that Zhang et al. developed their recursive search strategy.

3.3 Using Coq as a Verification Tool

Coq is a formal, interactive proof assistant that allows for machine-checked proofs of systems [1]. It implements the inductive language Gallina, which is based on the *Calculus of Inductive Constructions*, a typed λ -calculus. It allows definitions of methods that can be evaluated, the expression of theorems and software specifications, and assists the user in building machine-checkable proofs. If the proof is complete, it will compile.

Additionally, we make use of Coq’s module system, representing different parts of our system as modules. There is a module defining concrete execution, a module defining symbolic execution that includes the King properties as axioms, and a module defining the recursive symbolic execution strategy that includes the requirements laid out by Zhang et al. as axioms and the correctness property expressed as a theorem.

Our definitions and fixpoints are the methods that are implemented in the system, such as execution of the list of trees provided by the recursive symbolic execution tool. Our variables are system-specific variables, such as the initial state and the error states, and they are contained in the recursive symbolic execution module as well.

We use the built-in Logic library for assistance in small proofs and the Ensembles library for assistance reasoning about finite sets. Additionally, we use the built-in List structure to represent lists of symbolic execution trees.

4 Definitions and Notation

4.1 Concrete Execution

We model a hardware module as a tuple $P = (C, c_0, I, \text{concEx})$, where

- C is the finite set of states of the module,
- $c_0 \in C$ is the initial state of the module,
- $I = \{0, 1\}^n$ is the finite set of input values—the domain—of the module, and
- $\text{concEx} : C \times I \rightarrow C$ is the transition function of the module.

A state $c \in C$ of the module is a concrete valuation to all registers in the design: $r_0 = i, r_1 = j, \dots, r_m = k$, where r_0, r_1, r_m represent the stateful registers and $i, j, k \in \{0, 1\}^*$. The initial state of the module, c_0 , sometimes called the reset state, is the valuation taken by the stateful registers of the design after the power-on cycle. The domain of the module is the set of binary strings of length n , which represents the concatenation of multiple input parameters to the module. The transition function takes the module from one state to the next state. It represents the execution of a single clock-cycle in hardware. The transition function is left-total: for every $c \in C$ and every $i \in I$ concEx is defined. We do not model the output of the module explicitly; it is the identity function taken over a subset of the registers in the design.

4.2 Symbolic Execution

The result of symbolic execution is a rooted, binary tree $t = (N, E, l)$, where N is the set of nodes of the tree, E is the set of directed edges connecting two nodes, and $l \in N$ is a particular leaf node of interest in the tree. This leaf node represents a desired next-state of the module being symbolically explored, and in the recursive strategy, it is this leaf node that is joined to the root node of a subsequent tree in the search.

Each node $n \in N$ of the tree is a tuple $n = (s, pc)$, where

- s is a (partially) symbolic state of the module and
- pc is the current path condition.

A symbolic state assigns a symbolic expression, σ , to every register in the design: $r_0 = \sigma_0, r_1 = \sigma_1, \dots, r_m = \sigma_m$. A symbolic expression σ contains at least one symbol and may contain zero or more concrete literals, arithmetic operators, and logical operators. Examples of symbolic expressions include ' α ' and ' $\alpha + 1$,' where α is a symbol used by the symbolic execution engine.

A path condition, pc , is a conjunction of propositions involving symbolic expressions. For example ' $pc = \alpha + 1 \geq 0 \wedge \alpha < 1$ ' is a possible path condition.

We define `symEx()` for a particular hardware module as an abstract method that takes as input an initial symbolic state s , an initial path condition $pc_0 = \text{TRUE}$, and a set of symbolic inputs, and returns a tree of explored paths. In the recursive strategy, `symEx` is always called with an initial symbolic state that is fully symbolic: $r_0 = \alpha, r_1 = \beta, \dots, r_m = \omega$.

The alphabet of symbols that can appear in a path condition is the union of the alphabet of symbols used to define a symbolic state and the alphabet of symbols used as input values by `symEx`: $\Sigma_{pc} = \Sigma_s \cup \Sigma_i$.

4.3 Properties of Symbolic Execution

King formalized the use of symbolic execution [13] and described three fundamental properties provided by a symbolic execution engine. We name and summarize the properties and for each, give our formal expression of the property.

Property K.1 (Sound Paths). The path condition pc never becomes unsatisfiable. For each leaf node l of a symbolic execution tree, there exists, for the path condition associated with l , at least one satisfying concrete valuation to the symbols of the path condition; that is, one mapping of symbols to concrete values that would make the path condition evaluate to `TRUE`. If this mapping of satisfying concrete values were applied to the initial symbolic state and symbolic inputs, the resulting concrete execution would follow the same path through the program as was taken by the symbolic execution engine to arrive at the leaf node l . In other words, all paths taken by the symbolic execution engine correspond to feasible paths through the program.

We express this in the following way:

$$\forall m = \text{map}(\cdot), s \in S, \alpha \in \Sigma_i, n \in t = \text{symEx}(s, pc_0, \alpha), \\ \text{simplify}(\text{applymap}(n.pc, m)) = \text{TRUE}.$$

Where `map`(\cdot) is the set of all functions that map from the set of symbols Σ to the set of concrete values, S is the set of all possible symbolic states, Σ_i is the set of symbolic input values, and n is a node in the tree t produced by a call to `symEx`.

Property K.2 (Unique Paths). The path condition pc_1 and pc_2 associated with any two paths of the tree are mutually unsatisfiable. In other words, there exists no concrete valuation that could drive execution down two distinct paths of the symbolic execution tree.

We express this the following way:

$$\forall m = \text{map}(\cdot), s \in S, \alpha \in \Sigma_i, n_1, n_2 \in t = \text{symEx}(s, pc_0, \alpha), \\ n_1 \neq n_2 \\ \wedge (\text{ischildof}(n_1, n_2) \vee \text{ischildof}(n_2, n_1)) = \text{FALSE} \\ \rightarrow \text{simplify}(\text{applymap}(n_1.pc \wedge n_2.pc, m)) = \text{FALSE}.$$

Property K.3 (Commutativity). The actions of symbolically executing a program and instantiating symbols with concrete values (`applymap(·)` in our model) are commutative. If a mapping is first chosen and then the program is executed concretely, the end state will be the same as if the program is executed symbolically and then, for a particular leaf, a mapping is chosen such that the path constraint of that leaf is satisfied.

$$\begin{aligned} \forall m = \text{map}(\cdot), s \in S, \alpha \in \Sigma_i, l \in t = \text{symEx}(s, pc_0, \alpha) \wedge \text{simplify}(\text{applymap}(l.pc, m)) = \text{TRUE} \\ \rightarrow \text{simplify}(\text{applymap}(l.s, m)) = \\ \text{concEx}(\text{simplify}(\text{applymap}(s, m)), \text{simplify}(\text{applymap}(\alpha, m))). \end{aligned}$$

Where l is a leaf node of the tree returned by `symEx`.

4.4 Recursive Strategy Requirements

We express the three original requirements of the recursive strategy as laid out by Zhang et al. [23]. We start by formally defining two instantiation operations that are only informally described by Zhang et al. but that are used by the strategy requirements.

Instantiation Operations The root node of a symbolic execution tree t contains a symbolic state (`getroot(t).s`), which can be viewed as a representation of a set of possible concrete states. If s is fully symbolic, meaning that all registers in the design are assigned symbolic expressions ($r_0 = \sigma_0, r_1 = \sigma_1, \dots$), then it represents the set of all possible concrete states C . From the set of all possible concrete states, all possible next states are reachable, and these are represented by the leaves of the symbolic execution tree. The symbolic state of each leaf node of the tree represents a subset of C .

The effect of the operations (`concretize_root` and `concretize_leaf`) is to take a node (root or leaf) of a symbolic execution tree and find the set of concrete states represented by the symbolic state of that node.

Definition 1 (`concretize_root`).

For any given leaf node of the tree, the set of concrete states represented by that node is reachable, with a given input, from a subset of the concrete states represented by the root node. This instantiation operation finds that subset of concrete states for the particular leaf node of interest of a tree. The operation takes as input a tree (remember that a tree is the tuple $t = (N, E, l)$, where l is a particular leaf node of interest of the tree) and returns a set of concrete states. We define it formally here.

$$\begin{aligned} \forall t \in T, c \in C, c \in \text{concretize_root}(t) \leftrightarrow \\ \exists r, n \in t, m = \text{map}(\cdot) \text{ such that } \\ r = \text{getroot}(t), n = t.l, \text{simplify}(\text{applymap}(n.pc, m)) = \text{TRUE} \\ \text{and } c = \text{simplify}(\text{applymap}(r.s, m)). \end{aligned}$$

The definition says that any mapping (`map(·)`) from symbolic to concrete values that makes the path condition of the leaf node evaluate to `TRUE` will, when applied to the symbolic state of the root node, produce a concrete state in the set returned by `concretize_root`.

Definition 2 (`concretize_leaf`).

This instantiation operation finds the set of concrete states represented by the particular leaf node of interest of a tree.

$$\begin{aligned} \forall t \in T, c \in C, c \in \text{concretize_leaf}(t) \leftrightarrow \\ \exists n \in t, m = \text{map}(\cdot) \text{ such that } \\ n = t.l, \text{simplify}(\text{applymap}(n.pc, m)) = \text{TRUE} \\ \text{and } c = \text{simplify}(\text{applymap}(n.s, m)). \end{aligned}$$

The definition says that any mapping (`map(·)`) from symbolic to concrete values that makes the path condition of the leaf node evaluate to `TRUE` will, when applied to the symbolic state of that same leaf node, produce a concrete state in the set returned by `concretize_leaf`.

Three Original Requirements The goal of the symbolic execution of a hardware design is to find a sequence of n inputs that will take the hardware module from an initial reset state to an error state in n clock cycles. The gist of the recursive search strategy is to search backward from the error state as follows. First use symbolic execution to find a state s_i that has the error state as one of its possible next-state transitions. Then use symbolic execution to find a state s_{i-1} that has s_i as one of its possible next-state transitions. This search continues until one of the found s_i 's is a reset state. Each application of symbolic execution produces a tree with a particular leaf node of interest—the desired next-state s_i . This sequence of trees (*tree_list*) must satisfy these three requirements as laid out by Zhang et al.

Property Z.1 (Start in initial state). The leaf node of interest in the first tree in the sequence must be reachable from the initial, reset state.

$$c_0 \in \text{concretize_root}(\text{tree_list}[0]).$$

Property Z.2 (End in error state). The leaf node of interest in the last tree in the sequence must include, in the set of concrete states it represents, one of the desired error states.

$$\text{concretize_leaf}(\text{tree_list}[n]) \cap ER \neq \emptyset,$$

where ER represents the set of desired error states.

Property Z.3 (Stitch trees together). Consecutive trees in the sequence must form a continuous path of execution. That is, the leaf node of one tree must represent a subset of the states represented by the root node of the subsequent tree in the sequence.

$$\forall i, 0 \leq i < n, \\ \text{concretize_leaf}(\text{tree_list}[i]) \subseteq \text{concretize_root} \text{tree_list}[i + 1].$$

We find these properties are not sufficient to prove correctness of the strategy. We strengthen Property Z.2 by replacing it with the following.

Property Z.2' (Property Z.2 correction). The leaf node of interest in the last tree in the sequence must represent a subset of the desired error states. The leaf node can not represent any concrete state that is not an error state.

$$\text{concretize_leaf}(\text{tree_list}[n]) \subseteq ER.$$

5 Proof Strategy

The claim made by Zhang and Sturton is that a sequence of symbolic execution trees that abides by their three requirements will yield a sequence of concrete input values, which will take the hardware module from the reset state to an error state.

We prove that if a sequence of trees produced by our abstract Coq model of symbolic execution, which is based on the three King properties (Properties K.1, K.2, K.3), abides by Properties Z.1, Z.2', Z.3, then it does yield a sequence of concrete inputs that take the abstract model of concrete execution from the reset state to an error state.

In other words, we define a list of symbolic execution trees, called *tree_list*, the we bind with a set of properties and a method to execute the relevant leaves, called *execute_tree_list*, and show that it leads to a set of error states, called *error_states*. This can be expressed as the following theorem

Theorem 1 (Correctness of Recursive Strategy). $\text{execute_tree_list}(\text{tree_list}) \in \text{error_states}$.

In order to prove this, we first prove the following theorem:

Theorem 2 (Execution ends in leaf of the last tree). $\text{execute_tree_list}(\text{tree_list}) \in \text{concretize_leaf}(t)$, where t is the last element of *tree_list*.

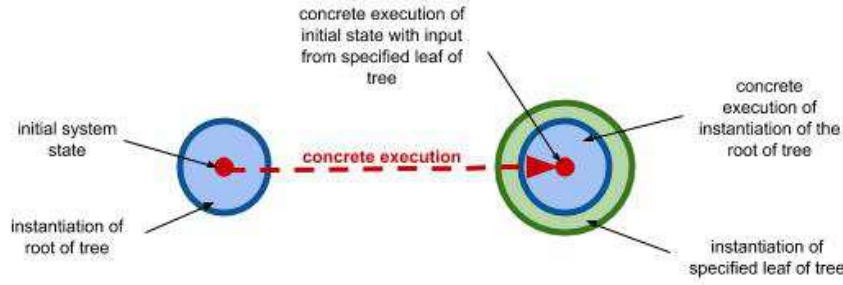


Fig. 2: Visual depiction of the base case of the proof.

We then show that $\text{concretize_leaf}(t) \in \text{error_states}$, giving us our result.

We prove Theorem 2 by induction. For our base case, we show that if the list only contains one tree, execution of that tree's root node with input specified by a selected leaf will result in an element of $\text{concretize_leaf}(t)$.

In other words, as depicted in Figure 2, we show that the initial state is an element of $\text{concretize_root}(t)$ of the tree, t , and that concretely executing any element of $\text{concretize_root}(t)$ will result in an element inside $\text{concretize_leaf}(t)$.

For our inductive step, as depicted in Figures 3 and 4, we show that execution of each root with inputs from each specified leaf in a tree list of size n will result in an element of $\text{concretize_leaf}(t_n)$.

Our inductive hypothesis is that $\text{execute_tree_list}(\text{tree_list}') \in \text{concretize_leaf}(t_{n-1})$, where $\text{tree_list}'$ is a tree_list with the last element removed. We then show that $\text{concretize_leaf}(t_{n-1}) \subseteq \text{concretize_root}(t_n)$, and therefore the concrete execution of any element in $\text{concretize_leaf}(t_{n-1})$ is in the set of the concrete execution of any element in $\text{concretize_root}(t_n)$. Next, we show that $\text{concretize_root}(t_n) \subseteq \text{concretize_leaf}(t_n)$, giving us our result.

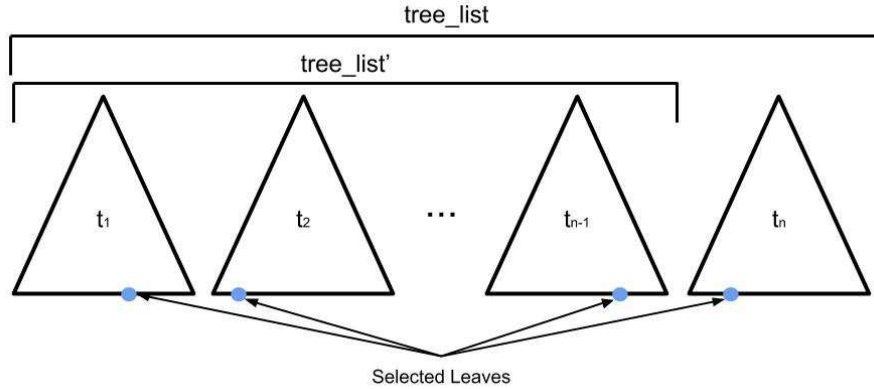


Fig. 3: List of trees of length n .

5.1 Coq Representation of Recursive Strategy

Our system contains the following three global variables:

- A list of symbolic execution trees $\in t$ called tree_list that represent the list of trees returned by the recursive strategy.
- A concrete state $\in C$ to represent the initial system state, called $\text{init_concrete state}$.
- A set of concrete states $\in C$ to represent all of the system error states, called error_states .

We then define the method $\text{execute_tree_list} : \{t\} \rightarrow \{C\}$, that takes a list of symbolic execution trees and executes them according to the inputs given by the leaves.

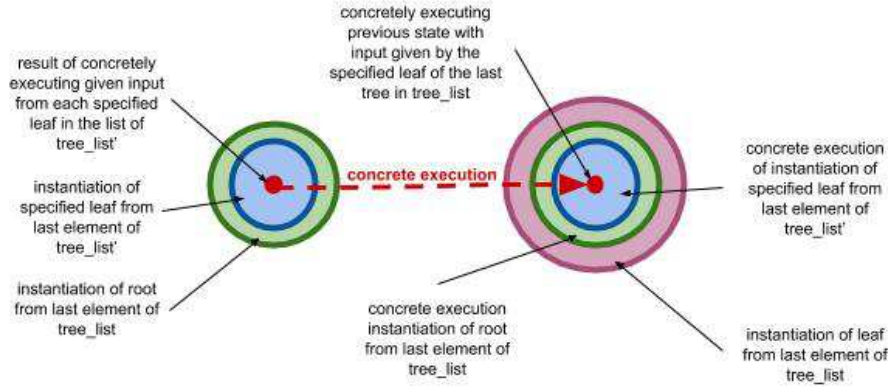


Fig. 4: Visual depiction of the inductive step of the proof.

Additionally, we define the abstract method, $\text{get_input} : \{\alpha\} \times \{\Sigma\} \rightarrow \{C\}$ which returns a concrete input that does not violate a given symbolic state's path constraint. This method is bound by the requirement,

Definition 3 (*get_input*). \forall symbolic inputs $i' \in \text{SymInputs}$, tree nodes n , and $m = \text{map}(\cdot)$ if \exists a symbolic state $s \in S$ such that n is a leaf of the tree output by $\text{symEx}(s, i)$ and $\text{pc_eval}(\text{instantiate}(n.pc, m)) = \text{TRUE}$, then $\text{instantiate}(i, m) = \text{get_input}(i)$.

We now can formally prove the following lemma, which we will use in our proof:

Lemma 1. *forall symbolic states s , symbolic inputs i' , concrete states c , and $m = \text{map}(\cdot)$, if $cs \in \text{concretize_root}(t)$, then $\text{conc_ex}(cs, \text{get_input}(i')) \in \text{concretize_leaf}(t)$, where l is a leaf of t and $t = \text{symEx}(s, i')$.*

In order to prove this, we utilize the commutativity property expressed earlier.

Our main correctness theorem that we prove is Theorem 1. In other words, given our three property requirements, executing our `tree_list` will get us to an error state.

6 Verification Approach

We give a basic outline of our proof of our correctness theorem.

We want to show that $\text{execute_tree_list}(\text{tree_list}) \in \text{error_states}$.

We prove this by first proving Theorem 2.

Proof (Theorem 2). This is a proof by induction on the size of `tree_list`.

For our base case we show that if `tree_list` is of length 1, then $\text{execute_tree_list}(\text{tree_list}) \in \text{concretize_leaf}(t)$.

To prove this we use the following set property (which we verify in Coq):

Theorem 3. \forall inputs i , If $A \in B$ and $\forall x \in B$, $\text{concEx}(x, i) \in C$, then $\text{concEx}(A, i) \in C$.

If `tree_list` is of length 1, we know we are executing from the initial concrete state of the system. Therefore, we consider the following properties:

- $\text{init_conc_state} \in \text{concretize_root}(\text{last_element}(\text{tree_list}))$. (Property 1)
- \forall inputs $i, \forall x \in \text{concretize_root}(\text{last_element}(\text{tree_list}))$, $\text{concEx}(x, i) \in \text{concretize_leaf}(\text{last_element}(\text{tree_list}))$.

Now, using Theorem 3, we conclude that $\text{concEx}(\text{init_conc_state}) \in \text{concretize_leaf}(\text{last_element}(\text{tree_list}))$.

Our inductive hypothesis is $\text{execute_tree_list}(\text{tree_list}') \in \text{concretize_leaf}(\text{last_element}(\text{tree_list}'))$ where `tree_list'` is `tree_list` with the last element removed.

We want to show that if our inductive hypothesis holds, then $\text{execute_tree_list}(\text{tree_list}) \in \text{concretize_leaf}(\text{tree_list})$.

In order to prove this, we must prove the following lemma:

Lemma 2. $\text{execute_tree_list}(\text{tree_list}') \in \text{concretize_root}(\text{last_element}(\text{tree_list}))$.

Proof (Lemma 2). We prove this using the following set property (which we verify in Coq):

Theorem 4. *If $A \in B$ and $B \subseteq C$, then $A \in C$.*

We know:

- $\text{execute_tree_list}(\text{tree_list}') \in \text{concretize_leaf}(\text{last_element}(\text{tree_list}'))$. (Inductive Hypothesis)
- $\text{concretize_leaf}(\text{last_element}(\text{tree_list}')) \subseteq \text{concretize_root}(\text{last_element}(\text{tree_list}))$. (Property 3)

So, using Theorem 4, we conclude that $\text{execute_tree_list}(\text{tree_list}') \in \text{concretize_root}(\text{last_element}(\text{tree_list}))$. \square

Now, to prove our inductive step, we know:

- $\text{execute_tree_list}(\text{tree_list}') \in \text{concretize_leaf}(\text{last_element}(\text{tree_list}'))$. (Lemma 2)
- if $x \in \text{concretize_root}(\text{last_element}(\text{tree_list}))$, then $\text{concEx}(x, \text{get_input}(l.pc)) \in \text{concretize_leaf}(\text{last_element}(\text{tree_list}))$, where l is a leaf of $\text{last_element}(\text{tree_list})$. (Lemma 1)
- $\text{concretize_leaf}(t) \neq \{\}$. (Property 3')

So, using Theorem 3, we can conclude that $\text{execute_tree_list}(\text{tree_list}) \in \text{concretize_leaf}(\text{last_element}(\text{tree_list}))$. \square

Now, we prove our correctness property.

Proof (Theorem 1). We know:

- $\text{execute_tree_list}(\text{tree_list}) \in \text{concretize_leaf}(\text{last_element}(\text{tree_list}))$. (Theorem 2)
- $\text{concretize_leaf}(\text{last_element}(\text{tree_list})) \subseteq \text{error_states}$. (Property 2')

so, using Theorem 4, we conclude $\text{execute_tree_list}(\text{tree_list}) \in \text{error_states}$. \square

The reason we need Property 2' is because Property 2 is not sufficient. This is because if $\text{execute_tree_list}(\text{tree_list}) \in \text{concretize_leaf}(\text{last_element}(\text{tree_list}))$ and $\text{concretize_leaf}(\text{last_element}(\text{tree_list})) \cap \text{error_states} \neq \{\}$, we could get the case where $\text{execute_tree_list}(\text{tree_list}) \notin \text{error_states}$, as shown in Figure 5.

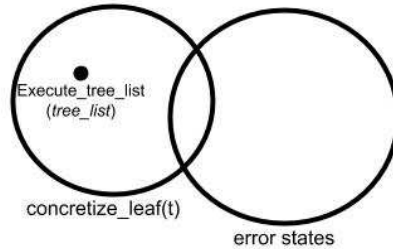


Fig. 5: Example of Property 2 not being sufficient to show $\text{execute_tree_list}(\text{tree_list}) \in \text{error_states}$.

7 Conclusion

In conclusion, we prove the correctness of a recursive symbolic execution strategy (with one alteration) while also demonstrating the usefulness of formal verification by finding a flaw in the strategy's requirements. We also provide a formal framework of symbolic execution in Coq, allowing for future verification of other symbolic execution tools and strategies.

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