

# Reinforcement Learning Assignment 2

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## 1 Introduction

The goal of this assignment is to do experiments with Monte-Carlo(MC) Learning and Temporal-Difference(TD) Learning. MC and TD methods learn directly from episodes of experience without knowledge of MDP model. TD method can learn after every step, while MC method requires a full episode to update value evaluation. Your goal is to implement MC and TD methods and test them in the small gridworld.

## 2 Small Gridworld

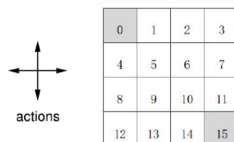


Figure 1: Gridworld

As shown in Fig.1, each grid in the gridworld represents a certain state. Let  $s_t$  denotes the state at grid  $t$ . Hence the state space can be denoted as  $S = \{s_t | t \in 0, \dots, 15\}$ .  $S_0$  and  $S_{15}$  are terminal states, where  $S_1$  to  $S_{14}$  are non-terminal states and can move one grid to north, east, south and west. Hence the action space is  $A = \{n, e, s, w\}$ . Note that actions leading out of the grid leave state unchanged. Each movement get a reward of -1 until the terminal state is reached.

## 3 Experiment Requirements

- Programming language: python3
- You should implement both first-visit and every-visit MC method and TD(0) and to evaluate state value in small grid world.

## 4 Report and Submission

- Your reports and source files (.py) should be compressed and named after "studentID+name".
- The files should be emailed to TA (yuankunjiang@126.com) before 2019.04.04 24:00.