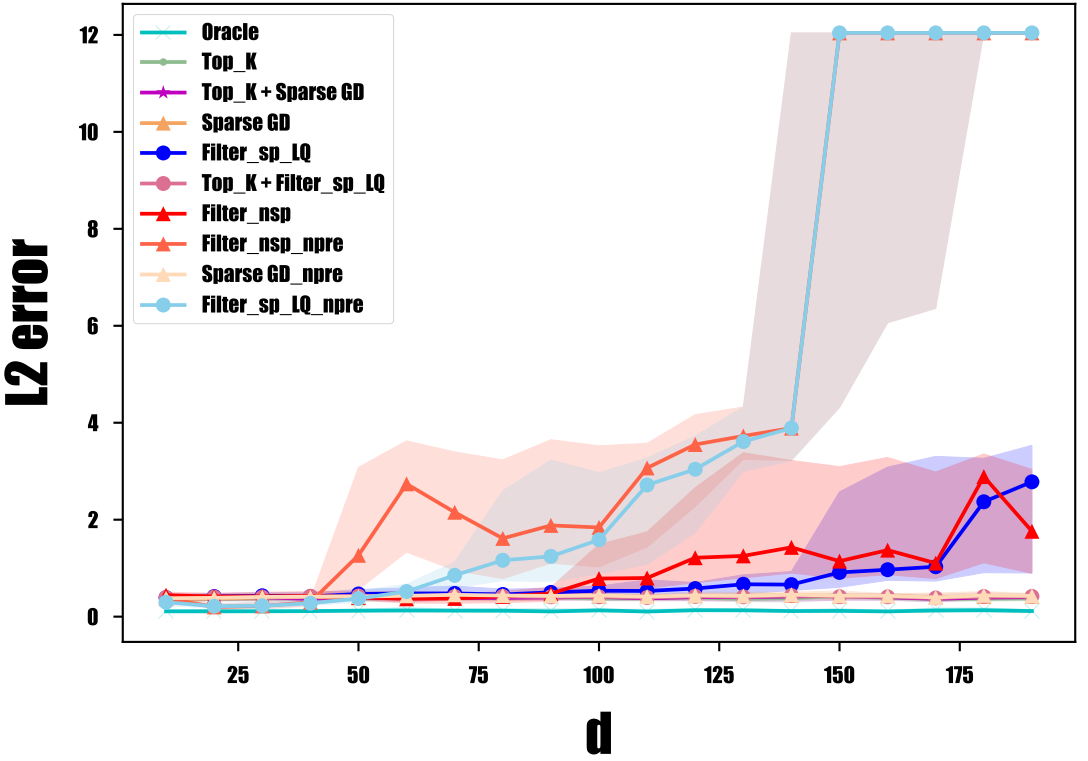m = 600, k = 4, eps = 0.1. Model is Fisk. Noise is constant -2 biased.