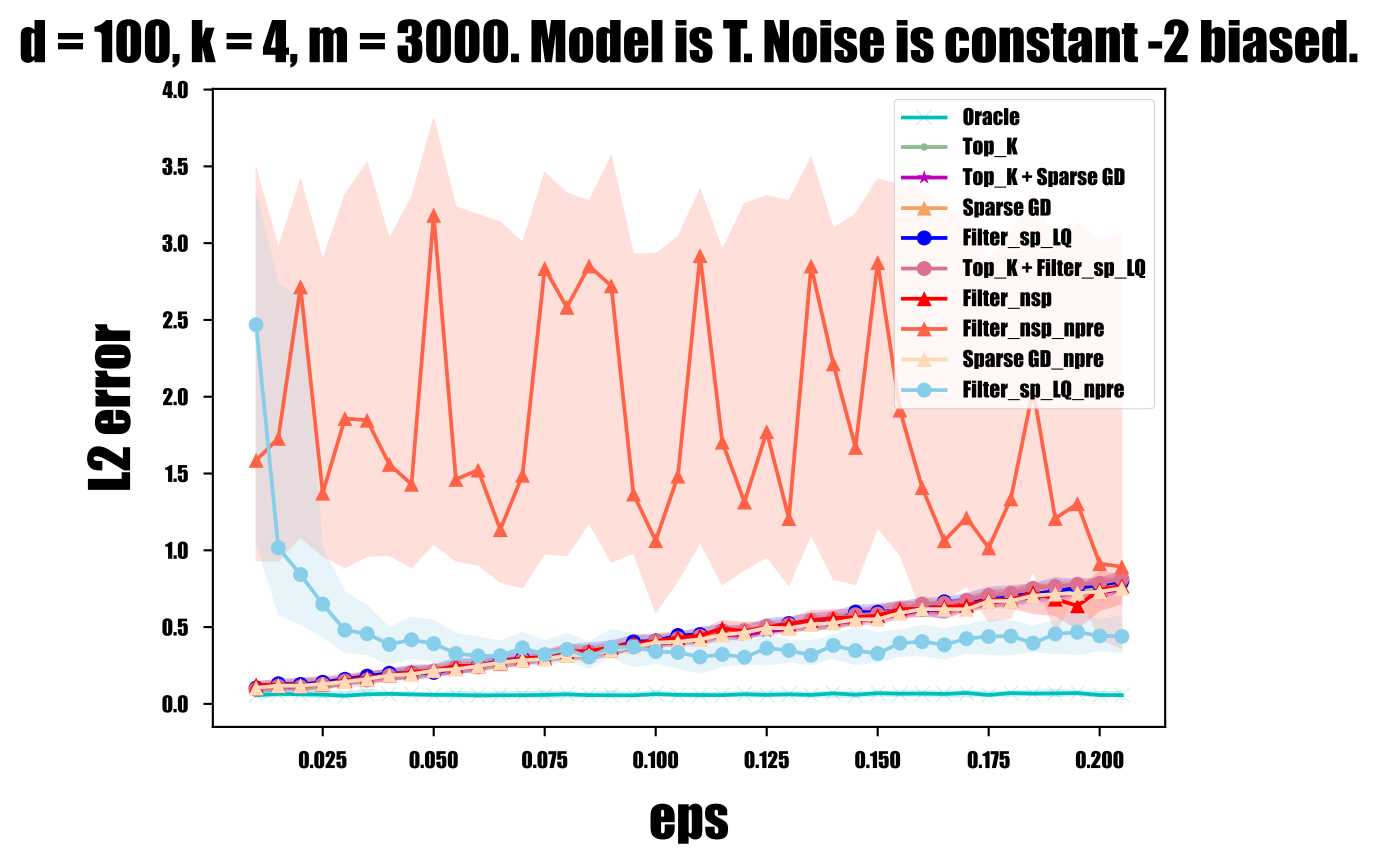
d = 100, k = 4, m = 3000. Model is T. Noise is constant -2 biased.
L2 error
eps
4.0
3.5
3.0
2.5
2.0
1.5
1.0
0.5
0.0
0.025
0.050
0.075
0.100
0.125
0.150
0.175
0.200
Oracle
Top_K
Top_K + Sparse GD
Sparse GD
Filter_sp_LQ
Top_K + Filter_sp_LQ
Filter_nsp
Filter_nsp_npre
Sparse GD_npre
Filter_sp_LQ_npre