# Computer Vision Case Study: Deep Learning for Satellite Imagery and Land Cover Statistical Estimation

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## **Outline**

#### Goal

Land Cover (LC) statistics and maps represent a critical statistical product, for Official Statistics, for example. Since they require a big effort to be created, the underlying idea is building an automatic and efficient system that processes satellite images in order to generate:

- Automatic Land Cover Maps
- Automatic Land Cover Estimates

## Methodology

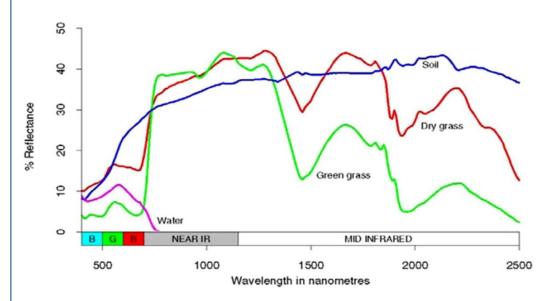
New Approach: using Deep Learning techniques to generate Land Cover maps (classification and segmentation through CNN and U-Net).

#### Results

A Deep Learning-based integrated (CNN + U-Net) and automated architecture that gives accurate results for all LC classes

## Deep Learning for Land Cover from Satellite Imagery

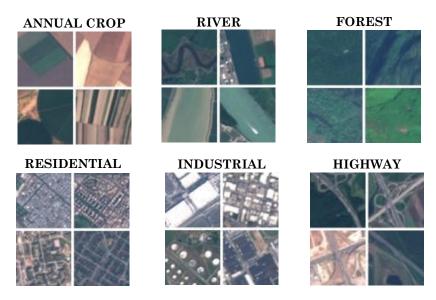
#### **Standard approach: Spectral Signature**



#### Different LC classes have different reflectance spectra

- Patterns of Reflectance Variation are used to predict LC classes
- A Trained ML algorithm predicts the LC class independently
- Decision on each data point does not depend on neighboring data points

#### **New approach: Computer Vision (Deep Learning)**



#### Different LC classes have different spatial/visual patterns

- The Variation of visual/spatial patterns is used to predict LC classes
- Trained ML algo (CNN) predicts the LC class of image pixels based on information from neighboring pixels
- Decision on each pixel depends on the whole sub-image (tile)
   the pixel belongs to

## Machine Learning for LC from satellite imagery

#### TRAINING DATASET

The Training.set affects the classification and prediction accuracy of our machine learning algorithm. We have harnessed the **EuroSAT** dataset features and its EuroSAT Land-Cover classification. EuroSAT is made of satellite imagery which is carefully collected and selected from Sentinel 2 Satellite Copernicus Project.



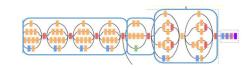
#### **INPUT**

Input images to be processed, must be in excellent agreement with training pictures. That's why we take portions of Italy satellite imagery from Sentinel 2 itself.



#### **ARCHITECTURE**

We chose our Algorithm Architecture accordingly: Classification Convolutionary Neural Network (CNN) or Segmentation Convolutionary Neural Networke (U-Net). We built the model by selecting the right hyper-parameters, optimizations and validations.

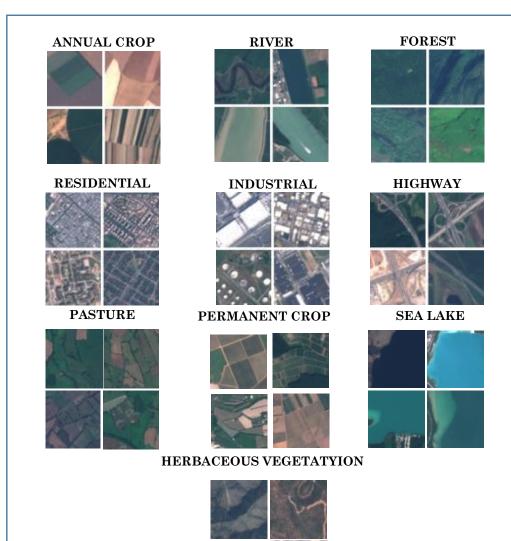


#### **OUTPUT**

The output ground truth is within the training dataset in order to validate the model. Then, the ouput is yielded by processing the Input dataset in order to perform classifications/predictions.



## **CNN: Satellite Imagery Dataset**

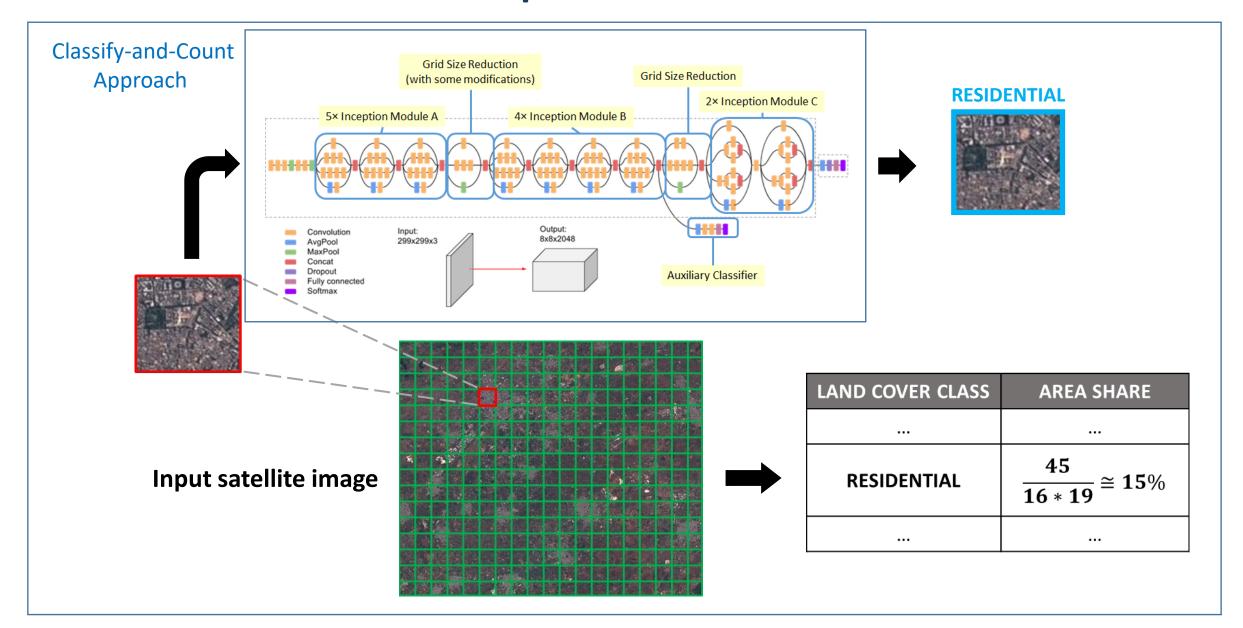


#### **EuroSAT dataset**

(https://github.com/phelber/eurosat):

- Based on Sentinel-2 satellite images
- 27000 geo-referenced and labeled image patches (each one of 64x64 pixels)
- 10 different Land Use and Land Cover classes,
   with 2000-3000 images per class
- RGB (8-bit) and Multi-Spectral (13 spectral bands, 16-bit) versions available

## **CNN:** Inception-V3 Architecture



## GoogleNet - Google (Szegedy, C., et al., 2015)

### Critical Feautures (Szegedy, C., et al., 2015):

Computationally Effective Deep architecture: 22 layers

Why the name inception, you ask? Because the module represents a network within a network. If you don't get the reference, go watch Christopher Nolan's "INCEPTION", computer scientists are hilarious.

**Inception**: it is basically the parallel combination of  $1\times1$ ,  $3\times3$ , and  $5\times5$  convolutional filters.

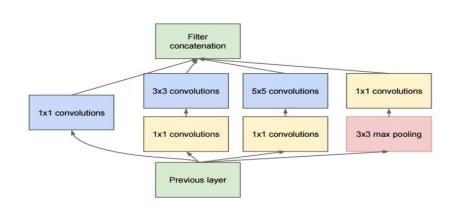
**Bottleneck layer:** The great insight of the inception module is the use of  $1\times1$  convolutional blocks (NiN) to reduce the number of features before the expensive parallel blocks.

**Upside:** 4 millions parameters!

**Downside:** Not scalable!

**Results:** 

7 Models Ensemble : 6.67% Top-5 Error.

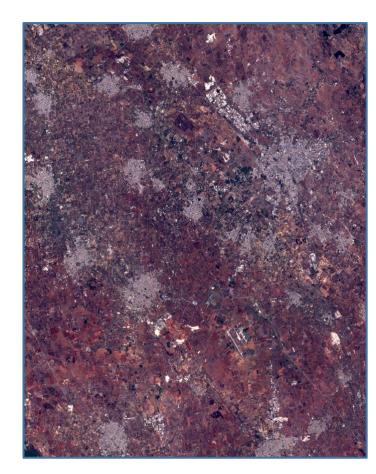


Convolution

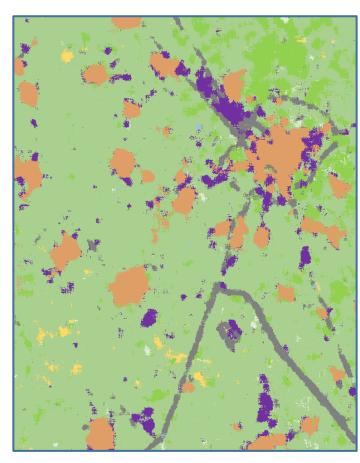
Concat/Normalize

Pooling

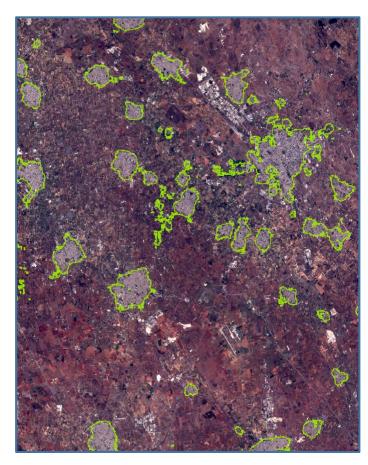
## **CNN: Example of Automatic Land-Cover Map**



[A] Input Lecce's picture (751 km²)



[B] Related Lecce LC Map (output)

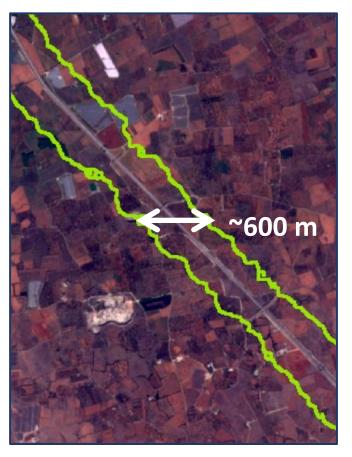


[C] Depiction of the *Residential* class generated by overlapping [A] and [B]

## CNN: Over-estimation effect of *River* and *Highway* classes



[D] Detailed overview of the **Arno River** pathway (**Pisa**, 443 km<sup>2</sup>) on top of a semi-transparent version of the corresponding LC map.



[E] Fragment of Lecce highlighting the border of the *Highway* class predicted by the model. We can see the extent of the over-estimation

## **U-Net: Dataset creation**

EuroSAT Imagery *River* 







Segmentation Masks *River* 

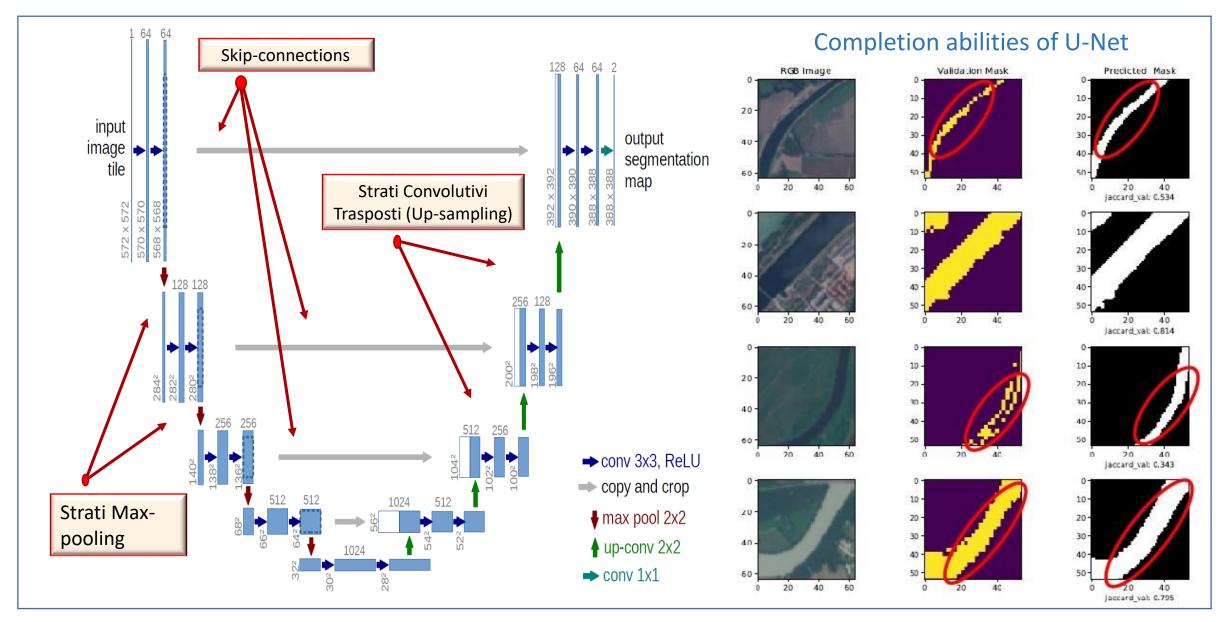




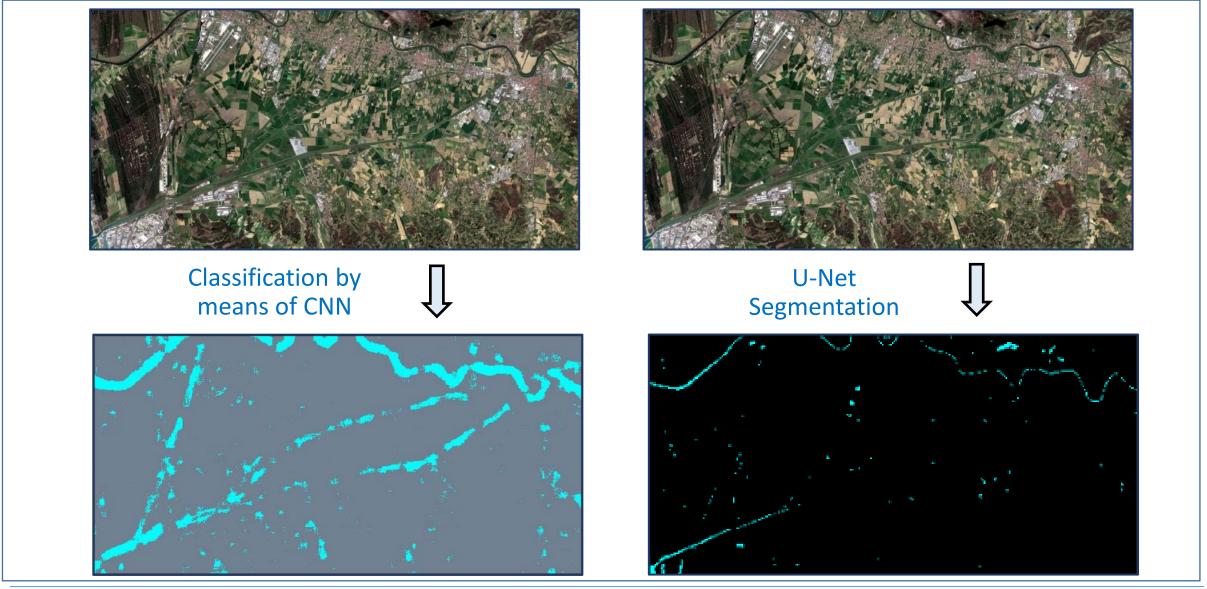


- The dataset creation to train the U-Net segmentation model was performed by exploting satellite pictures from River class by EuroSAT and data from the Copernicus High Resolution Layer.
- For each image we determined a label consisting in a mask keeping track of the class information for every pixel:
   0 means the pixel belongs to River class (black)
   1 means the pixel does not belong to River class (white)
- Main difference with the Standard (Classification) CNN
  Dataset: in classification, the class label refers to the whole
  image and not to each single pixel such as in segmentation
  stage.
- Final dataset: 1500 segmentartion masks validated.
- Implementation of a similar training dataset for *Highway* thanks to *Open Street Maps* data.

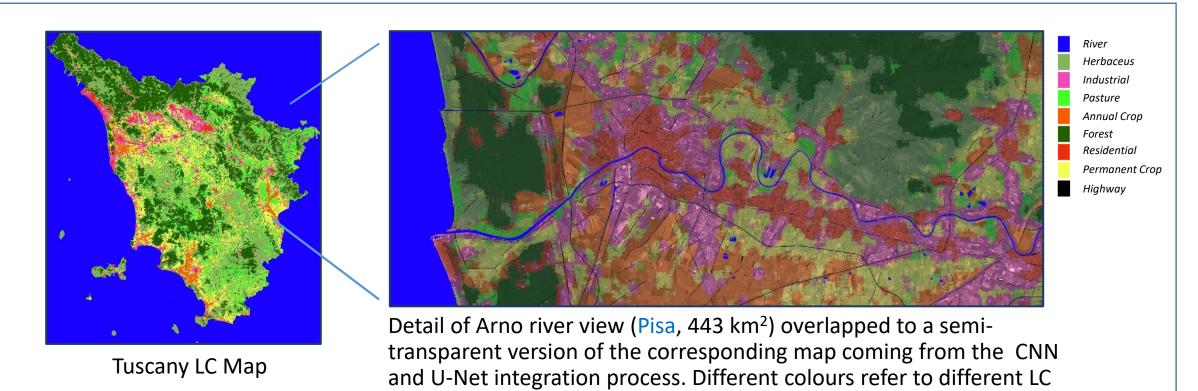
## **U-Net: Architecture**



## U-Net: adjustment of the over-estimation issue in "thread-like" classes such as River



## **Integrated Map CNN + U-Net**

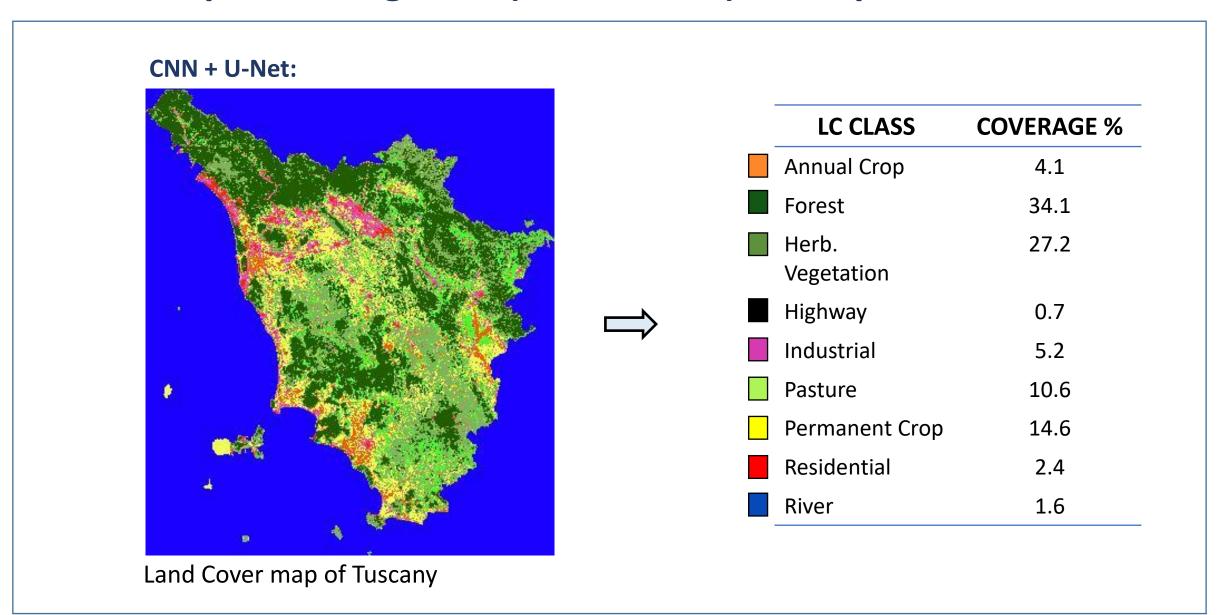


## Integrated system (CNN + U-Net) works perfectly with all the LC classes

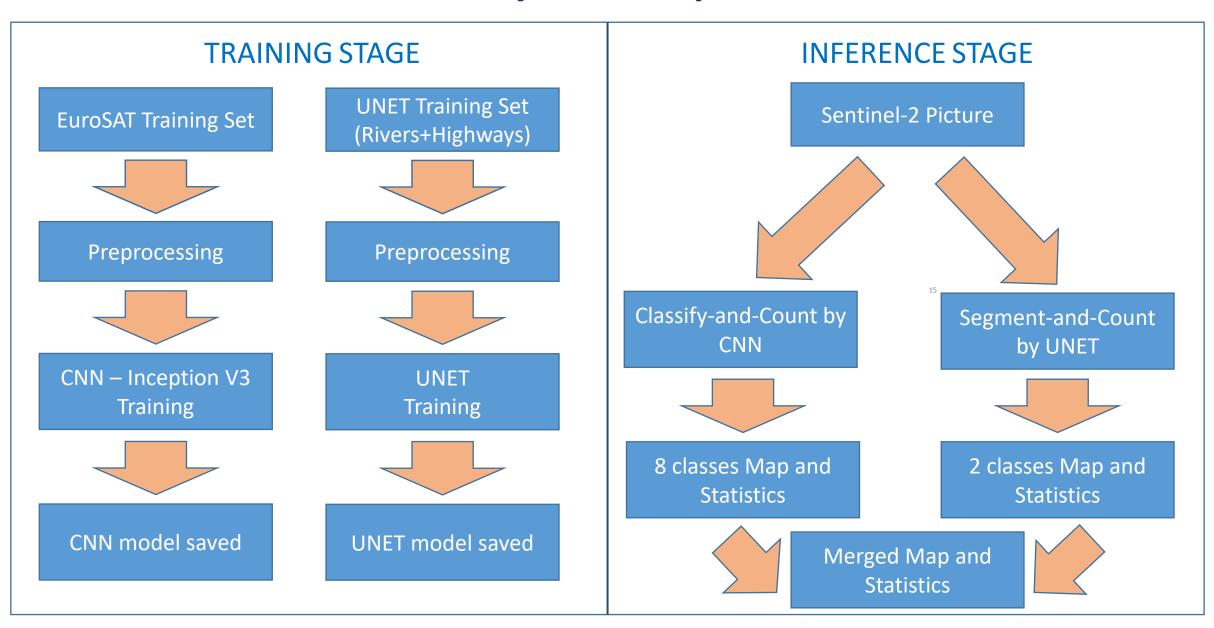
classes.

- U-Net predicts River and Highway.
- Whereas CNN classifies the other classes with are left over.

## **Example of integrated (CNN+U-Net) LC map and statistics**



## **Land Cover System – Pipeline Architecture**



## **References**

## **Azure Wishlist**

- 1) Hadoop and Spark to fasten pre-processing and post-processing with different cloud nodes
- 2) More GPUs like Tesla V100 or better to optimize Deep Neural Networks parallelization and speed up Training and Testing
- **3) Backup** systems to save data, models and code
- **4) Cognitive services** for Computer Vision and NLP tasks













# Thank you for your attention Francesco Pugliese