

# 2MAE404 MIMO control

## Homework report 7

(with later improvements)

Maciej Michałó

Marco Wijaya

December 2, 2022

## 1 Transmission Zeros, Zero-Pole Cancellation and Sigma Plots

### 1.1 Wind frequency resulting in highest amplitude

To compute the frequency resulting in the highest building vibration amplitude for a given amplitude of wind oscillations, a  $\sigma$  plot of the  $G(s)$  transfer matrix has been created. The MATLAB code is as following:

```
G11 = tf(-0.25,[1 0.2 0.25]);
G12 = tf(0.25,[1 0.2 0.25]);
G21 = tf(-1,[1 1]);
G22 = tf(-1,[1 1]);
G = [G11 G12; G21 G22]; % full transfer matrix

[sv, omega] = sigma(G); % sigma(omega) computation
[~, i_max] = max(sv(1,:)); % index of max singular value
sv_max = sv(1,i_max); % max singular value
omega_max = omega(i_max); % omega corresponding to max singular value
```

The  $\sigma$  plot is shown in Figure 1. The highest singular value is  $\sigma_{\max} = 11.15[\text{dB}] = 3.61[-]$  at a frequency of  $\omega = 0.48[\text{rad/s}]$ .

### 1.2 Wind direction resulting in highest amplitude

When analysing harmonic signals, it is useful to write them in complex form:

$$f(t) = A \sin(\omega t + \phi) = \text{Im}(Ae^{j(\omega t + \phi)}) \quad (1)$$

where  $A \in \mathbb{R}$  is the amplitude,  $\omega \in \mathbb{R}$  is the frequency in  $[\text{rad/s}]$  and  $\psi$  is the phase shift (w.r.t. a pure sine wave) in  $[\text{rad}]$ .

The whole complex signal  $\bar{f}(t)$  is used, rather than just the imaginary part, to exploit the properties of complex representation to the fullest:

$$\bar{f}(t) = Ae^{j(\omega t + \phi)} \quad (2)$$

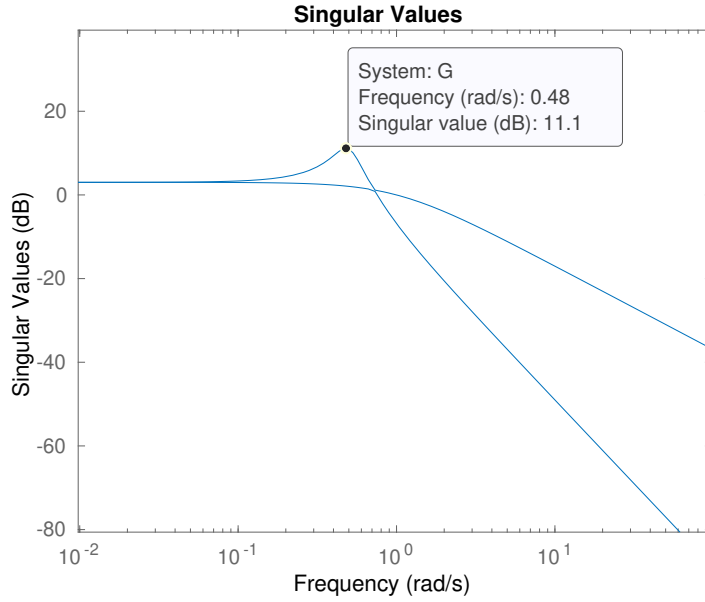


Figure 1:  $\sigma$  plot of  $G(s)$  with maximal singular value marked.

A complex signal can be conveniently described with a complex amplitude  $\hat{A}$ , encoding both amplitude and phase information:

$$\bar{f}(t) = Ae^{j(\omega t + \phi)} = Ae^{j\phi}e^{j\omega t} = \hat{A}e^{j\omega t} \quad (3)$$

The response  $y(t)$  of a SISO system to a sine input  $u(t)$  with a given frequency  $\omega$  is also a sine wave of frequency  $\omega$ , but with the amplitude scaled and phase shifted according to the transfer function of the system at the given frequency,  $F(j\omega)$ . For complex sine signals, this is especially easy to write down:

$$\bar{y}(t) = F(j\omega)\bar{u}(t) \quad (4)$$

Rewriting both signals in terms of complex amplitude results in:

$$\hat{y}e^{j\omega t} = F(j\omega)\hat{u}e^{j\omega t} \quad (5)$$

The time-dependent parts of the equation cancel out, therefore describing the input-output relationship purely in terms of complex amplitudes and the transfer function:

$$\hat{y} = F(j\omega)\hat{u} \quad (6)$$

The same holds for MIMO systems, including the one studied in this exercise. The relationship between the input  $u(t) = w(t)$  and output  $y(t) = p(t)$  is therefore, in expanded form:

$$\hat{y} = \begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \end{bmatrix} = \begin{bmatrix} G_{11}(j\omega) & G_{12}(j\omega) \\ G_{21}(j\omega) & G_{22}(j\omega) \end{bmatrix} \begin{bmatrix} \hat{u}_1 \\ \hat{u}_2 \end{bmatrix} = G(j\omega)\hat{u} \quad (7)$$

Note that  $G(j\omega)$  is simply a  $2 \times 2$  complex matrix and  $\hat{u}, \hat{y} \in \mathbb{C}^2$ . The most convenient way of finding the maximum amplitude is by performing an SVD on the  $G(j\omega)$  matrix:

$$G(j\omega) = U\Sigma V^* \quad (8)$$

where  $\Sigma$  is a diagonal matrix of singular values, while  $U$  and  $V^*$  are unitary complex matrices. The computation is performed in MATLAB:

```
Gjw = evalfr(G, omega_max*1j); % evaluate G(s) at s=j*omega
[U, S, V] = svd(Gjw); % perform SVD
```

The decomposition turned out to consist of matrices with the following structure:

$$G(j\omega) = \begin{bmatrix} e^{jv_1} & 0 \\ 0 & e^{jv_2} \end{bmatrix} \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} \quad (9)$$

The singular values are  $\sigma_1 = 3.61$  (just like in the  $\sigma$  plot) and  $\sigma_2 = 1.26$ , while  $v_1 = 1.78$  and  $v_2 = 2.69$  are phase shifts. The input-output relationship of the system can be rewritten as:

$$\hat{y} = U\Sigma V^* \hat{u} \quad (10)$$

Since the highest gain of the system is  $\sigma_1$ , the input  $\hat{u}$  should have the property of being multiplied only by  $\sigma_1$ . Since  $\Sigma$  is diagonal, this would suggest that  $V^* \hat{u}$  has a non-zero first component and a 0 in the second one. Expanding analytically the SVD formulation of the input-output relation makes this even more obvious:

$$\begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \end{bmatrix} = \begin{bmatrix} \sigma_1 e^{jv_1} (\hat{u}_1/\sqrt{2} - \hat{u}_2/\sqrt{2}) \\ \sigma_2 e^{jv_2} (\hat{u}_1/\sqrt{2} + \hat{u}_2/\sqrt{2}) \end{bmatrix} \quad (11)$$

Since  $\sigma_1$  only affects  $\hat{y}_1$ ,  $\hat{u}$  should be chosen in a way that results in  $\hat{y}_2 = 0$ . This is the case if the components of  $\hat{u}$  solve the equation:

$$\hat{u}_1/\sqrt{2} + \hat{u}_2/\sqrt{2} = 0 \quad (12)$$

This is obviously equivalent to  $\hat{u}_1 = -\hat{u}_2$ , implying wind blowing in the northwest-southeast axis. The  $\hat{u}$  vector has the form:

$$\hat{u} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} c \quad (13)$$

where  $c \in \mathbb{C}$  is an arbitrary non-zero complex constant. For the following computations,  $c = 1$  (meaning that  $\|\hat{u}\| = \sqrt{2}$ ) is assumed. The corresponding  $\hat{y}$  is computed in MATLAB:

```
u_hat = [-1; 1]; % input direction
y_hat = Gjw*u_hat; % output direction
```

The result is approximately:

$$\hat{y} = \begin{bmatrix} 1.0417 - 4.9957j \\ 0 \end{bmatrix} \quad (14)$$

The corresponding gain is:

$$\frac{\|\hat{y}\|}{\|\hat{u}\|} = 3.61 \quad (15)$$

This matches the singular value  $\sigma_1$ , therefore confirming the results of the computation.

### 1.3 Building vibration direction

As already noticed in the previous section, the highest oscillations of the building at the given wind frequency correspond to a situation where  $\hat{y}_2 = 0$ , what translates to oscillation purely in the east-west axis. This can be additionally shown by plotting  $y(t)$ :

```
t = linspace(0,2*pi/omega_max,100000); % sampled time over 1 period
y = imag(y_hat*exp(1j*omega_max*t)); % y(t)

p_mag = sqrt(y(1,:).^2 + y(2,:).^2); % |p(t)|
[~, i_max] = max(p_mag); % index of max |p(t)|

% phase plot of oscillation over one period
figure;
plot(y(1,:), y(2,:), 'DisplayName', 'p(t)');
hold on;
plot([-1 1]*y(1,i_max), [-1 1]*y(2,i_max), 'x', 'DisplayName', 'p_{max}');
xlabel('p_e [n]');
ylabel('p_n [m]');
legend();
grid("on");
hold off;
```

The resulting plot is shown in Figure 2. The amplitude is consistent with the previous computation.

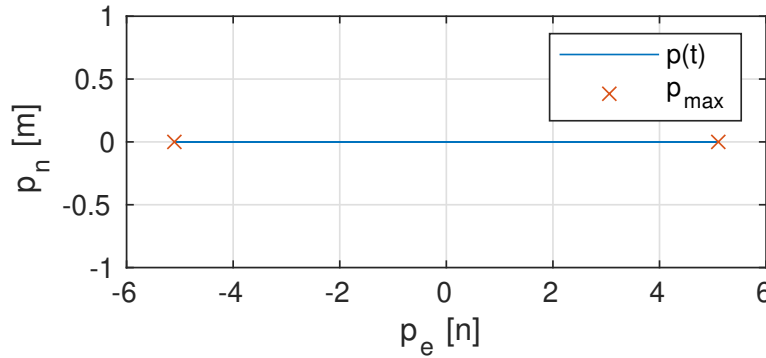


Figure 2: Parametric plot of the oscillation of  $p(t)$  over 1 period. Note that there is no oscillation in the north-south axis, just as predicted.

### 1.4 Drone minimum altitude

Suppose that the building is being subject to a wind oscillation:

$$w(t) = \begin{bmatrix} w_n(t) \\ w_e(t) \end{bmatrix} = \begin{bmatrix} 2 \cos(10\pi t) \\ 3 \sin(10\pi t) \end{bmatrix} \quad (16)$$

The minimum height  $h$  of the drone (to observe the oscillation using a camera with a  $60^\circ$  field of view) depends only on the maximum displacement of the tip of the building, i.e. on the maximum value of  $\|p(t)\|$ . The complex amplitude of the input signal is

$\hat{w} = [2e^{j\pi/2}, 3]^T$ , with the complex term in the first component encoding the phase of a cosine. Once again, the complex amplitudes of the oscillation can be computed using:

$$\hat{p} = G(j\omega)\hat{w} \quad (17)$$

This is performed using the following MATLAB code:

```
omega = 10*pi; % frequency [rad/s]
Gjw = evalfr(G, 1j*omega) % G(j*omega)
w_hat = [2*exp(1j*pi/2); 3]; % complex amplitude of w
p_hat = Gjw*w_hat; % complex amplitude of p
```

The maximum amplitude is (note that the computation must include the complex amplitudes, rather than their magnitudes, because the 2 axes are not in phase, and therefore achieve their peaks at different times):

$$\max ||p(t)|| = ||\hat{p}|| = 0.1147 \quad (18)$$

The obtained maximum displacement corresponds to an altitude:

$$h_{min} = \frac{||p||_{max}}{\tan(30^\circ)} = \frac{0.1147}{0.577} = 0.1987 \quad (19)$$

Hence, the drone should be at least  $h_{min} = 0.1987[m]$  above the top of the building.