

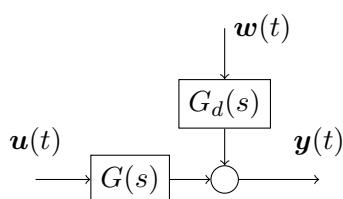
#### HW4: LINEAR SYSTEMS DESCRIPTIONS

##### Exercise 1 (Frequency Domain Models)

This exercise is part of a series of activities leading to the implementation of an interactive MIMO control law for the **Flying-Chardonnay**, an automatic drink delivery device. This exercise exploits the MATLAB model implemented previously, and follows the following configuration its parameters (in S.I. units):

$$\overline{m_d = 1 \quad m_c = 1 \quad l = 1 \quad l_d = 1 \quad J = 1 \quad C_D = 0.01 \quad g = 10}$$

1. **(5pts)** Using the hovering linear state-space model approximation computed in the previous exercise, find the system transfer matrix  $G(s)$ , assuming full-state output, i.e.,  $\mathbf{y}(t) = \mathbf{x}(t)$ .
2. **(5pts)** Compute the disturbance transfer matrix  $G_d(s)$ , assuming the disturbance architecture below.



##### Exercise 2 (Linear Model Representations)

Consider the following state-space system:

$$\dot{\mathbf{x}} = \begin{bmatrix} 5 & -3 & 2 \\ 15 & -9 & 6 \\ 10 & -6 & 4 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -1 & 0 \end{bmatrix} \mathbf{u} \quad (1)$$

$$\mathbf{y} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \mathbf{u} \quad (2)$$

where  $\mathbf{x} \in \mathbb{R}^3$ ,  $\mathbf{u} \in \mathbb{R}^2$  and  $\mathbf{y} \in \mathbb{R}^2$ . Unless otherwise stated, answer the following questions **by hand**.

1. **(2pts)** Find the equivalent Impulse Matrix  $H(t)$  description.
2. **(2pts)** Find the equivalent Markov Parameters  $H_k$  description.
3. **(2pts)** Find the equivalent Transfer Matrix  $H(s)$  description.
4. **(2pts)** Using the MATLAB command `tf(ss(A,B,C,D))`, compute the equivalent Transfer Matrix  $H(s)$  description. How does this compare with the one computed by hand?

##### Exercise 3 (Noncommutative Property of MIMO Systems)

Consider the following transfer matrices:

$$G_1(s) = \begin{bmatrix} 0 & \frac{-1}{s} \\ 0 & \frac{2}{s} \end{bmatrix} \quad G_2(s) = \begin{bmatrix} \frac{3}{s} & \frac{5}{s} \\ 0 & 0 \end{bmatrix} \quad (3)$$

1. **(1pts)** Compute  $G_1(s)G_2(s)$  and  $G_2(s)G_1(s)$ . Is  $G_1(s)G_2(s) = G_2(s)G_1(s)$ ?
2. **(1pts)** Based on that, could one interchange the arrangement of the blocks in a series connection block diagram? What about in a parallel connection diagram?