

2. Controlling Cars on a Bridge

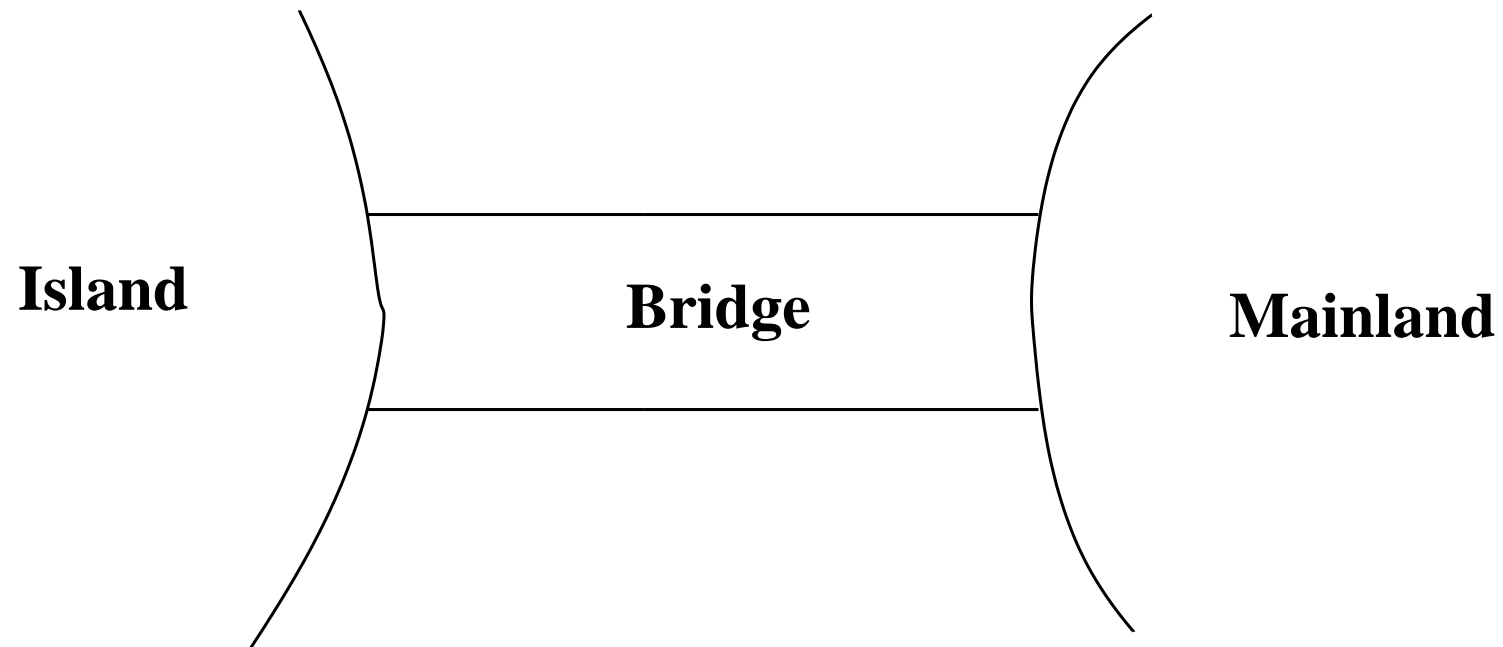
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2009

- The system we are going to build is a **piece of software** connected to some **equipment**.
- There are two kinds of requirements:
 - those concerned with the **equipment**, labeled **EQP**,
 - those concerned with the **function** of the system, labeled **FUN**.
- The function of this system is to **control cars** on a **narrow bridge**.
- This bridge is supposed to link the **mainland** to a small **island**.

The system is controlling cars on a bridge between the mainland and an island	FUN-1
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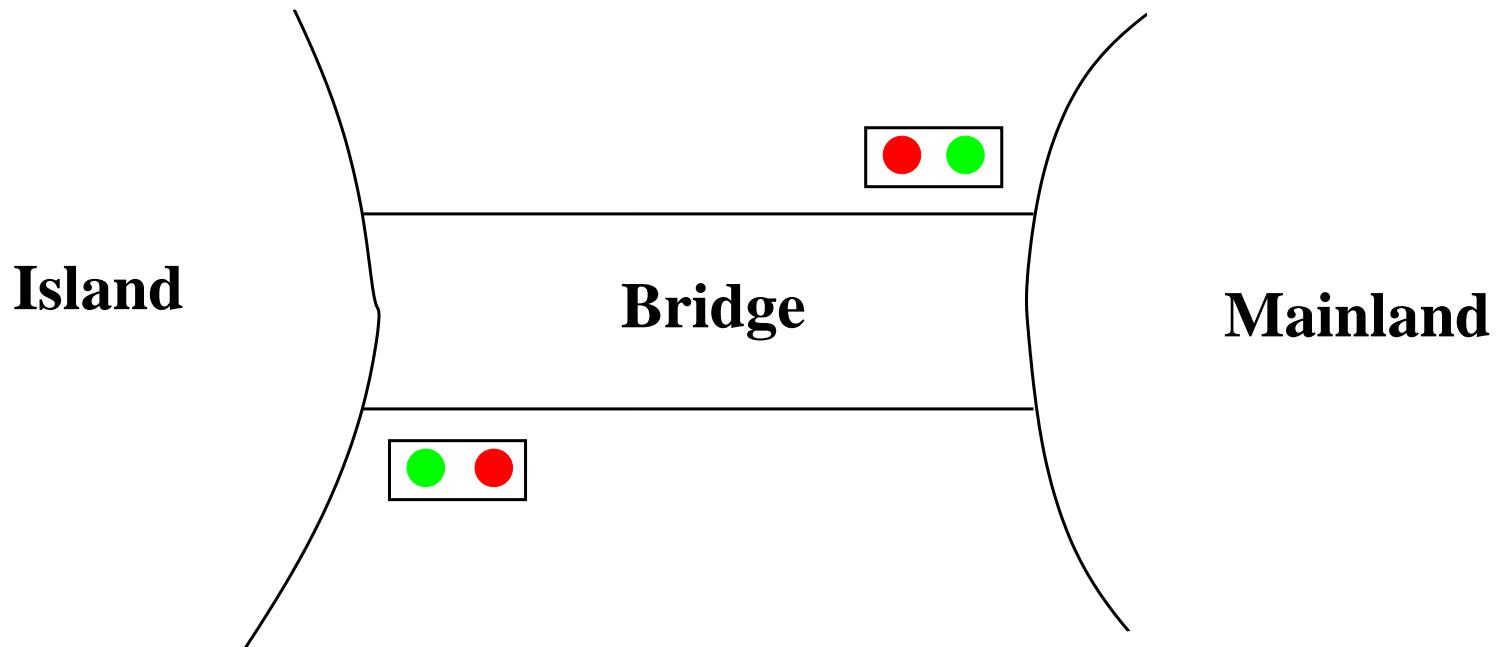
- This can be illustrated as follows



- The controller is equipped with two traffic lights with two colors.

The system has two traffic lights with two colors: green and red	EQP-1
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- One of the traffic lights is situated on the mainland and the other one on the island. Both are close to the bridge.
- This can be illustrated as follows



The traffic lights control the entrance to the bridge at both ends of it

EQP-2

- Drivers are supposed to obey the traffic light by not passing when a traffic light is red.

Cars are not supposed to pass on a red traffic light, only on a green one

EQP-3

- There are also some car sensors situated at both ends of the bridge.
- These sensors are supposed to detect the presence of cars intending to enter or leave the bridge.
- There are four such sensors. Two of them are situated on the bridge and the other two are situated on the mainland and on the island.

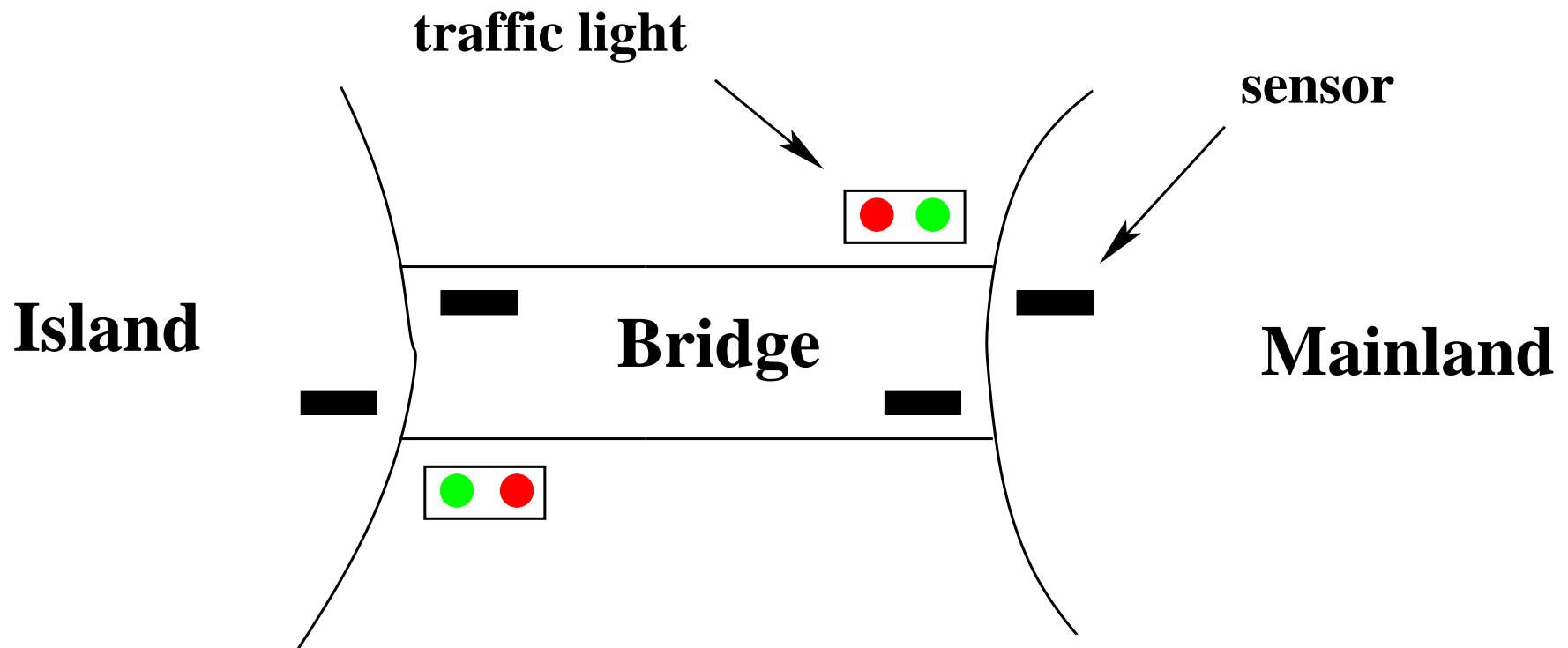
The system is equipped with four car sensors each with two states: on or off

EQP-4

The sensors are used to detect the presence of cars entering or leaving the bridge

EQP-5

- The pieces of equipment can be illustrated as follows:



- This system has two main constraints: the number of cars on the bridge and the island is limited and the bridge is one way.

The number of cars on the bridge and the island is limited

FUN-2

The bridge is one way or the other, not both at the same time

FUN-3

The system is controlling cars on a bridge between the mainland and an island

FUN-1

The number of cars on the bridge and the island is limited

FUN-2

The bridge is one way or the other, not both at the same time

FUN-3

The system has two traffic lights with two colors: green and red

EQP-1

The traffic lights control the entrance to the bridge at both ends of it

EQP-2

Cars are not supposed to pass on a red traffic light, only on a green one

EQP-3

The system is equipped with four car sensors each with two states: on or off

EQP-4

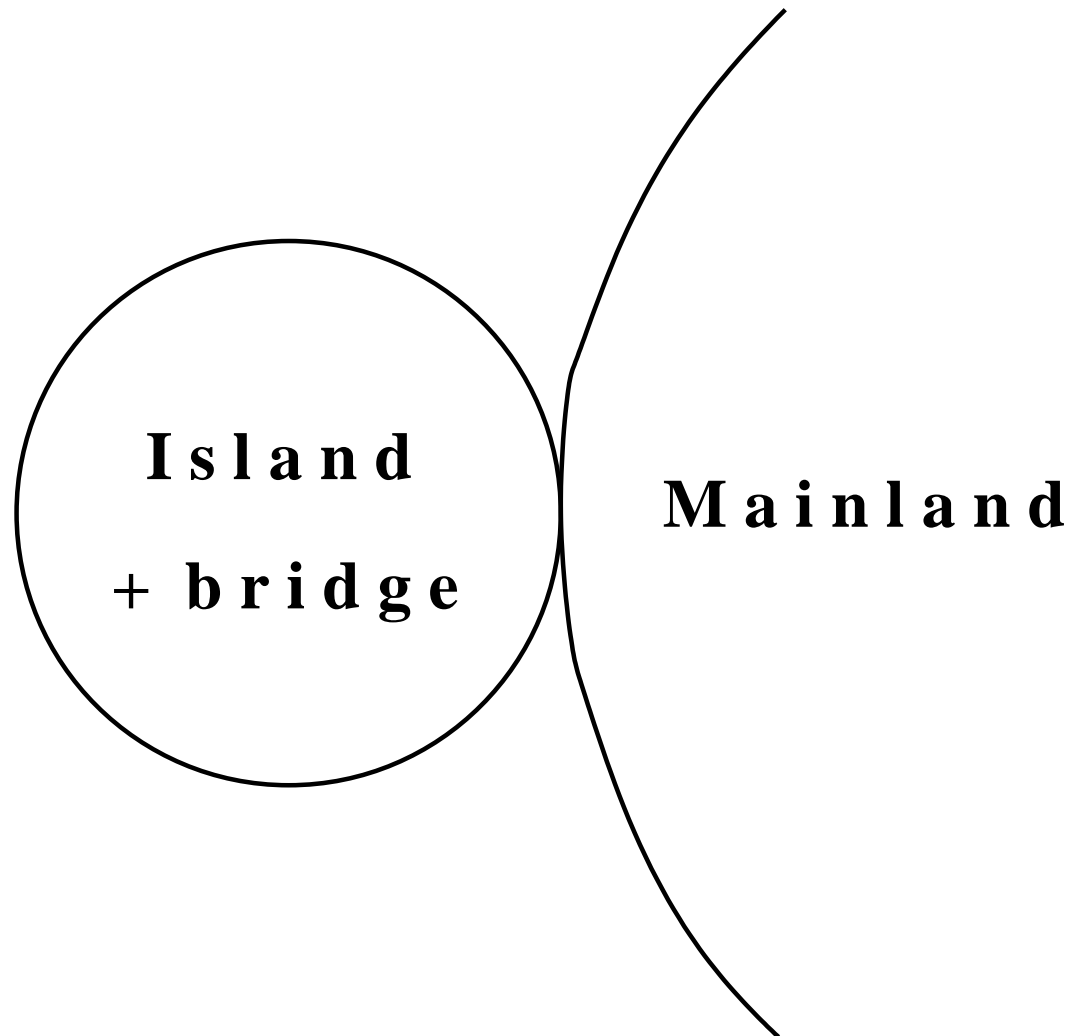
The sensors are used to detect the presence of cars entering or leaving the bridge

EQP-5

- **Initial model**: Limiting the number of cars (FUN-2)
- **First refinement**: Introducing the one way bridge (FUN-3)
- **Second refinement**: Introducing the traffic lights (EQP-1,2,3)
- **Third refinement**: Introducing the sensors (EQP-4,5)

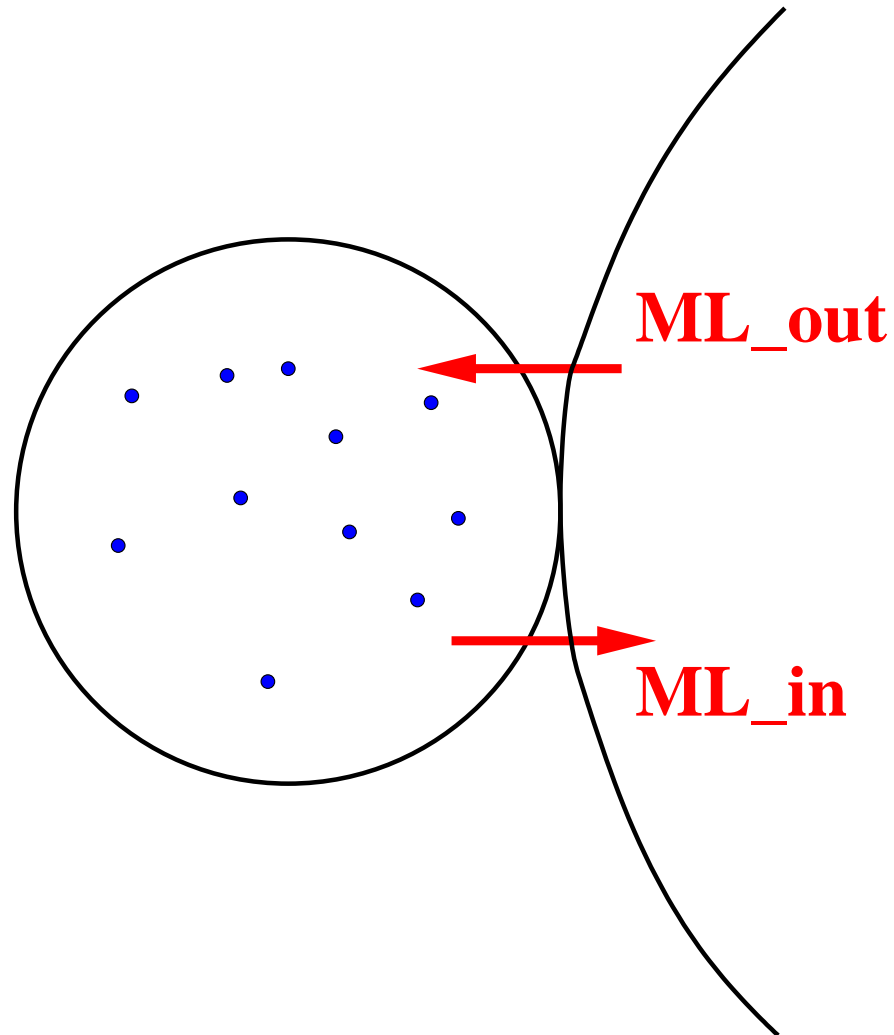
- **Initial model**: Limiting the number of cars (FUN-2)
- **First refinement**: Introducing the one-way bridge (FUN-3)
- **Second refinement**: Introducing the traffic lights (EQP-1,2,3)
- **Third refinement**: Introducing the sensors (EQP-4,5)

- It is **very simple**
- We completely ignore the equipment: traffic lights and sensors
- We do not even consider the bridge
- We are just interested in the **pair “island-bridge”**
- We are focusing **FUN-2**: limited number of cars on island-bridge



Two Events that may be Observed

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- **STATIC PART** of the state: **constant** d with **axiom** **axm0_1**

constant: d

axm0_1: $d \in \mathbb{N}$

- d is the **maximum number of cars** allowed on the Island-Bridge
- **axm0_1** states that d is a **natural number**
- Constant d is a member of the set $\mathbb{N} = \{0, 1, 2, , \dots\}$

- **DYNAMIC PART**: variable v with invariants **inv0_1** and **inv0_2**

variable: n

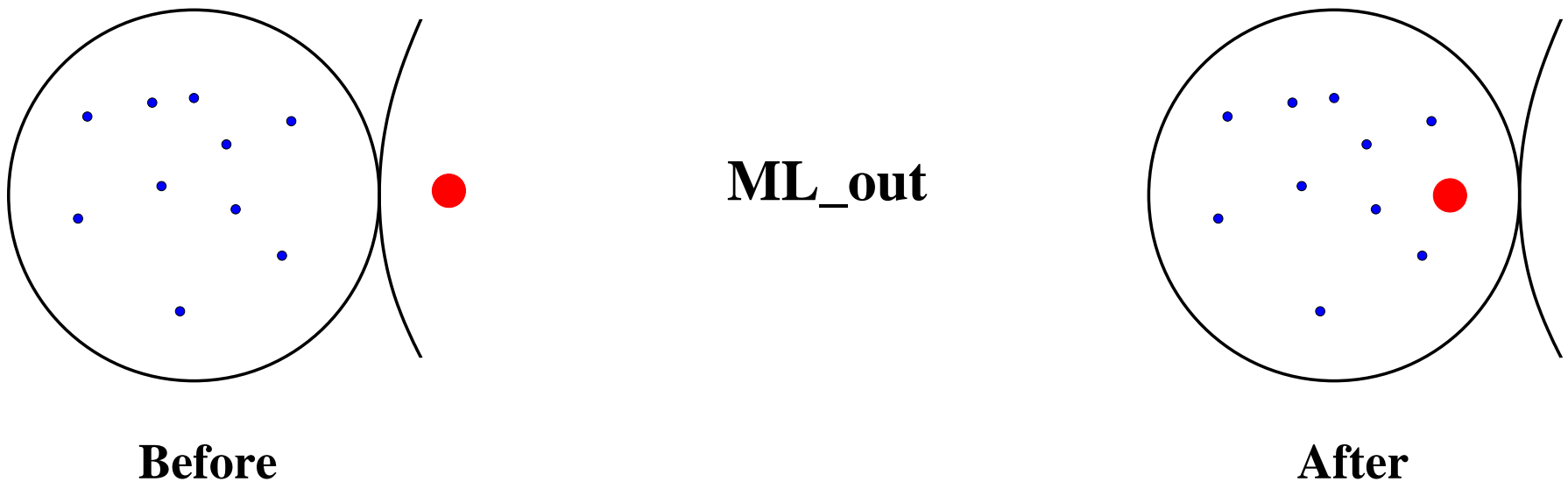
inv0_1: $n \in \mathbb{N}$

inv0_2: $n \leq d$

- n is the **effective number of cars** on the Island-Bridge
- n is a natural number (**inv0_1**)
- n is always smaller than or equal to d (**inv0_2**): this is **FUN_2**

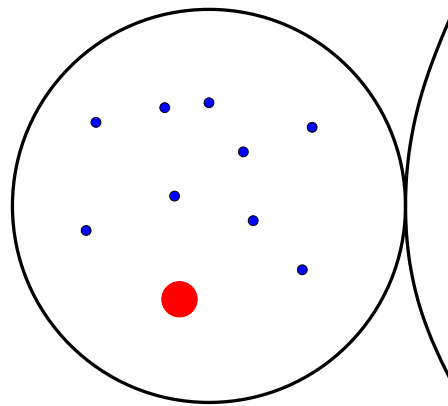
- Labels **axm0_1**, **inv0_1**, ... are chosen **systematically**
- The label **axm** or **inv** recalls the **purpose**:
axiom of constants or **invariant** of variables
- The **0** as in **inv0_1** stands for the initial model.
- Later we will have **inv1_1** for an invariant of refinement **1**, etc.
- The **1** like in **inv0_1** is a serial number
- Any convention is **valid** as long as it is **systematic**

- This is the **first transition** (or event) that can be **observed**
- A car is leaving the mainland and entering the Island-Bridge



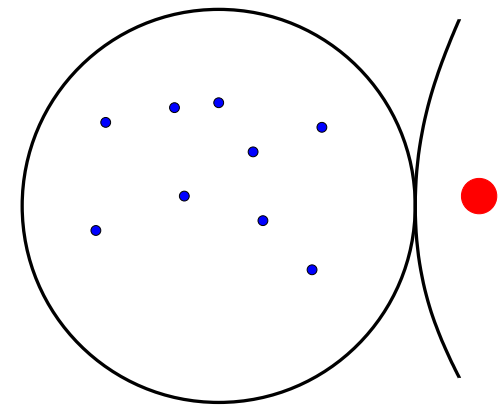
- The **number of cars** in the Island-Bridge is **incremented**

- We can also observe a **second transition** (or event)
- A car leaving the Island-Bridge and re-entering the mainland



Before

ML_in



After

- The **number of cars** in the Island-Bridge is **decremented**

- Event ML_out **increments** the number of cars

ML_out
 $n := n + 1$

- Event ML_in **decrements** the number of cars

ML_in
 $n := n - 1$

- An event is denoted by its **name** and its **action** (an assignment)

These events are approximations for **two reasons**:

1. They might be **refined** (made more precise) later
2. They might be **insufficient** at this stage because **not consistent with the invariant**

We have to perform a **proof** in order to **verify this consistency**.

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- An invariant is a **constraint** on the allowed values of the variables
 - An invariant **must hold on all reachable states** of a model
 - To verify that this holds we must show that
 1. the invariant holds for **initial states** (**later**), and
 2. the invariant is **preserved by all events** (**following slides**)
 - We will formalize these two statements as **proof obligations (POs)**
 - We need a **rigorous proof** showing that these POs indeed hold

ML_out

when

$n < d$

then

$n := n + 1$

end

ML_in

when

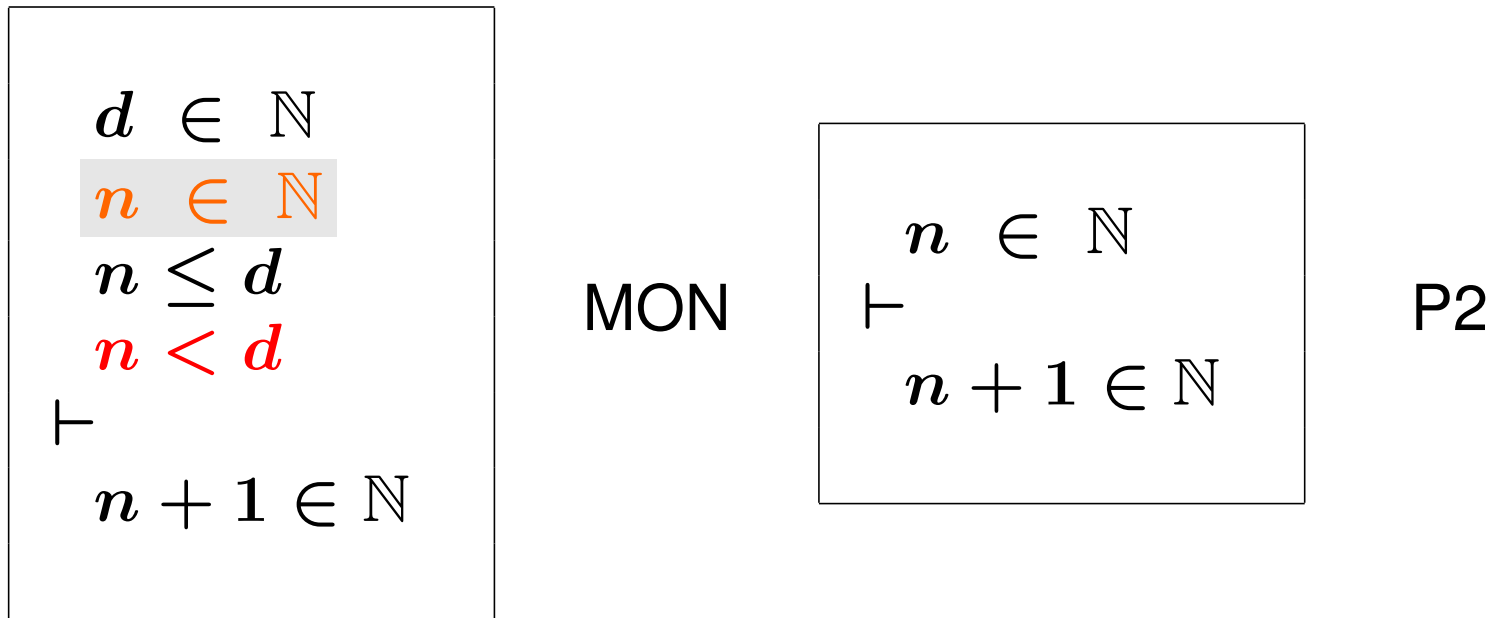
$0 < n$

then

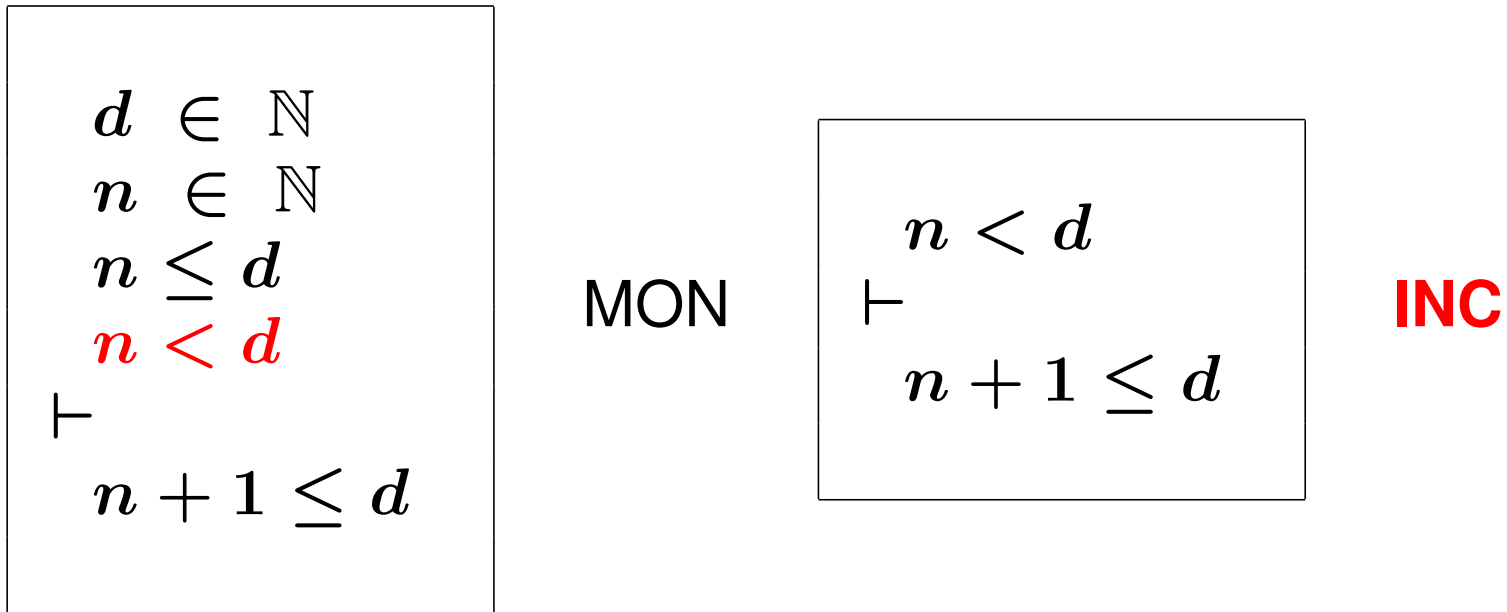
$n := n - 1$

end

- We are adding **guards** to the events
- The guard is the **necessary condition** for an event to “occur”



- Adding new assumptions to a sequent **does not affect its provability**



- Now we can conclude the proof using rule **INC**

$\frac{n < m \quad \vdash \quad n + 1 \leq m}{\text{INC}}$
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- It is possible for the system to be blocked if both guards are false
- We do not want this to happen
- We figure out that one important requirement was missing

Once started, the system should work for ever

FUN-4

- Given c with axioms $A(c)$ and v with invariants $I(c, v)$
- Given the guards $G_1(c, v), \dots, G_m(c, v)$ of the events
- We have to prove the following:

$\begin{array}{l} A(c) \\ I(c, v) \\ \vdash \\ G_1(c, v) \vee \dots \vee G_m(c, v) \end{array}$	DLF
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- If d is equal to 0, then no car can ever enter the Island-Bridge

$$\text{axm0_2: } 0 < d$$

constant: d

variable: n

axm0_1: $d \in \mathbb{N}$

axm0_2: $d > 0$

inv0_1: $n \in \mathbb{N}$

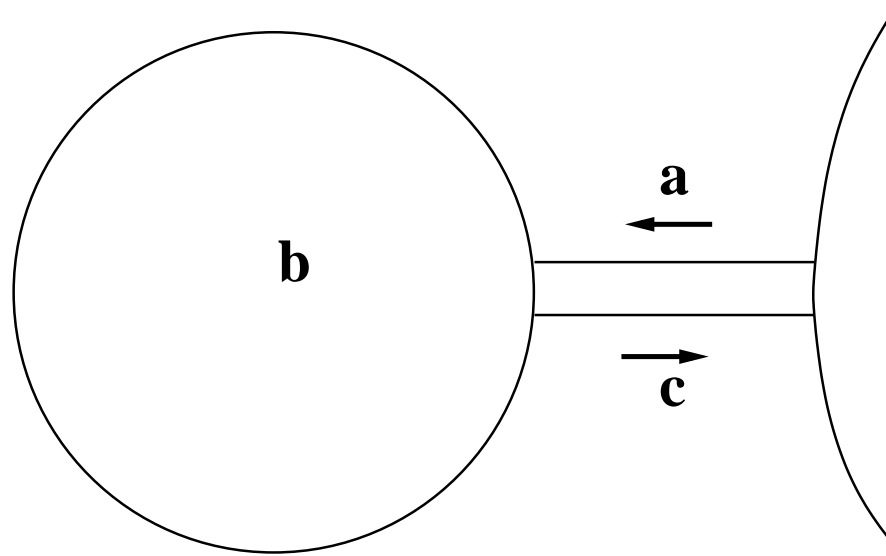
inv0_2: $n \leq d$

init
 $n := 0$

ML_out
when
 $n < d$
then
 $n := n + 1$
end

ML_in
when
 $0 < n$
then
 $n := n - 1$
end

- **Initial model**: Limiting the number of cars (FUN-2)
- **First refinement**: Introducing the one way bridge (FUN-3)
- **Second refinement**: Introducing the traffic lights (EQP-1,2,3)
- **Third refinement**: Introducing the sensors (EQP-4,5)



- a denotes the number of cars on bridge going to island
- b denotes the number of cars on island
- c denotes the number of cars on bridge going to mainland
- a , b , and c are the concrete variables
- They replace the abstract variable n

constants: d

variables: a, b, c

inv1_1: $a \in \mathbb{N}$

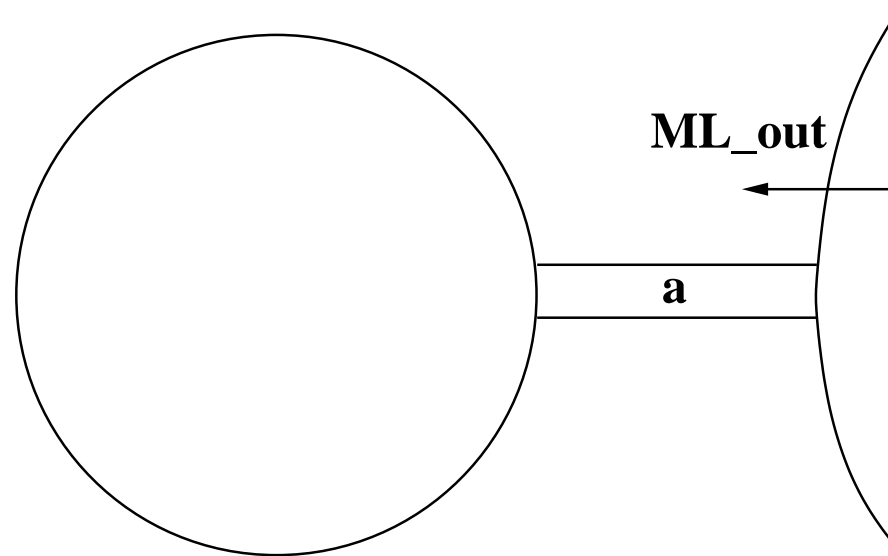
inv1_2: $b \in \mathbb{N}$

inv1_3: $c \in \mathbb{N}$

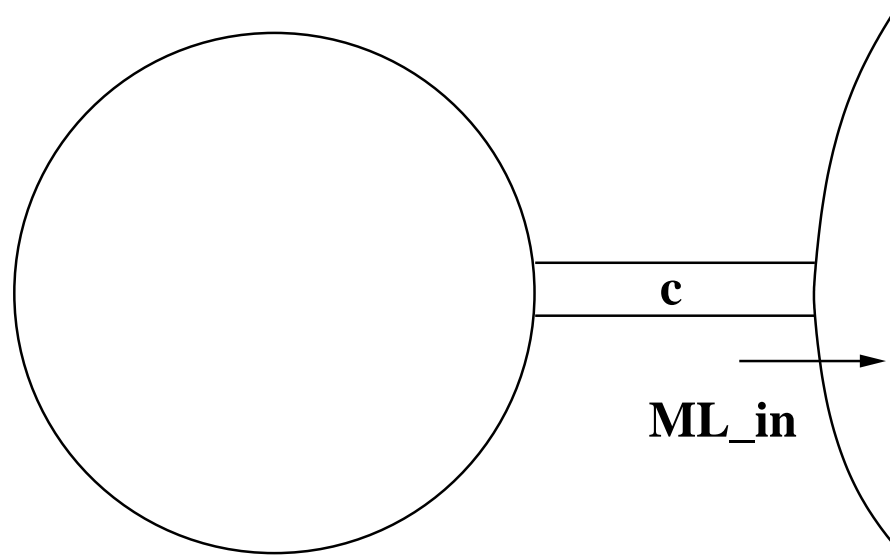
inv1_4: $a + b + c = n$

inv1_5: $a = 0 \vee c = 0$

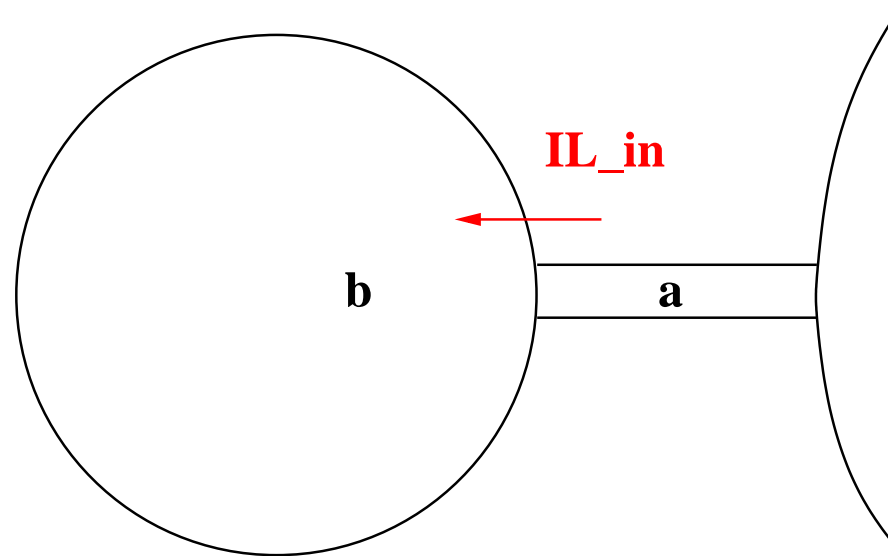
- Invariants **inv1_1** to **inv1_5** are called the **concrete invariants**
- **inv1_4** glues the abstract state, n , to the **concrete state**, a, b, c



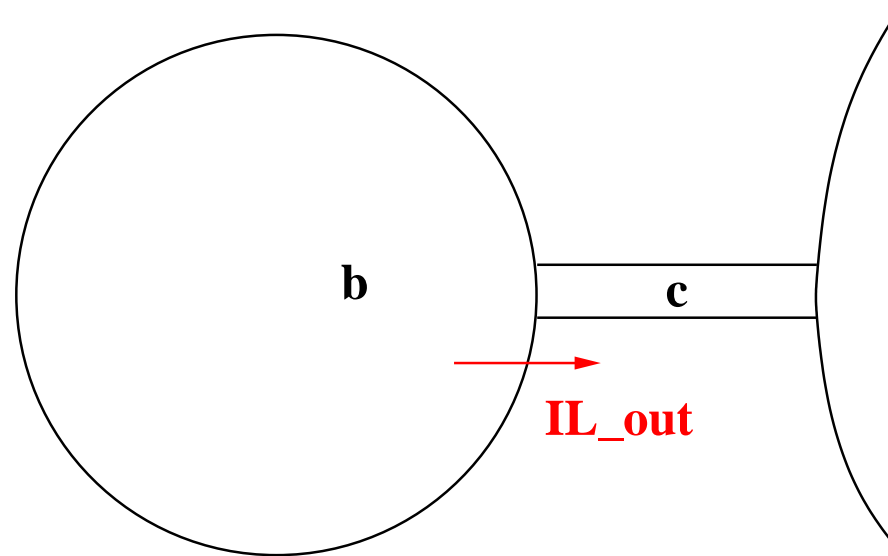
```
ML_out
  when
     $a + b < d$ 
     $c = 0$ 
  then
     $a := a + 1$ 
  end
```



```
ML_in  
  when  
     $0 < c$   
  then  
     $c := c - 1$   
  end
```



```
IL_in
  when
     $0 < a$ 
  then
     $a := a - 1$ 
     $b := b + 1$ 
  end
```



```
IL_out
  when
     $0 < b$ 
     $a = 0$ 
  then
     $b := b - 1$ 
     $c := c + 1$ 
  end
```

constants: d

variables: a, b, c

inv1_1: $a \in \mathbb{N}$

inv1_2: $b \in \mathbb{N}$

inv1_3: $c \in \mathbb{N}$

inv1_4: $a + b + c = n$

inv1_5: $a = 0 \vee c = 0$

variant1: $2 * a + b$

init

$a := 0$

$b := 0$

$c := 0$

ML_in

when

$0 < c$

then

$c := c - 1$

end

ML_out

when

$a + b < d$

$c = 0$

then

$a := a + 1$

end

IL_in

when

$0 < a$

then

$a := a - 1$

$b := b + 1$

end

IL_out

when

$0 < b$

$a = 0$

then

$b := b - 1$

$c := c + 1$

end

```
(abstract_)ML_out  
  when  
     $n < d$   
  then  
     $n := n + 1$   
  end
```

```
(concrete_)ML_out  
  when  
     $a + b < d$   
     $c = 0$   
  then  
     $a := a + 1$   
  end
```

- The concrete version is **not contradictory** with the abstract one
- When the **concrete version is enabled** then **so is the abstract one**
- **Executions** seem to be **compatible**

axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5

Concrete guards of ML_out

⊢

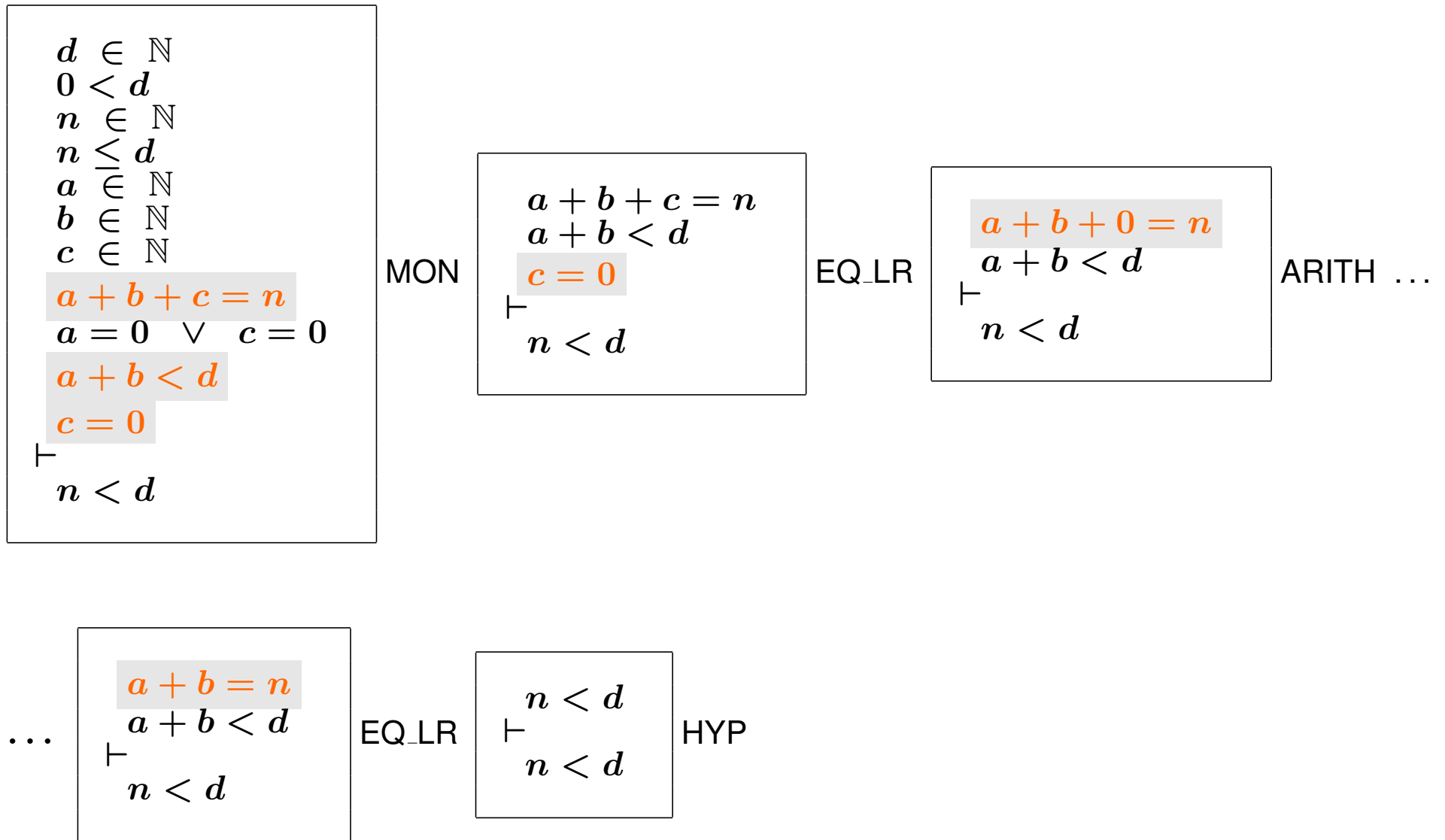
Abstract guard of ML_out

$d \in \mathbb{N}$
 $0 < d$
 $n \in \mathbb{N}$
 $n \leq d$
 $a \in \mathbb{N}$
 $b \in \mathbb{N}$
 $c \in \mathbb{N}$
 $a + b + c = n$
 $a = 0 \vee c = 0$
 $a + b < d$
 $c = 0$
⊢
 $n < d$

ML_out / GRD

(abstract-)ML_out
when
 $n < d$
then
 $n := n + 1$
end

(concrete-)ML_out
when
 $a + b < d$
 $c = 0$
then
 $a := a + 1$
end



The "rule" name ARITH stands for **simple arithmetic simplifications**.