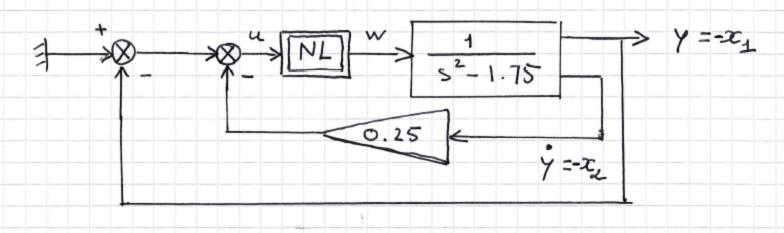
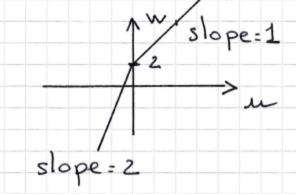
FXERCISE |

Consider the following system:



where the nonlinearity is given by:



Objectives =

- . Plot de phase portrait (x1, x2)
- . Characterize the stability domain.