

OPTIMISING STATIC PROGRAM ANALYSIS USING SCALA NATIVE

Abdullah Sabaa Allil

May 31, 2023

Promotor: Prof. Dr. Coen De Roover

Advisors: Noah Van Es, Jens Van der Plas and Bram Vandenbogaerde

sciences and bioengineering sciences

Abstract

Analyzing programs using static analysis tools might not always be as fast as the programmer expects it to be. In this dissertation, we investigate some possibilities to optimise analyses created in MAF ("Modular Analysis Framework") by rewriting some performance-critical parts of MAF in a low-level implementation. Profiling has pointed out that abstract domains are a good candidate for optimisation. We present a low-level implementation for an abstract domain, supported by a domain-specific memory manager that is responsible for garbage collection during the analysis.

Contents

1	Intr	roduction	1
2	Bac	ekground	2
	2.1	Static Analysis	2
		2.1.1 Abstract Domain	2
		2.1.2 Join Semilattice	2
	2.2	Modular Static Analysis	3
		2.2.1 Intra-Component Analysis	3
		2.2.2 Inter-Component Analysis	3
	2.3	Modular Analysis Framework	4
		2.3.1 ModAnalysis	4
		2.3.2 IntraAnalysis	4
		2.3.3 GlobalStore and ReturnValue	5
		2.3.4 SequentialWorkListAlgortihm	5
		2.3.5 AbstractDomain and Lattice	6
			6
		2.3.7 Core Lattices of MAF	6
		2.3.8 ConstantPropagationlattice	7
		2.3.9 ModularSchemeLattice and Value	8
	2.4	Abstract Domains as a Candidate for Optimisation	8
	2.5	Scala Native	9
		2.5.1 Scala Native Memory Management	9
		2.5.2 Features of Scala Native	0
		2.5.3 Scala Native Configurations	1
		2.5.4 MAF Cross-compilation using Scala Native	2
3	Ove	erview of the Native Lattice	3
	3.1	BoolLattice	3
	3.2	IntLattice and RealLattice	_
	3.3	NativeString	
	3.4	StringLattice and SymbolLattice	
	3.5	CharLattice	
	3.6	Alternative Implementations for Some Lattices	
		3.6.1 StringLattice and SymbolLattice	
		3.6.2 BoolLattice	

iv CONTENTS

4	Domain-Specific Memory Management	22
	4.1 Idea and Pseudocode	22
	4.2 Example	25
	4.3 Implementation	26
	4.3.1 NativeString	26
	4.3.2 The GC and IntraGC Trait	27
	4.3.3 The NativeGC Trait	29
5	Implemenation Validation	30
	5.1 Testing the Native Lattice Implementation	30
	5.2 Testing and Debugging Memory Management	30
6	Performance Evaluation	32
	6.1 Implementation Details	32
	6.2 Benchmarking Methodology	33
	6.3 Results	35
	6.4 Comparing Relative Analysis Times	35
7	Conclusion	41
	7.1 Future Work	41

Chapter 1

Introduction

Static program analysis helps programmers reason about the correctness and the behaviour of their programs without executing them. In some cases, analyzing a program could take several minutes, or even hours, which becomes an inconvenience for the programmer. Static analysis needs to provide the programmer with results within a relatively reasonable time in order to be deemed valuable.

MAF ("Modular Analysis Framework") is a framework in which modular static analyses can be created. The framework is implemented in Scala. Therefore, analyses that are created in MAF are, by default, compiled to Java bytecode, which means that they run on a Java Virtual Machine.

The goal of this dissertation is to investigate the possibilities to improve the performance of modular analyses created in MAF by rewriting some performance-critical parts of the framework in an optimised, low-level implementation. An analysis uses for example lattices to represent values and operations in the analyzed programs. Rewriting the lattices in low-level code might improve the performance of the analysis, given that their values and operations are very frequently used in the analysis, since they form the building blocks of that analysis. Profiling analyses helped us identify that a significant amount of time of an analysis is spent in the implementation of lattices. Therefore, optimising this implementation might have the most noticeable performance gain.

Since the framework is written in Scala, Scala Native can be used for this purpose. Using Scala Native, Scala code gets compiled to native code that runs natively on the machine. Scala Native also offers features for integrating low-level constructs, such as C types and manual memory management, directly into Scala, which can be used for the low-level implementation.

This dissertation makes the following contributions:

- We present a low-level implementation for the constant propagation abstract domain for the function-modular analysis of Scheme programs that is created in MAF.
- We present a domain-specific approach for managing the memory of the low-level abstract domain elements by using specific properties of the analysis, allowing elements to be efficiently deallocated.
- We evaluate the performance of the low-level abstract domain and the memory manager and compare it with several implementations, including one that runs on a Java Virtual Machine.

Before describing the implementation of the abstract domain, we explain the background needed to grasp the concepts of this dissertation.

Chapter 2

Background

2.1 Static Analysis

Static program analysis aims at reasoning about the runtime behaviour of a program without executing that program. This behaviour can be for example reaching an error state such as a buffer overflow, where a program writes outside the bounds of an array [11].

2.1.1 Abstract Domain

Static program analysis does not usually work with concrete values due to uncomputability [10, 11]. It is impossible to reason about all the states that a program can reach during its execution. For instance, if a program takes an integer as input, testing input values would require considering all possible input values, which include all possible integers, as well as all possible strings, real numbers, etc. Therefore, static program analysis uses an abstract representation for the values that are used in a program. In the context of the example of the integer input, the input could be represented using 4 types of abstract elements: an element that represents all positive integers, an element that represents all integers (i.e., positive or negative integers), and an element that represents non-integer values. This is called an abstract domain. An abstract domain is a set of abstract values that are used to represent concrete values with common properties.

2.1.2 Join Semilattice

In abstract domains, abstract values are usually represented using join semilattices [8]. A join semilattice is a partially ordered set with a least upper bound for each two elements of that set, which means that each two elements can be joined together using a join operator [3]. The join operator joins two elements of the lattice and produces the least upper bound. That is the "smallest" upper bound of two elements in that lattice. In the context of the example in Section 2.1.1, a lattice can be used to represent the abstract elements of that abstract domain. Joining the element representing all positive integers and the element representing all negative integers results in the element that represents all integers. In static analysis, the join operator is used in order to combine results obtained from analyzing different states of the program, which allows the analysis to produce more accurate information on the program's behaviour [8].

A lattice has a top element and a bottom element. A top element usually represents an element that does not have any useful information, such as the element that represents all

integers in our previous example. A bottom element usually represents a contradictory element to that set [4]. In our previous example, the element that represents all non-integer values would be the bottom element. In the context of static analysis, a bottom element usually represents the set of program states that are unreachable during the analysis of that program. For example, this could be an input argument of a different type than the required input type [8].

A Hasse diagram can be used to represent the lattice elements and their relationships with one another [4]. Figure 2.1 shows an example of such diagrams. This diagram represents the elements of the example in Section 2.1.1. The top element is represented by \top and the bottom element is represented by \bot . The element that represents all positive integers is represented in this Hasse diagram by +, and the element that represents all negative integers is represented by -

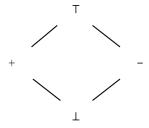


Figure 2.1: An example of a Hasse diagram.

2.2 Modular Static Analysis

Modular static analysis analyzes a program by dividing it into components and analyzing each component in isolation from the other components [2, 14]. These components can be for example modules, classes, or function calls. The analysis combines the results of analyzing the components in order to produce results for the whole program. The function-modular analysis is an example of modular static analysis. In function-modular analyses, components are function calls.

A modular static analysis consists of two parts: Intra-component analysis, and inter-component analysis. In the following subsections, both analyses are explained.

2.2.1 Intra-Component Analysis

An intra-component analysis analyzes a single component in isolation from the other components. Components can also depend on other components, however. A function may call another function in its body. Therefore, an intra-component analysis also keeps track of dependencies that it encounters during the analysis, in order to register them at the end of the intra-component analysis to the global analysis state.

2.2.2 Inter-Component Analysis

The inter-component analysis is responsible for keeping track of the components that need to be analyzed. These components are stored in a worklist. The inter-component analysis is also responsible for deciding which component needs to be analyzed first by an intra-component

analysis. For example, using a Last-In-First-Out worklist algorithm, the most recently added component to the worklist will be the first component to be analyzed by an intra-component analysis.

The inter-component analysis also stores the global analysis state, which consists of results of analyzing components by an intra-component analysis, and results of combining results of analyzed components. The inter-component analysis keeps track of components that have a dependency on parts of the global analysis state.

2.3 Modular Analysis Framework

MAF is a framework in which modular static analyses can be created for higher-order languages [14]. ModF is an example of such analyses. ModF is a function-modular analysis for Scheme created in MAF. This dissertation aims at optimising analyses created by this framework. Specifically, this dissertation attempts at optimising ModF in MAF. In this section, the main components of MAF and ModF are explained.

2.3.1 ModAnalysis

ModAnalysis is the base class of all modular analyses that are created in MAF. This class is used to implement the inter-component analysis as explained in Section 2.2.2. Therefore, it stores a worklist of the components that need to be analyzed by the intra-component analysis. It also keeps track of which components depend on which parts of the analysis state.

2.3.2 IntraAnalysis

```
abstract class IntraAnalysis(val component: Component):
    /** Set of dependencies read by this intra—component analysis. */
    var R: Set[Dependency] = Set()
    /** Set of dependencies written (triggered) by this intra-component analysis. */
    var W: Set[Dependency] = Set()
    /** Set of components discovered by this intra-component analysis. */
    var C: Set[Component] = Set()
    /** Registers a read dependency. */
    def register(dep: Dependency): Unit = R += dep
    /** Triggers a written dependency. */
    def trigger(dep: Dependency): Unit = W += dep
    /** Spawns a discovered component. */
    \mathbf{def} spawn(cmp: Component): Unit = C += cmp
     * Performs the intra-component analysis of the given component.
     * Important: should only update the *local* analysis state, and must
     * not modify the global analysis state directly.
    \mathbf{def} analyzeWithTimeout(timeout: Timeout.T): Unit
    /** Pushes the local changes to the global analysis state. */
    def commit(): Unit =
        R.foreach(inter.register(component, ))
        W.foreach(dep = > if doWrite(dep) then inter.trigger(dep))
```

C.foreach(inter.spawn(, component))

IntraAnalysis represents an intra-component analysis in the modular analysis. It analyzes a single component in isolation from the other components. As previously mentioned in Section 2.2.1, the intra-component analysis keeps track of different dependencies and components it encounters. Concretely, it keeps track of the following:

- If the currently analyzed component reads a part of the global analysis state, then it has a dependency on that part. These dependencies are stored during the intra-component analysis in the R set.
- If the currently analyzed component updates a part of the global analysis state that is a dependency for other components, then the components that depend on that part of the global analysis state need to be (re)analyzed by the intra-component analysis. These parts of the global analysis state are stored during the intra-component analysis in the W set.
- If new components are discovered in the currently analyzed component (e.g., a function call in the body of the component that is being analyzed), then these components need to be added to the worklist of the inter-component analysis in order to be analyzed later by the intra-component analysis. These components are stored during the intra-component analysis in the C set.

Once the intra-component analysis finishes analyzing the component, all the elements that were locally stored during the intra-component analysis need to be registered in the inter-component analysis. This happens using the commit method.

2.3.3 GlobalStore and ReturnValue

When analyzing programs, it is often necessary to emulate the heap memory. Therefore, GlobalStore is a trait that provides an analysis with a global store in which the analysis can store results of analyzed components, such as function calls, with their unique address. To manipulate the store during the analysis, methods such as writeAddr, to write a value to a memory address, and readAddr, to read a value from a specific address, are provided in the trait.

Components, such as function calls, can also have return values. Therefore, the ReturnValue trait extends the capabilities of GlobalStore in order to store return values, accompanied by their address.

In the context of ModF, the global store, with its extended capabilities to store return values, is one of the central components of the analysis, and it is an integral part of the global analysis state, as well as the result of the analysis of a program.

Components can have dependencies on addresses in the store. If an address in the global store is updated (e.g., a return value of a function call is registered), then all components that have a dependency on that address, i.e., components that have previously read the value of that address, need to be reanalyzed.

2.3.4 SequentialWorkListAlgortihm

```
trait SequentialWorklistAlgorithm[Expr <: Expression] extends ModAnalysis[Expr]:
def emptyWorkList: WorkList[Component]
var workList: WorkList[Component] = emptyWorkList.add(initialComponent)
def addToWorkList(cmp: Component) = workList = workList.add(cmp)
def finished: Boolean = workList.isEmpty
```

```
def step(timeout: Timeout.T): Unit =
    val current = workList.head
    workList = workList.tail
    val intra = intraAnalysis(current)
    intra.analyzeWithTimeout(timeout)
    if timeout.reached then
        addToWorkList(current)
    else
        intra.commit()
    def run(timeout: Timeout.T): Unit =
        while !finished && !timeout.reached do step(timeout)
```

SequentialWorkListAlgorithm is a trait that can be used to implement worklist algorithms for analyses of which the components are analyzed sequentially. Using the run method, the intercomponent analysis of the program is initiated. Inside that method, a leading decision loop calls the step method, which will perform an intra-component analysis on the first component of the worklist ("first" depends on which worklist is used. The first component of a Last-In-First-Out worklist would be the most recently added component to the worklist, which is different than a First-In-First-Out worklist). Once the intra-component analysis of that component is finished, all local changes of that analysis will be registered in the global analysis state using the commit method of intraAnalysis.

2.3.5 AbstractDomain and Lattice

As previously explained in Section 2.1.1, analyses use an abstract domain to approximate values in the analysis. AbstractDomain represents an abstract domain that is used in an analysis. The values of an abstract domain are represented by the Lattice trait, which is a join semilattice structure that, as explained in Section 2.1.2 has a top element, bottom element, and a join operator to produce the least upper bound.

2.3.6 SchemeLattice and SchemeDomain

The SchemeLattice trait is an interface that represents the base lattice for Scheme that can be used in an abstract domain for ModF, augmented with Scheme-specific operations. These operations can be for instance injecting primitive values, such as strings and integers, into the lattice (i.e., creating an element in the lattice from the provided primitive value), or testing whether a given value should be considered true in a conditional.

The SchemeDomain trait is an interface that represents an abstract domain for Scheme programs in ModF.

2.3.7 Core Lattices of MAF

MAF provides lattices to represent some elements that are frequently used in analyses as well as their operations. These lattices represent for instance boolean values, strings, integers, and real values.

- BoolLattice represents boolean values in an analysis, and offers an interface for common operations that are used on booleans, such as isTrue and not.
- Intlattice represents integer values in an analysis, and offers an interface for common operations that are used between integers, such as plus and modulo.

- RealLattice represents real values in an analysis, and offers an interface for real operations, such as sqrt, ceiling and log.
- CharLattice represents character values in an analysis, and offers an interface for operations that are used on characters, such as isLower and upCase.
- StringLattice represents string values in an analysis, and offers an interface for operations that are used on strings, such as append, substring, and length.
- SymbolLattice represents symbol values, which are commonly used values in Scheme. Its interface offers the toString operation, which converts a symbol to an element of StringLattice.

2.3.8 ConstantPropagationlattice

```
object ConstantPropagation:
     sealed trait L[A]
     case object Top extends L[Nothing]
     case class Constant[A](x: A) extends L[A]
     case object Bottom extends L[Nothing]
     type I = L[BigInt]
     object L:
          implicit val intCP: IntLattice[I] = new IntLattice[I] {
          private def binop(
          op: (Int, Int) => Int,
          n1: I,
          n2: I
          ) = (n1, n2) match
                case (Top, Top) => Top
                \mathbf{case} \; (\mathsf{Top}, \, \mathsf{Constant}(\_)) => \mathsf{Top}
                \mathbf{case}\ (\mathrm{Constant}(\_),\,\mathrm{Top}) => \mathrm{Top}
                case (Constant(x), Constant(y)) => Constant(op(x, y))
                case => Bottom
          \mathbf{def} \ \mathrm{plus}(\mathrm{n1:}\ \mathrm{I,\ n2:}\ \mathrm{I}) \mathrm{:}\ \mathrm{I} = \mathrm{binop}(\underline{\phantom{a}} + \underline{\phantom{a}}, \ \mathrm{n1,\ n2})
          }
          ...
```

Constant propagation is an evaluation technique in which variables are replaced by their constant values. For the given variables x = 10 and y = x + 5, propagating x in y means that x will be replaced by its constant value, thus y = 10 + 5.

Constant propagation is an example of how the operations of the core lattices in Section 2.3.7 could be implemented. For instance, the plus operation of IntLattice can be implemented to evaluate the addition of two arguments if both arguments are known constants. If at least one of both arguments is \top , meaning that there is no useful information known about that argument, then the result would also be \top .

Another example is appending strings. In the constant propagation domain of the string lattice, appending two strings means creating a new constant value with the result of the concatenation of both strings, if they are both known constants.

2.3.9 ModularSchemeLattice and Value

```
class ModularSchemeLattice[A <: Address, S: StringLattice, B: BoolLattice, I: IntLattice, R:
    RealLattice, C: CharLattice, Sym: SymbolLattice]
    extends Serializable
    with SchemeLattice:
    ...
    trait Value
    ...
    case class Int(i: I) extends Value:
        override def toString: String = IntLattice[I].show(i)
    ...
    object Value:
        ...
    def op(op: SchemeOp)(args: List[Value]): Value =
        op match
        ...
    case Plus =>
        (args(0), args(1)) match
        case (Int(n1), Int(n2)) => Int(IntLattice[I].plus(n1, n2))
        ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ....
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ...
    ..
```

The ModularSchemeLattice trait is a wrapper that is used to combine lattices of Scheme primitive values, such as a string lattice and an integer lattice. ModularSchemeLattice is modular in the sense that the analysis programmer can choose which implementation for each core lattice to use in ModularSchemeLattice (e.g., constant propagation).

The Value trait and its companion object are used to implement the primitive values and operations of the modular Scheme lattice. The Int case class for example is a wrapper around elements from IntLattice, and thus represents integers inside the ModularSchemeLattice. There are operations that could be performed on integers, such as Plus and Minus. These operations originate from the respective lattice and can be implemented using ConstantPropagationlattice that is explained in Section 2.3.8 for example.

2.4 Abstract Domains as a Candidate for Optimisation

The function-modular analysis for Scheme was profiled in order to determine the parts of the analysis that consume a substantial amount of time. This could help us identify the parts of the analysis that could possibly be optimised. The initial hypothesis is that abstract domains and their lattices are a good candidate for optimisation. Abstract domains and their operations form the building blocks for analyses. Therefore, an analysis is very likely spending a lot of time in primitive operations and values.

2.5. SCALA NATIVE 9

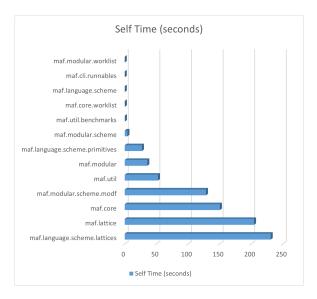


Figure 2.2: CPU profiling results aggregated by the package.

The profiling results confirmed our initial hypothesis. Indeed, as illustrated in Figure 2.2, it is clearly observed that an analysis spends a significant amount of time in lattices and their operations [12]. Therefore, this dissertation aims at investigating potential performance improvements in analyses if abstract domains are implemented using an optimised, low-level implementation.

2.5 Scala Native

By default, Scala code is compiled into Java bytecode that runs on a Java Virtual Machine. Using Scala Native, it is also possible to compile Scala code to machine code. Scala Native is an ahead-of-time compiler that compiles Scala code to machine code (using LLVM), which will then run natively on the host machine, instead of running on a Java Virtual Machine [5]. Scala Native has low-level constructs, such as C types, and manual memory management. Scala Native also offers an interoperability layer in order to interoperate with low-level languages such as C.

Scala Native is the technology used in this dissertation. Since it offers low-level features, it is possible to write and integrate a low-level implementation in Scala. It is important to take into consideration, however, that Scala Native is still an experimental technology, and no functionalities of Scala Native are guaranteed to perform as expected.

2.5.1 Scala Native Memory Management

Scala Native includes a garbage collector, which is Immix GC by default, that automatically manages memory for objects and class instances [5]. Similar to Scala Native programs, this garbage collector also runs natively on the host machine.

Memory can also be manually allocated for C types [5]. This could be useful to interact with external C functions that have pointers as arguments, or to improve the performance of a Scala Native program by minimizing the amount of work the garbage collector has to do. For example, encoding frequently used elements in a byte sequence, and manually managing their memory, reduces the need for the garbage collector.

This is different from the Scala memory model, which relies on the Java Virtual Machine memory model. Given that Scala is compiled with the just-in-time compiler to Java bytecode which will run on a Java Virtual Machine, the Java Virtual Machine will load classes dynamically at run time to the heap memory. Generally, the Java Virtual Machine will store all objects on the heap memory. Variables are references to those objects, and can be stored on the stack, e.g., when calling a function that has local variables [6]. The garbage collection is taken care of by the Java Virtual Machine. Scala has no way of manually allocating memory.

2.5.1.1 Manual Memory Allocation for C Types

Scala Native offers multiple kinds of manual memory management: heap memory management, stack memory management, and Zone memory management (which is a technique that is used to perform semi-automatic memory management) [5]. In order to avoid the overhead of automatic memory management, we use manual heap memory management. Heap memory can be manually managed in Scala Native using the bindings that Scala Native offers for the C functions that perform dynamic heap memory manipulation [5]. These functions are malloc, free, and realloc. Using these functions, memory from the heap can be dynamically allocated and freed once it is no longer needed. It is the responsibility of the programmer to free the dynamically allocated heap memory. If the allocated memory is not freed, the program will suffer from memory leaks.

2.5.2 Features of Scala Native

2.5.2.1 Low-level Primitives

Scala Native provides built-in equivalents of C types that are frequently used. A complete list can be found in the documentation of the scala.scalanative.unsafe package¹. Table 2.1 shows a list of the most popular ones, alongside their Scala Native equivalent.

C type	Scala Native
void	Unit
int	CInt
int*	Ptr[CInt]
long	CLong
char	CChar
char*	CString
<pre>struct { int x, char *y, uint8_t z; }*</pre>	Ptr[CStruct3[CInt, CString, Byte]]

Table 2.1: Popular C types and their Scala Native equivalent.

Scala Native also supports pointer arithmetic operations in order to manipulate memory pointers, such as dereferencing a pointer variable. These operations and their Scala Native equivalents can be found in Table 2.2 [5].

Having low-level primitives with pointer operations integrated in Scala Native allows us to directly write low-level code in Scala, instead of relying on an implementation from a low-level language like C.

 $^{{}^1} https://javadoc.io/doc/org.scala-native/nativelib_native0.4_3/latest/scala/scalanative/unsafe.html$

2.5. SCALA NATIVE

Operation	C syntax	Scala Native syntax
Load a value from an address	*ptr	!ptr
Store a value to a given address	*ptr = value	!ptr = value
Pointer to an index	ptr + i; &ptr[i]	ptr + i
Load a value from an index	ptr[i]	ptr(i)
Store a value to an index	ptr[i] = value	ptr(i) = value
Pointer to a field of a struct	&ptr->name	ptr.atN
Load a value from a field of a struct	ptr->name	ptrN
Store a value to a field of a struct	ptr->name = value	ptrN = value

N is the index of that field in the struct.

Table 2.2: Pointer operations in C and their Scala Native equivalent.

2.5.2.2 Native Code Interoperability

As mentioned earlier, Scala Native makes it possible to interoperate with low-level programming languages such as C. In order to do so, extern objects can be used. extern objects declare methods that are defined elsewhere in a native library in the library path, or in the Scala Native resources. Inside an extern object, bindings of the methods, with which Scala Native interoperates, should be defined. This binding is the Scala Native equivalent signature of the signature of that method in its native implementation. Below is an example of such objects. The test method takes two arguments, a C integer, and a pointer to a null-terminated C string. This method is defined elsewhere in native code.

```
import scalanative.unsafe._
@extern
object myapi {
    def test(a: CInt, b: CString): Unit = extern
}
```

2.5.3 Scala Native Configurations

Scala Native includes an optimiser that offers a lot of optimisations for the code during the compilation phase in order to achieve a good performance [13]. The following Scala Native optimisation modes were used:

- debug mode: This is the default mode for Scala Native. It offers the shortest compilation time, but performs fewer optimisations on the code. This mode was employed during the implementation of the work presented in this dissertation.
- release-full mode: This mode performs all optimisations on the code in order to achieve the best runtime performance. This mode was employed during the performance evaluation that is explained in Chapter 6.

Additionally, Scala Native also offers some extra optimisations that are applied at link time. Specifically, the thin link time optimisation mode is used during the performance evaluation, which uses LLVM's ThinLTO optimisations to optimise C code with which the Scala Native program is interoperating.

The heap size that the garbage collection of Scala Native uses can also be configured. This could be achieved by setting the environment variables SCALANATIVE_MAX_HEAP_SIZE and

SCALANATIVE_MIN_HEAP_SIZE in order to respectively update the maximum heap size, and the initial heap size of the garbage collector. This will be used during the performance evaluation so that programs that run natively have the same heap size as programs that run on the Java Virtual Machine.

2.5.4 MAF Cross-compilation using Scala Native

MAF is by default compiled to Java bytecode that runs on a Java Virtual Machine. Using cross-compilation, MAF already has a secondary build option to compile to JavaScript using Scala.js. For this dissertation, cross-compilation support for Scala Native is added to MAF. That is, using Scala Native, MAF is compiled to native code that runs natively on the machine.

Chapter 3

Overview of the Native Lattice

For this dissertation, we developed a low-level implementation of the different lattices that are used in the abstract domain of ModF, which we refer to as the *Native Lattice*. This chapter provides a comprehensive explanation of the Native Lattice implementation. The main idea is that high-level constructs are eliminated, and optimised low-level constructs are used instead, in order to gain some additional performance.

The Native Lattice is based on the Constant Propagation Lattice that was explained earlier in this dissertation. Lattice elements can be either a top element, a bottom element, or a constant element. In the Native lattice, we no longer use case classes and objects to represent the lattice elements. Instead, each lattice uses its own representation of a top element, a bottom element, and constant elements depending on how these elements can be efficiently encoded using a low-level implementation.

3.1 BoolLattice

The BoolLattice is used to represent boolean values and their operations inside an abstract domain. Since there are only 4 different sorts of elements inside this lattice, it would make sense to encode them in bits. Concretely, the elements are encoded as follows:

Element	Bitwise Representation
false	0000
true	0001
bottom	0010
top	0100

Table 3.1: The bitwise representation of the BoolLattice elements.

Figure 3.1 illustrates a Hasse diagram representing the BoolLatice elements and the relationships among these elements. Using this bitwise representation, booleans can now be encoded in a 4-bit data type. Since a byte is the smallest data type that can be used for values, this is used to store the values of the BoolLattice.

The bitwise representation is not arbitrarily chosen, but rather to make it easier and more efficient for the operations of this lattice to be implemented. Indeed, if we consider the implementation of the isTrue operation as an example, we can easily check whether the given element is a constant (i.e., true or false), the top element, or the bottom element.

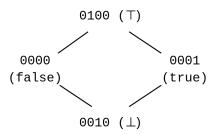


Figure 3.1: A Hasse diagram for BoolLattice.

If the given element is a constant, then we can apply a bitwise and with the 0001 mask, which will be 0000 if the element is false, or 0001 if the element is true.

If the element is a top or bottom element, however, we can obtain the results by simply, and efficiently shifting the byte 2 times to the right.

```
uint8_t boolIsTrue(uint8_t b)
{
    if(b < 2) {
        return b & 1;
    }
    return b >> 2;
}
```

The other operations of the BoolLattice are similarly implemented.

The operations were implemented in C and imported in the BoolLattice implementation using extern objects that were explained in Section 2.5.2.2. Some operations in BoolLattice need to return a Scala boolean (i.e., true or false from the Boolean data type of Scala). isTrue and isFalse are examples of such functions. Therefore, an additional function is written in order to convert the results from the C functions that implement these lattice operations, which return 0 or 1, to Scala booleans. This is done by simply checking whether the return value is equal to one (i.e., i == 1.toByte).

3.2 IntLattice and RealLattice

The elements of the IntLattice and RealLattice are both represented using literals without any additional wrappers. Concretely, elements of the IntLattice are represented using CInt, and elements of the RealLattice are represented using CDouble. For the IntLattice, the top and bottom elements are respectively the maximum value for an integer, and the minimum value for an integer. For the RealLattice, the top and bottom elements are respectively the maximum value for a double, and the minimum value for a double. The elements of both lattices are illustrated in a Hasse diagram in Figure 3.2, where Int.MinValue < n < Int.MaxValue and Double.MinValue < m < Double.MaxValue.

The simple operations of these lattices such as addition and subtraction are implemented using the underlying system. More advanced operations, such as logarithmic and trigonometric operations, are implemented using the math library of the Standard C Library. The functionalities of the library may be less safe, since there are no try catch constructs in C for instance,

3.3. NATIVESTRING 15

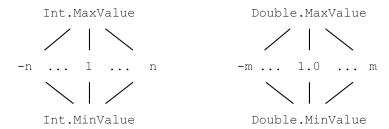


Figure 3.2: Hasse diagrams for respectively the IntLattice and the RealLattice.

but the performance of these functionalities might be better, due to less safety.

Provided below is the implementation of the sin operation from the ReaLattice as an example.

```
val top = Double.MaxValue
val bottom = Double.MinValue
...
def sin(n: R): R =
   if(n == top || n == bottom) then n
   else scalanative.libc.math.sin(n)
```

3.3 NativeString

Implementing strings and symbols in a low-level fashion is harder than other data types, since they consist of a sequence of characters. One could use a null-terminated string of which the memory is manually managed. These are the strings that are usually used in a low-level language like C.

Scala Native supports this kind of strings. In the domain-specific language of Scala Native, these are called CString, which is essentially a pointer to an array of CChar characters.

Some problems might arise, however, when using CString: we do not want to calculate the length of the string each time it is requested. To this end, a struct can be used to store the length of the string, as well as the pointer to the string.

Below is the struct that will be used to store the relevant information of strings in our implementation.

```
type Sn_struct = CStruct3[CInt, CString, CChar]
type S = Ptr[Sn_struct]
```

CStruct3 is the equivalent primitive of a struct C type with three fields in the domain-specific language of Scala Native. The first element of the Sn_struct is the length of the string. The second element is the pointer to the string. The third element is the reference counter that will be used by the domain-specific memory management, which will be explained in Chapter 4.

Another problem that we may encounter when using CString is checking for equality. The == operator between Ptr elements will check for referential equality, meaning that two CString pointers are equal when they point to the same string in memory. It might also be necessary to check for string equality. That is, if two strings contain the same characters, but they are not

necessarily pointing to the same array of characters in memory, then they are equal. We would also want to implement the necessary string operations, such as appending strings, in a concise way.

To this end, a new class NativeString is used to implement the string operations. The NativeString is implemented as a value class, meaning that it extends the AnyVal class of Scala. AnyVal is the root class for all value classes, such as integers, in Scala. Value classes in Scala are used for their efficiency advantages and low runtime overhead [9].

The NativeString class stores a pointer to a Sn_struct that is mentioned above. It implements different methods that are needed for the string elements, such as referential equality, string equality, appending strings, getting a substring, etc.

Since lattice elements cannot be imperatively modified, some optimisations can be made. When comparing two strings using string equality, for instance, referential equality of both strings can be first compared. If they both point to the same array of characters, then they are equal.

Comparing equality between a NativeString and either top or bottom should only happen via referential equality, since both are unique objects that never get altered. In order to make sure that string equality fails when one of the arguments is top or bottom, their length is set to respectively Integer.MaxValue, and Integer.MinValue. This ensures that the string equality fails when the lengths of both arguments are compared, so that the character sequences of the input arguments do not get tested for equality.

```
class NativeString(val underlying: S) extends AnyVal:
    // assuming lengths are equals
    @tailrec
    private def cstrEquals(s1: CString, s2: CString): Boolean =
        if(!s1 == 0.toByte) then true
        else if (!s1 != !s2) then false
        else cstrEquals(s1 + 1, s2 + 1)
    \mathbf{def} == (other: NativeString): Boolean =
        \mathbf{val}\ 11 = \mathrm{underlying.}\_1
        val 12 = other.underlying. 1
        val s1 = underlying. 2
        val s2 = other.underlying. 2
        eq(other) \mid\mid (l1 == l2 \&\& cstrEquals(s1, s2))
    // Referential equality.
    // two values are referring to the same object
    def eq(other: NativeString): Boolean =
        this.underlying == other.underlying
```

Since NativeString objects are represented in their underlying representation by null-terminated strings, some operations, such as copying and concatenating a string, could be efficiently implemented without the need for additional variables or counters in order to know when a loop is finished. As an example, the ++ implementation is provided below.

```
@tailrec
private def strcpy(dest: CString, src: CString): Unit =
  if(!src == 0.toByte) then
    !dest == 0.toByte
  else
```

3.3. NATIVESTRING 17

```
!{\rm dest} = !{\rm src}
        strcpy(dest + 1, src + 1)
@tailrec
private def strcat(dest: CString, src: CString): Unit =
   if(!src == 0.toByte) then
        !dest = 0.toByte
   else
        !dest = !src
        strcat(dest + 1, src + 1)
def ++(other: NativeString): NativeString =
        val struct = malloc(sizeof[Sn struct]).asInstanceOf[S]
        val stringLength = this.length + other.length
        struct. 1 = \text{stringLength}
        struct. \_2 = malloc(stringLength.toULong + 1.toULong).asInstanceOf[CString]
        struct. 3 = 0
        strcpy(struct.\_2,\,underlying.\_2)
        strcat(struct. 2 + underlying. 1, other.underlying. 2)
        val ns = new NativeString(struct)
        NativeString.allocatedStrings += ns
```

strcpy and strcat are helper functions that are implemented using tail recursion. The optimiser bears the burden of ensuring that tail-recursive functions are optimised efficiently and correctly by transforming them into loops when compiling the code. In the strcpy function for instance, the current pointer of src, which is what strcpy is copying from, will be dereferenced to check whether the end of the string is reached. If that is the case, then the null-terminator can be added to the destination. Otherwise, the current character of src will be copied to dest, and both pointers will be incremented for the next iteration.

The NativeString companion object creates two elements that are treated differently in some cases: top and bottom. As the names suggest, these elements will be used in lattices that use NativeString to represent their elements. These elements are special in the sense that they only need to be allocated and deallocated once. Specifically, they need to be allocated when the analysis of a program starts, and they need to be deallocated upon completion of the analysis (or, if there will be multiple analyses running in the same program, when the program that runs the analyses starts, and when the program finishes). Since those are unique objects that do not get modified during analyses, it would be inefficient to keep allocating and deallocating top and bottom elements.

The NativeString companion object stores all created NativeString objects in an hashSet for easy retrieval when those need to be deallocated. It also has an apply method, which creates new NativeString objects from a Scala string.

```
object NativeString:
    var allocatedStrings : mutable.HashSet[NativeString] = mutable.HashSet.empty

private val ignoreTopLength = Int.MaxValue
private val ignoreBottomLength = Int.MinValue
var top: NativeString =
    val temp = NativeString("top")
    temp.underlying._1 = ignoreTopLength
    temp.underlying._3 = 1
    temp
```

```
var bottom: NativeString =
    val temp = NativeString("bottom")
    temp.underlying. \_1 = ignoreBottomLength temp.underlying. \_3 = 1
    temp
def apply(x: String): NativeString =
    val struct = malloc(SnSize).asInstanceOf[S]
    val stringLength = x.length()
    struct. 1 = \text{stringLength}
    struct. \ \ \underline{\ } 2 = malloc(stringLength.toULong + 1.toULong).asInstanceOf[CString]
    struct._3 = 0
    \mathbf{var} \; \mathbf{i} = 0
    \mathbf{while}(i < stringLength) \ \mathbf{do}
         !(struct. 2 + i) = x(i).toByte
    !(struct. 2 + stringLength) = 0.toByte
    val ns = new NativeString(struct)
    allocated
Strings += ns
    ns
```

Creating a new NativeString from a Scala string requires allocating enough memory for the Sn_Struct as well as the character sequence for the null-terminated string. After that, the character sequence of the Scala string can be copied to the null-terminated string.

3.4 StringLattice and SymbolLattice

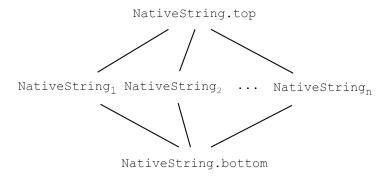


Figure 3.3: A Hasse diagram for the StringLattice and the SymbolLattice.

Figure 3.3 illustrates a Hasse diagram of the StringLattice and the SymbolLattice. Elements of the StringLattice and SymbolLattice are implemented using NativeString. NativeString indicates a lattice constant represented by a NativeString instance.

3.5. CHARLATTICE 19

When applying one of the operations of those lattices, such as append, we first need to check whether one of both arguments is the top or the bottom element. This can be efficiently done using the eq method of NativeString that checks for referential equality.

Below is the implementation of the append operation from the StringLattice as an example.

```
 \begin{array}{l} \textbf{def} \ append(s1: S, \, s2: \, S): \, S = \\ \textbf{if}(s1.eq(bottom) \mid\mid s2.eq(bottom)) \ then \ bottom \\ \textbf{else} \ \textbf{if}(s1.eq(top) \mid\mid s2.eq(top)) \ then \ top \\ \textbf{else} \ s1 \ ++ \ s2 \\ \end{array}
```

First, both arguments are tested to check whether one of them is the top element or the bottom element. If both elements are constants, then the ++ operator will be applied, which will return a NativeString containing the concatenation of both strings.

3.5 CharLattice

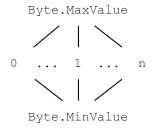


Figure 3.4: A Hasse diagram for the CharLattice.

The CharLattice is used to represent characters in an abstract domain. Similar to the IntLattice and the RealLattice, elements of the CharLattice are represented by literals, namely: a byte.

The top and bottom elements of this lattice are respectively the maximum value of a byte and the minimum value of a byte. The elements of this lattice are illustrated using a Hasse diagram in Figure 3.4.

Operations of this lattice, such as toUpper and toLower, are implemented using the functionalities of the Standard C library.

```
override def charEqCI(c1: C, c2: C): BoolLattice =

if(c1 == top || c2 == top) then BoolLattice.top

else if(c1 == bottom || c2 == bottom) thenBoolLattice.bottom

else BoolLattice.inject(scalanative.libc.ctype.toupper(c1) == scalanative.libc.ctype.toupper(c2))
```

3.6 Alternative Implementations for Some Lattices

Some lattices have an alternative implementation. In this section, these alternative solutions are briefly motivated and described. The performance of these implementations are also evaluated in Chapter 6.

3.6.1 StringLattice and SymbolLattice

3.6.1.1 An Implementation using Scala Strings

Instead of manually allocating memory for lattice elements that rely on strings for their representation, another option is to use Scala strings. The memory manager of Scala Native takes care of allocating and deallocating memory for those strings. To this end, an alternative implementation for StringLattice and SymbolLattice is also tested. This implementation uses Scala strings to represent the lattice elements. To prevent the need for additional wrappings around the strings, which are present in the constant propagation implementation that is explained in Section 2.3.8, a randomly generated string can be used for the top and the bottom elements. This is to avoid using any wrappings around strings. This approach avoids the need for creating additional wrapping objects.

Figure 3.5 illustrates the lattice elements in this alternative implementation using a Hasse diagram. $Scala.String_m$ indicates an instance of Scala.String that is used as a lattice element in StringLattice or SymbolLattice.

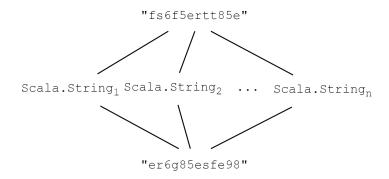


Figure 3.5: A Hasse diagram for the alternative implementation of StringLattice and SymbolLattice.

Since Scala strings are used, the interface of the Scala strings can now be used to implement the lattice operations. Below is the implementation of append as a demonstration.

```
val top: S2 = "fs6f5ertt85e"
val bottom: S2 = "er6g85esfe98"

def append(s1: S2, s2: S2): S2 =
    if(s1 == bottom || s2 == bottom) then bottom
    else if(s1 == top || s2 == top) then top
    else
        inject(s1 ++ s2)
```

3.6.1.2 An Implementation without AnyVal

The NativeString class is implemented using the AnyVal class of Scala, which is the base class for all value classes in Scala, such as integers. Value classes are intended to be efficient at runtime. However, in some cases, such as when storing value class instances in an array, some

inefficiencies might arise [1]. Therefore, an alternative implementation for the lattice elements of StringLattice and SymbolLattice was also tested. In this implementation, we do not use any wrappers around the struct that was discussed earlier. The operations between the strings are implemented in a NonClassNativeString object. They have an identical implementation as the operations of the NativeString, with the exception that they now take an additional argument, being the string that was previously the instance of NativeString to which messages were sent.

```
object NonClassNativeString:
    type Sn_struct = CStruct3[CInt, CString, CChar]
    type S = Ptr[Sn_struct]
    def ++(first: S, second: S): S =
        /* Same implementation as the NativeString */
```

3.6.2 BoolLattice

Since the BoolLattice only has 4 elements, it might also be an option to implement its operations without using any bitwise manipulation. Therefore, an alternative implementation of the BoolLattice is provided that directly implements the lattice operations in Scala by simply testing whether the given argument is the top element, the bottom element, or a constant (i.e., true or false). This way, we do not need to calculate the results using bitwise manipulation first and then convert these results to Scala booleans. The elements of this lattice still have the same representation as the implementation described in section 3.1. The implementation of isTrue is provided as an example.

```
val top = 4.toByte
val bottom = 2.toByte
def isTrue(b: B): Boolean =
   if(b == top) then true
   else if(b == bottom) then false
   else b == 1.toByte
```

Chapter 4

Domain-Specific Memory Management

As we have seen in section 3.4, the memory of the StringLattice and the SymbolLattice elements is manually managed. A question that arises: when should the memory for the allocated strings and symbols be deallocated. Naively, all strings and symbols could be deallocated when the analysis is finished, but this might result in a big overhead, since all strings and symbols have to be kept in memory, even the ones that are no longer needed by the analysis. When analyzing a program, a significant number of garbage values can be generated, since some parts of the program need to be repeatedly analyzed.

To this end, some kind of memory management is required in order to deallocate the elements that are no longer needed during the analysis.

4.1 Idea and Pseudocode

Each intra-component analysis keeps its own store in which it stores all the elements that are needed for that analysis. When an intra-component analysis is initiated, that analysis stores a copy of the global analysis state in its store to which it writes results during the analysis. Once an intra-component analysis finishes, the global analysis state needs to be updated with the results from that intra-component analysis (using the commit method, as explained in Section 2.3.2). For instance, if there was a dependency on the return value of the component that the intra-component analysis was analyzing, then that dependency should be updated in the global analysis state with the newly calculated results, in case those are different from the previously stored return value for that component in the global analysis state. There are also values in the store of the intra-component analysis that will not be written to the global analysis state. These are values that were needed during the intra-component analysis, but did not have any known dependants for them in the global analysis state. Values of local variables are an example of such values. When a component is analyzed, those local values are no longer needed, and thus can be deallocated. Several questions arise:

- How can we determine which values need to be deallocated?
- When should the garbage values be deallocated?

The answer to the first question is *reference counting*. The idea is as follows: for each value, a counter is stored that keeps track of how many times that value is being stored in the global

analysis state as a dependency. If that counter is zero, it means that the value is no longer needed in the global analysis state, and can be deallocated. The reference counter of a given value gets incremented each time the value is written to the global analysis state.

As mentioned earlier, the global analysis state needs to be updated at the end of an intracomponent analysis. This means that garbage values produced by an intra-component analysis need to be deallocated after the global analysis state is updated by that intra-component analysis. This answers the second question. Indeed, after an intra-component analysis commits its changes to the global analysis state, all reference counters are updated, and the values of which the reference counter is equal to zero, are not needed in the global analysis state, nor in the current intra-component analysis, since it is already finished analyzing the component. These values can thus be deallocated.

When updating the global analysis state, we should also take the values that were previously stored in the state into consideration. If a certain part of the global analysis state is updated with a new value that does not equal the old value, then that old value is no longer needed in that part of the global analysis state, which means that its reference counter needs to be decremented, since the new value replaces that old value for that part of the global analysis state.

Provided below is a simplified pseudocode of the algorithm divided in three parts: memory management, intra-component analysis and inter-component analysis. Only the parts that are relevant for the domain-specific memory management are included in the pseudocode.

Algorithm 1 Domain-specific memory management.

```
AllocatedElements \leftarrow EmptyDict \qquad \triangleright \ A \ dictionary \ containing \ each \ allocated \ value \ and \ its \ reference \ counter. \\ \textbf{procedure CollectGarbage()} \\ \textbf{for each } (element, referenceCounter) \in AllocatedElements \ \textbf{do} \\ \textbf{if } referenceCounter = 0 \ \textbf{then} \\ \textbf{DeallocatedElement)} \\ AllocatedElements \leftarrow AllocatedElements - element \\ \textbf{end if} \\ \textbf{end for} \\ \textbf{end procedure} \\ \end{aligned}
```

Pointers to all allocated elements will be stored in a dictionary together with their reference counter. The garbage collection iterates over all allocated elements, and deallocates those of which the reference counter is equal to zero.

Algorithm 2 Domain-specific memory management in the intra-component analysis.

```
Dependencies \leftarrow EmptySet
Store \leftarrow Copy(GlobalAnalysisState)
procedure Analyze(Component)
   * Intra-component analysis for Component */
   COMMIT()
end procedure
procedure Commit()
   WRITETOGLOBALSTATE(Dependencies)
   CollectGarbage()
end procedure
procedure WriteToGlobalState(Dependencies)
   for each dependency \in Dependencies do
      UPDATEGLOBALSTATE(dependency)
      IncreaseReferenceCounter(AllocatedElements, dependency)
   end for
end procedure
```

During an intra-component analysis of a component, elements that were discovered during the analysis will be allocated and thus added to AddedElements. When the analysis finishes, CollectGarbage will be called in order to deallocate all elements that are no longer needed. When the local changes of the intra-component analysis are committed, some allocated values need to be stored in the global analysis state. Specifically, those are values of addresses in the global analysis state that have dependencies on them. For example, if a component has a dependency on an address of the return value of the currently analyzed component (e.g., because it is also its return value), then this value needs to be updated in the global analysis state, in case it is different from the previous value.

Algorithm 3 Domain-specific memory management in the inter-component analysis.

```
GlobalAnalysisState \leftarrow Empty\overline{Dict}
procedure UPDATEGLOBALSTATE(dependency)
   if dependency already exists then
      OldDependency \leftarrow GetOldDependency(GlobalState)
      DecreaseReferenceCounter(AllocatedElements, OldDependency)
      SetDependency (GlobalState, dependency)
   end if
end procedure
procedure RunAnalysis()
   PrepareMemory()
   Analyze()
end procedure
procedure EmptyAnalysisMemory()
   for each Element \in AllocatedElements do
      Deallocate(Element)
   end for
   Allocated Elements \leftarrow Empty Dict
end procedure
```

4.2. EXAMPLE 25

PrepareMemory is called before analyzing a given program by the inter-component analysis. This procedure makes sure that the storage for the allocated elements is ready to store elements. If AddedElements is a low-level implementation of a dictionary for instance that requires some initialisation (e.g., memory allocation), then this can happen in PrepareMemory.

When the global analysis state is no longer needed, the user can free the remaining memory of the analysis by calling EmptyAnalysisMemory.

4.2 Example

Consider the following Scheme program:

We assume the entry point to the program is the main function. Therefore, this is the initial component of the analysis. The analysis is using a LIFO worklist in this example, which means that the component most recently added to the worklist will be the first component to be analyzed by the intra-component analysis. The worklist will be denoted in this example by a \mathbb{W} . Components will be denoted by a $C_{\mathbf{f}}$, \mathbf{f} being the function that is called. This example is a simplified version of how a program in MAF is analyzed. The concrete execution of the analysis in MAF can deviate from the provided steps.

```
\bullet \ \mathbb{W} = \{C_{\mathtt{main}}\}
```

The main component is first added to the worklist. The component will be then removed from the worklist and analyzed by the intra-component analysis. The intra-component analysis discovers a call to greet. Therefore, a component for greet is created, and will be registered in the inter-component analysis, in order to be added to the worklist such that it can be analyzed later by the intra-component analysis. Since the return value of the call to greet is also the return value of main, a dependency between C_{main} and the return value of the call to greet is registered.

• $\mathbb{W} = \{C_{\mathtt{greet}}\}$

Next, $C_{\tt greet}$ is analyzed by the intra-component analysis. The argument of the call to $\tt greet$ is injected into the string lattice, and therefore, a lattice element of the string lattice is allocated. Inside the body of $\tt greet$, two local strings are defined, $\tt prefix$ and $\tt suffix$. Both strings are injected to the string lattice, and lattice elements of the string lattice are thus allocated for them.

A call to string-append is found in the body, which is a primitive function. Therefore, the function is evaluated using the append operator from the string lattice. The return value for $C_{\tt greet}$ is updated in the local store of its intra-component analysis. The intra-component analysis for this component is now finished, and the local changes need to be registered in the global analysis state.

Since there is a dependency on the return value of $C_{\tt greet}$, it needs to be written to the global analysis state. The reference counter of the return value is thus incremented, which means that it is not garbage and should not be deallocated.

As for the other strings, these are no longer needed in the global analysis state, nor in the analysis of other elements. Therefore, their reference counters do not get incremented, and thus stay at zero. This means that these values are garbage and need to be deallocated during this garbage collection cycle.

The return value of $C_{\tt greet}$ is now registered in the global analysis state. All components that have a dependency on this return value need to be reanalyzed by the intra-component analysis. Therefore, $C_{\tt main}$ is added to the worklist in order to be analyzed by the intra-component analysis.

```
• \mathbb{W} = \{C_{\mathtt{main}}\}
```

The main component is reanalyzed by the intra-component analysis. Since the return value of the call to greet is now known, the return value of C_{main} can now be updated with the same return value of C_{greet} . If the analysis and its global state and results are no longer needed, the programmer can call emptyAnalysisMemory, which frees the remaining allocated memory for that analysis.

4.3 Implementation

In this section, the concrete implementation for the above explained approach to manage the memory of lattice elements is described. Some technical parts of the code are abstracted away, in order to make the explanation of the code in this dissertation comprehensible.

In our implementation, elements of StringLattice and SymbolLattice are allocatable. The other elements are implemented as literal C types, such as CInt, and the memory of which could be managed using the Scala Native memory manager with minimal overhead. The implementation of the domain-specific memory manager could be further expanded to other lattices and their elements if needed.

4.3.1 NativeString

Below is the memory management part of the NativeString implementation. NativeString has increaseReferenceCounter and DecreaseReferenceCounter methods. The definition of these methods can be found on lines 3 until 11.

The increaseReferenceCounter and DecreaseReferenceCounter methods respectively increment and decrement the reference counter of a NativeString object, if it is not a top or bottom element, since those are treated differently, as explained in Section 3.3. The isGarbage method indicates whether a NativeString object is garbage, i.e., whether its reference counter is equal to zero.

The makeGarbage method sets the reference counter of a NativeString at zero in order for the element to be considered garbage. This method will be used when the remaining memory for the analysis is emptied, and the analysis is no longer needed.

Deallocating a NativeString requires deallocating the underlying character sequence, as well as the surrounding struct that is explained in Section 3.3.

```
class NativeString(val underlying: S) extends AnyVal:

...

def increaseReferenceCounter() =

if(!(eq(top) || eq(bottom))) then

underlying._3 = (underlying._3 + 1).toByte
```

```
7
        def decreaseReferenceCounter() =
            val ctr = underlying. 3
8
9
            if(ctr > 0) then
10
                if(!(eq(top) || eq(bottom))) then
                    underlying. 3 = (ctr - 1).toByte
11
12
13
        def isGarbage: Boolean =
            underlying. 3 == 0
14
15
        def makeGarbage(): Unit =
16
17
            if(!(eq(top) || eq(bottom))) then
                underlying. 3 = 0.toByte
18
19
20
        def deallocate(): Unit =
            if(!(eq(top) || eq(bottom))) then
21
22
                free(underlying. 2.asInstanceOf[Ptr[Byte]])
23
                free(underlying.asInstanceOf[Ptr[Byte]])
```

For the implementation of the domain-specific memory management, we do not use a dictionary to store and update the reference counters. This would not be very efficient, since the program needs to search for the element and its reference counter in the dictionary first. To this end, we store the reference counter of a given element inside the struct that contains the pointer to that element. This way, it is not needed to search for the counter before increasing or decreasing it. A HashSet is used to store all the allocated elements. This makes it easier to retrieve the allocated elements in order to deallocate them when needed.

Initializing the memory storage for the NativeString objects in our implementation just empties allocatedStrings. In implementations where that storage is manually managed, initializing the memory requires allocating memory for the storage.

The gc method frees all the NativeString elements that are no longer needed, and removes them from allocatedStrings. deallocateAllStrings frees all the allocated strings.

```
object NativeString:
 1
 2
3
         var allocatedStrings: mutable.HashSet[NativeString] = mutable.HashSet.empty
 4
 5
         def initializeMemory(): Unit =
6
             allocatedStrings = mutable.HashSet.empty
7
8
         \mathbf{def} \ \mathrm{gc}(): Unit =
             val garbage = allocatedStrings.filter( .isGarbage)
9
10
             garbage.foreach(s =>
11
                 s.deallocate()
                 allocatedStrings −= s)
12
13
14
         def deallocateAllStrings(): Unit =
15
16
             allocatedStrings.foreach( .deallocate())
```

4.3.2 The GC and IntraGC Trait

The GC trait defines the main memory management algorithm using the template method pattern. It offers an interface of abstract methods that will be used for the memory management, as well

as public methods that can be used by the programmer to empty the analysis memory once the analysis is no longer needed. Implementing a memory manager requires extending this trait and implementing the abstract methods. The methods that are left abstract depend on the concrete implementation and representation of the lattice elements.

The implementation directly follows the pseudocode of the algorithm. Indeed, we can see in updateAddr, which updates the value of an address in the global analysis state, that if the old value does not equal the new value, then its reference counter is decremented, and the address is updated with the new value. This happens in lines 18 to 22.

```
1
    trait GC[Expr <: Expression] extends ModAnalysis[Expr] with SequentialWorklistAlgorithm[Expr]
         with GlobalStore[Expr] with ReturnValue[Expr] { inter =>
 2
        override def run(timeout: Timeout.T): Unit =
 3
            initializeMemory()
 4
            super.run(timeout)
 5
 6
        def initializeMemory(): Unit
 7
        def emptyAnalysisMemory(): Unit
 8
        def increaseReferenceCounter(value: Value): Unit
 9
        def decreaseReferenceCounter(value: Value): Unit
        \mathbf{def}\ \mathrm{gc}(): Unit
10
11
12
        def writeAddr(addr: Addr, value: Value): Boolean =
13
            updateAddr(inter.store, addr, value)
14
                .map(updated => inter.store = updated)
15
                .isDefined
16
17
        override def updateAddr(store: Map[Addr, Value], addr: Addr, value: Value): Option[Map[Addr,
             Value]] =
18
            store.get(addr) match
19
                case None if lattice.isBottom(value) => None
20
                case None => Some(store + (addr -> value))
21
                case Some(oldValue) =>
22
                    val newValue = lattice.join(oldValue, value)
23
                    if newValue == oldValue then
24
25
                    else
                        decreaseReferenceCounter(oldValue)
26
27
                        Some(store + (addr -> newValue))
```

In IntragC, doWrite updates the value of a dependency in the global analysis state when the local changes of an intra-component analysis need to be committed to the global analysis state. If the value of the dependency is updated, which means that this dependency was not yet known in the global analysis state, or the old value of that dependency did not equal the new value, then true is returned, which indicates that the global analysis state is updated. This means that the reference counter for that value needs to be incremented, which happens at lines 8 and 9.

Once the local changes are committed to the global analysis state, the garbage values can be deallocated, which happens by calling gc in line 19.

```
trait IntraGC extends GlobalStoreIntra with ReturnResultIntra {
intra =>

override def doWrite(dep: Dependency): Boolean =
dep match
```

```
case Addr Dependency(addr) =>
 6
 7
                           val value = intra.store(addr)
 8
                           val isGlobalStateUpdated = inter.writeAddr(addr, value)
9
                           {f if} is Global State Updated then
10
                               increaseReferenceCounter(value)
11
                           is Global State Updated \\
12
                      \mathbf{case} \ \_ => \mathbf{super}.\mathrm{doWrite}(\mathrm{dep})
13
14
             override def commit(): Unit =
15
                  R.foreach(inter.register(component, _))
16
17
                  W.foreach(dep => if doWrite(dep) then inter.trigger(dep))
18
                  C.foreach(inter.spawn(\_, component))
19
                  gc()
20
         }
```

4.3.3 The NativeGC Trait

The NativeGC trait provides a concrete implementation for the memory management based on the GC trait that was explained in Section 4.3.2. It implements the abstract methods of that trait using the implementation of the NativeString that is described in Section 4.3.1. This trait is mainly technical glue code between GC and NativeString. Therefore, it will not be explained in detail in this dissertation.

Chapter 5

Implemenation Validation

5.1 Testing the Native Lattice Implementation

It is important to test the correctness of the Native Lattice implementation. MAF comes with a set of generator-driven, property-based tests for the core lattices (called LatticeTest). These tests check several properties for each lattice for at least 100 different instances that get injected into the lattice. For example, a test for the BoolLattice checks whether injecting an element to the BoolLattice preserves the truthiness of that element.

We extended these tests in order to test the Native Lattice implementation. Therefore, we implemented generators that generate elements for each lattice according to the Native Lattice implementation. When testing strings, the generator generates Scala strings, and injects them to the StringLattice implementation in the Native Lattice. An important difference between Scala strings, and null-terminated strings in C, however, is that the latter uses the ASCII character set, while the former uses the Unicode character set. This means that the StringLattice is limited to only the ASCII character set. Therefore, the string generator in the tests is also modified to only generate strings from the ASCII character set.

Additionally, we implemented unit tests written in order to test the correctness of the NativeString implementation. These tests check whether the NativeString methods produce correct results. For example, appending an empty NativeString to a non-empty NativeString, checking for referential or string equality between different NativeString instances and the other NativeString methods are tested.

Additional unit tests were added in order to test the correctness of the C implementation of the operations of BoolLattice that is explained in Section 3.1 in isolation.

Finally, in order to check whether analyses that use the Native Lattice implementation produce correct results, additional tests were written that compare the global analysis state of analyses that use the Native Lattice implementation with an analysis that uses the constant propagation domain implementation. The results of analyses that use the alternative implementations that are described in Section 3.6 are similarly tested.

5.2 Testing and Debugging Memory Management

Detecting and diagnosing memory-related bugs can be challenging due to their elusive nature. Therefore, additional debugging infrastructure was implemented in order to debug the memory manager. DebuggableNativeString provides the same implementation of NativeString, aug-

mented with additional code in order to debug memory-related issues. For instance, the free and malloc functions are replaced with functions that collect data when memory for strings is allocated and freed, in order to detect memory leaks. These data are counters that are used to detect whether there are more free calls than malloc calls, and objects that were previously freed which could be used to detect whether an object is freed again. The use of <code>DebuggableNativeString</code> has greatly enhanced the debugging process for memory-related issues, resulting in the detection of errors that were previously undetected.

Additionally, in order to ensure the effectiveness of the domain-specific memory management, it is necessary to check that the domain-specific memory management does not leave any garbage values deallocated. Therefore, additional tests were written to test whether there are no more remaining allocated strings left than the ones that are present in the global analysis state. Indeed, if there are more strings left, this would indicate that there are garbage values left deallocated. There could be fewer strings left, since the same NativeString instance could be used for different parts of the global analysis state.

Finally, it is also crucial to test whether analyses that use the Native Lattice and the accompanying memory manager produce the correct result. In order to do so, an analysis that uses the constant propagation implementation for lattices is compared with an analysis that uses the Native Lattice implementation. Both analyses are used to analyze several non-trivial Scheme programs. At the end of the analysis of each program, the global analysis state of the analysis that uses the constant propagation implementation is compared with the global analysis state of the analysis that uses the Native Lattice implementation. If the values at addresses of the global analysis state of the latter analysis correspond to values at addresses of the former analysis, then the analysis has indeed produced correct results.

Chapter 6

Performance Evaluation

In this chapter, we empirically evaluate the performance of the Native Lattice implementation and the accompanying memory manager. Therefore, we measure the analysis time and compare the analysis times when different settings are used for the analysis. The various analyses configurations are listed and explained in Table 6.1. The deployment target is the environment in which the analysis is benchmarked. JVM indicates that the analysis is benchmarked while running on the JVM, while Native indicates that the analysis is benchmarked while running natively on the host machine.

Benchmarking JVMCP helps us estimate how much performance gain or loss was acquired when running analyses natively on the host machine. Benchmarking NativeCP and comparing with JVMCP helps us compare the performance of analyses under the same settings, but compiled to different targets. Both JVMCP and NativeCP analyses have identical settings. As for NativeS, benchmarking this analysis and comparing it with analyses that use the NativeString give us some additional insights on whether using a domain-specific memory manager and a low-level implementation of string elements in analyses helps improve the performance.

Finally, benchmarking NativeGCB, NativeSB and NonClassNativeGCB help us see whether the alternative implementations for the different lattices are any better.

6.1 Implementation Details

In order to perform the analyses and calculate the results, we implement a benchmarking infrastructure. The infrastructure is identical for both the JVM program and the Scala Native program. The only difference is that the Scala Native program has more configurations for which the performance needs to be evaluated.

Several Scala and Java libraries are not supported by Scala Native. Frameworks such as Akka, and several parts of the standard Java Library, such as Java.util.Calendar are not supported. Therefore, the code base of MAF had to be adjusted in order to support Scala Native. Parts of the code that have conflicts with Scala Native were removed if they are not needed for the work in this dissertation. If some conflicting code is needed, then an equivalent substitute for that code is implemented.

When benchmarking Scala programs that run on the JVM, sbt-assembly¹ is used to build a fat jar that can run on the Java Virtual Machine. For programs that are compiled using Scala Native and Clang, an executable is produced that can run natively on the machine.

¹https://github.com/sbt/sbt-assembly

Analysis name	Deployment target	Lattice implementation used
JVMCP	JVM	Constant propagation implementation for lat-
		tices, as explained in Section 2.3.8.
NativeCP	Native	Constant propagation implementation for lat-
		tices, as explained in Section 2.3.8.
NativeGC	Native	The Native Lattice as explained from Section
		3.1 through 3.5, and the memory manager,
		which is explained in Chapter 4.
NativeS	Native	The Native Lattice with the alternative
		implementation for StringLattice and
		SymbolLattice that uses Scala strings, as
		explained in Section 3.6.1.1.
NativeSB	Native	The Native Lattice, the alternative implemen-
		tation for StringLattice and SymbolLattice
		that uses Scala strings, as explained in Section
		3.6.1.1, and the alternative implementation for
		BoolLattice, as explained in Section 3.6.2.
NativeGCB	Native	The Native Lattice, the memory man-
		ager and the alternative implementation for
		BoolLattice, as explained in Section 3.6.2.
NonClassNativeGCB	Native	The Native Lattice, the alternative implemen-
		tation for StringLattice and SymbolLattice
		that do not use AnyVal, as explained in Section
		3.6.1.2, and the alternative implementation for
		BoolLattice, as explained in Section 3.6.2.

Table 6.1: The benchmarked configurations for the ModF analysis.

In order to ensure that all compiler optimisations are effectively utilized when compiling MAF using Scala Native, the project settings were modified. Specifically, the optimisation mode was set to release-full, and the link time optimisation mode was set to thin.

The heap size settings of Scala Native were used to set the maximal heap size used by the garbage collector of Scala Native to the same maximal heap size used by the Java Virtual Machine. In order to make sure that the heap size settings are correctly set, we also extended Scala Native in a public pull request in order to expose the heap size information². On the Java Virtual Machine, this information could be retrieved using System.getRuntime().MaxMemory from the Java Standard Library. These parts of the Java Standard Library are not yet implemented in Scala Native. Our extension for Scala Native can now also be used in order to implement these missing functionalities.

6.2 Benchmarking Methodology

All benchmarks were executed on a machine with the following specifications:

- Hardware:
 - Manufacturer and model: Lenovo Yoga 7i 16iah7

²https://github.com/scala-native/scala-native/pull/3275

- Year of manufacture: 2022

CPU: Intel® Core™ i7-12700H Processor (14 cores @ 2.30GHz that include 6 performance cores up to 4.70GHz boost and 8 efficiency cores up to 3.50 GHz boost, 20 threads).

- **RAM:** 32 GB LPDDR5-4800

- **SSD:** 1 TB SSD M.2 2242 PCIe 4.0x4 NVMe

• Software:

- Operating System: Ubuntu 22.04.2 LTS

- **Performance mode:** Performance

- JVM version: openidk version 11.0.18 (Java 11)

- Clang version: 14.0.0-1ubuntu1

- Scala version: 3.2.1

- Scala Native version: 0.4.12

The heap sizes for both the JVM and the garbage collector of Scala Native are set at 8 GB. Each program is analyzed 200 times, preceded by 50 warm-up runs for each program, allowing the JVM to perform optimizations on the code. The 200 runs are cumulated into groups of 20 runs. The reported results are the average of the cumulative runs for each program. The 95% confidence interval is reported as well. The average of the 20 cumulative runs is referred to in this dissertation as *cumulative analysis time*.

To ensure that the benchmarking of previous analyses does not interfere with the accuracy of the results of the current analysis, each execution of the benchmarking infrastructure is dedicated to benchmarking a single analysis.

We benchmark our configurations by analyzing several non-trivial Scheme programs. Concretely, these programs are listed in Table 6.2, and are included in the code base of MAF. The lines of code that each program contains are also reported in Table 6.2. These lines of code are calculated using $cloc^{3}$, and they do not include the comments nor the blank lines.

File name	LOC
$icp/icp_3_leval.scm$	334
icp/icp_1c_prime-sum-pair.scm	394
$icp/icp_1c_ambeval.scm$	379
icp/icp_8_compiler.scm	466
$icp/icp_2_aeval.scm$	300
$icp/icp_5_regsim.scm$	396
$icp/icp_1c_ontleed.scm$	412
$icp/icp_1c_multiple-dwelling.scm$	402
$icp/icp_7_eceval.scm$	774
scm/peval.scm	497
scm/sboyer.scm	632
scm/scheme.scm	767

Table 6.2: The programs that are used for benchmarking ModF analyses.

³https://github.com/AlDanial/cloc

6.3. RESULTS 35

6.3 Results

In this section, we present the benchmarking results in bar diagrams. The results are divided into three groups according to the analysis time duration.

Figure 6.1 depicts the analyses with a cumulative analysis time lower than 30000 ms. We can see that all native analyses perform better than the JVM. The NativeGCB analysis seems to finish analyzing the programs the fastest. In Figure 6.2, programs are shown for which the cumulative analysis time of the analyses is between 30000 ms and 100000 ms. For these programs, we notice that the performance of all native analyses is similar to JVMCP.

Finally, Figure 6.3 shows the analyses with a cumulative analysis time higher than 100000 ms. Interestingly, we can see that JVMCP outperforms all native lattices by a big margin when the cumulative analysis time is high. This is likely due to the various optimisations that the JVM performs, given that it utilizes a just-in-time compiler. Therefore, the longer an analysis runs, the more hot code paths are detected and optimized, resulting in better performance. This is not the case in the native analysis, given that all code is compiled ahead of time, and no optimisations on any parts of the compiled code are performed during the execution of these analyses. We can also observe that the confidence interval for JVMCP is larger than the other analyses, which indicates more variation in analysis time. This is possibly for the same reason. Further empirical investigations a required to validate that code optimisations of JVMCP are the primary factor for the differences in longer analysis times.

6.4 Comparing Relative Analysis Times

In this section, we compare the analysis times of different lattice implementations in relation to one another. This enables us to assess the performance of the alternative implementations for the lattices when employed in the analyses.

The results presented in this section are the relative analysis time. This is computed by dividing the mean of the cumulative analysis time of a given analysis A by the mean of the cumulative analysis time of another analysis B that A is being compared to. Lower relative analysis times mean that the analysis A performed better in the experiments.

Figure 6.4 depicts the analysis time of NativeGCB and NativeSB relative to the analysis time of respectively NativeGC and NativeS. These results help us assess whether the alternative implementation for BoolLattice, as described in Section 3.6.2, performs better than the implementation of BoolLattice that uses bitwise operations, which is described in Section 3.1.

As we can see from the results, analyses that use the alternative implementation for BoolLattice perform better than analyses that use the BoolLattice implementation with bitwise operations in most cases. These results were to be expected, given that additional code was required for some lattice operations in order to convert the results from the bitwise operations to Scala booleans, which might have added an additional overhead to that implementation.

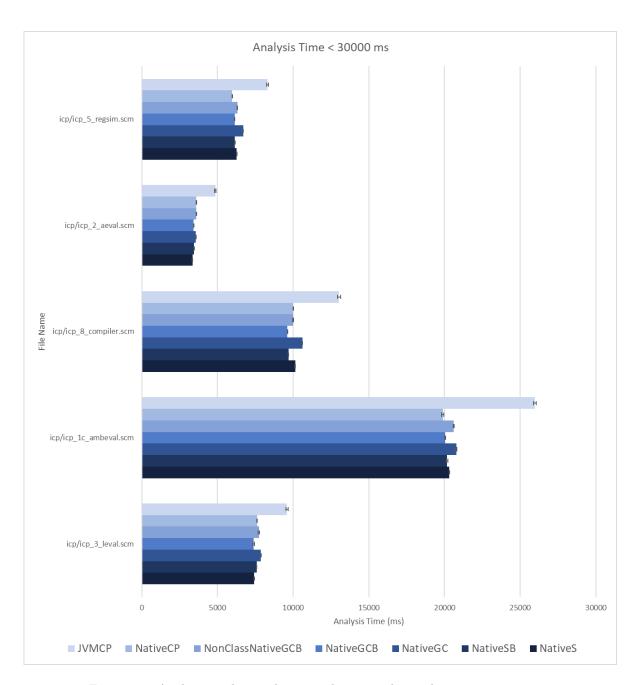


Figure 6.1: Analyses with cumulative analysis time lower than 30000 ms.

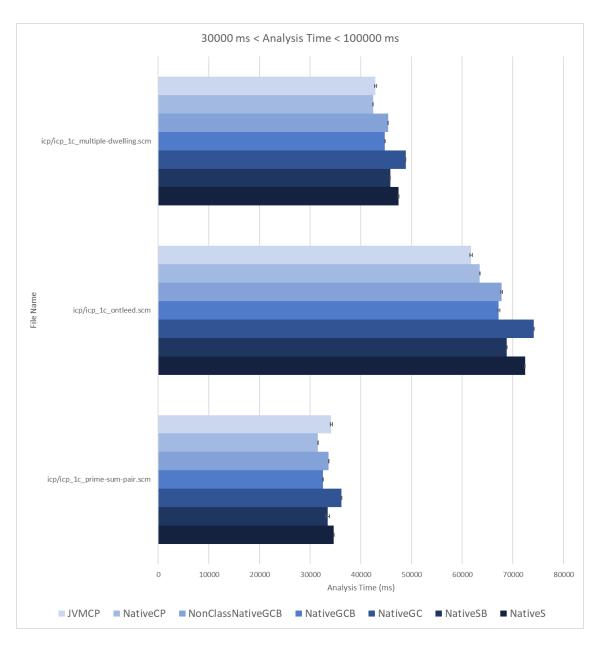


Figure 6.2: Analyses with cumulative analysis time between 30000 ms and 100000 ms.

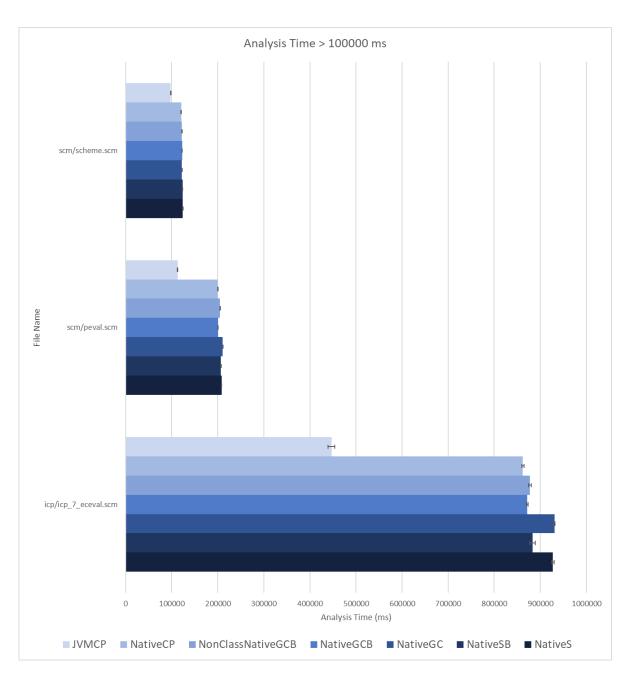


Figure 6.3: Analyses with cumulative analysis time higher than 100000 ms.

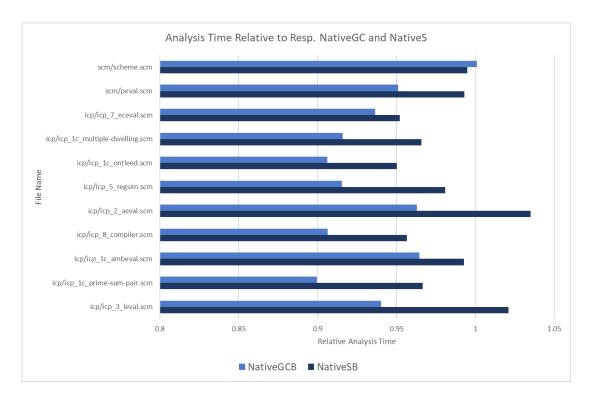


Figure 6.4: Analysis times of NativeGCB and NativeSB relative to respectively NativeGC and NativeS.

Figure 6.5 depicts the analysis time of NonClassNativeGCB relative to the analysis time of NativeGCB. These results help us assess whether using value classes around the underlying representation for strings introduced additional overhead. As we can see, the differences are fairly minimal, and in most cases in favor of NativeGCB.

Lastly, we also compare NativeGCB and NativeSB to NativeCP. This comparison helps us assess the performance of the analyses when low-level constructs are used. This comparison is also valuable for evaluating the domain-specific memory manager, given that NativeSB relies on the memory manager of Scala Native in order to manage the memory of the string lattice and the symbol lattice elements, while NativeGCB uses the domain-specific memory manager which uses analyses properties to manage the memory of the string lattice and the symbol lattice elements.

Figure 6.6 shows the analysis time of NativeGCB and NativeSB relative to NativeCP. In all programs, NativeGCB performed better than NativeSB. This might be an indication that using a low-level string representation for the StringLattice and SymbolLattice elements, accompanied by the domain-specific memory manager, improve the analysis performance, given that symbols are frequently used in Scheme. We can also observe that, in some programs for which the analysis time is low, the NativeGCB analysis performed better than NativeCP. However, in most cases, the performance of both analyses is very similar to NativeCP. The compiler optimiser of Scala Native performs a substantial amount of optimisations that are intended for the high-level object-oriented and functional features of Scala [13, 7]. Therefore, it is possible that these optimisations have improved the performance of NativeCP, which relies entirely on the object-oriented and functional features that Scala provides. Additional experiments are needed in order to identify the reasons behind the performance similarities between the analyses.

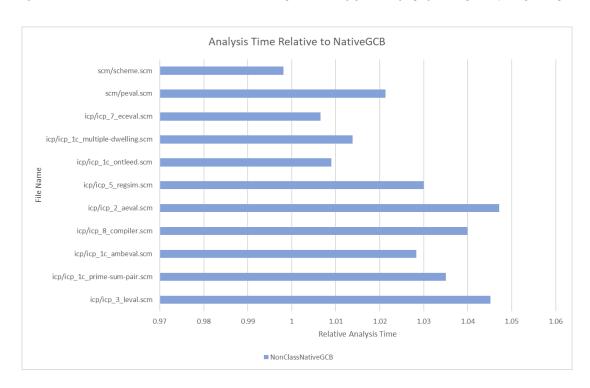


Figure 6.5: Analysis time of NonClassNativeGCB relative to NativeGCB.

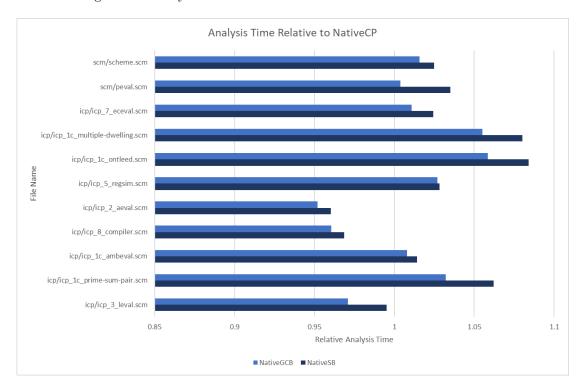


Figure 6.6: Analysis time of NativeGCB and NativeSB relative to NativeCP.

Chapter 7

Conclusion

In this dissertation, we presented a low-level efficient implementation for the constant propagation abstract domain that is used in function-modular analyses for Scheme programs. We presented a domain-specific memory manager, which uses analyses properties in order to manage the memory of some elements of the abstract domain. We demonstrated the correctness of the results that are produced by analyses that use the low-level abstract domain and the domain-specific memory manager.

As we saw in Chapter 6, using a low-level implementation for analyzing programs with a relatively low analysis time improved the performance of analyses. In most cases, running analyses natively on the local machine, whether these analyses use the Native Lattice low-level implementation or the high-level constant propagation domain implementation, closely matches the performance of the Java Virtual Machine whilst still being entirely compiled ahead of time. The Java Virtual Machine performs significantly better when running analyses for programs with a long analysis time, which could be explained by its just-in-time optimisations.

7.1 Future Work

The results of our experiments raised some interesting questions. Analyses that run on the Java Virtual Machine perform better when the analysis time is very high. The low-level implementation of the Native Lattice, augmented with the domain-specific memory manager, closely matches the performance of the high-level constant propagation domain. Therefore, additional experimental studies might be needed in order to identify the main factors that are behind these results. For example, microbenchmarking the various lattice implementations independently and in isolation from the rest of the analysis should provide us with more precise insights. Unfortunately, given the time limitations, it was not feasible to perform these experiments for this dissertation.

Additionally, the presented domain-specific memory manager could be further extended and optimised. An idea worth exploring, for example, might be optimising compound data structures that are used in analyses, such as cons-cells and vectors. In this case, it is also a possibility to extend the capabilities of the memory manager in order to also manage the memory of compound data structures. This opens doors for using interesting algorithms, such as an efficient iterative implementation of the Deutsch-Schorr-Waite algorithm.

Bibliography

- [1] Stephen Compall. The high cost of anyval subclasses. 2017.
- [2] Patrick Cousot and Radhia Cousot. Modular Static Program Analysis. In *International Conference on Compiler Construction*, pages 159–179. Springer, 2002.
- [3] Brian A. Davey and Hilary A. Priestley. *Introduction to lattices and order*, chapter Complete Lattices and Galois Connections. Cambridge University Press, Cambridge, 1990.
- [4] Brian A. Davey and Hilary A. Priestley. *Introduction to lattices and order*, chapter Ordered Sets. Cambridge University Press, Cambridge, 1990.
- [5] Denys Shabalin et al. Scala Native Documentation, chapter User's Guide. EPFL, 2022. Release 0.4.9.
- [6] Tim Lindholm, Frank Yellin, Gilad Bracha, Alex Buckley, and Daniel Smith. *The Java Virtual Machine Specification, Java SE 8 Edition*, chapter The Structure of the Java Virtual Machine. Oracle, 2022.
- [7] Wojciech Mazur. A Deep Dive into Scala Native Internals. Scala Love conference, 2021.
- [8] Anders Møller and Michael I. Schwartzbach. *Static Program Analysis*, chapter Lattice Theory. 2008. Aarhus University, Denmark.
- [9] Martin Odersky, Jeff Olson, Paul Phillips, and Joshua Suereth. SIP-15 Value classes. EPFL, 2012.
- [10] Henry Gordon Rice. Classes of Recursively Enumerable Sets and Their Decision Problems. Transactions of the American Mathematical society, 74(2):358–366, 1953.
- [11] Xavier Rival and Kwangkeun Yi. Introduction to Static Analysis: An Abstract Interpretation Perspective, chapter Pogram Analysis. The MIT Press, 2020.
- [12] Abdullah Sabaa Allil, Noah Van Es, Jens Van der Plas, Quentin Stiévenart, and Coen De Roover. Research training: Optimising static program analysis using scala native. 2023.
- [13] Denys Shabalin and Martin Odersky. Interflow: Interprocedural Flow-Sensitive Type Inference and Method Duplication. In *Proceedings of the 9th ACM SIGPLAN International Symposium on Scala*, pages 61–71, 2018.
- [14] Noah Van Es, Jens Van der Plas, Quentin Stiévenart, and Coen De Roover. MAF: A Framework for Modular Static Analysis of Higher-Order Languages. In 2020 IEEE 20th International Working Conference on Source Code Analysis and Manipulation (SCAM), pages 37–42. IEEE, 2020.