

Non-Local ConvLSTM for Video Compression Artifact Reduction

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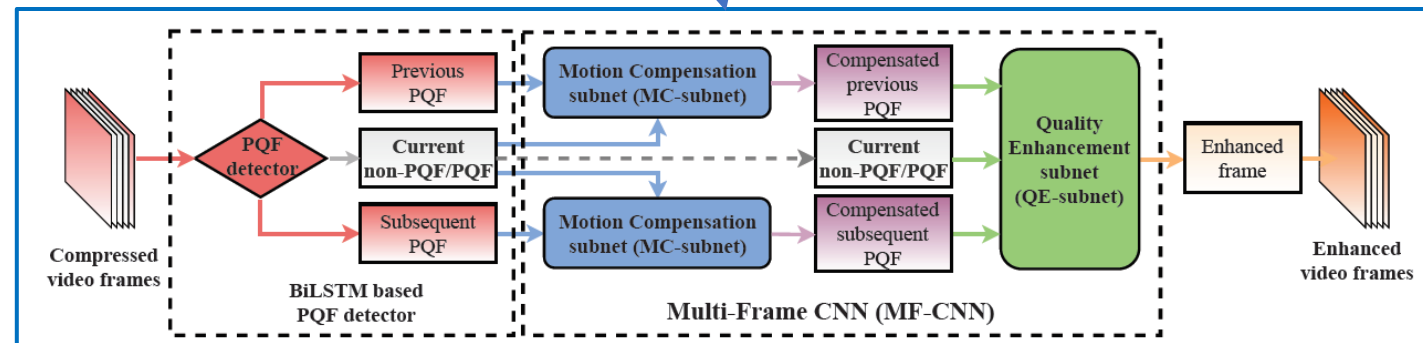
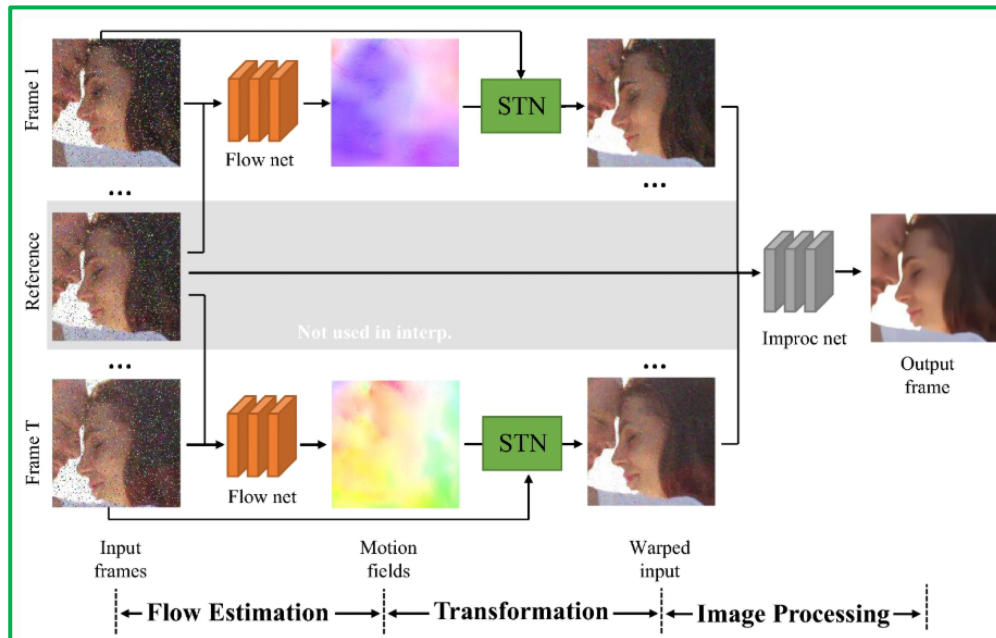
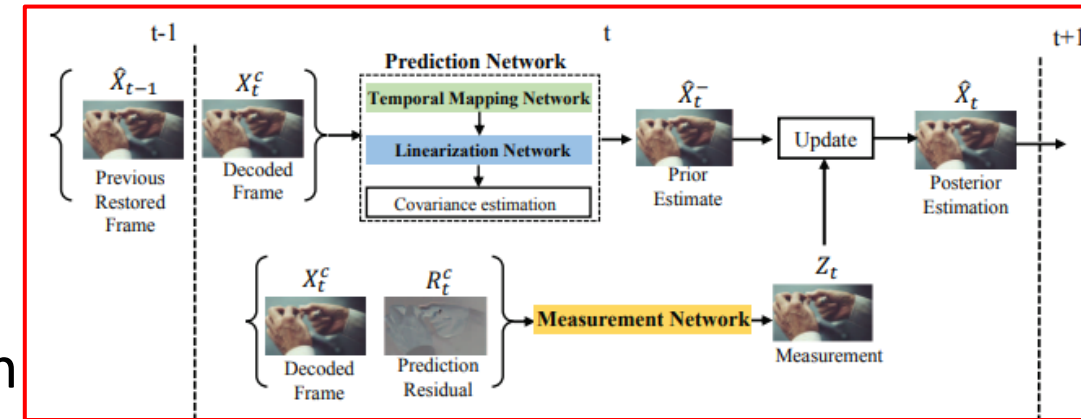
ICCV 2019

Presented by Qing Lyu on 7/22/20

Background

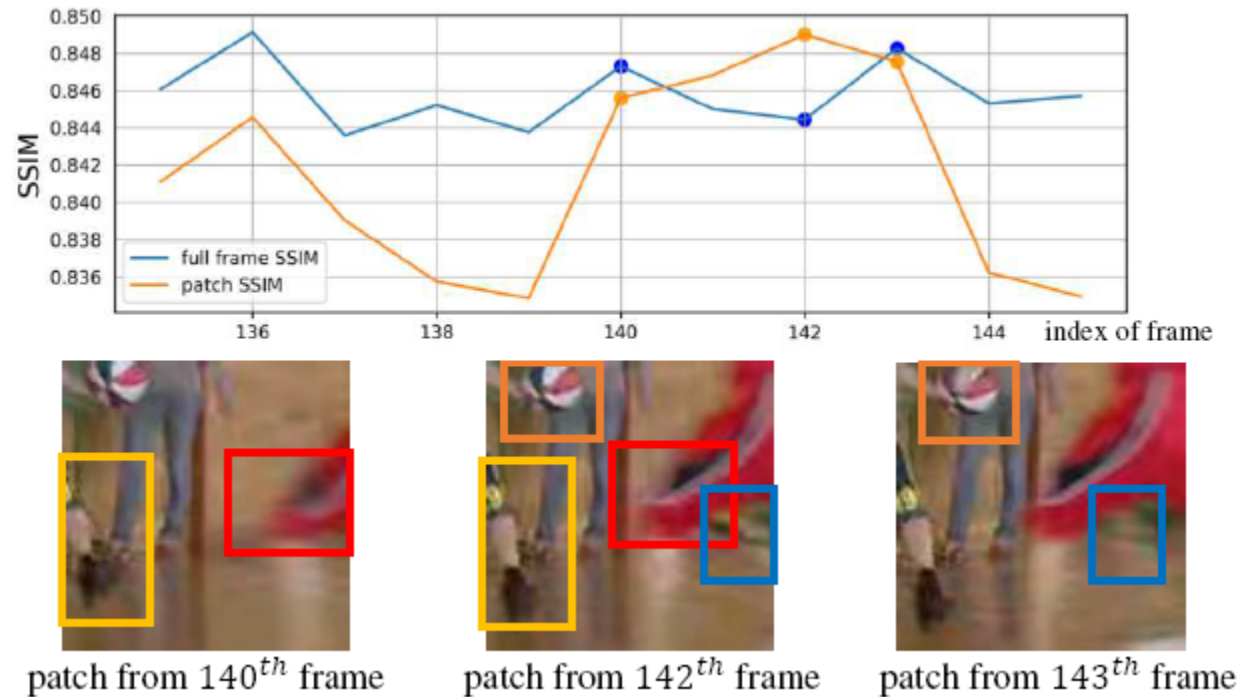
- Video compression artifact reduction
 - Single image compression artifact reduction
 - Video compression artifact reduction

- Deep Kalman filter network (ECCV 2018, DL club: July 31, 2019)
- Task-oriented motion-based network (IJCV 2019, DL club: September 11, 2019)
- Network using motion-compensated nearest PQFs (PAMI 2019)



Shortcoming of existing methods

- Existing methods used a pair of neighboring frames, may **miss** high-quality details of some other neighbor frames



Advantageous

- No accurate motion estimation and compensation is explicitly needed
- It is applicable to videos compressed by various commonly-used compression algorithms such as H.264/AVC and H.265/HEVC
- The proposed method outperforms the existing methods

Method: network

- End-to-end framework with three modules
 - Encoder
 - NL-ConvLSTM
 - Decoder

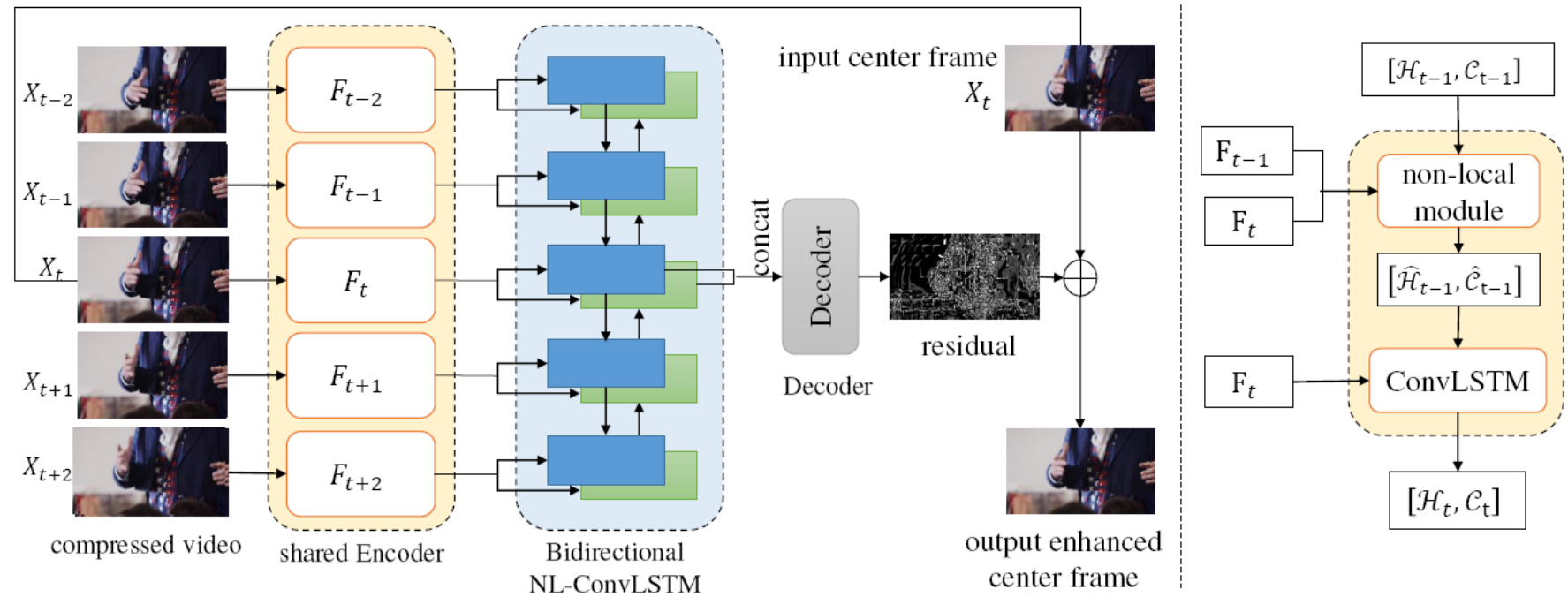


Figure 2. The framework of our method (left) and the architecture of NL-ConvLSTM (right)

Method: Non-Local ConvLSTM

- ConvLSTM

$$[\mathcal{H}_t, \mathcal{C}_t] = \text{ConvLSTM}(F_t, [\mathcal{H}_{t-1}, \mathcal{C}_{t-1}])$$

- NL-ConvLSTM

$$S_t = \text{NL}(F_{t-1}, F_t),$$

$$[\hat{\mathcal{H}}_{t-1}, \hat{\mathcal{C}}_{t-1}] = \text{NLWarp}([\mathcal{H}_{t-1}, \mathcal{C}_{t-1}], S_t),$$

$$[H_t, C_t] = \text{ConvLSTM}(F_t, [\hat{\mathcal{H}}_{t-1}, \hat{\mathcal{C}}_{t-1}]),$$

$$D_t(i, j) = \|F_{t-1}(i) - F_t(j)\|_2,$$

$$S_t(i, j) = \frac{\exp(-D_t(i, j) / \beta)}{\sum_{\forall i} \exp(-D_t(i, j) / \beta)},$$

$$[\hat{\mathcal{H}}_{t-1}, \hat{\mathcal{C}}_{t-1}] = [\mathcal{H}_t \cdot S_t, \mathcal{C}_t \cdot S_t],$$

Calculation simplification

- Directly compute S is the warping operation will incur extremely high computation and memory cost
- To simplify the calculation, proposing a two stage NL approximation method
 - Use average pooling to downsample the feature map from the Encoder

$$D_t(i, j) = \|F_{t-1}(i) - F_t(j)\|_2, \quad \longrightarrow \quad D_t^p(i, j) = \|F_{t-1}^p(i) - F_t^p(j)\|_2$$

- Compute and store the similarities between each pixel of F_t^p and the corresponding $k \times p^2$ pixels of F_{t-1}^p . While for the other pixels in the preceding frame, the elements of D_t and S_t are set to infinity and 0 respectively.

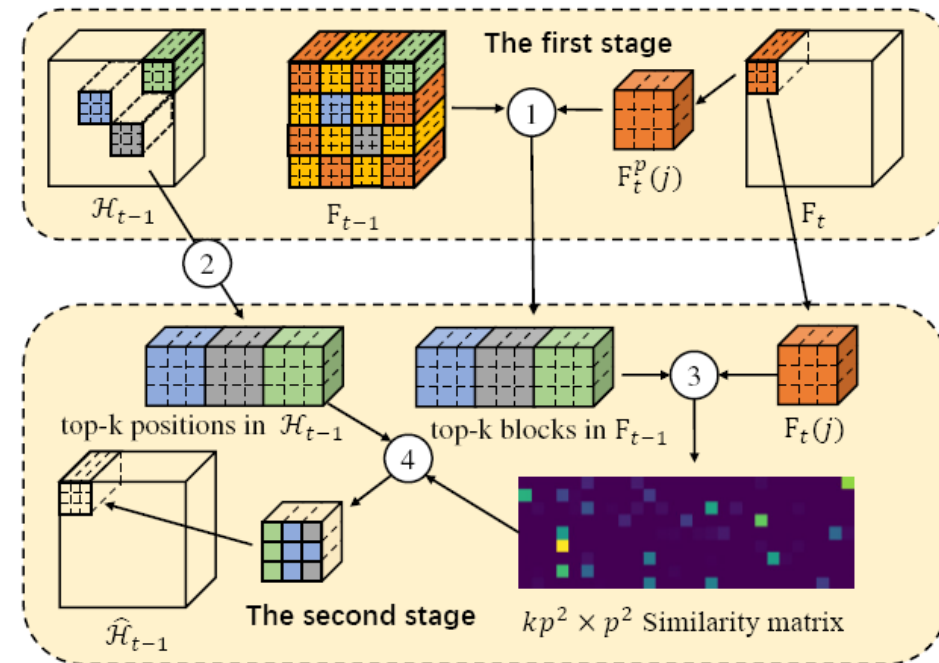


Figure 3. The workflow of two-stage similarity approximation. ① finding the top- k most similar blocks in F_{t-1} with respect to block $F_t^p(j)$ from F_t ; ② extracting blocks in \mathcal{H}_{t-1} from the corresponding positions of the top- k most similar blocks in F_{t-1} ; ③ calculating pixel-wise similarity between the selected blocks from F_{t-1} and $F_t^p(j)$; ④ NLWarp operation for \mathcal{H}_t .

Complexity analysis

Table 1. Complexity comparison of the original non-local approach and ours. Here, N and C are the numbers of positions and channels, k and p are the number of pre-filtered blocks and the downsampling scale. By setting $k=4$ and $p=10$, our method cuts the time and space to about 1/1000 of that consumed by the original non-local method in 1080P videos.

	Original non-local	NL-ConvLSTM
Time	$\mathcal{O}(2N^2C)$	$\mathcal{O}((N/p^2)^2(C + \log k) + 2kNCp^2)$
Space	$\mathcal{O}(2N^2)$	$\mathcal{O}((N/p^2)^2 + kN/p^2 + 2kNp^2)$

to $\mathcal{O}((N/p^2)^2C + 2kNCp^2)$. By properly choosing the values of k and p so that $kp^2 \ll N$, we have $\phi/\psi = 1/(2p^4) + kp^2/N \ll 1$, which means that our method dramatically reduces the computation cost of the original method. And for a given k , ϕ/ψ achieves the minimum $1.5(k/N)^{2/3}$ with $p=(N/k)^{1/6}$. Similar conclusion can be

Experiment

- Datasets
 - Vimeo-90K
 - 89,800 video sequences
 - 448x256 resolution
 - Compression algorithm: x265 in FFmpeg with QP=32 or 37
 - Yang's dataset
 - 70 video sequences
 - Resolution vary from 352x240 to 2560x1600
 - Compression algorithm: HEVC LDP

Ablation study

Table 2. Ablation study of the proposed NL-ConvLSTM on Yang *et al.*'s dataset with $QP=37$. The results of PSNR improvement $\Delta PSNR$ (db) are reported in the 1st row. The results of SSIM improvement $\Delta SSIM$ ($\times 10^{-2}$) are listed in the 2nd row.

	Encoder-Decoder with 1 frame	ConvLSTM with 7 frames	ME-ConvLSTM with 7 frames	Our method with 7 frames
$\Delta PSNR$	0.395	0.456	0.503	0.601
$\Delta SSIM$	0.684	0.723	0.827	0.897

Quantitative comparison

Table 3. Average PSNR/SSIM on Vimeo-90K.

QP	32	37
HEVC [34]	34.19 / 0.950	31.98 / 0.923
ARCNN [11]	34.87 / 0.954	32.54 / 0.930
DnCNN [49]	35.58 / 0.961	33.01 / 0.936
DSCNN [44]	35.61 / 0.960	32.99 / 0.938
DKFN [26]	35.81 / 0.962	33.23 / 0.939
3D CNN	35.81 / 0.961	33.25 / 0.938
Our method	35.95 / 0.965	33.39 / 0.943

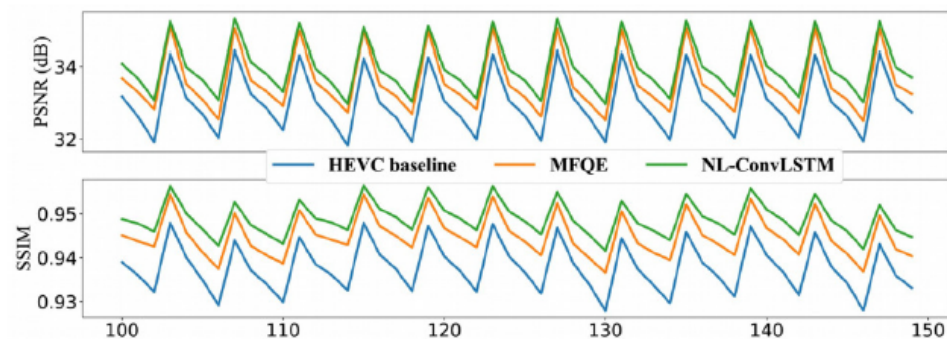


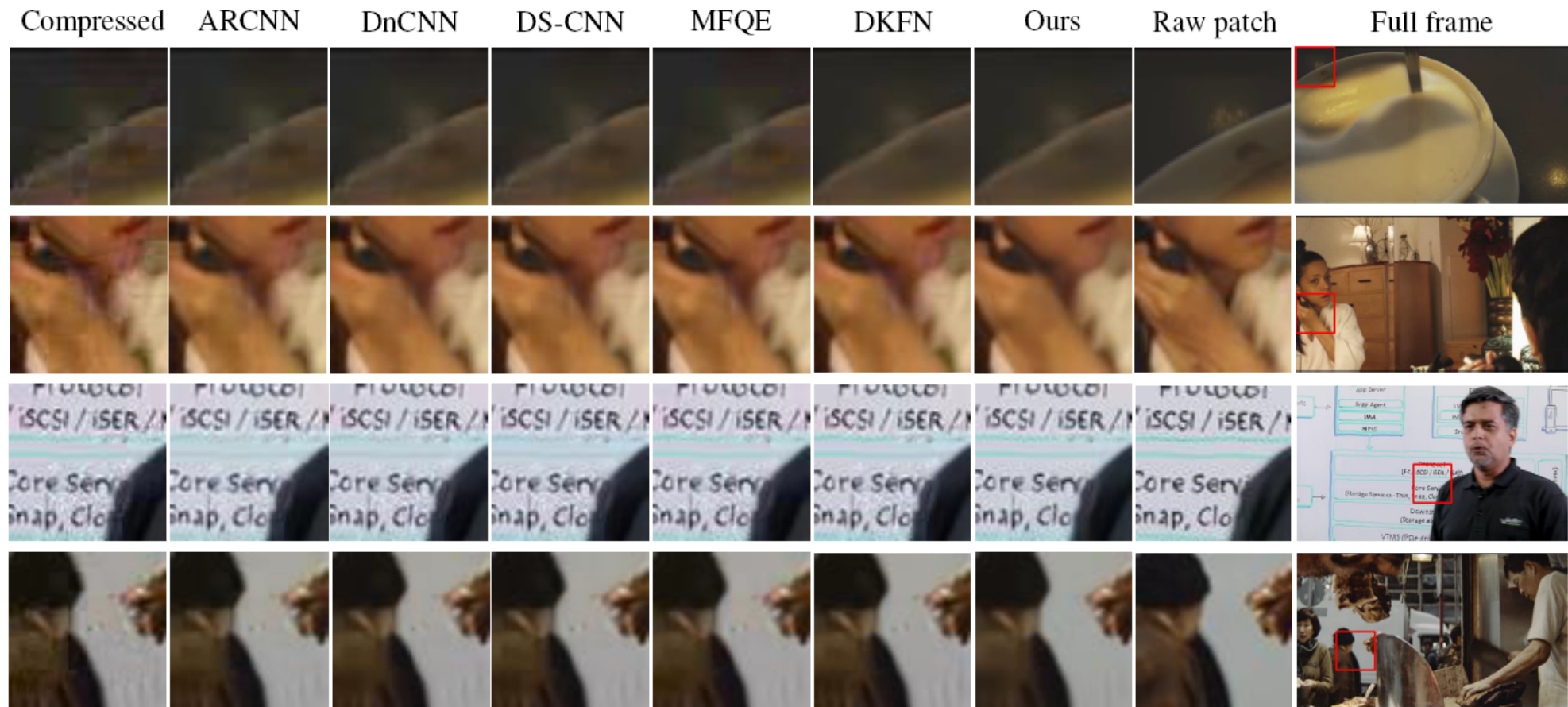
Figure 5. PSNR/SSIM curves of HEVC baseline, MFQE and NL-ConvLSTM on the sequence *TunnelFlag* with $QP=37$.

Table 4. Average Δ PSNR (dB) and Δ SSIM ($\times 10^{-2}$) on Yang *et al.*'s dataset.

QP	Seq.	ARCNN [11]	DnCNN [49]	DSCNN [44]	MFQE [45]	Our method
37	1	0.241 / 0.51	0.448 / 0.83	0.492 / 0.87	0.772 / 1.15	0.827 / 1.21
	2	0.115 / 0.30	0.439 / 0.52	0.458 / 0.58	0.604 / 0.63	0.971 / 0.92
	3	0.161 / 0.49	0.276 / 0.76	0.271 / 0.74	0.472 / 0.91	0.483 / 0.99
	4	0.183 / 0.35	0.377 / 0.55	0.393 / 0.54	0.438 / 0.48	0.576 / 0.66
	5	0.150 / 0.30	0.333 / 0.48	0.356 / 0.53	0.550 / 0.52	0.598 / 0.74
	6	0.161 / 0.23	0.415 / 0.50	0.435 / 0.49	0.598 / 0.51	0.658 / 0.67
	7	0.128 / 0.29	0.284 / 0.44	0.277 / 0.45	0.390 / 0.45	0.394 / 0.58
	8	0.125 / 0.37	0.276 / 0.61	0.230 / 0.63	0.484 / 1.01	0.563 / 1.18
	9	0.149 / 0.38	0.299 / 0.71	0.271 / 0.66	0.394 / 0.92	0.439 / 1.03
	10	0.146 / 0.24	0.289 / 0.58	0.274 / 0.54	0.402 / 0.80	0.501 / 0.99
	Ave.	0.156 / 0.35	0.344 / 0.59	0.346 / 0.60	0.510 / 0.74	0.601 / 0.90
42	Ave.	0.252 / 0.83	0.301 / 0.96	0.364 / 1.06	0.461 / —	0.614 / 1.47

1: *PeopleOnStreet* 2: *TunnelFlag* 3: *Kimono* 4: *BarScene* 5: *Vidyo1*
 6: *Vidyo3* 7: *Vidyo4* 8: *BasketballPass* 9: *RaceHorses* 10: *MaD*

Qualitative comparison



Run time comparison

Table 5. Run-time (*ms per frame*) comparison among six methods.

Resolution	180x180	416x240	640x360	1280x720	1920x1080
ARCNN [11]	1.73	4.58	9.19	36.06	80.70
DnCNN [49]	6.30	15.84	35.51	139.77	315.83
DSCNN [44]	15.26	36.88	82.31	322.92	731.21
MFQE ⁴ [45]	20.28+	51.01+	112.87+	443.82+	1009.00+
original NL	4391.75	-	-	-	-
ours	102.13	304.11	621.94	2607.60	6738.00

Contribution

- Propose a new idea for video compression artifact reduction by **exploiting multiple preceding and following frames** of the target frame, **without explicitly computing and compensating motion** between frames
- Develop an **end-to-end deep neural network** called non-local ConvLSTM to learn the spatiotemporal information from multiple neighboring frames
- Design an **approximate method** to compute the inter-frame pixel-wise similarity
- Conduct extensive experiments over two datasets to evaluate the proposed method, which **achieves state-of-the-art performance** for video compression artifact reduction