

Expectation-Maximization Based Defense Mechanism for Distributed Model Predictive Control



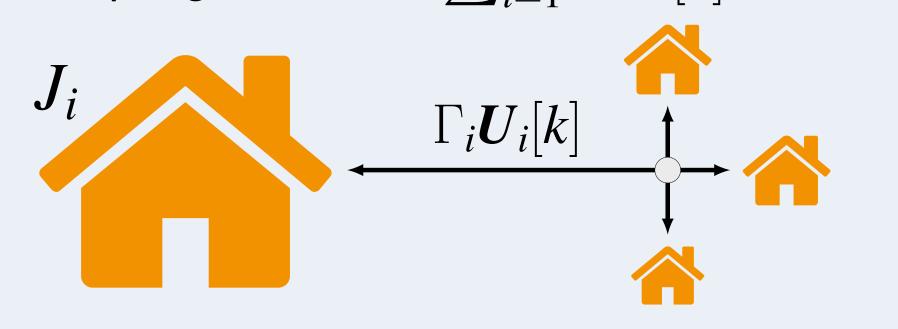
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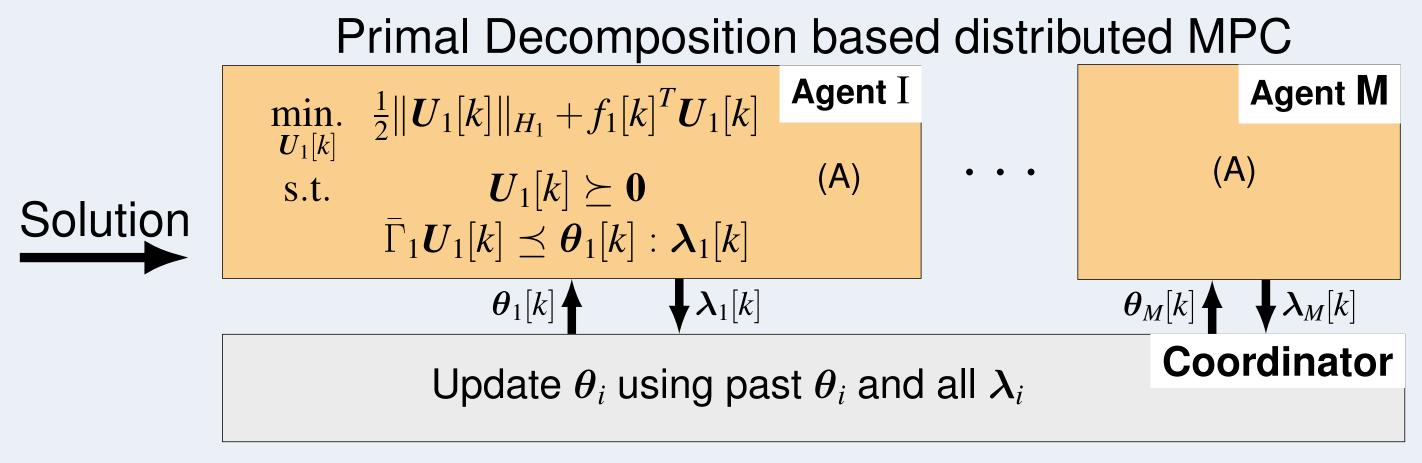
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1. Challenge - False Data injection in dMPC exchange

- lacksquare Decomposable quadratic objective $\sum_{i=1}^M J_i$
- lacksquare Coupling constraint $\sum_{i=1}^{M} \Gamma_i oldsymbol{U}_i[k] \leq oldsymbol{U}_{\max}$





Coordinator allocates θ_i Agent has dissatisfaction λ_i

What happens if an agent lies about λ_i ?



2. Attack and consequences

- $\triangleright \lambda_i$ is the dissatisfaction of *i* to allocation θ_i
- ► Attacker increases λ_i using function $\gamma(\cdot)$
- $ightharpoonup \uparrow$ dissatisfaction == \uparrow allocation

Remark

Attacker says it is satisfied only when it is

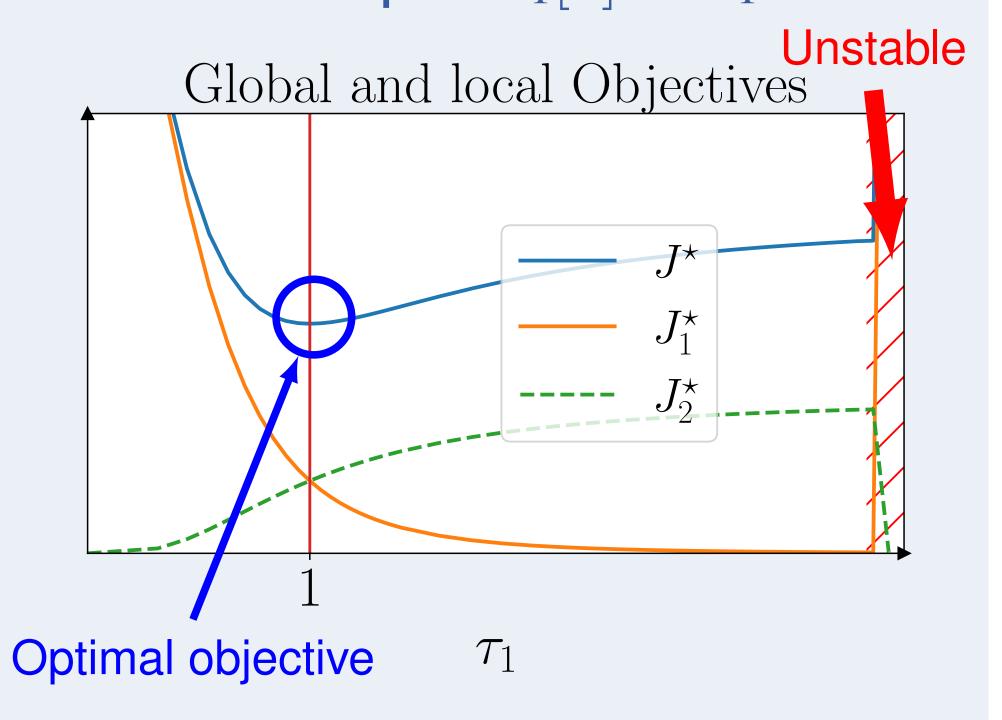
Assumption

Attacker chooses an invertible linear function

$$\lambda_i = \gamma_i(\lambda_i) = T_i[k]\lambda_i,$$

- ► Effects of cheating matrix $T_i[k]$
 - Increase on global objective
 - Destabilization

Example $T_1[k] = \tau_1 I$



Can we mitigate the effects?

YES! If we estimate $T_i[k]$ and invert it But how?

3. Estimating cheating matrix $T_i[k]$

Local problems (A) are QP

Explicit Solution with PWA form w.r.t θ_i :

 $\lambda_i[k] = -P_i^n \theta_i[k] - s_i^n[k]$, if $G_i^n[k] \theta_i[k] \leq b_i^n[k]$ (B) with $n \in \{1:N\}$. $G_i^n[k]$ and $b_i^n[k]$ define regions. **Remark**

Sensibilities P_i^n are **time invariant**.

Another assumption

In Region 1 local constraints are active:

$$\lambda_i[k] = -P_i^1 \theta_i[k] - s_i^1[k]$$
, if $G_i^1[k] \theta_i[k] \leq b_i^1[k]$ (C) and $\theta_i = \mathbf{0}$ belongs to it

Attacker modifies sensibility $\tilde{P}_i[k] = T_i[k]\bar{P}_i$ and $\tilde{s}_i[k] = T_i[k]s_i[k]$

If we can know **nominal** \bar{P}_i^1 , by estimating $\tilde{P}_i[k]$, we can find $T_i[k]^{-1}$:

$$\widehat{T_i[k]}^{-1} = \overline{P}_i^1 \widehat{\widetilde{P}_i^1[k]}^{-1} \tag{D}$$

But how can we estimate the $\tilde{P}_i^1[k]$?

Enter Expectation Maximization

- Classify data in regions (latent variables)
- Estimates parameters using weighted LS

EM needs minimally excited inputs θ_i and λ_i .

- During negotiation (time dependence) X
- Solution: estimate in a separate phase
 - ► Generate independent points near $\theta_i = \mathbf{0}$ Artificial Scarcity Sampling

4. Expectation Maximization

- ▶ Regions are indexed by $z \in \mathcal{Z} = \{1 : Z\}$
- ► Gaussian mixture (mean (B) and $\Sigma \rightarrow 0$)
- Parameters $\mathcal{P} = \{\mathcal{P}^z \mid z \in \mathcal{Z}\}$, with $\mathcal{P}^z = (\tilde{P}^z, \tilde{s}^z, \pi^z)$.
- ► Observations $o \in \mathcal{O} = \{1 : O\}$ of (θ_i, λ_i) stacked as $(\underline{\Theta}, \underline{\Lambda})$ with corresponding \underline{Z}

Algorithm 1: Expectation Maximization

Initialize parameters \mathcal{P}_{new}

repeat

 $\mathcal{P}_{\text{cur}} \leftarrow \mathcal{P}_{\text{new}}$

E step:

Evaluate $\zeta_{zo}(\mathcal{P}_{cur}) = \mathbb{P}(\underline{z}_o = z | \underline{\lambda}_o, \underline{\theta}_o; \mathcal{P}_{cur})$

M step:

Reestimate parameters using:

$$\mathcal{P}_{\text{new}} = \arg \max_{\mathcal{P}} \mathbb{E}_{\zeta_{zo}(\mathcal{P}_{\text{cur}})} \left[\ln \mathbb{P}(\underline{\Theta}, \underline{\Lambda}, \underline{Z}; \mathcal{P}) \right]$$

until \mathcal{P}_{cur} converges

5. Secure dMPC

Modified negotiation (some additional steps):

- 1. Detection Phase
- 1.1 Estimate sensibility $\widehat{P}_{i}^{1}[k]$
 - Artificial Scarcity Sampling + EM
- 1.2 Detect attack if $\|\tilde{P}_i^1[k] \bar{P}_i^1\|_F \ge \epsilon_P$
- 2. Negotiation Phase
- 2.1 If detected reconstruct λ_i

$$\boldsymbol{\lambda}_{i\mathrm{rec}} = T_i[k]^{-1} \widetilde{\boldsymbol{\lambda}}_i$$
 (E

2.2 Use adequate λ_i to update θ_i

6. Example: Control of a heating network under power scarcity - 3 Scenarios (Nominal, Selfish, + Correction)

