

# **Expectation-Maximization Based Defense Mechanism** for Distributed Model Predictive Control



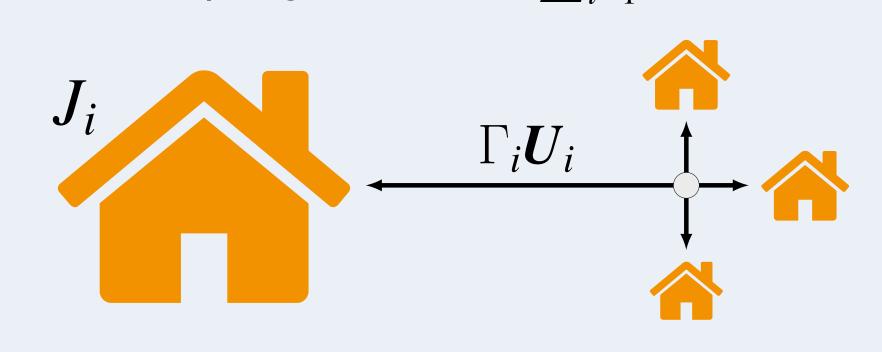
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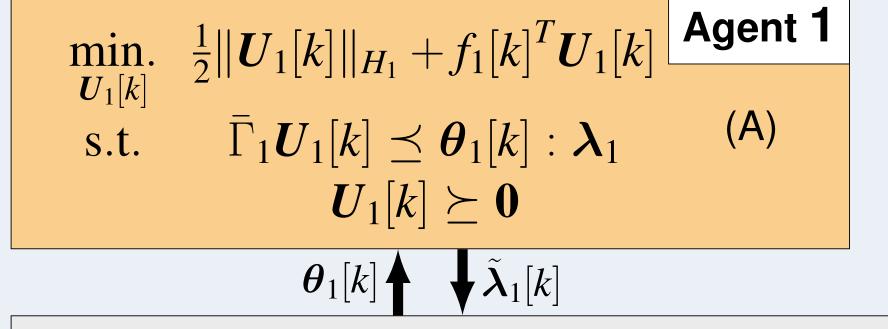
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### 1. Challenge - False Data injection in dMPC exchange

- ► Global decomposable quadratic objective  $\sum_{i=1}^{M} J_i$
- ► Global coupling constraint  $\sum_{i=1}^{M} \Gamma_i U_i \leq U_{\text{max}}$





(??) Coordinator  $\boldsymbol{\theta}[k]^{(p+1)} = \operatorname{Proj}^{\mathcal{S}}(\boldsymbol{\theta}[k]^{(p)} + \rho^{(p)}\boldsymbol{\lambda}[k]^{(p)})$  (B)

What happens if an agent lies?



### 2. Attack and consequences

- $\triangleright \lambda_i$  is the dissatisfaction of i to allocation  $\theta_i$
- ► Attacker increases  $\lambda_i$  using function  $\gamma(\cdot)$
- $ightharpoonup \uparrow$  dissatisfaction ==  $\uparrow$  allocation

#### Assumption 1

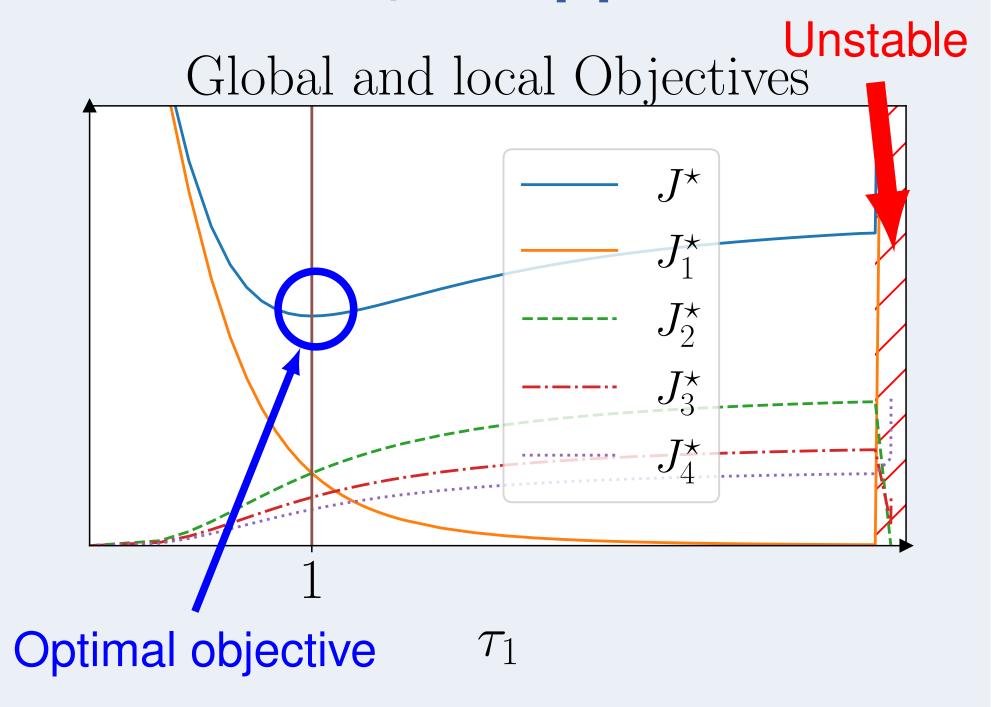
The attacker chooses a linear function

$$\tilde{\lambda}_i = \gamma_i(\lambda_i) = T_i[k]\lambda_i,$$

 $\widetilde{\boldsymbol{\lambda}}_i = \mathbf{0}$  only if  $\boldsymbol{\lambda}_i = \mathbf{0} \to T_i[k]$  is invertible.

- Effects
  - Increase on global objective
  - Destabilization

## Example $T_i[k] = \tau_1 I$



## Can we mitigate the effects?

YES! If we estimate  $T_i[k]$  and invert it But how??

## 3. Estimating cheating matrix $T_i[k]$

Local problems (??) are QP

Explicit Solution with PWA form w.r.t  $\theta_i$ :

$$\lambda_i[k] = -P_i^n \boldsymbol{\theta}_i[k] - s_i^n[k], \text{ if } G_i^n[k] \boldsymbol{\theta}_i[k] \leq \boldsymbol{b}_i^n[k]$$
 (C)

with  $n \in \{1:N\}$ .  $G_i^n[k]$  and  $\boldsymbol{b}_i^n[k]$  define regions. Remark 1

Sensibilities  $P_i^n$  are **time invariant**.

#### Assumption 2

In Region 1 local constraints are active:

$$\boldsymbol{\lambda}_i[k] = -P_i^1 \boldsymbol{\theta}_i[k] - \boldsymbol{s}_i^1[k], \text{ if } G_i^1[k] \boldsymbol{\theta}_i[k] \preceq \boldsymbol{b}_i^1[k] \hspace{1mm} (D)$$

#### Assumption 3

 $\theta_i = \mathbf{0}$  belongs to Region 1

Attacker modifies sensibility  $\tilde{P}_i[k] = T_i[k]\bar{P}_i$ 

If we can know **nominal**  $\bar{P}_i^1$ , estimating  $\tilde{P}_i[k]$ , we can find  $T_i[k]^{-1}$ :

$$\widehat{T_i[k]}^{-1} = \bar{P}_i^1 \widehat{\tilde{P}_i^1[k]}^{-1} \tag{E}$$

## But how do we estimate $\tilde{P}_i^1[k]$ ?

**Enter Expectation Maximization** 

- Classify data in regions (latent variables)
- Estimates parameters using weighted LS

EM needs minimally excited inputs  $\theta_i$  and  $\lambda_i$ .

- Estimation negotiation (time dependence)
- Solution: estimate in a separate phase
  - ► Generate independent points near  $\theta_i = \mathbf{0}$ **Artificial Scarcity Sampling**

### 4. Expectation Maximization

Agent M

- ▶ Regions are indexed by  $z \in \mathcal{Z} = \{1 : Z\}$
- ► Gaussian mixture (mean (??) and  $\Sigma \to 0$ )
- ▶ Parameters  $\mathcal{P} = \{\mathcal{P}^z \mid z \in \mathcal{Z}\}$ , with  $\mathcal{P}^z = (P^z, \widetilde{\mathbf{s}}^z, \pi^z)$ .
- ▶ Observations  $o \in \mathcal{O} = \{1 : O\}$  of  $(\theta_i, \lambda_i)$

Algorithm 1: Expectation Maximization Initialize parameters  $\mathcal{P}_{\text{new}}$ 

repeat

 $\mathcal{P}_{\mathrm{cur}} \leftarrow \mathcal{P}_{\mathrm{new}}$ 

E step:

Evaluate  $\zeta_{zo}(\mathcal{P}) = \mathbb{P}(\underline{z}_o = z | \underline{\lambda}_o, \underline{\theta}_o; \mathcal{P})$ 

M step:

Reestimate parameters using:

 $\mathcal{P}_{\text{new}} = \arg \max_{\mathcal{P}} \mathbb{E}_{\zeta_{zo}(\mathcal{P}_{\text{cur}})} \left[ \ln \mathbb{P}(\underline{\Theta}, \underline{\Lambda}, \underline{Z}; \mathcal{P}) \right]$ 

until  $\mathcal{P}_{cur}$  converges to a local maximum

#### 5. Secure dMPC

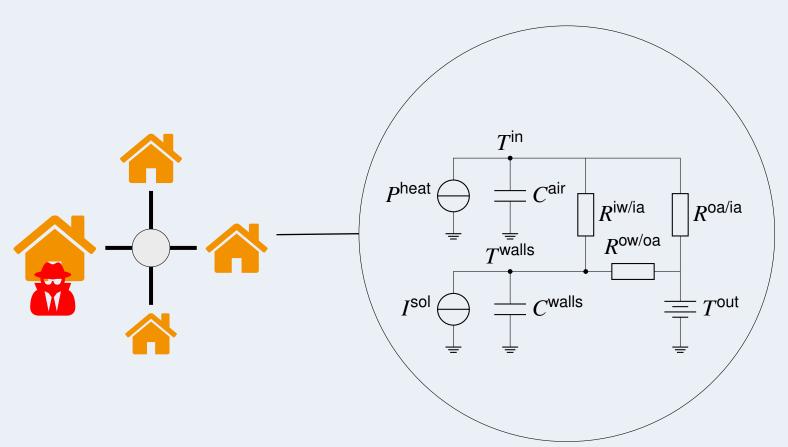
Modified negotiation (some additional steps):

- **Detection Phase**
- 1.1 Estimate sensibility  $\tilde{P}_{i}^{1}[k]$ 
  - Artificial Scarcity Sampling + EM
- 1.2 Detect attack if  $\|\tilde{P}_i^1[k] \bar{P}_i^1\|_F \ge \epsilon_P$
- 2. Negotiation Phase
- 2.1 If detected reconstruct  $\lambda_i$

$$oldsymbol{\lambda}_{i\mathrm{rec}} = \widehat{T_i[k]}^{-1} \widetilde{oldsymbol{\lambda}}_i$$
 (F)

2.2 Use adequate  $\lambda_i$  to update  $\theta_i$  (??)

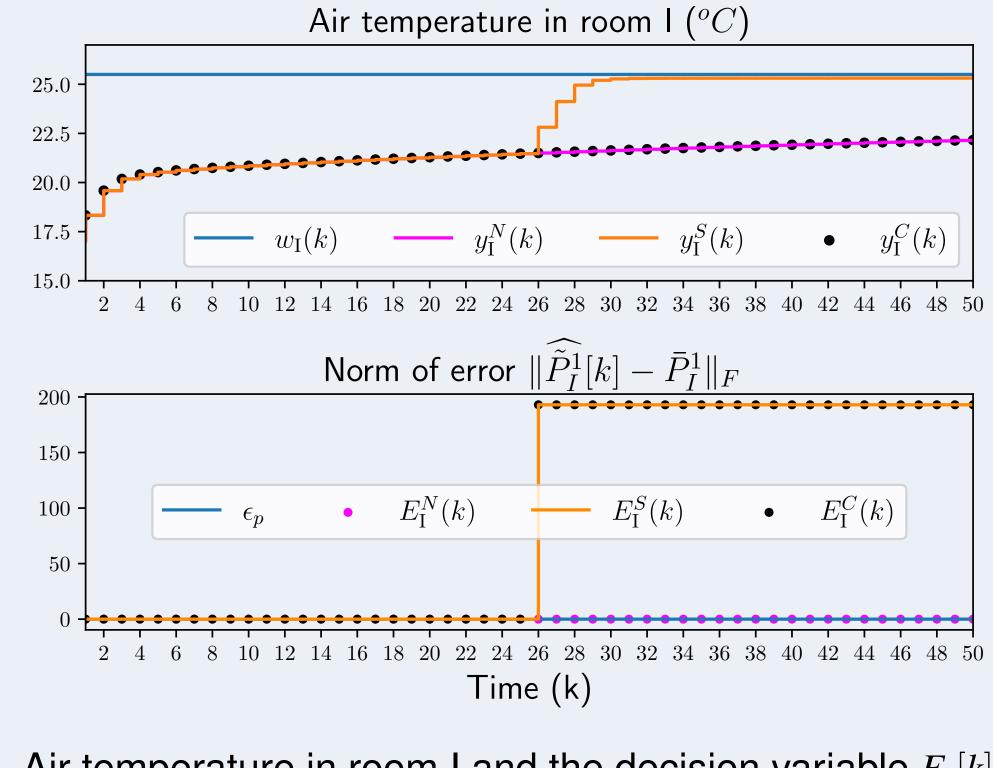
## 6. Example | 4 distinct rooms | 3 scenarios (Nominal, Selfish, Selfish + Correction)



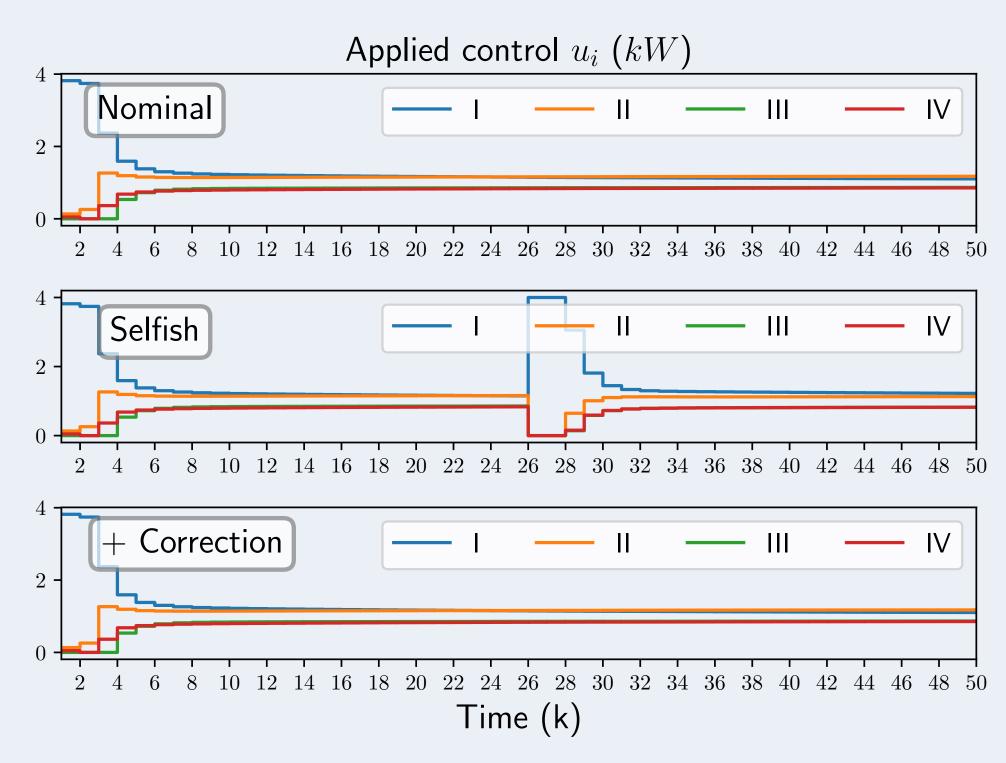
3R-2C Thermic Model.

Objective functions  $J_i$  (% error)

Agent	Nominal	Selfish	+ Correction
I	35008.7 (0.0)	21969.6 (-40.0)	35008.7 (-0.0)
П	29495.3 (0.0)	38867.4 (30.0)	29495.4 (0.0)
Ш	24808.7 (0.0)	33266.4 (30.0)	24808.7 (0.0)
IV	23457.8 (0.0)	31511.0 (30.0)	23457.8 (0.0)
Global	112770.6 (0.0)	125614.4 (10.0)	112770.6 (-0.0)



Air temperature in room I and the decision variable  $E_I[k]$ for three scenarios: nominal (N), selfish behavior (S), and selfish behavior with correction (C).



Control applied in all rooms for the 3 scenarios.







