Acceleration x RH, Acceleration y RH, Acceleration z RH. Acceleration x LH, Acceleration v LH. Acceleration z LH, Angular Velocity x RH. Angular Velocity y RH, Angular Velocity z RH, Angular Velocity x LH, Angular\_Velocity\_y\_LH, Angular Velocity z LH, Pitch RH. Roll RH, Yaw RH. Pitch LH, Roll LH. Yaw LH,

Acceleration x RH. Acceleration y RH, Acceleration z RH. Acceleration x LH, Acceleration y LH, Acceleration z LH. Angular Velocity x RH, Angular Velocity v RH. Angular\_Velocity\_z\_RH, Angular Velocity x LH, Angular Velocity y LH, Angular Velocity z LH, Pitch RH. Roll RH, Yaw RH. Pitch LH. Roll LH, Yaw LH. Timestamp, Cutting task ID, Worker ID, Knife's edge state, On-task. Experience, **Cutting Task type** 

Acceleration RH module, Acceleration LH module, Angular\_Velocity\_RH\_module, Angular Velocity LH module, Pitch RH calibrated. Roll RH calibrated, Yaw RH calibrated. Pitch LH calibrated. Roll LH calibrated. Yaw L calibratedH. Timestamp, Cutting task ID. Worker ID, Knife's edge state, On-task. Experience, **Cutting Task type**