Side Notes

- Nomial scale: $f: R \to R: f$ is bijective .Ordinal scale: $f: R \to R: f(x_1) < f(x_2) \ \forall x_1 < x_2$, Interval scale: $f: R \to R: f(x) = ax + c$ and a is positive, Ration scale: $f: R \to R: f(x) = ax$ and a is positive, Absolute scale: $f: R \to R: f$ is identity
- The Bayes optimal classifier with the maximum a posteriori rule vields linear classification rules for Gaussian class conditional densities when the variances are the same. So in this situation linear classifier is optimal because MAP classifier is optimal regarding to 0-1 loss. When variances differ, it leads to a quadratic boundry.
- Early stopping is like putting noise in the dataset.
- WINNOW algorithm's motivation is to use exponential updates instead of additive updates of perceptron for a faster convergence.
- In SSVM the number of features depends on the dimensionality of the joint feature map only and is "independent" of the number of classes.
- Prediction is hard in SSVM because for a fixed w finding the max f across all classes is combinatorial and needs extra assumptions to become possible.
- Arding is adaptive reweighting and combining a extension of bagging.
- $(1-x)^n < e^{-x}$
- VC-dimension of convex polygons in \mathbb{R}^2 is ∞ . and VC-dimension of convex polygons with at most k vertices is 2k + 1

Derivatives

$$\begin{array}{l} \frac{\partial}{\partial \Sigma^{-1}}log|\Sigma| = -\Sigma\\ \frac{\partial}{\partial \Sigma^{-1}}a^T\Sigma^{-1}a = aa^T\\ \frac{\partial}{\partial \mathbf{x}}(\mathbf{x}^{\top}\mathbf{A}\mathbf{x}) = (\mathbf{A}^{\top} + \mathbf{A})\mathbf{x}\\ \frac{\partial}{\partial \mathbf{x}}(|\mathbf{X}|) = |\mathbf{X}| \cdot \mathbf{X}^{-1} \quad |X| = 1/|X^{-1}|\\ \frac{\partial}{\partial x}(\mathbf{Y}^{-1}) = -\mathbf{Y}^{-1}\frac{\partial \mathbf{Y}}{\partial x}\mathbf{Y}^{-1} \end{array}$$

Taylor Expansion

$$f(x) = f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots \qquad P(\begin{bmatrix} \mathbf{a} \mathbf{1} \\ \mathbf{a} \mathbf{2} \end{bmatrix}) = \mathcal{N}$$

$$f(x) \approx f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(b)}{2!}(x-a)^2 \text{ and } b \text{ is } p(\mathbf{a} \mathbf{2} | \mathbf{a} \mathbf{1}) = 0$$
in the line between a and x .
$$\mathcal{N}(\mathbf{a} \mathbf{2} | \mathbf{u} \mathbf{2} + \mathbf{a})$$

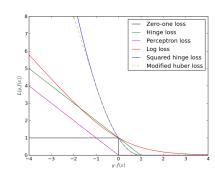
Cauchy Swartz

 $E^2[XY] \le E[X^2]E[Y^2]$

Risk, Bias, Variance

- Conditional expected risk: $R(X, f(X)) = \int_{\mathcal{U}} Loss(y, f(X)) P(y|X) dy$
- Total expected risk: $R(f(X)) = \int_{x} \int_{y} Loss(y, f(x))p(y|x)dydx$
- How good we are? $P(|\hat{R}(\hat{f}(X^{test}), \mathcal{Z}^{test}) - E_X[R(\hat{f}(X), X)] >$
- Bias: $\mathbb{E}_x[\mathbb{E}_D \hat{f}_D(x) \mathbb{E}_y[Y|X=x]]$
- Variance: $\mathbb{E}_X[\mathbb{E}_D[(\hat{f}_D(X) \mathbb{E}_D[\hat{f}_D(X)])^2]]$
- Noise: $\mathbb{E}_Y[Y \mathbb{E}_y[Y|X=x]]$

Loss functions(Classification)



Bayesian Inference for Guassian

$$p(\mu) = \mathcal{N}(\mu_0, \sigma_0^2)$$

$$p(x|\mu) = \mathcal{N}(\mu, \sigma^2)$$

$$\Rightarrow p(\mu|x) = \mathcal{N}(\mu_N, \sigma_N) \text{ where}$$

$$\mu_N = \frac{\sigma^2}{N\sigma_0^2 + \sigma^2} \mu_0 + \frac{N\sigma_0^2}{N\sigma_0^2 + \sigma^2} \mu_{ML} \text{ where } \mu_{ML} \text{ is}$$

$$\frac{1}{N} \sum x_i \text{ and } \frac{1}{\sigma_N^2} = \frac{1}{\sigma_0^2} + \frac{N}{\sigma^2}$$

Effective sample size for bayesian learning in guassains is $\frac{\sigma}{\sigma_0}$ prediction on new sample x is: $p(x|\mathcal{X}) = \int p(x|\mu)p(\mu|\mathcal{X})d\mu \sim \mathcal{N}(\mu_N, \sigma^2 + \sigma_N^2)$

Multivariate Gaussian

$$\mathbb{P}(\underline{x}) = \frac{1}{\sqrt{(2\pi)^k |\Sigma|}} exp(\frac{-1}{2}(\underline{x} - \mu)^T \Sigma^{-1}(\underline{x} - \mu)) \text{ and}$$
 in this case the posterior is: $\Sigma_n^{-1} = n\Sigma^{-1} + \Sigma_0^{-1}$ and $\Sigma_n^{-1} \mu_n = n\Sigma^{-1} \hat{\mu}_n + \Sigma_0^{-1} \mu_0$

Coefficient Matching for Posterior

$$ax^{T}AX + bx^{T}B + c \Rightarrow \Sigma = A^{-1}, \ \mu = \Sigma B$$

$$P(\begin{bmatrix} \mathbf{a}\mathbf{1} \\ \mathbf{a}\mathbf{2} \end{bmatrix}) = \mathcal{N}(\begin{bmatrix} \mathbf{a}\mathbf{1} \\ \mathbf{a}\mathbf{2} \end{bmatrix} | \begin{bmatrix} \mathbf{u}\mathbf{1} \\ \mathbf{u}\mathbf{2} \end{bmatrix}, \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix})$$

$$\neq p(\mathbf{a}\mathbf{2}|\mathbf{a}\mathbf{1}) = \mathcal{N}(\mathbf{a}\mathbf{2}|\mathbf{u}\mathbf{2} + \Sigma_{21}\Sigma_{11}^{-1}(\mathbf{a}\mathbf{1} - \mathbf{u}\mathbf{1}), \Sigma_{22} - \Sigma_{21}\Sigma_{11}^{-1}\Sigma_{12})$$

Properties of Estimators

- unbiased: $E[\hat{\theta}_n] = \theta_0$
- consistent: $\forall \epsilon \ P(|\hat{\theta}_n \theta_0| > \epsilon) \xrightarrow{n \to \infty} 0$
- asymptotically normal: $\frac{(\theta_n \theta_0)}{\sqrt{N}}$ converges in distribution to a random variable with distribution $\mathcal{N}(0, J^{-1}(\theta)I(\theta)J^{-1}(\theta))$ and $I(\theta) = var\left[\frac{\partial log P(x|\theta)}{\partial \theta}\right]$ and $J(\theta) = -E[\frac{\partial^2 log P(x|\theta)}{\partial \theta \partial \theta^T}]$ and I and J are equal iff true θ which is θ^* is equal to
- asymptotically efficient: $E[(\hat{\theta}_n \theta_0)^2]$ is minimizes as $n \to \infty$
- θ_{ML} is not always unbiased. It is consistent, asymptotically normal and asymptotically efficient but if N is finite if is not efficient.(Stein)

Rao-Cramer bound

 $E[(\hat{\theta}_n - \theta_0)^2] \ge \frac{1}{I_n(\theta_0)}$ for any unbiased estimator $\hat{\theta_n}$ where $I_n(\theta_0)$ is Fisher's information:

$$I_n(\theta_0) = Var[V] = Var[\frac{\partial}{\partial \theta}[logP(y_1, y_2, ..., y_n | \theta)]_{\theta_0}] \uparrow, \text{ var } \downarrow. \text{ Rule of thumb for K-fold cv?}$$

For switching integral and derivative, the function shoud be continuously differentiable and integral convergence should be uniform For biased estimators:

$$E[(\hat{\theta}_n - \theta_0)^2] \ge \frac{1 + \frac{\partial}{\partial \theta} b_{\hat{\theta}}}{I_n(\theta_0)} + b_{\hat{\theta}}^2$$

Convergence in Distribution

random variable $r_1, r_2, ..., r_n$ converges to r in distribution if for every continuous and **bounded** function f we have: $E[f(r_n)] \xrightarrow{n \to \infty} E[r]$

Linear Regression

Let $f(x,\beta) = x^T \beta$ then for $X^{n \times d}$: $\hat{\beta} = (X^T X)^{-1} X^T Y$. If $y = X\beta + \epsilon$ then we know $\hat{\beta} \sim \mathcal{N}(\beta, (X^T X)^{-1} \sigma^2)$. Least square estimate has lowest variance among all linear unbiased estimates e.g. $E_y[\hat{\beta}(y)]$ is minimum.

• Ridge:

 $RSS(\beta) = (X - \beta Y)^T (X - \beta Y) + \lambda \beta^T \beta$ which is equal to $P(Y|\beta, X) \sim \mathcal{N}(x^T\beta, \sigma^2 I)$ and $\beta \sim \mathcal{N}(0, \frac{\sigma^2}{\lambda}I)$ **Bayesian**: $p(\hat{\beta}|\Gamma) \sim \mathcal{N}(0,\Gamma^{-1})$ and $p(\beta|\Gamma, X, y) = \mathcal{N}((X^TX +$ $(\sigma^2 \gamma)^{-1} X^T y, \sigma^2 (X^T X + \sigma^2 \Gamma)^{-1})$

- Lasso: $RSS(\beta) = (X - \beta Y)^T (X - \beta Y) + \lambda |\beta|$ which is equal to $P(Y|\beta, X) \sim \mathcal{N}(x^T \beta, \sigma^2 I)$ and $p(\beta_i) = \frac{\lambda}{4\sigma^2} exp(-|\beta| \frac{\lambda}{2\sigma^2})$
- Ridge regression shrinks directions of column space X which have low variance(low predictive value) the shrinkage factor is $\frac{d_j}{d_i + \lambda}$ where d_j is eigen value i of X

Gaussian Process

The joint distribution is $P(y, f^*) \sim$ $\mathcal{N}(0, \begin{bmatrix} K(X,X) + \sigma^2 I & K(X,X^*) \\ K(X^*,X) & K(X^*,X^*) + \sigma^2 I \end{bmatrix}) \text{ Then }$ $P(f^*|y) \sim \mathcal{N}(\mu_{f^*}, cov(f^*))$ where $\mu_{f^*} = K(X^*, X)[K(X, X) + \sigma^2 I]^{-1}y$ and $cov(f^*) = K(X^*, X^*) + \sigma^2 I K(X^*,X)[K(X,X)+\sigma^2I]^{-1}K(X,X^*)$

Validation

Cross-Validation

 $\hat{R}^{CV} = \frac{1}{N} \sum_{i} (y_i - \hat{f}^{-\kappa(i)}(x_i))^2$ If $k \uparrow (LOOCV) \Rightarrow bias \downarrow$, var \uparrow , if $k \downarrow$ then bias $=E[V^2]^{k}=min(\sqrt(n),10).$

Bootstrapping

training data \rightarrow surrogate data source. sample $Z^{*1},...,Z^{*B}$ from training data with replacement. Then compute mean and variance: mean is $\bar{S} = \frac{1}{B} \sum_{b \leq B} S(Z^{*b})$ and variance is $\sigma^{2}(S) = \frac{\bar{1}}{B-1} \sum_{b \leq B} (S(Z^{*b}) - \bar{S})^{2}$ Consistency of bootstrapping means $\lim_{B\to\infty}\frac{1}{B}\sum_{b\leq B}(S(Z^{*b})-\overline{S})^2=V_F[S(Z)].$ How to use it for **model selection**?

 $R^* = \frac{1}{B} \frac{1}{N} \sum_b \sum_i l(y_i, \hat{f}^{b*}(x_i))$ which is **too** optimistic because each sample i with probability $1 - \frac{1}{a} \approx 0.6$ appears in bootstrap b

Jackknife Bias Estimator

 $bias^{JK} = (n-1)(\tilde{S}_n - \hat{S}_n)$ where $\tilde{S}_n = \frac{1}{n} \sum_i \hat{S}_{n-1}^{-i}$ Then $E[bias^{JK}] = \frac{a_1}{n} + O(n^{-2})$ and the final estimator is $\hat{S}^{JK} = \hat{S}_n - bias^{JK}$. Bias corrected estimators can have a considerably larger variance than uncorrected estimators

Example Exercise Jackknife

Setup: $X \sim \mathcal{U}[0, \theta], \hat{S}_n = max(X) = X_n$.

- 1) Expected value of estimator:
- 1.1) CDF $P(X_n \leq x) = (\frac{x}{\theta})^n$
- 1.2) PDF: $p(x) = \frac{\delta P(X_n \le x)}{\delta} = n \frac{x^{n-1}}{n}$
- 1.3) $\mathbb{E}(\hat{S}_n) = \int_0^{\theta} x n \frac{x^{n-1}}{\theta^n} = \frac{n}{n+1} \theta$ 2) $\hat{S}_{n-1}^{i-1} = X_n$ if $i \neq i^*$ else X_{n-1}
- 3) $\hat{S}^{JK} = X_n + \frac{n-1}{n}(X_n X_{n-1})$

4) Expected value of X_{n-1}

4.1) $P(X_{n-1} \le x) = (\frac{x}{\theta})^n + (\frac{x}{\theta})^{n-1} \frac{\theta - x}{\theta} n$

4.2) $p(x) = \frac{n(n-1)}{\theta} \left(\frac{x}{\theta}\right)^{n-2} \left(1 - \frac{x}{\theta}\right)$ 4.3) $\mathbb{E}(X_{n-1}) = \frac{n-1}{n+1}\theta$

5) $\mathbb{E}(\hat{S}_{n}^{JK}) = (1 - \frac{1}{n^{2} + n})\theta$

Neyman-Pearson Lemma

 $A_n(T) = \{ \frac{P_0(x_1, x_2, \dots, x_n)}{P_1(x_1, x_2, \dots, x_n)} \ge T \}$. False positive is $P_0(A^c(T)) = \alpha^*$ and false negative is $P_1(A(T))$ then it holds $\beta > \beta^*$ iff $\alpha < \alpha^*$

Classification Error

 $R(\hat{c}|\mathcal{Z}) = \sum_{i} I_{(\hat{c}(x_i) \neq y_i)}$ $R(\hat{c}) = \sum_{y \le k} p(y) E_{x|y} [I_{(\hat{c}(x_i) \ne y_i)} | Y = y] + \text{terms}$

Gradient Descent and Newton

Gradient descent:

 $a(k+1) = a(k) - \eta_k \nabla J(a(k))$ Then using taylor second order expansion on J(k) we have: $J(a(k+1)) \approx J(a(k)) - \eta_k \nabla J^T J + \frac{1}{2} \eta_k^2 \nabla J^T H \nabla J$ Then $\eta^{opt} = \frac{\|\nabla J\|^2}{\nabla J^T H \nabla J}$ or we can use it another way as Newton's method: $a(k+1) = a(k) - H^{-1}\nabla J(a(k))$. But this is hard boundary and are misclassified.

to compute because of **hessian high**

dimentionality.

Newton Exercise:

higher order roots: $\frac{f(x_n)}{f'(x_n)} = \frac{1}{\frac{k}{\epsilon_n} + \frac{g'(x_n)}{g(x_n)}}$ therefore $\epsilon_{n+1} = \epsilon_n \left(1 - \frac{1}{k + \epsilon_n \frac{g'(x_n)}{2}}\right)$ Then use the Taylor $\frac{1}{k+x} = \frac{1}{k} - \frac{x}{k^2} + O(x^2)$. How to change? $x_{n+1} = x_n - k \frac{f(x_n)}{f'(x_n)}$

Perceptron

goal: $\forall x_i : a^T \tilde{x_i} \geq 0$ and cost function is: $J(a) = \sum_{\tilde{x} \in \mathcal{X}^{mc}} -a^T \tilde{x}$. Update rule in single sample mode is $a \leftarrow a + \tilde{x}$ if \tilde{x} is mis-classified. If \hat{a} exists as a solution for perceptron it can be proved that it always converges. Idea: $||a(k+1) - \alpha \hat{a}||^2$ shrinks depending on using proper α . How many iterations to converge? $k_0 = \frac{\max_{i \in \mathcal{X}^{mc}} \|\tilde{x}_i\|^2 \|\hat{a}\|^2}{(\min_{i \in \mathcal{X}^{mc}} \hat{a}^T x_i)^2}$ So for data almost orthogonal to a we need more iterations to converge.

Dual problem

 $\max \inf_{w} \mathcal{L}(w, \lambda, \alpha)$ when $\forall \alpha_i : \alpha_i \geq 0$ Strong duality holds only by Slater's condition: f and gare convex and h is affine we should have: $h_i(w) < 0 \ \forall i$.

SVM

Hard Margin

Minimize $\frac{1}{2}w^T w$ s.t. $\forall i z_i (w^T y_i + x_0) \geq 1$ Then

$$\theta(\alpha) = \sum_{i \le n} a_i - \sum_{i \le n} \sum_{j \le n} \alpha_i \alpha_j z_i z_j y_i^T y_j \text{ s.t.}$$

 $\forall i: \alpha_i \geq 0 \text{ and } \forall i: \sum_{i \leq n} \alpha_i z_i = 0.$ Then after solving that we have optimal w as: $w^* = \sum_{i \le n} \alpha_i^* z_i y_i$ (number of effective y_i s are limited due to slack property. and $w_0^* = \frac{-1}{2} [min_{i:z_i=-1} \ w^{*T} y_i + min_{i:z_i=1} \ w^{*T} y_i].$ Optimal margin: $w^T w = \sum_{i \in SV} \alpha_i^*$

KKT Conditions: only then strong duality holds: $\alpha_i^* > 0$ $\alpha_i^*(z_i g^*(y_i) - 1) = 0, (z_i g^*(y_i) - 1) \ge 0$

Soft Margin

Minimize $\frac{1}{2}w^Tw + C\sum_{i \le n} \xi_i$ s.t. $\forall i z_i (w^T y_i + x_0) \geq 1 - \xi_i, \ \xi_i \geq 0$. Exactly like before but we have also $0 \le \alpha \le C$ and if C is large we want less data points violate the margin. KKT condition has extra term $\xi_i(C - \alpha_i) = 0$. Data points with $\xi_i = 0$ are correctly classified and are either on the margin or on the correct side of the margin. Points for which $0 < \xi_i < 1$ lie inside the margin, but on the correct side of the decision boundary, and those data points for

Multi Class SVM

 $\min_{w,\xi \geq 0} \frac{1}{2} w^T w + C \sum_i \xi_i \text{ and } \frac{1}{2} w^T w = \sum_z \frac{1}{2} w_z^T w_z.$ such that:

 $\forall y_i \in \mathcal{Y}: w_{z_i}^T y_i \!+\! w_{z_i,0} \!-\! \max_{z \neq z_i} (w_z^T y_i \!+\! w_{z,0}) \geq 1 \!-\! \xi_i$

 $\min_{w,\xi \geq 0} \frac{1}{2} w^T w + C \sum_i \xi_i \text{ such that: } \forall y_i \in \mathcal{Y}:$ $w^{T} \Psi(z_{i}, y_{i}) - \max_{z \neq z_{i}} w^{T} \Psi(z, y_{i}) \ge \Delta(z, z_{i}) - \xi_{i} \Leftrightarrow$ $w^T \Psi(z_i, y_i) - \max_{z \neq z_i} (w^T \Psi(z, y_i) + \Delta(z_i, z)) \ge -\xi_i$

Bagging and Boosting

Bagging

For comparing two bagged classifiers, first compare then bag! meaning: compare risks in each bootstrap samples, at the end look at the median. Because sometimes the variability in bootstrap samples is much higher than the variability of the classifiers!

Boosting

In this approach data everything is deterministic and diversity doesn't come from randomness, but from the weights that we assign to each data point. start with $w_0 = \frac{1}{n}$ and in iteration number b do the following:

1.
$$\epsilon_b \leftarrow \frac{\sum_i w_b^i I_{c_b(x_i) \neq y_i}}{\sum_i w_b^i}$$

2. $\alpha_b \leftarrow log \frac{1-\epsilon_b}{\epsilon_b}$

3. $\forall i: w_h^i \leftarrow w_h^i exp(\alpha_b I_{ch(x_i) \neq y_i})$

The final classifier is $\hat{c}_B(x) = sign(\sum_b \alpha_b c_b(x))$. This approach is equivalent to minimizing the exponential loss $exp(-y\hat{F}_B(x))$

PAC Learning

Definition: Algorithm \mathcal{A} can learn a concept c if for sample size $n \geq poly(\frac{1}{\epsilon}, \frac{1}{\delta}, dim(\mathcal{X}))$ we have: $\mathbb{P}_{Z \sim \mathcal{D}^n}(\mathcal{R}(\hat{c}) \leq \epsilon) > 1 - \delta$. If \mathcal{A} runs polynomial in $\frac{1}{\epsilon}$ and $\frac{1}{\delta}$ then c is efficiently PAC learnable. if labels are not deterministic:

$$\mathbb{P}_{Z \sim \mathcal{D}^n}(\mathcal{R}(\hat{c}) - inf_{c \in \mathcal{C}R(c)} \le \epsilon) > 1 - \delta.$$

If we have uniform convergence for $R(\hat{c}_n^*)$ to $R(c_n^*)$ and point-wise convergence for $\hat{R}(c^*)$ where c^* is the best possible classifier, then we can show: $\mathbb{P}\{\mathcal{R}(\hat{c}_n^*) - \mathcal{R}(c^*) > \epsilon\} \leq \mathbb{P}\{\sup_{c \in \mathcal{C}} |\hat{\mathcal{R}}(c) - \mathcal{R}(c)| > \epsilon\}$

If we train a classifier $\hat{c}_n^*(x)$ on dataset \mathcal{Z} the generalization error is $\mathbb{P}(\hat{c}_n^*(X) \neq Y | \mathcal{Z})$ **Hoeffding's Inequality**: (Markov) if X is a non-negative r.v. : $\mathbb{P}\{X > \epsilon\} < \frac{\mathbb{E}[X]}{\epsilon}$ If $\mathbb{E}[X] = 0$ and $a \leq X \leq b$ then: which $\xi_i > 1$ lie on the wrong side of the decision $\mathbb{E}[e^{sX}] \leq exp(s^2(b-a)^2/8)$. How to prove? notice **De Finetti's Theorem** $e^{sX} \leq e^{sb} \frac{x-a}{b-a} + e^{sa} \frac{b-x}{b-a}$ then let

> side is equal to $e^{\Phi(u)}, \Phi(u) = -pu + \log(1 - p + pe^u).$ Then by using Taylor expansion and approx we reach the

result. Final result:
$$\mathbb{P}\{s_n - \mathbb{E}[S_n] \ge t\} \le exp(-\frac{2t^2}{\sum_i (b_i - a_i)^2}) \text{ and }$$

$$\mathbb{P}\{s_n - \mathbb{E}[S_n] \le -t\} \le exp(-\frac{2t^2}{\sum_i (b_i - a_i)^2}).$$

Useful Lemma

$$\mathbb{P}(a+b>\epsilon) \le \mathbb{P}(a>\epsilon/2) + \mathbb{P}(b>\epsilon/2)
\mathbb{P}(\bigcup_{i} A_{i}) = \sum_{i} A_{i} - \sum_{1 \le i_{1} < i_{2} \le n} \mathbb{P}(A_{i_{1}} \cap A_{i_{2}}) + \dots + (-1)^{n-1} \mathbb{P}(A_{1}, \dots, A_{n})$$

Error Bounds for Finite Classifier Sets

 $\mathbb{P}\{\sup_{c\in\mathcal{C}}|\hat{\mathcal{R}}_n(c) - \mathcal{R}(c)| > \epsilon\} < 2|\mathcal{C}|\exp(-n\epsilon^2)$ Then we can say:

$$\mathcal{R}(c) \le \hat{\mathcal{R}}_n(c) + \sqrt{\frac{\ln|\mathcal{C}| - \ln(\sigma/2)}{2n}}$$

Error Bounds for Hyperplanes in \mathbb{R}^d

$$\mathbb{P}\{\mathcal{R}(\hat{c}) - \mathcal{R}(c^*) > \epsilon\} \le (2\binom{n}{d} + 1)e^{2d\epsilon}e^{-n\epsilon^2/2}$$

Beta and Dirichlet Distribution

$$Beta(x|a,b) = \frac{1}{B(a,b)} x^{a-1} (1-x)^{b-1}, \ x \in [0,1], \ a,b > 0 \ \text{and} \ B(a,b) = \frac{\Gamma(a)\Gamma(b)}{\Gamma(a+b)}, \\ \Gamma(a) = \int_0^\infty e^{-x} x^{a-1} dx \\ Dir(x|\alpha) = \frac{1}{B(\alpha)} \prod_k x_k^{a_k-1} \ \text{where} \\ x = [x_1,x_2,...,x_n], \ x_k \in [0,1], \ \alpha_k > 0. \ B(\alpha) \ \text{is a generalization of beta function meaning} \\ B(\alpha) = \frac{\prod_k \Gamma(a_k)}{\Gamma(\sum_k a_k)}$$

Clustering Purity Exercise:

$$\begin{split} I(\mathcal{U},\mathcal{V}) &= \sum_{i=1}^{R} \sum_{j=1}^{C} p_{UV}(i,j) \log_{2} \frac{p_{UV}(i,j)}{p_{U}(i)p_{V}(j)} \\ &= \sum_{i=1}^{R} \sum_{j=1}^{C} p_{UV}(i,j) \frac{p_{V}(j)}{p_{V}(j)} \log_{2} \frac{p_{UV}(i,j)}{p_{U}(i)p_{V}(j)} \\ &= \sum_{i=1}^{R} \sum_{j=1}^{C} p_{V}(j) \frac{p_{UV}(i,j)}{p_{V}(j)} \left(\log_{2} \frac{p_{UV}(i,j)}{p_{V}(j)} - \log_{2} p_{U}(i) \right) \\ &= \sum_{j=1}^{C} p_{V}(j) \sum_{i=1}^{R} \frac{p_{UV}(i,j)}{p_{V}(j)} \left(\log_{2} \frac{p_{UV}(i,j)}{p_{V}(j)} - \log_{2} p_{U}(i) \right) \\ &= \sum_{j=1}^{C} p_{V}(j) \left(-H(\mathcal{U} \mid \mathcal{V}) - \sum_{i=1}^{R} \frac{p_{UV}(i,j)}{p_{V}(j)} \log_{2} p_{U}(i) \right) \\ &= -H(\mathcal{U} \mid \mathcal{V}) - \sum_{j=1}^{C} \sum_{i=1}^{R} p_{UV}(i,j) \log_{2} p_{U}(i) \\ &= -H(\mathcal{U} \mid \mathcal{V}) - \sum_{i=1}^{R} p_{U}(i) \log_{2} p_{U}(i) \\ &= H(\mathcal{U}) - H(\mathcal{U} \mid \mathcal{V}) \end{split}$$

Jensen's Inequality:

$$\begin{split} &-\sum_{i}\sum_{j}p_{UV}(i,j)log\frac{p_{U}(i)p_{V}(j)}{p_{UV}(i,j)} \geq \\ &-log\sum_{i}\sum_{j}p_{UV}(i,j)\frac{p_{U}(i)p_{V}(j)}{p_{UV}(i,j)} \end{split}$$

if $(X_1,...,X_n)$ n infinitely exchangeable sequence $p:=\frac{-a}{b-a}$, u:=s(b-a) and notice the right hand of random variables. Then $\forall n$:

$$P(X_1,...,X_n) = \int (\prod_i p(x_i|G)) dP(G)$$

Gibbs Sampling

$$\begin{aligned} &p(z_i=k|z_{-i},x,\mu,\alpha) \propto p(z_i=k|z_{-i},\alpha)p(x_i|x_{-i},z_i,z_{-i},\mu) \\ &p(z_i=k|z_{-i}=\text{prior} \times \text{likelihood:} \\ &\left\{ \begin{array}{l} \frac{N_{k,-i}}{\alpha+N-1} \frac{p(x_i,x_{-i,k}|\mu)}{p(x_{-i,k}|\mu)} & \text{for existing k} \\ \frac{\alpha}{\alpha+N-1} p(x_i|\mu) & \text{for new k} \end{array} \right. \end{aligned}$$

1: **for** i = 1 to N in random order **do**

Remove x_i 's sufficient statistics from old cluster z_i ; 3:

for
$$k = 1$$
 to K do

Compute
$$p_k(x_i) = p_k(x_i|\mathbf{x}_{-i,k});$$

$$\operatorname{Set} N_{k,-i} = |x_{-i,k}|;$$

Compute
$$p(z_i = k | z_{-i}, x) = \frac{N_{k,-i}}{\alpha + N - 1}$$
;

7: end for

4:

5:

6:

8: Compute $p_{\star}(x_i) = p(x_i|\boldsymbol{\mu})$;

9: Compute $p(z_i = \star | z_{-i}, x)$;

10: Normalize $p(z_i|\cdot)$;

11: Sample $z_i \sim p(z_i|\cdot)$;

12: Add x_i 's sufficient statistics to new cluster z_i ;

If any cluster is empty, remove it and decrease K;

14: end for

Latent Dirichlet Allocation

Distribution of topics in document d: $\theta_d \sim Dir(\alpha)$ What topic the word w belongs to in document d: $z_{d,w} \sim \text{Categorical}(\theta_d)$

Distribution of words in topic $k:\Phi_k \sim Dir(\beta)$

What is the word w in document d: $w_{d,w} \sim \text{Categorical}(\Phi_{z_{d,w}})$