

# A Book of High School and Engineering Common Core Mathematical Formulae

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# Part I

## Algebra



# Chapter 1

## Logarithm

### 1.1 Basic Formulae

For  $a^x = b$ :

$$\log_a x, \forall x \leq 0 \text{ is undefined} \quad (1.1)$$

$$\log_a b = x, \text{ if } a^x = b, a \neq 1 \quad (1.2)$$

$$\log_b a^m = m \log_b a, \text{ for } a^m = b \quad (1.3)$$

$$a^{\log_a x} = x \quad (1.4)$$

$$a^{\log_b c} = c^{\log_b a} \quad (1.5)$$

$$\frac{1}{\log_a b} = \log_b a \quad (1.6)$$

$$\log_c(ab) = \log_c a + \log_c b \quad (1.7)$$

$$\log_c \left( \frac{a}{b} \right) = \log_c a - \log_c b \quad (1.8)$$

$$|\log_a x| = \begin{cases} -\log_a x, & \text{if } 0 < x < 1 \\ \log_a x, & \text{if } 1 \leq x < \infty \end{cases} \quad (1.9)$$

### 1.2 Series

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \cdots \infty \quad (1.10)$$

$$= \lim_{n \rightarrow \infty} \sum_{i=0}^n \frac{x^i}{i!} \quad (1.11)$$

$$\log(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \cdots \infty \quad (1.12)$$

$$= \lim_{n \rightarrow \infty} \sum_{i=1}^n (-1)^{(i-1)} \frac{x^i}{i} \quad (1.13)$$

## Chapter 2

### Complex Numbers

### 2.1 Basic Formulae

For  $z = x + iy$ ,

$$|z| = \sqrt{x^2 + y^2} \quad (2.1)$$

$$\tan \theta = \frac{y}{x} \quad (2.2)$$

$$\bar{z} = x - iy \quad (2.3)$$

### 2.2 Arithmetic Operation of Complex Number

For two complex numbers  $z_1 = x_1 + iy_1$  and  $z_2 = x_2 + iy_2$ :

$$z_1 + z_2 = (x_1 + x_2) + i(y_1 + y_2) \quad (2.4)$$

$$z_1 z_2 = (x_1 x_2 - y_1 y_2) + i(x_1 y_2 + x_2 y_1) \quad (2.5)$$

$$|z_1 z_2| = |z_1| \cdot |z_2| \quad (2.6)$$

$$\frac{z_1}{z_2} = \frac{(x_1 x_2 + y_1 y_2) + i(x_2 y_1 - x_1 y_2)}{a_2^2 + b_2^2} \quad (2.7)$$

$$\left| \frac{z_1}{z_2} \right| = \frac{|z_1|}{|z_2|} \quad (2.8)$$

### 2.3 Euler's Formula

$$z = re^{i\theta}, \text{ where} \quad (2.9)$$

$$r = |z| \quad (2.10)$$

$$e^{i\theta} = \cos \theta + i \sin \theta \quad (2.11)$$

$$\theta = \arctan \left( \frac{y}{x} \right) \quad (2.12)$$

## 2.4 Trigonometric Ratios in Complex Form

$$e^{i\theta} + e^{-i\theta} = 2 \cos \theta \quad (2.13)$$

$$\Rightarrow \cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2} \quad (2.14)$$

$$e^{i\theta} - e^{-i\theta} = 2 \sin \theta \quad (2.15)$$

$$\Rightarrow \sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2} \quad (2.16)$$

## 2.5 De Moivre's Formula

According to DeMoivre's Formula:

$$(\cos \theta + i \sin \theta)^n = \cos(n\theta) + i \sin(n\theta) \quad (2.17)$$

**Proof**

$$\begin{aligned} \cos \theta + i \sin \theta &= e^{i\theta} \\ \Rightarrow (\cos \theta + i \sin \theta)^n &= e^{n(i\theta)} \\ &= \cos(n\theta) + i \sin(n\theta) \\ &\text{Q.E.D.} \end{aligned}$$

## 2.6 Application of Euler's and De Moivre's Formula

For  $z_1 = |r_1| e^{i\theta_1}$  and  $z_2 = |r_2| e^{i\theta_2}$

$$z_1 z_2 = (r_1 r_2) e^{i(\theta_1 + \theta_2)} \quad (2.18)$$

$$\frac{z_1}{z_2} = \left( \frac{r_1}{r_2} \right) e^{i(\theta_1 - \theta_2)} \quad (2.19)$$

## 2.7 Roots of Unity

$$\sqrt[n]{1} = e^{i \frac{2k\pi}{n}}, \text{ where } k \in [0, n-1] \quad (2.20)$$

## 2.8 Important Relations of Complex Numbers

$$|z_1 + z_2| \leq |z_1| + |z_2| \quad (2.21)$$

$$|z_1 - z_2| \leq |z_1| + |z_2| \quad (2.22)$$

$$|z_1 - z_2| \geq ||z_1| - |z_2|| \quad (2.23)$$

$$|z_1 + z_2| \geq ||z_1| - |z_2|| \quad (2.24)$$

$$|z_1 + z_2|^2 = 2 \left( |z_1|^2 + |z_2|^2 \right) \quad (2.25)$$

### 3.1.2 Important Relation

If the three terms  $a, b, c$  are in A.P., then

$$2b = a + c \quad (3.2)$$

## 3.2 Geometric Progression (G.P.)

An geometric sequence is  $a, ar, ar^2, \dots \infty$  or  $t_n = ar^{n-1}$ , where  $a$  is the first term,  $r$  is the common ratio, and  $n$  is the  $n^{th}$ -term. An geometric series is  $a + ar + ar^2 + \dots \infty$ .

### 3.2.1 The Value of 'r'

$$r = \frac{t_2}{t_1} = \frac{t_3}{t_2} = \dots = \frac{t_n}{t_{n-1}} \quad (3.3)$$

### 3.2.2 Sum of a G.P. Series

For a definite G.P. series, where there are  $n$  terms in the series, the sum of the series is:

$$S_n = \frac{a|r^n - 1|}{|r - 1|} \quad (3.4)$$

For an infite G.P. series the sum of the series is defined for  $r < 1$ . Sum of such a series is:

$$S_\infty = \frac{a}{1 - r} \quad (3.5)$$

### 3.5.1 Riemann Zeta Function

$$\zeta(s) = \sum_{n=1}^{\infty} \frac{1}{n^s} \quad (3.13)$$

### 3.5.2 Riemann's Infinite Series as an Integration

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=r_1}^{r_2} f\left(\frac{i}{n}\right) = \int_{\frac{r_1}{n}}^{\frac{r_2}{n}} f(x) dx \quad (3.14)$$

## Chapter 4

### Test of Convergence of Infinite Series

If  $a_1, a_2, a_3, \dots, a_n$  is a sequence by  $a_n$  and their sum of series is  $S_n$ , then the following apply.

#### 4.1 Definition

If

$$\lim_{n \rightarrow \infty} S_n = l$$

where  $l$  is a finite value, the series  $S_n$  is said to converge. A non-convergent series is called a divergent series.

#### 4.2 Tests of Convergence

##### 4.2.1 Comparison Test

If  $u_n$  and  $v_n$  are two positive series, then:

1. (a)  $v_n$  converges  
(b)  $u_n \leq v_n \forall n$  Then  $u_n$  converges.
2. (a)  $v_n$  diverges  
(b)  $u_n \geq v_n \forall n$  Then  $u_n$  diverges.

##### 4.2.2 Limit Form

If

$$\lim_{x \rightarrow \infty} \frac{u_n}{v_n} = l$$

where  $l$  is a finite quantity  $\neq 0$ , then  $u_n$  and  $v_n$  converge and diverge together.

##### 4.2.3 Integral Test or Maclaurin-Cauchy Test

For a series

$$\sum_{i=N}^{\infty} f(x), \text{ where } N \in \mathbb{Z} \quad (4.1)$$

will only converge if the improper integral

$$\int_N^{\infty} f(x)dx \quad (4.2)$$

is finite.

If the improper integral is finite, the upper and lower limit of the infinite series is given by:

$$\int_N^{\infty} f(x)dx \leq \sum_{i=N}^{\infty} f(x) \leq f(N) + \int_N^{\infty} f(x)dx \quad (4.3)$$

#### 4.2.4 Ratio Test

If, for two series  $\sum u_n$  and  $\sum v_n$ :

1. (a)  $\sum v_n$  converges  
 (b) from or after a particular term  $\frac{u_n}{u_{n+1}} > \frac{v_n}{v_{n+1}}$ , then  $u_n$  converges.
2. (a)  $\sum v_n$  diverges  
 (b) from or after a particular term  $\frac{u_n}{u_{n+1}} < \frac{v_n}{v_{n+1}}$ , then  $u_n$  diverges.

#### 4.2.5 D'Alembert's Ratio Test

$$\lim_{n \rightarrow \infty} \frac{u_n}{u_{n+1}} = \lambda \quad (4.4)$$

- series converges if  $\lambda < 1$
- series diverges if  $\lambda > 1$
- fails if  $\lambda = 1$

#### 4.2.6 Rabbe's Test

$$\lim_{n \rightarrow \infty} n \left[ \frac{u_n}{u_{n+1}} - 1 \right] = \kappa \quad (4.5)$$

- series converges if  $\kappa < 1$
- series diverges if  $\kappa > 1$
- fails if  $\kappa = 1$

#### 4.2.7 Cauchy's Root Test

$$\lim_{n \rightarrow \infty} |u_n|^{\frac{1}{n}} = \lambda \quad (4.6)$$

- series converges for  $\lambda < 1$
- series diverges for  $\lambda > 1$
- test fails for  $\lambda = 1$

### 4.2.8 Logarithmic Test

$$\lim_{n \rightarrow \infty} n \log \left( \frac{u_n}{u_{n+1}} \right) = \kappa \quad (4.7)$$

- series converges for  $\kappa < 1$
- series diverges for  $\kappa > 1$
- test fails for  $\kappa = 1$



### 5.1.1 Minor and Cofactor

For a third order determinant

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

**Minor**

$$M(a_{11}) = M_{11} = \begin{vmatrix} b_2 & c_2 \\ b_3 & c_3 \end{vmatrix} \quad (5.2)$$

i.e., all the terms of determinant except those in the same row and columns as the one of which the minor is being calculated.

**Cofactor**

$$C_{ij} = (-1)^{i+j} M_{ij} \quad (5.3)$$

## 5.2 Properties of Determinants

1. Transposing a determinant does not alter its value.

$$\Delta = \Delta^T \quad (5.4)$$

2. If rows and columns are interchanges  $m$  times, the value of the new determinant is

$$\Delta' = (-1)^m \Delta \quad (5.5)$$

3. If two parallel lines are equal, then  $\Delta = 0$

4. For  $\Delta = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$  and  $\Delta_1 = \begin{vmatrix} ka_1 & kb_1 & kc_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$ , then  $\Delta_1 = k\Delta$

5. For  $\Delta = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$  and  $\Delta_1 = \begin{vmatrix} ka_1 & b_1 & c_1 \\ ka_2 & b_2 & c_2 \\ ka_3 & b_3 & c_3 \end{vmatrix}$ , then  $\Delta_1 = k\Delta$

6. For  $C_n \rightarrow k_1 C_l + k_2 C_m + k_3 C_n$  or  $R_n \rightarrow k_1 R_l + k_2 R_m + k_3 R_n$ ,  $\Delta' = \Delta$

## 5.3 Cramer's Rule

For a system of equations:

$$a_1x + b_1y + c_1z = d_1$$

$$a_2x + b_2y + c_2z = d_2$$

$$a_3x + b_3y + c_3z = d_3$$

the following determinants are defined:

$$D = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

$$D_x = \begin{vmatrix} d_1 & b_1 & c_1 \\ d_2 & b_2 & c_2 \\ d_3 & b_3 & c_3 \end{vmatrix}$$

$$D_y = \begin{vmatrix} a_1 & d_1 & c_1 \\ a_2 & d_2 & c_2 \\ a_3 & d_3 & c_3 \end{vmatrix}$$

$$D_z = \begin{vmatrix} a_1 & b_1 & d_1 \\ a_2 & b_2 & d_2 \\ a_3 & b_3 & d_3 \end{vmatrix}$$

The solution for the system of equations is:

$$x = \frac{D_x}{D} \tag{5.6}$$

$$y = \frac{D_y}{D} \tag{5.7}$$

$$z = \frac{D_z}{D} \tag{5.8}$$

### 5.3.1 Consistency Test

1. If  $D \neq 0$ , the system is consistent and has unique solutions.
2. If  $D = D_x = D_y = D_z = 0$ , the system may or may not be consistent and it will have infinite solutions and the system will be dependent.
3. If  $D = 0$  and at least one of  $D_x, D_y, D_z$  is non zero, the system is inconsistent

## 6.2 Multiplication of Two Matrices

If

$$C_{m \times p} = A_{m \times n} \cdot B_{n \times p} \quad (6.2)$$

then,

$$c_{ik} = \sum_{j=1}^n a_{ij} \cdot b_{jk} \quad (6.3)$$

### 6.2.1 Multiplicative Properties

1. Multiplication of matrices is associative, hence  $(AB)C = A(BC)$ .
2.  $AI = A$
3.  $A \cdot A^{-1} = I$
4.  $A \cdot (\text{adj } A) = (\text{adj } A) \cdot A = |A|I$
5.  $A^{-1} = \frac{1}{|A|}(\text{adj } A)^t$
6.  $(AB)^t = B^t A^t$

## 6.3 Adjoint of a Matrix

$$\text{adj } A = \begin{bmatrix} M_{11} & M_{12} & \cdots & M_{1n} \\ M_{21} & M_{22} & \cdots & M_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ M_{m1} & M_{m2} & \cdots & M_{mn} \end{bmatrix}^t, \text{ where } M_{ij} \text{ is the minor of } a_{ij} \quad (6.4)$$

## 6.4 Martin's Rule

For a system of equation,

$$\begin{aligned}a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n &= b_1 \\a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n &= b_2 \\&\vdots \\a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n &= b_n\end{aligned}$$

The system can be written as:

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} \quad (6.5)$$

$$\Rightarrow AX = B \quad (6.6)$$

$$\Rightarrow X = A^{-1}B \quad (6.7)$$

## 7.4 Pascal's Rule

For  $1 \leq k \leq n$  and  $k, n \in \mathbb{N}$ :

$$\binom{n}{k} + \binom{n}{k-1} = \binom{n+1}{k} \quad (7.7)$$

# Chapter 8

## Boolean Algebra

Let  $B$  be a set of  $a, b, c$  with operations sum  $(+)$  and product  $(\cdot)$ .  
Then  $B$  is said to belong to the Boolean Structure if the following conditions are satisfied:

Table 8.1: Properties of Boolean Algebraic Structure

Property	Name of Property
$a + b \in B$ $a \cdot b \in B$	Closure Property
$a + b = b + a$ $a \cdot b = b \cdot a$	Associative Law
$a(b + c) = ab + ac$ $a + bc = (a + b)(a + c)$	Commutative Law
$\{0, 1\} \in B$ $a + 0 = a$ $a + 1 = 1$ $a \cdot 0 = 0$ $a \cdot 1 = a$	Laws of 1 and 0
$a + ab = a$ $a(a + b) = a$	Absorption Law
$(a + b)' = (a'b')$	De'Morgan's Law

## Chapter 9

### Remainder Theorems

### 9.1 Remainder Theorem

If a function  $f(x)$  is divided by a binomial  $x - a$ , then the remainder is provided by  $f(a)$ .

$$\frac{f(x)}{x - a} \equiv f(a) \pmod{(x - a)} \quad (9.1)$$

#### Worked Example

Find the remainder when  $f(x) = x^3 - 4x^2 - 7x + 10$  is divided by  $(x - 2)$ .  
The remainder:

$$R = (x^3 - 4x^2 - 7x + 10) \pmod{(x - 2)}$$

is given by:

$$\begin{aligned} R = f(2) &= (2)^3 - 4(2)^2 - 7(2) + 10 \\ &= 8 - 16 - 14 + 10 = -12 \end{aligned}$$

### 9.2 Euler's Remainder Theorem

According to Euler's Remainder Theorem, if  $x$  and  $n$  are two co-prime numbers:

$$x^{\varphi(n)} \equiv 1 \pmod{n}, x, n \in \mathbb{Z}^+ \quad (9.2)$$

where,  $\varphi(n)$  is Euler's totient function.

#### 9.2.1 Euler's Totient Function

For a number defined as:

$$n = \prod_{i=1}^r a_i^{b_i} \quad (9.3)$$

then Euler's totient function is defined as:

$$\begin{aligned}\varphi(n) &= n \cdot \left[ \left(1 - \frac{1}{a_1}\right) \cdot \left(1 - \frac{1}{a_2}\right) \cdot \left(1 - \frac{1}{a_3}\right) \cdots \right] \\ &= n \prod_{i=1}^r \left(1 - \frac{1}{a_i}\right)\end{aligned}\tag{9.4}$$

### Worked Example

Find the remainder if  $3^{76}$  is divided by 35.

Since:

$$35 = 5^1 \times 7^1$$

Hence the totient quotient of 35 is:

$$\begin{aligned}\varphi(35) &= 35 \cdot \left(1 - \frac{1}{5}\right) \cdot \left(1 - \frac{1}{7}\right) \\ &= 35 \times \frac{4}{5} \times \frac{6}{7} \\ &= 24\end{aligned}$$

Hence Euler's Theorem yields:

$$\begin{aligned}3^{24} &\equiv 1 \pmod{35} \\ 3^{76} &\equiv 3^{24 \times 3 + 4} \\ &\equiv (3^{24})^3 \times 3^4 \pmod{35} \\ &\equiv (1)^3 \times 3^4 \pmod{35} \\ &\equiv 81 \pmod{35} \\ &\equiv 11 \pmod{35}\end{aligned}$$

The remainder when  $3^{76}$  is divided by 35 is 11.

## 9.3 Wilson Theorem

According to Wilson Theorem:

$$(n-1)! \equiv -1 \pmod{n}\tag{9.5}$$



**Worked Example**

Find the remainder when  $28!$  is divided by 31.

By Wilson's Theorem:

$$\begin{array}{ll} 30! & \equiv -1 \pmod{31} \\ \Rightarrow 30 \cdot 29 \cdot 28! & \equiv -1 \pmod{31} \\ \text{Let } 28! \pmod{31} & = x \\ \Rightarrow (-1) \cdot (-2) \cdot x & \equiv 30 \pmod{31} \\ \Rightarrow 2x & = 30 \\ \Rightarrow x & = 15 \end{array}$$

The remainder when  $28!$  is divided by 31 is 15.

# Part II

## Co-ordinate Geometry

## Chapter 10

### 2-D Co-ordinate Geometry

For the ordered pairs,  $A(x_1, y_1)$  and  $B(x_2, y_2)$ :

#### 10.1 Distance between Two Points

$$AB = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2} \quad (10.1)$$

(10.2)

#### 10.2 Section Formula

If point  $C$  divides  $AB$  in the ratio  $m : n$ :

$$C = \left( \frac{nx_1 + mx_2}{m + n}, \frac{ny_1 + my_2}{m + n} \right) \quad (10.3)$$

##### 10.2.1 Corollary: Mid - Point Formula

If  $C$  is the mid-point of  $AB$ , and  $m : n = 1 : 1$ :

$$C = \left( \frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2} \right) \quad (10.4)$$

(10.5)

## Chapter 11

### Triangles

For a triangle defined with three vertices  $A(x_1, y_1)$ ,  $B(x_2, y_2)$ ,  $C(x_3, y_3)$  and corresponding sides of length  $a, b, c$ , then:

#### 11.1 Centroid of a Traiangle

$$\text{Centroid of } \triangle ABC = \left( \frac{x_1 + x_2 + x_3}{3}, \frac{y_1 + y_2 + y_3}{3} \right) \quad (11.1)$$

$$(11.2)$$

#### 11.2 Area of Triangle

##### 11.2.1 Determinant Method

$$\text{Area of } \triangle ABC = \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix} \quad (11.3)$$

##### 11.2.2 Heron's Formula

For a triangle, the semi-perimeter,  $s$ , is defined as:

$$s = \frac{a + b + c}{2}$$

The area of the triangle can be defined as:

$$\text{Area of } \triangle ABC = \sqrt{s \cdot (s - a) \cdot (s - b) \cdot (s - c)} \quad (11.4)$$

### 11.3 Incircle of a Triangle

The radius,  $r$ , and centre of incircle,  $o$ , is:

$$o = \left( \frac{ax_1 + bx_2 + cx_3}{a + b + c}, \frac{ay_1 + by_2 + cy_3}{a + b + c} \right) \quad (11.5)$$

$$r = \sqrt{\frac{(s - a) \cdot (s - b) \cdot (s - c)}{s}} \quad (11.6)$$

$$(11.7)$$

### 11.4 Circumcircle of a Triangle

The radius,  $R$ , and centre,  $O$ , of circumcircle is defined as:

$$O = \left( \frac{x_1 \sin 2A + x_2 \sin 2B + x_3 \sin 2C}{\sin 2A + \sin 2B + \sin 2C}, \frac{y_1 \sin 2A + y_2 \sin 2B + y_3 \sin 2C}{\sin 2A + \sin 2B + \sin 2C} \right) \quad (11.8)$$

$$2R = \frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C} \quad (11.9)$$

## Chapter 12

### Straight Line

A straight line can be defined as:

$$y = mx + c \quad (12.1)$$

$$\frac{x}{a} + \frac{y}{b} = 1, \text{ where } a \text{ and } b \text{ are the intercepts at x and y axes respectively} \quad (12.2)$$

$$x \cos \alpha + y \sin \alpha = p \text{ (Normal Form)} \quad (12.3)$$

$$Ax + By + C = 0 \text{ (General Form)} \quad (12.4)$$

### 12.1 Equation of Straight Line Passing Through $(x_0, y_0)$ and Slope $m$

$$(y - y_0) = m(x - x_0) \quad (12.5)$$

### 12.2 Distance Between Two Points on a Line

$$\frac{y_1 - y_2}{\sin \theta} = \frac{x_1 - x_2}{\cos \theta} = \gamma \quad (12.6)$$

$$\theta = \tan^{-1} m \quad (12.7)$$

### 12.3 Angle Between Two Lines

For two lines with slopes  $m_1, m_2$ , the angle between them,  $\theta$ :

$$\theta = \arctan \left( \frac{m_1 - m_2}{1 + m_1 m_2} \right) \quad (12.8)$$

## 12.4 Distance of a Point from a Line

Line:  $ax + by + c = 0$  Point:  $(g, h)$

$$S = \frac{ag + bh + c}{\sqrt{a^2 + b^2}} \quad (12.9)$$

## 12.5 Angle Bisector of a Line

For the two lines:  $a_1x + b_1y + c_1 = 0$  and  $a_2x + b_2y + c_2 = 0$ , the angle bisector is:

$$\frac{a_1x + b_1y + c_1}{\sqrt{a_1^2 + b_1^2}} = \frac{a_2x + b_2y + c_2}{\sqrt{a_2^2 + b_2^2}} \quad (12.10)$$

If the sign of  $c_1$  and  $c_2$  is the same, then the equation obtained is the internal bisector.

## 12.6 Equation of a Straight Line Passing through the Intersection of Two Lines

$$(a_1x + b_1y + c_1) + k(a_2x + b_2y + c_2) = 0 \quad \forall k \in \mathbb{R} \quad (12.11)$$

## 12.7 Relative Position of Points w.r.t. a Line

For the points  $(x_1, y_1)$  and  $(x_2, y_2)$ :

$$\begin{aligned} k_1 &= ax_1 + by_1 + c \\ k_2 &= ax_2 + by_2 + c \end{aligned}$$

If  $k_1$  and  $k_2$  have the same sign, they are on the same side of a line, otherwise on opposite sides.

## 12.8 Ratio of Division of Line Segment

For any line,  $f(x, y) = 0$ , the ratio in which it divides  $(x_1, y_1)$  and  $(x_2, y_2)$  is given by:

$$r = -\frac{f(x_1, y_1)}{f(x_2, y_2)} \quad (12.12)$$

If  $\begin{cases} r > 0, \text{ then division is internal} \\ r < 0, \text{ then division is external} \end{cases}$ .

## Chapter 13

### General Theory of Second Degree Equation

For any general equation of the form:

$$ax^2 + by^2 + 2gx + 2fy + 2hxy + c = 0 \quad (13.1)$$

$\Delta$  is defined as:

$$\Delta = \begin{vmatrix} a & h & g \\ h & b & f \\ g & f & c \end{vmatrix} \quad (13.2)$$

If  $\Delta = 0$  then the equation is a pair of straight lines. If  $a + b = 0$  then the lines are  $\perp$ .

If the  $\Delta \neq 0$ :

1.  $a = b, h = 0 \rightarrow$ circle
2.  $h^2 = ab \rightarrow$ parabola
3.  $h^2 < ab \rightarrow$ ellipse
4.  $h^2 > ab \rightarrow$ hyperbola



## Chapter 14

### Conics

The four conic sections are: circle, parabola, ellipse, and hyperbola. Circle has been done separately in the next chapter.

## 14.1 Parametric Form of Conics

### 14.1.1 Hyperbola

$$x = a \sec \theta \quad (14.1)$$

$$y = b \tan \theta \quad (14.2)$$

### 14.1.2 Ellipse

$$x = a \cos \phi \quad (14.3)$$

$$y = b \sin \phi \quad (14.4)$$

### 14.1.3 Parabola

$$x = at^2 \quad (14.5)$$

$$y = 2at \quad (14.6)$$

## 14.2 Equation form of Conics

### 14.2.1 Parabola

Table 14.1: Properties of a Parabola

Property	$y^2 = 4ax$	$x^2 = 4ay$
Axis	$y = 0$	$x = 0$
Eccentricity	1	1
Directrix	$x + a = 0$	$y + a = 0$
Focus	$(a, 0)$	$(0, a)$
Vertex	$(0, 0)$	$(0, 0)$
Length of latus rectum	$ 4a $	$ 4a $
Equation of latus rectum	$x - a = 0$	$y - a = 0$

### 14.2.2 Ellipse and Hyperbola

For  $a > b$ :

Table 14.2: Properties of Ellipse and Hyperbola

Property	$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ Ellipse	$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$ Hyperbola
Length of Major Axis	$2a$	$2a$
Length of Minor Axis	$2b$	$2b$
Equation of Major Axis	$x = 0$	$x = 0$
Equation of Minor Axis	$y = 0$	$y = 0$
Eccentricity $e$	$\sqrt{1 - \frac{b^2}{a^2}}$	$\sqrt{1 + \frac{b^2}{a^2}}$
Vertices	$(\pm a, 0)$	$(\pm a, 0)$
Foci	$(\pm ae, 0)$	$(\pm ae, 0)$
Equation of Directrix	$x \pm \frac{a}{e} = 0$	$x = \pm \frac{a}{e}$
Length of latus rectum	$\frac{2b^2}{a}$	$\frac{2b^2}{a}$
Equation of latus rectum	$x \pm ae = 0$	
Centre	$(0, 0)$	$(0, 0)$

## Chapter 15

### Circles

#### 15.1 Locus Form

$$(x - g)^2 + (y - h)^2 = r^2 \quad (15.1)$$

where the centre is  $(g, h)$  and the radius is  $r$ .

#### 15.2 Diameter Form

$$(x - a)(x - c) + (y - b)(y - d) = 0 \quad (15.2)$$

where  $(a, b)$  and  $(c, d)$  are the two ends of the diameter.

#### 15.3 General Form

If the equation of a circle is in the form:

$$x^2 + y^2 + 2gx + 2fy + c = 0 \quad (15.3)$$

Then the following is true about the circle:

1. centre of the circle is  $(-g, -f)$
2. radius of circle is  $\sqrt{g^2 + f^2 - c}$

#### 15.4 Important Relations

1. If the circle passes through the origin,  $g = 0, f = 0$ .
2. If the circle touches the x-axis  $c = g^2$ .
3. If the circle touches the y-axis  $c = f^2$ .

## 15.5 Common for Two Circles

1. The common chord passing between two circles  $S_1$  and  $S_2$  are:

$$S_1 - S_2 = 0 \tag{15.4}$$

2. Circles passing through the intersection of two circles is:

$$S_2 + k(S_1 - S_2) = 0 \quad \forall k \in \mathbb{R} \tag{15.5}$$

## Chapter 16

### Vectors

Let two vectors be  $\vec{a} = a\hat{i} + b\hat{j} + c\hat{k}$  and  $\vec{b} = x\hat{i} + y\hat{j} + z\hat{k}$ :

#### 16.1 Modulus of a Vector

For a vector  $\vec{a}$ , the modulus of the vector is:

$$|\vec{a}| = \sqrt{a^2 + b^2 + c^2} \quad (16.1)$$

#### 16.2 Sum of Vectors

The sum of two vectors is:

$$|\vec{a} + \vec{b}| = \sqrt{|\vec{a}|^2 + |\vec{b}|^2 + 2|\vec{a}||\vec{b}|\cos\theta} \quad (16.2)$$

$$\vec{a} + \vec{b} = (a + x)\hat{i} + (b + y)\hat{j} + (c + z)\hat{k} \quad (16.3)$$

The direction of the resultant vector is:

$$\tan\alpha = \frac{b\sin\theta}{a + b\cos\theta} \quad (16.4)$$

where,  $\theta$  is the angle between the two vectors.

#### 16.3 Product of Vectors

##### 16.3.1 Dot Product

$$\vec{a} \cdot \vec{b} = |a||b|\cos\theta \quad (16.5)$$

$$\vec{a} \cdot \vec{b} = ax + by + cz \quad (16.6)$$

##### 16.3.2 Cross Product

$$\vec{a} \times \vec{b} = |a||b|\sin\theta\hat{n} \quad (16.7)$$

$$(16.8)$$

where  $\hat{n}$  is a vector  $\perp \vec{a}, \vec{b}$ .

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a & b & c \\ x & y & z \end{vmatrix} \quad (16.9)$$

## 16.4 Test of Co-planarity

Three vectors are called co-planar if:

$$\lambda \vec{a} + \mu \vec{b} = \vec{c} \quad (16.10)$$

$$(\vec{a} \times \vec{b}) \cdot \vec{c} = 0 \quad (16.11)$$

## Chapter 17

### 3D - Space

## 17.1 Line segments in 3D - Space

For points defined in a 3D space as  $A(x_1, y_1, z_1)$  and  $B(x_2, y_2, z_2)$ :

### 17.1.1 Distance between Two Points

$$AB = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2} \quad (17.1)$$

### 17.1.2 Section Formula of a Line Segment Divided in the ratio $m : n$

$$P = \left( \frac{nx_1 + mx_2}{m + n}, \frac{ny_1 + my_2}{m + n}, \frac{nz_1 + mz_2}{m + n} \right) \quad (17.2)$$

## 17.2 Line in 3D - Space

For a line which is defined as  $\vec{a} = a\hat{i} + b\hat{j} + c\hat{k}$ :

1. Line numbers of the line is

$$< a, b, c > \quad (17.3)$$

2. The line cosines are:

$$< \frac{a}{\sqrt{a^2 + b^2 + c^2}}, \frac{b}{\sqrt{a^2 + b^2 + c^2}}, \frac{c}{\sqrt{a^2 + b^2 + c^2}} > \quad (17.4)$$

$$=< l, m, n > \quad (17.5)$$

### 17.2.1 Angle between Two Lines

$$\cos \theta = \frac{a_1a_2 + b_1b_2 + c_1c_2}{\sqrt{a_1^2 + b_1^2 + c_1^2} \sqrt{a_2^2 + b_2^2 + c_2^2}} \quad (17.6)$$

$$\Rightarrow \cos \theta = l_1l_2 + m_1m_2 + n_1n_2 \quad (17.7)$$

When two lines are  $\perp$ ,  $l_1l_2 + m_1m_2 + n_1n_2 = 0$ .

When two lines are  $\parallel$   $\frac{l_1}{l_2} = \frac{m_1}{m_2} = \frac{n_1}{n_2} = 1$ .

### 17.2.2 Skew and Co-planar Lines

Let there be two lines  $r_1$  and  $r_2$ ,

$$r_1 = a_1 + \mu b_1 r_2 = a_2 + \lambda b_2 \quad (17.8)$$

### 17.2.3 Distance between Lines

The shortest distance between  $r_1$  and  $r_2$

$$S = \left| \frac{(\vec{a}_1 - \vec{a}_2) \cdot (\vec{b}_1 \times \vec{b}_2)}{|\vec{b}_1 \times \vec{b}_2|} \right| \quad (17.9)$$

If  $S = 0$ , the lines intersect.

#### Cartesian Form

For two lines defined as  $\frac{x - x_1}{a_1} = \frac{y - y_1}{b_1} = \frac{z - z_1}{c_1}$  and  $\frac{x - x_2}{a_2} = \frac{y - y_2}{b_2} = \frac{z - z_2}{c_2}$ :

$$S = \begin{vmatrix} x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix} \quad (17.10)$$

#### Distance Between Parallel Lines

$$S = \left| \frac{\vec{b} \cdot (\vec{a}_2 - \vec{a}_1)}{|\vec{b}|} \right| \quad (17.11)$$

#### Distance of a Point to a Line

For a point,  $(x_1, y_1, z_1)$  the distance to a line  $\frac{x - \alpha}{l} = \frac{y - \beta}{m} = \frac{z - \gamma}{n}$ :

$$S = \left( \left| \frac{x_1 - \alpha}{l} - \frac{y_1 - \beta}{m} \right| + \left| \frac{y_1 - \beta}{m} - \frac{z_1 - \gamma}{n} \right| + \left| \frac{z_1 - \gamma}{n} - \frac{x_1 - \alpha}{l} \right| \right)^{\frac{1}{2}} \quad (17.12)$$

## 17.3 Triangular Plane

### 17.3.1 Centroid of a Triangle

$$G = \left( \frac{x_1 + x_2 + x_3}{3}, \frac{y_1 + y_2 + y_3}{3}, \frac{z_1 + z_2 + z_3}{3} \right) \quad (17.13)$$



## Chapter 18

### 3D - Plane

A plane in 3-D space can be defined as:

1. Cartesian Form:

$$ax + by + cz + d = 0 \quad (18.1)$$

2. Vectorial Form:

$$\vec{r} \cdot \vec{n} = p \quad (18.2)$$

, where  $\vec{r}$  is a line on the plane,  $\vec{n}$  is a normal to the plane, and  $p$  is perpendicular distance to the plane from the origin.

## 18.1 Angle Between Two Planes

For two planes,  $\vec{r}_1 \cdot \vec{n}_1 = p_1$  and  $\vec{r}_2 \cdot \vec{n}_2 = p_2$ , the angle between the planes,  $\theta$  is:

$$\cos \theta = \frac{\vec{n}_1 \cdot \vec{n}_2}{|\vec{n}_1||\vec{n}_2|} \quad (18.3)$$

In the Cartesian Form:

$$\cos \theta = \frac{a_1 a_2 + b_1 b_2 + c_1 c_2}{\sqrt{a_1^2 + b_1^2 + c_1^2} \sqrt{a_2^2 + b_2^2 + c_2^2}} \quad (18.4)$$

## 18.2 Distance of a Point from a Plane

### 18.2.1 Cartesian Form

For the point  $(p, q, r)$  and the plane,  $ax + by + cz + d = 0$ :

$$S = \frac{ap + bq + cr + d}{\sqrt{a^2 + b^2 + c^2}} \quad (18.5)$$

**18.2.2 Vector Form**

For the point  $\vec{g} = p\hat{i} + q\hat{j} + r\hat{k}$  and the plane  $\vec{r} \cdot (a\hat{i} + b\hat{j} + c\hat{k}) + d = 0$ :

$$S = \frac{(a\hat{i} + b\hat{j} + c\hat{k}) \cdot (p\hat{i} + q\hat{j} + r\hat{k})}{\sqrt{a^2 + b^2 + c^2}} \quad (18.6)$$

$$\Rightarrow S = \frac{(a\hat{i} + b\hat{j} + c\hat{k}) \cdot \vec{g}}{|a\hat{i} + b\hat{j} + c\hat{k}|} \quad (18.7)$$

# Part III

## Statistics

## Chapter 19

### Descriptive Statistics

## 19.1 Measure of Location

### 19.1.1 Mean

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i \quad (19.1)$$

### 19.1.2 Median

For odd number of elements in a dataset:

$$\tilde{x} = x_{\frac{n+1}{2}} \quad (19.2)$$

For even number of elements in a dataset:

$$\tilde{x} = \frac{x_{\frac{n}{2}} + x_{(\frac{n}{2}+1)}}{2} \quad (19.3)$$

### 19.1.3 Mode

$$Mo(x) = \max(f(x_i)) \quad (19.4)$$

### 19.1.4 Quartile

Measure of percentage of elements less than or equal to a term

## 19.2 Measure of Spread

### 19.2.1 Variance

Variance measured on the whole population

$$\sigma^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2 \quad (19.5)$$

### 19.2.2 Sample Variance

Variance measured on a sample population

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2 \quad (19.6)$$

### 19.2.3 Standard Deviation and Sample Standard

$$\sigma = \sqrt{\sigma^2} \quad (19.7)$$

$$s = \sqrt{s^2} \quad (19.8)$$

### 19.2.4 Co-efficient of Variance

$$v = \frac{s}{\bar{x}} \quad (19.9)$$

## 19.3 Skewness

### 19.3.1 Types of Skewness

Name	Other Name	Characteristic
Right Skew	Positive Skew	Data concentrated on the lower side
Symmetric Distribution	Normal Distribution	Data distributed evenly
Left Skew	Negative Skew	Data concentrated on the higher side

### 19.3.2 Measure of Skewness

Skewness is measured by the Moment Co-efficient of Skewness.

$$g_m = \frac{m_3}{s^3}, \text{ where} \quad (19.10)$$

$$m_3 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^3 \quad (19.11)$$

#### Type of Skewness

The type of skewness from the value is  $g_m$  is:

Value of $g_m$	Type
$g_m = 0$	Symmetric
$g_m > 0$	Positive Skew
$g_m < 0$	Negative Skew

Value of $g_m$	Degree
$ g_m  > 1$	High Skewness
$0.5 <  g_m  \leq 1$	Moderate Skewness
$ g_m  \leq 0.5$	Low Skewness

### Degree of Skewness

The degree of skewness from the value is  $g_m$  is:

## 19.4 Kurtosis

Kurtosis is the measure of peakedness of data. Fisher's kurtosis measure is defined as:

$$\gamma = \frac{m_4}{s^4}, \text{ where} \quad (19.12)$$

$$m_4 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^4 \quad (19.13)$$

### 19.4.1 Type of Kurtosis

The types of kurtosis from the value of  $\gamma$  are:

Value of $\gamma$	Type
$\gamma = 0$	Normal Distribution or Mesokurtic
$\gamma < 0$	Flattened or Platykurtic
$\gamma > 0$	Peaked or Lepokurtic

## Chapter 20

### Hypothesis Testing

#### 20.1 T-Test

$$T = \frac{\bar{X} - \mu}{\frac{s}{\sqrt{n}}} \quad (20.1)$$

where:

$\bar{X}$  = Sample Mean

$\mu$  = Assumed Mean

$s$  = Number of Samples

$n$  = Number of observations

If  $T < t_c$  the  $H_0$  is not rejected.  $t_c$  is a functions of level of significance ( $\alpha$ ) and degrees of freedom ( $v = n - 1$ ).

#### 20.2 $\chi^2$ Test

$$\chi^2 = \sum_i \sum_j \frac{(h_{ij}^o - h_{ij}^e)^2}{h_{ij}^e} \quad (20.2)$$

where:

$h_e$  = Expected Value

$h_o$  = Actual Value

If  $\chi^2 < \chi_c^2$  then  $H_0$  is not rejected.  $\chi_c$  is a functions of level of significance ( $\alpha$ ) and degrees of freedom ( $v = (i - 1)(j - 1)$ ).

Chapter 21

Research and Survey Design

### 21.1 Population Covariance

$$\text{Cov}(x, y) = \frac{1}{n} \sum_{i=1}^n (x_i - \mu_x)(y_i - \mu_y) \quad (21.1)$$

### 21.2 Sample Covariance

$$\text{Cov}(x, y) = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y}) \quad (21.2)$$

### 21.3 Bravais-Pearson Correlation Co-efficient

$$r = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} \cdot \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}} \quad (21.3)$$

$$= \frac{\text{Cov}(x, y)}{\sqrt{\text{Var}(x) \cdot \text{Var}(y)}} \quad (21.4)$$

$$= \frac{\text{Cov}(x, y)}{\sigma_x \cdot \sigma_y} \quad (21.5)$$

### 21.4 Spearman's Rank Correlation Co-efficient

$$r_s = 1 - \frac{6 \sum d_i^2}{n(n^2 - 1)} \quad (21.6)$$

$$d_i = R(X_i) - R(Y_i) \quad (21.7)$$



## Chapter 22

### Estimation of Regression Function

For the regression functions:

$$Y_i = \beta_0 + \beta_1 X_1 \quad (22.1)$$

$$\hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 X_1 \quad (22.2)$$

$$(22.3)$$

where  $Y_i$  is the observed dependent variable (DV),  $\hat{Y}_i$  is the estimated DV, and  $X_i$  is the independent variable (IV).

$$u_i = Y_i - \hat{Y}_i \quad (22.4)$$

$$\Rightarrow Y_i = \hat{Y}_i + u_i \quad (22.5)$$

$$\Rightarrow Y_i = \hat{\beta}_0 + \hat{\beta}_1 X_1 + u_i \quad (22.6)$$

$$Y_i = \beta_0 + \beta_1 X_i + \epsilon_i \quad (22.7)$$

The objective function is:

$$\min_{u_i} \sum u_i = \min \sum_i \left[ Y_i - \hat{\beta}_0 - \hat{\beta}_1 X_i \right]^2$$

Since the regression function passes through:  $(\bar{X}, \bar{Y})$

$$\beta_0 = \bar{Y} - \hat{\beta}_1 \bar{X}$$

$$\begin{aligned} \min_{u_i} \sum u_i &= \min \sum_i \left[ Y_i - \bar{Y} + \hat{\beta}_1 \bar{X} - \hat{\beta}_1 X_i \right]^2 \\ &= \min \sum_i \left[ (Y_i - \bar{Y}) - \hat{\beta}_1 (X_i - \bar{X}) \right]^2 \\ &= \min \sum_i \left[ (Y_i - \bar{Y})^2 - 2 \cdot (Y_i - \bar{Y}) \cdot \hat{\beta}_1 (X_i - \bar{X}) + \hat{\beta}_1^2 (X_i - \bar{X})^2 \right] \\ &= \min \left[ \sum_i (Y_i - \bar{Y})^2 - 2 \cdot \hat{\beta}_1 \sum_i (Y_i - \bar{Y}) \cdot (X_i - \bar{X}) + \hat{\beta}_1^2 \sum_i (X_i - \bar{X})^2 \right] \\ \Rightarrow u_i^{\beta_1} &= -2 \sum_i (Y_i - \bar{Y}) + 2 \hat{\beta}_1 \sum_i (X_i - \bar{X})^2 = 0 \quad (\text{For optima Conditions}) \end{aligned}$$

$$\Rightarrow \hat{\beta}_1 = \frac{\sum_i (Y_i - \bar{Y})(X_i - \bar{X})}{\sum_i (X_i - \bar{X})^2}$$

$$\Rightarrow \hat{\beta}_0 = \bar{Y} - \hat{\beta}_1 \bar{X}$$

## 22.1 Sum of Squares Error

$$TSS = \sum_i (Y_i - \bar{Y})^2 \quad (22.8)$$

$$= \underbrace{\sum_i (\hat{Y}_i - \bar{Y})^2}_{\text{Explained Sum of Square Error (ESS)}} + \underbrace{\sum_i u_i^2}_{\text{Residual Sum of Squares Error (RSS)}} \quad (22.9)$$

### 22.1.1 $R^2$ : Coefficient of Determination

$$R^2 = \frac{ESS}{TSS} \quad (22.10)$$

$$= 1 - \frac{RSS}{TSS} \quad (22.11)$$

$$= 1 - \frac{\sum_i u_i^2}{\sum_i (Y_i - \bar{Y})^2} \quad (22.12)$$

For a regression analysis with single IV:

$$\sqrt{R^2} = v$$

**22.1.2  $\bar{R}^2$ : Coefficient of Determination**

$$\bar{R}^2 = 1 - \frac{\frac{\sum_i u_i^2}{(N - K - 1)}}{\frac{\sum_i (Y_i - \bar{Y})^2}{(N - 1)}} \quad (22.13)$$

where,  $N$  is the number of observations and  $K$  is the number of independent variables.

**22.2 T-Test**

Test for statistical significance of a single IV.

$$T = \frac{\hat{\beta}_1 - 0}{S_e(\hat{\beta}_1)} \quad (22.14)$$

**22.3 F-Test**

Test for statistical significance of all IVs together.

$$F = \frac{\frac{\text{ESS}}{(K - 1)}}{\frac{\text{RSS}}{(N - K)}} \quad (F \geq F_c, H_0 \text{ is rejected})$$

**22.4 Test for Heteroskedasticity****22.4.1 Definition**

$$\sigma_{\epsilon_i} \forall \epsilon_i \in [X_a, X_b] = \sigma_{\epsilon_i} \forall \epsilon_i \in [X_{b+1}, X_c]$$

**22.4.2 Durbin-Watson Test**

$$d_e = \frac{\sum_{t=2}^n (\hat{u}_t - \hat{u}_{t-1})^2}{\sum_{t=2}^n \hat{u}_t^2} \quad (22.15)$$

For the  $H_0$ : No autocorrelation:

$d$	$H_0$
$0 \leq d_e \leq d_L$ & $(4 - d_L) \leq d_e \leq 4$	Rejected
$d_L < d_e \leq d_U$ & $(4 - d_U) < d_e \leq (4 - d_L)$	Decision Free Zone
$d_L < d_e < D_U$	Not rejected

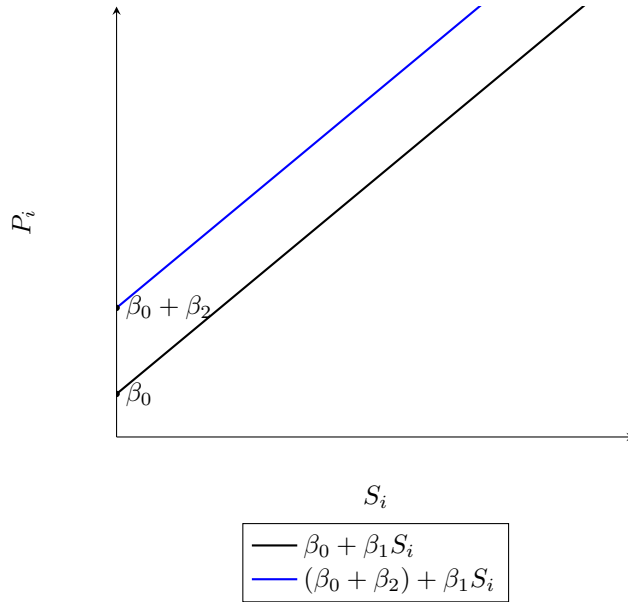
# Chapter 23

## Dummy Variables

### 23.1 Dummy Variable

$$P_i = \beta_0 + \beta_1 S_i + \beta_2 D_i + \epsilon_i \quad (23.1)$$

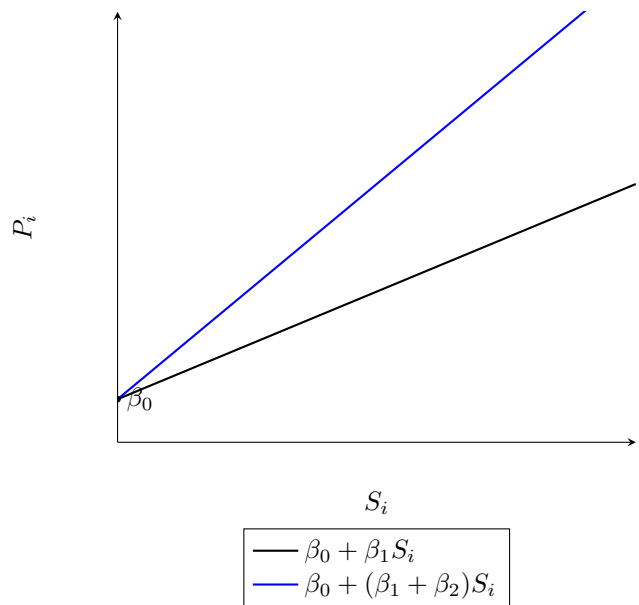
$$E(P_i) = \begin{cases} (\hat{\beta}_0 + \hat{\beta}_2) + \hat{\beta}_1 S_i, & D_i = 1 \\ \hat{\beta}_0 + \hat{\beta}_1 S_i, & D_i = 0 \end{cases} \quad (23.2)$$



### 23.2 Slope Dummy Variable

$$P_i = \beta_0 + \beta_1 S_i + \beta_2 (S_i \cdot D_i) + \epsilon_i \quad (23.3)$$

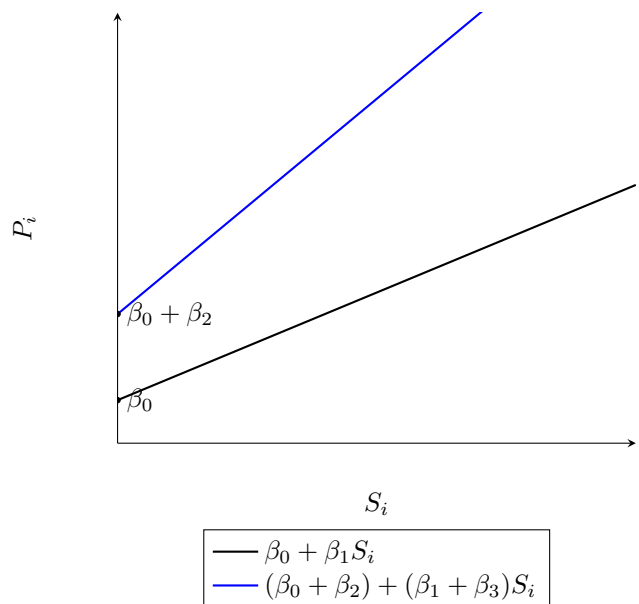
$$E(P_i) = \begin{cases} \hat{\beta}_0 + (\hat{\beta}_1 + \hat{\beta}_2) S_i, & D_i = 1 \\ \hat{\beta}_0 + \hat{\beta}_1 S_i, & D_i = 0 \end{cases} \quad (23.4)$$



### 23.3 Slope & Dummy Variable

$$P_i = \beta_0 + \beta_1 S_i + \beta_2 D_i + \beta_3 S_i D_i + \epsilon_i \tag{23.5}$$

$$E(P_i) = \begin{cases} (\hat{\beta}_0 + \hat{\beta}_2) + (\hat{\beta}_1 + \hat{\beta}_3) S_i, & D_i = 1 \\ \hat{\beta}_0 + \hat{\beta}_1 S_i, & D_i = 0 \end{cases} \tag{23.6}$$



## 23.4 Multi-Categories Dummy Variable

$$P_0 = b_0 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + b_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + b_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + b_3 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad (23.7)$$

Leads to Perfect Multicollinearity

### Alternatives

- $B_n$  captures the mean of each category, but F-Test is impossible

$$y = \beta_1 D_{1i} + \beta_2 D_{2i} + \beta_3 D_{3i} \quad (23.8)$$

- Computer drops automatically drops a variable

$$y = \beta_0 + \beta_1 D_{1i} + \beta_2 D_{2i} + \beta_3 D_{3i} \quad (23.9)$$

- Manually dropping a variable

$$y = \beta_0 + \beta_1 D_{1i} + \beta_2 D_{2i} \quad (23.10)$$

## Chapter 24

### Logistic Regression

For  $Y_i \in \{0, 1\}$ :

$$z_k = \beta_0 + \sum_{j=1}^n \beta_{jk} x_j + \epsilon_k, \beta_j \rightarrow \text{Logit Coefficient} \quad (24.1)$$

$$p = \frac{\exp^k}{1 + \exp^k} = \frac{1}{1 + \exp^{-k}} \quad (24.2)$$

where  $p$  is the probability of  $y = 1$ .

Part IV

Trigonometry



## Chapter 25

### Circular Trigonometric Functions

#### 25.1 Trigonometric Ratios of Standard Angles

Table 25.1: Trigonometric Ratios of Standard Angles

$\theta$	$\sin \theta$	$\cos \theta$	$\tan \theta$
$0^\circ$	0	1	0
$15^\circ$	$\frac{1}{4}$	$\frac{1}{4(2-\sqrt{3})}$	$2 - \sqrt{3}$
$18^\circ$	$\frac{\sqrt{5}-1}{4}$	$\frac{\sqrt{10+2\sqrt{5}}}{4}$	$\frac{\sqrt{5}-1}{\sqrt{10+2\sqrt{5}}}$
$30^\circ$	$\frac{1}{2}$	$\frac{\sqrt{3}}{2}$	$\frac{1}{\sqrt{3}}$
$36^\circ$	$\frac{\sqrt{5}+1}{4}$	$\frac{\sqrt{10-2\sqrt{5}}}{4}$	$\frac{\sqrt{5}+1}{\sqrt{10-2\sqrt{5}}}$
$45^\circ$	$\frac{1}{\sqrt{2}}$	$\frac{1}{\sqrt{2}}$	1
$60^\circ$	$\frac{1}{\sqrt{3}}$	$\frac{1}{2}$	$\sqrt{3}$
$72^\circ$	$\frac{\sqrt{10+2\sqrt{5}}}{4}$	$\frac{\sqrt{5}-1}{4}$	$\frac{\sqrt{10+2\sqrt{5}}}{\sqrt{5}-1}$
$90^\circ$	1	0	$\infty$

For any given triangle:

$$\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C} = 2R \quad (25.1)$$

, where  $R$  is the radius of circumcircle. Refer to 11.4.

#### 25.2 Negative Angle Formula

$$\sin(-\theta) = -\sin \theta \quad (25.2)$$

$$\cos(-\theta) = \cos \theta \quad (25.3)$$

$$\tan(-\theta) = -\tan \theta \quad (25.4)$$

$$\csc(-\theta) = -\csc \theta \quad (25.5)$$

$$\sec(-\theta) = \sec \theta \quad (25.6)$$

$$\cot(-\theta) = -\cot \theta \quad (25.7)$$

### 25.3 Sum of Angles Formula

$$\sin(A + B) = \sin A \cos B + \cos A \sin B \quad (25.8)$$

$$\cos(A + B) = \cos A \cos B - \sin A \sin B \quad (25.9)$$

$$\tan(A + B) = \frac{\tan A + \tan B}{1 - \tan A \tan B} \quad (25.10)$$

### 25.4 Difference of Angles Formula

$$\sin(A - B) = \sin A \cos B - \cos A \sin B \quad (25.11)$$

$$\cos(A - B) = \cos A \cos B + \sin A \sin B \quad (25.12)$$

$$\tan(A - B) = \frac{\tan A - \tan B}{1 + \tan A \tan B} \quad (25.13)$$

### 25.5 Multiples and Sub-multiples of $\pi$ and $\frac{\pi}{2}$

$$\forall k \in \mathbb{Z}$$

$$\sin \left[ (4k + 1) \frac{\pi}{2} \right] = 1 \quad (25.14)$$

$$\sin \left[ (4k - 1) \frac{\pi}{2} \right] = -1 \quad (25.15)$$

$$\sin k\pi = 0 \quad (25.16)$$

$$\sin \left[ (2k + 1) \frac{\pi}{2} \right] = 0 \quad (25.17)$$

$$\sin \left[ (2k - 1) \frac{\pi}{2} \right] = 0 \quad (25.18)$$

$$\sin k\pi = (-1)^k \quad (25.19)$$

**25.6  $\left(\frac{\pi}{2} \pm \theta\right)$  Formula**

$$\sin\left(\frac{\pi}{2} - \theta\right) = \cos \theta \quad (25.20)$$

$$\sin\left(\frac{\pi}{2} + \theta\right) = \cos \theta \quad (25.21)$$

$$\cos\left(\frac{\pi}{2} - \theta\right) = \sin \theta \quad (25.22)$$

$$\cos\left(\frac{\pi}{2} + \theta\right) = -\sin \theta \quad (25.23)$$

$$\tan\left(\frac{\pi}{2} - \theta\right) = \cot \theta \quad (25.24)$$

$$\tan\left(\frac{\pi}{2} + \theta\right) = -\cot \theta \quad (25.25)$$

$$\cot\left(\frac{\pi}{2} - \theta\right) = \tan \theta \quad (25.26)$$

$$\cot\left(\frac{\pi}{2} + \theta\right) = -\tan \theta \quad (25.27)$$

$$\csc\left(\frac{\pi}{2} - \theta\right) = \sec \theta \quad (25.28)$$

$$\csc\left(\frac{\pi}{2} + \theta\right) = \sec \theta \quad (25.29)$$

$$\sec\left(\frac{\pi}{2} - \theta\right) = \csc \theta \quad (25.30)$$

$$\sec\left(\frac{\pi}{2} + \theta\right) = -\csc \theta \quad (25.31)$$

**25.7  $\left(\frac{\pi}{4} \pm \theta\right)$  Formula**

$$\tan\left(\frac{\pi}{4} + \theta\right) = \frac{1 + \tan \theta}{1 - \tan \theta} \quad (25.32)$$

$$\tan\left(\frac{\pi}{4} - \theta\right) = \frac{1 - \tan \theta}{1 + \tan \theta} \quad (25.33)$$

**25.8 Trigonometric Identities**

$$\sin^2 \theta + \cos^2 \theta = 1 \quad (25.34)$$

$$\tan^2 \theta + 1 = \sec^2 \theta \quad (25.35)$$

$$\cot^2 \theta + 1 = \csc^2 \theta \quad (25.36)$$

## 25.9 Double Angle Formula

$$\sin 2\theta = 2 \sin \theta \cos \theta \quad (25.37)$$

$$= \frac{2 \tan \theta}{1 + \tan^2 \theta} \quad (25.38)$$

$$\cos 2\theta = \cos^2 \theta - \sin^2 \theta \quad (25.39)$$

$$= 2 \cos^2 \theta - 1 \quad (25.40)$$

$$= 1 - 2 \sin^2 \theta \quad (25.41)$$

$$= \frac{1 - \tan^2 \theta}{1 + \tan^2 \theta} \quad (25.42)$$

$$\tan 2\theta = \frac{2 \tan \theta}{1 - \tan^2 \theta} \quad (25.43)$$

## 25.10 Triple Angle Formula

$$\sin 3\theta = 3 \sin \theta - 4 \sin^3 \theta \quad (25.44)$$

$$\cos 3\theta = 4 \cos^3 \theta - 3 \cos \theta \quad (25.45)$$

$$\tan 3\theta = \frac{3 \tan \theta - \tan^3 \theta}{1 - 3 \tan^2 \theta} \quad (25.46)$$

## 25.11 Sum and Product of Two Ratios

For  $A > B$ :

$$\sin A + \sin B = 2 \sin \left( \frac{A+B}{2} \right) \cos \left( \frac{A-B}{2} \right) \quad (25.47)$$

$$\sin A - \sin B = 2 \cos \left( \frac{A+B}{2} \right) \sin \left( \frac{A-B}{2} \right) \quad (25.48)$$

$$2 \sin A \cos B = \sin(A+B) + \sin(A-B) \quad (25.49)$$

$$2 \cos A \sin B = \sin(A+B) - \sin(A-B) \quad (25.50)$$

$$\cos A + \cos B = 2 \cos \left( \frac{A+B}{2} \right) \cos \left( \frac{A-B}{2} \right) \quad (25.51)$$

$$\cos A - \cos B = -2 \sin \left( \frac{A+B}{2} \right) \sin \left( \frac{A-B}{2} \right) \quad (25.52)$$

$$2 \cos A \cos B = \cos(A+B) + \cos(A-B) \quad (25.53)$$

$$2 \cos A \sin B = \sin(A+B) - \sin(A-B) \quad (25.54)$$

$$\sin(A-B) \sin(A+B) = \sin^2 A - \sin^2 B \quad (25.55)$$

$$\cos(A-B) \cos(A+B) = \cos^2 A - \sin^2 B \quad (25.56)$$

$$\tan(A-B) \tan(A+B) = \frac{\tan^2 A - \tan^2 B}{1 - \tan^2 A \tan^2 B} \quad (25.57)$$

## 25.12 General Solutions

If  $\sin \theta = \sin \alpha$ :

$$\theta = n\pi + (-1)^n \alpha \quad (25.58)$$

$n \in \mathbb{Z}$

If  $\cos \theta = \cos \alpha$ :

$$\theta = 2n\pi \pm \alpha \quad (25.59)$$

$n \in \mathbb{Z}$

If  $\tan \theta = \tan \alpha$ :

$$\theta = n\pi \pm \alpha \quad (25.60)$$

$n \in \mathbb{Z}$

## 25.13 Taylor Series Expansion of Trigonometric Ratios

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \cdots \infty = \sum_{i=1}^{\infty} (-1)^{i+1} \frac{x^{2i-1}}{(2i-1)!} \quad (25.61)$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \cdots \infty = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i}}{(2i)!} \quad (25.62)$$

## Chapter 26

### Inverse Circular Trigonometric Function

## 26.1 Definition of Inverse Circular Trigonometric Function

### 26.1.1 For $\sin x$

$y = \arcsin x$  iff  $x = \sin y$ , then:

1.  $y \in [-\frac{\pi}{2}, \frac{\pi}{2}]$
2. domain of  $x \in [-1, 1]$
3.  $\sin(\arcsin x) = x, \forall x \in [-1, 1]$
4.  $\arcsin(\sin y) = y, \forall y \in [-\frac{\pi}{2}, \frac{\pi}{2}]$
5.  $\sin x$  is a strictly increasing in the domain  $[-\frac{\pi}{2}, \frac{\pi}{2}]$  and one-one.

### 26.1.2 For $\cos x$

$y = \arccos x$  iff  $x = \cos y$ , then:

1.  $y \in [0, \pi]$
2. domain of  $x \in [-1, 1]$
3.  $\cos(\arccos x) = x, \forall x \in [-1, 1]$
4.  $\arccos(\cos y) = y, \forall y \in [0, \pi]$
5.  $\cos x$  is a strictly decreasing in the domain  $[0, \pi]$  and one-one.

### 26.1.3 For $\tan x$

$y = \arctan x$  iff  $x = \tan y$ , then:

1.  $y \in (-\frac{\pi}{2}, \frac{\pi}{2})$
2. domain of  $x \in \mathbb{R}$
3.  $\tan(\arctan x) = x, \forall x \in \mathbb{R}$

4.  $\arctan(\tan y) = y, \forall y \in [-\frac{\pi}{2}, \frac{\pi}{2}]$
5.  $\tan x$  is a strictly increasing in the domain  $[-\frac{\pi}{2}, \frac{\pi}{2}]$  and one-one.

#### 26.1.4 For $\cot x$

$y = \cot^{-1} x$  iff  $x = \cot y$ , then:

1.  $y \in (0, \pi)$
2. domain of  $x \in \mathbb{R}$
3.  $\cot(\cot^{-1} x) = x, \forall x \in \mathbb{R}$
4.  $\cot^{-1}(\cot y) = y, \forall y \in (0, \pi)$
5.  $\cot x$  is a strictly decreasing in the domain  $(0, \pi)$  and one-one.

#### For $\sec x$

$y = \sec^{-1} x$  iff  $x = \sec y$

1.  $y \in \{[0, \frac{\pi}{2}) \cup (\frac{\pi}{2}, \pi]\}$
2.  $x \in \{(-\infty, -1] \cup [1, \infty)\}$
3.  $\sec(\sec^{-1} x) = x, \forall |x| \geq 1$
4.  $\sec^{-1}(\sec y) = y, \forall y \in \{[0, \frac{\pi}{2}) \cup (\frac{\pi}{2}, \pi]\}$

#### 26.1.5 For $\csc x$

$y = \csc^{-1} x$  iff  $x = \csc y$

1.  $y \in \{[-\frac{\pi}{2}, 0) \cup (0, \frac{\pi}{2}]\}$
2.  $x \in \{(-\infty, -1] \cup [1, \infty)\}$
3.  $\csc(\csc^{-1} x) = x, \forall |x| \geq 1$
4.  $\csc^{-1}(\csc y) = y, \forall y \in \{[-\frac{\pi}{2}, 0) \cup (0, \frac{\pi}{2}]\}$

## 26.2 Negative Arguments

$$\arcsin(-x) = -\arcsin x \quad (26.1)$$

$$\arctan(-x) = -\arctan x \quad (26.2)$$

$$\csc^{-1}(-x) = -\csc^{-1} x \quad (26.3)$$

$$\arccos(-x) = \pi - \arccos x \quad (26.4)$$

$$\cot^{-1}(-x) = \pi - \cot^{-1} x \quad (26.5)$$

$$\sec^{-1}(-x) = \pi - \sec^{-1} x \quad (26.6)$$

## 26.3 Reciprocal Relations

$$\csc^{-1} x = \arcsin \frac{1}{x} \quad (26.7)$$

$$\sec^{-1} x = \arccos \frac{1}{x} \quad (26.8)$$

$$\sec^{-1} x = \begin{cases} \arctan \frac{1}{x}, x > 0 \\ \pi + \arctan \frac{1}{x}, x < 0 \end{cases} \quad (26.9)$$

## 26.4 I.T.F. Identities

$$\arcsin x + \arccos x = \frac{\pi}{2}, |x| \leq 1 \quad (26.10)$$

$$\arctan x + \cot^{-1} x = \frac{\pi}{2}, x \in \mathbb{R} \quad (26.11)$$

$$\sec^{-1} x + \csc^{-1} x = \frac{\pi}{2}, |x| \geq 1 \quad (26.12)$$

## 26.5 Sum of Two Angles

$$\arctan x + \arctan y = \arctan \left( \frac{x+y}{1-xy} \right) \quad (26.13)$$

$$\arcsin x + \arcsin y = \arcsin \left( y\sqrt{1-x^2} + x\sqrt{1-y^2} \right) \quad (26.14)$$

$$\arccos x + \arccos y = \arccos \left( xy - \sqrt{1-x^2}\sqrt{1-y^2} \right) \quad (26.15)$$

## 26.6 Difference of Two Angles

$$\arctan x - \arctan y = \arctan \left( \frac{x-y}{1+xy} \right) \quad (26.16)$$

$$\arcsin x - \arcsin y = \arcsin \left( x\sqrt{1-y^2} - y\sqrt{1-x^2} \right) \quad (26.17)$$

$$\arccos x - \arccos y = \arccos \left( xy + \sqrt{1-x^2}\sqrt{1-y^2} \right) \quad (26.18)$$

## 26.7 Interconversion of Ratios

$$\arcsin x = \arccos \sqrt{1-x^2} \quad (26.19)$$

$$= \arctan \left( \frac{x}{\sqrt{1-x^2}} \right) \quad (26.20)$$



$$\arccos x = \arcsin \sqrt{1 - x^2} \quad (26.21)$$

$$= \arctan \left( \frac{\sqrt{1 - x^2}}{x} \right) \quad (26.22)$$

$$2 \arctan x = \arcsin \left( \frac{2x}{1 + x^2} \right) \quad (26.23)$$

$$= \arccos \left( \frac{1 - x^2}{1 + x^2} \right) \quad (26.24)$$

$$= \arctan \left( \frac{2x}{1 - x^2} \right) \quad (26.25)$$

## 26.8 Miscellaneous Relations

$$\cos(\arcsin x) = \sin(\arccos x) = \sqrt{1 - x^2} \quad (26.26)$$

$$\arctan x = \frac{\pi}{2} - \arctan \left( \frac{1}{x} \right), x > 1 \quad (26.27)$$

## Chapter 27

# Hyperbolic Trigonometric Functions

### 27.1 Definition

Hyperbolic trigonometric functions are defined such that  $(\cosh t, \sinh t)$  form the right half of an equilateral hyperbola. The functions are defined as follows:

$$\sinh x = \frac{\exp(x) - \exp(-x)}{2} \quad (27.1)$$

$$\cosh x = \frac{\exp(x) + \exp(-x)}{2} \quad (27.2)$$

$$\tanh x = \frac{\sinh x}{\cosh x} = \frac{\exp(x) - \exp(-x)}{\exp(x) + \exp(-x)} \quad (27.3)$$

$$\coth x = \frac{1}{\tanh x} = \frac{\exp(x) + \exp(-x)}{\exp(x) - \exp(-x)} \quad (27.4)$$

$$\operatorname{csch} x = \frac{1}{\sinh x} = \frac{2}{\exp(x) - \exp(-x)} \quad (27.5)$$

$$\operatorname{sech} x = \frac{1}{\cosh x} = \frac{2}{\exp(x) + \exp(-x)} \quad (27.6)$$

### 27.2 Identities

$$\coth^2 x - \sinh^2 x = 1 \quad (27.7)$$

$$\tanh^2 x + \operatorname{sech}^2 x = 1 \quad (27.8)$$

$$\coth^2 x - \operatorname{csch}^2 x = 1 \quad (27.9)$$

### 27.3 Inverse Hyperbolic Function

$$\sinh^{-1} z = \ln(z + \sqrt{z^2 + 1}) \quad (27.10)$$

$$\cosh^{-1} z = \ln(z \pm \sqrt{z^2 - 1}) \quad (27.11)$$

$$\tanh^{-1} z = \frac{1}{2} \ln \left( \frac{1+z}{1-z} \right) \quad (27.12)$$

$$\coth^{-1} z = \frac{1}{2} \ln \left( \frac{z+1}{z-1} \right) \quad (27.13)$$

$$\operatorname{csch}^{-1} z = \ln \left( \frac{1 \pm \sqrt{z^2 + 1}}{z} \right) \quad (27.14)$$

$$\operatorname{sech}^{-1} z = \ln \left( \frac{1 \pm \sqrt{1 - z^2}}{2} \right) \quad (27.15)$$

### 27.4 Relation to Circular Trigonometric Functions

$$\sinh(z) = -i \sin(iz) \quad (27.16)$$

$$\cosh(z) = \cos(iz) \quad (27.17)$$

$$\tanh(z) = -i \tan(iz) \quad (27.18)$$

$$\operatorname{csch}(z) = i \csc(iz) \quad (27.19)$$

$$\operatorname{sech}(z) = \sec(iz) \quad (27.20)$$

$$\coth(z) = i \cot(iz) \quad (27.21)$$

# Part V

## Calculus

## Chapter 28

### Limits

$$\lim_{x \rightarrow 0} \frac{\sin x}{x} = 1 \quad (28.1)$$

$$\lim_{x \rightarrow 0} \frac{\tan x}{x} = 1 \quad (28.2)$$

$$\lim_{x \rightarrow 0} \cos x = 1 \quad (28.3)$$

$$\lim_{x \rightarrow a} \frac{x^n - a^n}{x - a} = na^{n-1} \quad (28.4)$$

$$\lim_{x \rightarrow a} f(x)g(x) = \lim_{x \rightarrow a} f(x) \cdot \lim_{x \rightarrow a} g(x) \quad (28.5)$$

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \frac{\lim_{x \rightarrow a} f(x)}{\lim_{x \rightarrow a} g(x)}, \lim_{x \rightarrow a} g(x) \neq 0 \quad (28.6)$$

$$\lim_{x \rightarrow 0} \exp(x) = 1 \quad (28.7)$$

$$\lim_{x \rightarrow a} \exp(x) = \exp(c) \quad (28.8)$$

$$\lim_{x \rightarrow 0} \frac{\exp(x) - 1}{x} = 1 \quad (28.9)$$

$$\lim_{x \rightarrow a} c^x = c^a \quad (28.10)$$

$$\lim_{x \rightarrow a} \ln x = \ln a \quad (28.11)$$

$$\lim_{x \rightarrow 0} (1 + x)^{\frac{1}{x}} = e \quad (28.12)$$

$$\lim_{x \rightarrow 0} \frac{\ln(1 + x)}{x} = 1 \quad (28.13)$$

$$\lim_{x \rightarrow 0} \frac{a^x - 1}{x} = \ln a \quad (28.14)$$

$$\lim_{n \rightarrow \infty} \frac{x^n}{n!} = 0, \forall x \in \mathbb{R} \quad (28.15)$$

### 28.1 L'Hospital Rule

If:

$$L = \lim_{x \rightarrow a} \frac{f(x)}{g(x)}$$

is such that  $f(a) = 0$  and  $g(a) = 0$ , or  $f(a) = \infty$  and  $g(a) = \infty$ , then:

$$L = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$$

## Chapter 29

### Differentiation

#### 29.1 Differentiation by First Principle

$$\frac{df(x)}{dx} = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} \quad (29.1)$$

#### 29.2 Standard Differentiation Formulae

$$\frac{dk}{dx} = 0 \quad (29.2)$$

$$\frac{dx^n}{dx} = nx^{n-1} \quad (29.3)$$

$$\frac{da^x}{dx} = \ln a \cdot a^x \quad (29.4)$$

$$\frac{d \exp(x)}{dx} = \exp(x) \quad (29.5)$$

$$\frac{d \ln x}{dx} = \frac{1}{x} \quad (29.6)$$

$$\frac{d\sqrt{x}}{dx} = \frac{1}{2\sqrt{2}} \quad (29.7)$$

$$(29.8)$$

### 29.2.1 Circular Trigonometric Functions

$$\frac{d \sin x}{dx} = \cos x \quad (29.9)$$

$$\frac{d \cos x}{dx} = -\sin x \quad (29.10)$$

$$\frac{d \tan x}{dx} = \sec^2 x \quad (29.11)$$

$$\frac{d \sec x}{dx} = \sec x \cdot \tan x \quad (29.12)$$

$$\frac{d \csc x}{dx} = -\csc x \cdot \cot x \quad (29.13)$$

$$\frac{d \cot x}{dx} = -\csc^2 x \quad (29.14)$$

### 29.2.2 Inverse Circular Trigonometric Functions

$$\frac{d \arcsin x}{dx} = \frac{1}{\sqrt{1-x^2}}, |x| \leq 1 \quad (29.15)$$

$$\frac{d \arccos x}{dx} = -\frac{1}{\sqrt{1-x^2}}, |x| \leq 1 \quad (29.16)$$

$$\frac{d \arctan x}{dx} = \frac{1}{1+x^2} \quad (29.17)$$

$$\frac{d \cot^{-1} x}{dx} = -\frac{1}{1+x^2} \quad (29.18)$$

$$\frac{d \sec^{-1} x}{dx} = \frac{1}{x \cdot \sqrt{x^2-1}}, |x| \geq 1 \quad (29.19)$$

$$\frac{d \csc^{-1} x}{dx} = -\frac{1}{x \cdot \sqrt{x^2-1}}, |x| \geq 1 \quad (29.20)$$

### 29.2.3 Hyperbolic Trigonometric Function

$$\frac{d \sinh x}{dx} = \cosh x \quad (29.21)$$

$$\frac{d \cosh x}{dx} = \sinh x \quad (29.22)$$

$$\frac{d \tanh x}{dx} = 1 - \tanh^2 x = \operatorname{sech}^2(x) \quad (29.23)$$

$$\frac{d \coth x}{dx} = 1 - \coth^2 x = -\operatorname{csch}^2(x) \quad (29.24)$$

$$\frac{d[\operatorname{sech}(x)]}{dx} = -\tanh x \operatorname{sech} x \quad (29.25)$$

$$\frac{d[\operatorname{csch}(x)]}{dx} = -\coth x \operatorname{csch} x \quad (29.26)$$



### 29.2.4 Inverse Hyperbolic Trigonometric Function

$$\frac{d \sinh x}{dx} = \frac{1}{\sqrt{x^2 + 1}} \quad (29.27)$$

$$\frac{d \cosh x}{dx} = \frac{1}{\sqrt{x^2 - 1}} \quad (29.28)$$

$$\frac{d \tanh x}{dx} = \frac{1}{1 - x^2} \quad (29.29)$$

$$\frac{d \coth x}{dx} = \frac{1}{1 - x^2} \quad (29.30)$$

$$\frac{d[\operatorname{sech}(x)]}{dx} = \frac{1}{x\sqrt{1 - x^2}} \quad (29.31)$$

$$\frac{d[\operatorname{csch}(x)]}{dx} = \frac{1}{|x|\sqrt{1 + x^2}} \quad (29.32)$$

## 29.3 Rules of Differentiation

$$\frac{d[c \cdot f(x)]}{dx} = c \cdot \frac{df(x)}{dx} \quad (29.33)$$

$$\frac{d[f_1(x) + f_2(x)]}{dx} = \frac{d[f_1(x)]}{dx} + \frac{d[f_2(x)]}{dx} \quad (29.34)$$

$$\frac{d[f_1 \cdot f_2]}{dx} = f_1 \cdot f_2' + f_2 \cdot f_1' \quad (29.35)$$

$$\frac{d\left(\frac{f_1}{f_2}\right)}{dx} = \frac{f_2 \cdot f_1' - f_1 \cdot f_2'}{f_2^2} \quad (29.36)$$

## 29.4 Chain Rule

If two functions are defined as  $z = f(y)$  and  $y = g(x)$ :

$$\frac{dz}{dx} = \frac{dz}{dy} \cdot \frac{dy}{dx} \quad (29.37)$$

If two functions are defined as  $x = f(\theta)$  and  $y = g(\theta)$ :

$$\frac{d^2 y}{dx^2} = \left[ \frac{d}{d\theta} \left( \frac{\frac{dy}{d\theta}}{\frac{dx}{d\theta}} \right) \right] \frac{d\theta}{dx} \quad (29.38)$$

Chapter 30

Successive Differentiation

$$D^n(ax+b)^m = m(m-1) \cdots (m-n+1)a^n(ax+b)^{m-n} \quad (30.1)$$

$$D^n \left( \frac{1}{ax+b} \right) = \frac{(-1)^n \cdot n! \cdot a^n}{(ax+b)^{n+1}} \quad (30.2)$$

$$D^n \ln(ax+b) = \frac{(-1)^{n-1} \cdot (n-1)! \cdot a^n}{(ax+b)^n}, n \geq 2 \quad (30.3)$$

$$D^n(a^{mx}) = m^n (\ln a)^n \cdot a^{mx} \quad (30.4)$$

$$D^n(e^{mx}) = m^n e^{mx} \quad (30.5)$$

$$D^n \sin(ax+b) = a^n \sin(ax+b+n\frac{\pi}{2}) \quad (30.6)$$

$$D^n \cos(ax+b) = a^n \cos(ax+b+n\frac{\pi}{2}) \quad (30.7)$$

$$D^n[e^{ax} \sin(bx+c)] = (a^2+b^2)^{\frac{n}{2}} e^{ax} \sin(bx+c+n \arctan \frac{b}{a}) \quad (30.8)$$

$$D^n[e^{ax} \cos(bx+c)] = (a^2+b^2)^{\frac{n}{2}} e^{ax} \cos(bx+c+n \arctan \frac{b}{a}) \quad (30.9)$$

### 30.1 Leibnitz's Theorem

For two functions  $u$  and  $v$  of  $x$ , the successive differentiation of their product is defined as:

$$(uv)_n = {}^nC_0 u_n v + {}^nC_1 u_{n-1} v_1 + \cdots + {}^nC_n u v_n \quad (30.10)$$

$$= \sum_{i=0}^n {}^nC_i u_{n-i} v_i \quad (30.11)$$

## Chapter 31

### Partial Derivative

If  $f(x, y)$  is a function of  $(x, y)$ , then  $\frac{\partial f(x, y)}{\partial x}$  is the differentiation of  $f(x, y)$  w.r.t.  $x$ , keeping all other parameters constant.

### 31.1 Chain Rule

If  $f$  is a function of  $u$  and  $v$ , which are functions of  $x$  and  $y$ , then:

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial x} \quad (31.1)$$

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial y} \quad (31.2)$$

$$(31.3)$$

If  $f$  is a function of  $x$  and  $y$ , which are functions of  $t$ , then:

$$\frac{df}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} \quad (31.4)$$

### 31.2 Euler's Theorem

For a homogeneous function <sup>1</sup>,  $f(x_i)$  of degree  $n$ :

$$\sum x_i \frac{\partial f}{\partial x_i} = n f(x_i) \quad (31.5)$$

---

<sup>1</sup>Homogeneous functions are defined as  $f(ax, ay) = a^\kappa f(x, y)$ , where  $\kappa$  is the degree of homogeneity. E.g.  $f(x, y) = x^2 + y^2$ , then  $f(tx, ty) = t^2(x^2 + y^2)$ , and the degree of homogeneity is 2.

## Chapter 32

### Application of Differential

### 32.1 Rolle's Theorem

For a function  $f(x)$ :

1. is continuous in  $[a, b]$
2. is differentiable in  $(a, b)$
3.  $f(a) = f(b)$ ,

then there exists a point  $x = c$  such that  $f'(c) = 0$ ,  $c \in (a, b)$

### 32.2 Mean Value Theorem or LaGrange's Theorem

For a function  $f(x)$ :

1. is continuous in  $[a, b]$
2. is differentiable in  $(a, b)$ ,

then there exists a point  $x = c$  such that  $f'(c) = \frac{f(b) - f(a)}{b - a}$ ,  $c \in (a, b)$ , i.e., the tangent is parallel to the line joining the the points  $(a, f(a))$  and  $(b, f(b))$ .

### 32.3 Cauchy's Mean Value Theorem

For a function  $f(x)$  and  $g(x)$ :

1. are continuous in  $[a, b]$
2. are differentiable in  $(a, b)$
3.  $g'(x) \neq 0$  in  $(a, b)$ ,

then there exists a point  $c \in (a, b)$ , such that  $\frac{f(x)}{g(x)} = \frac{f(b) - f(a)}{g(b) - g(a)}$ .

## 32.4 Maxima and Minima

### 32.4.1 Maxima

For the local maxima of a function  $f(x)$ :

1.  $f'(c) = 0$  and

$$\lim_{\epsilon \rightarrow c^-} f'(\epsilon) > 0$$

$$\lim_{\epsilon \rightarrow c^+} f'(\epsilon) < 0$$

OR

2.  $f'(c) = 0$  and  $f''(x) < 0$ ,

then  $f(c)$  is the local maxima point of the function  $f(x)$ .

### 32.4.2 Minima

For the local minima of a function  $f(x)$ :

1.  $f'(c) = 0$  and

$$\lim_{\epsilon \rightarrow c^-} f'(\epsilon) < 0$$

$$\lim_{\epsilon \rightarrow c^+} f'(\epsilon) > 0$$

OR

2.  $f'(c) = 0$  and  $f''(x) > 0$ ,

then  $f(c)$  is the local minima point of the function  $f(x)$ .

## 32.5 Taylor's Theorem

For a function which is differentiable  $n$  times:

$$f(a+h) = f(a) + h \cdot f'(a) + \frac{h^2}{2!} \cdot f''(a) + \cdots + \frac{h^{n-1}}{(n-1)!} \cdot f^{n-1}(a) + \frac{h^n}{x!} \cdot R_n \quad (32.1)$$

where  $R_n$  is the remainder term.

### 32.5.1 Remainder Term

**LeGrange's Form**

$$R_n = f^n(a + \theta h), \theta \in (0, 1) \quad (32.2)$$

**Cauchy's Form**

$$R_n = n(1 - \theta)^{n-1} f^n(a + \theta h), \theta \in (0, 1) \quad (32.3)$$

### 32.5.2 Conditions for Validity of Expansion

For validity of Taylor Expansion, the condition

$$\lim_{n \rightarrow \infty} R_n = 0 \quad (32.4)$$

needs to be satisfied either where  $R_n$  is the remainder term in either LeGrange's Form or Cauchy's Form. If the condition is satisfied in a certain domain, then the expansion is valid within that domain only.

### 32.5.3 Taylor's Theorem for Two Variables

$$\begin{aligned} f(a+x, b+y) = & f(x, y) + \left( a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} \right) f(x, y) + \frac{1}{2!} \left( a^2 \frac{\partial^2}{\partial x^2} + b^2 \frac{\partial^2}{\partial y^2} \right) f(x, y) + \cdots + \\ & \frac{1}{n!} \left( a^n \frac{\partial^n}{\partial x^n} + b^n \frac{\partial^n}{\partial y^n} \right) f(x + \theta a, y + \theta b), \theta \in (0, 1) \end{aligned} \quad (32.5)$$

## 32.6 Maclaurin's Series

$$f(x) = f(0) + x f'(0) + \frac{1}{2!} x^2 f''(0) + \frac{1}{3!} x^3 f'''(0) + \cdots \infty \quad (32.6)$$

$$= \sum_{i=0}^{\infty} \frac{1}{i!} x^i f^{(i)}(0) \quad (32.7)$$

### 32.6.1 Maclaurin's Series with Two Variables

$$f(a, b) = f(0, 0) + \left( a \frac{\delta}{\delta x} + b \frac{\delta}{\delta y} \right) f(0, 0) + \frac{1}{2!} \left( a^2 \frac{\delta^2}{\delta x^2} + b^2 \frac{\delta^2}{\delta y^2} \right) f(0, 0) + \cdots \infty \quad (32.8)$$

$$= \sum_{i=0}^{\infty} \frac{1}{n!} \left( a^i \frac{\delta^i}{\delta x^i} + b^i \frac{\delta^i}{\delta y^i} \right) f(0, 0) \quad (32.9)$$

## 32.7 Curvature

Curvature is the rate of change of direction w.r.t. arc. Mathematically:

$$\text{Curvature} = \frac{d(\text{direction})}{d(\text{arc})} \quad (32.10)$$

$$\lim_{\Delta s \rightarrow 0} \frac{\Delta \psi}{\Delta s} = \frac{d\psi}{ds} \quad (32.11)$$

### 32.7.1 Radius of Curvature

#### Cartesian Form

For a curve  $y = f(x)$ :

$$\rho = \frac{(1 + y'^2)^{\frac{3}{2}}}{y''} \quad (32.12)$$

However, this formula fails for  $y' \rightarrow \infty$ .

#### Parametric Form

For a curve defined as  $x = \phi(t)$  and  $y = \psi(t)$ :

$$\rho = \frac{(\ddot{x}^2 + \ddot{y}^2)^{\frac{3}{2}}}{x\ddot{y} - y\ddot{x}} \quad (32.13)$$

### 32.7.2 Newton's Formula

1. If the curve passes through origin, and the tangent at origin is the x-axis:

$$\rho = \lim_{\substack{x \rightarrow 0 \\ y \rightarrow 0}} \frac{x^2}{2y} \quad (32.14)$$

2. If the curve passes through origin, and the tangent at origin is the y-axis:

$$\rho = \lim_{\substack{x \rightarrow 0 \\ y \rightarrow 0}} \frac{y^2}{2x} \quad (32.15)$$

3. If the curve passes through origin and  $ax + by + c = 0$  is the tangent at origin:

$$\rho(0, 0) = \frac{1}{2} \sqrt{a^2 + b^2} \lim_{\substack{x \rightarrow 0 \\ y \rightarrow 0}} \frac{a^2 + y^2}{ax + by} \quad (32.16)$$

### 32.7.3 Tangent at Origin

For a curve

$$\sum c_i x^j y^k = 0, i \in \mathbb{N} \text{ and } j, k \in \mathbb{Z} - \{0\} \quad (32.17)$$

The curve passes through origin  $c = 0$ . Then the lowest degree term equated to  $x$  gives the tangent at origin.

## 32.8 Asymptotes

If the distance between a line  $P$  and a curve  $f(x)$ ,  $s$  is such that  $s \rightarrow 0$ , as  $x \rightarrow \infty$ , then  $P$  is the asymptote of  $f(x)$ . For asymptotes not parallel to x-axis:

Let  $y = mx + c$  be the asymptote of the function  $y = f(x)$ , then:

$$m = \lim_{x \rightarrow \infty} \frac{y}{x} \quad (32.18)$$

$$c = \lim_{x \rightarrow \infty} (y - mx) \quad (32.19)$$

### 32.8.1 Asymptote of Algebraic Curves

For an algebraic curve, passing through origin, defined as:

$$\begin{aligned}
 & (a_0x^n + a_1x^{n-1}y^1 + \cdots + a_{n-1}xy^{n-1} + a_ny^n) \\
 & + (b_0x^{n-1} + b_1x^{n-2}y^1 + \cdots + b_{n-1}xy^{n-2} + b_ny^{n-1}) + \cdots = 0 \\
 & \Rightarrow x^n\phi_n\left(\frac{y}{x}\right) + x^{n-1}\phi_{n-1}\left(\frac{y}{x}\right) + \cdots + x\phi_1\left(\frac{y}{x}\right) = 0
 \end{aligned} \tag{32.20}$$

The asymptote(s) defined as  $y = mx + c$ ,

1.  $m$  is the solution for the equation

$$\phi_n(m) = 0 \tag{32.21}$$

- 2.

$$c = -\frac{\phi_{n-1}(m)}{\phi_n(m)} \tag{32.22}$$

where  $c$  is a finite value.