Mathematical Formulae A Book of High School and Engineering Common Core Mathematical Formulae

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—Part I— Algebra

Logarithm

1.1 Basic Formulae

For $a^x = b$:

$$\log_a x, \forall x \le 0 \text{ is undefined} \tag{1.1}$$

$$\log_a b = x, bax \neq 1, a \neq 1 \tag{1.2}$$

$$\log_b a^m = m \log_b a, \text{ for } a^m = b \tag{1.3}$$

$$a^{\log_a x} = x \tag{1.4}$$

$$a^{\log_b c} = c^{\log_b a} \tag{1.5}$$

$$\frac{1}{\log_a b} = \log_b a \tag{1.6}$$

$$\log_c(ab) = \log_c a + \log_c b \tag{1.7}$$

$$\log_c \left(\frac{a}{b}\right) = \log_c a - \log_c b \tag{1.8}$$

$$|\log_a x| = \begin{cases} -\log_a x, & \text{if } 0 < x < 1\\ \log_a x, & \text{if } 1 \le x < \infty \end{cases}$$
 (1.9)

1.2 Series

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots = \lim_{n \to \infty} \sum_{i=0}^n \frac{x^i}{i!}$$
 (1.10)

$$\log(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots = \lim_{n \to \infty} \sum_{i=1}^{n} (-1)^{(i-1)} \frac{x^i}{i}$$
 (1.11)

-Chapter 2-

Complex Numbers

2.1 Basic Formulae

For z = x + iy,

$$|z| = \sqrt{x^2 + y^2} \tag{2.1}$$

$$an \theta = \frac{y}{x} \tag{2.2}$$

$$\bar{z} = x - iy \tag{2.3}$$

2.2 Arithmetic Operation of Complex Number

For two complex numbers $z_1 = x_1 + iy_1$ and $z_2 = x_2 + iy_2$:

$$z_1 + z_2 = (x_1 + x_2) + i(y_1 + y_2)$$
(2.4)

$$z_1 z_2 = (x_1 x_2 - y_1 y_2) + i(x_1 y_2 + x_2 y_1)$$
(2.5)

$$|z_1 z_2| = |z_1| \cdot |z_2| \tag{2.6}$$

$$\frac{z_1}{z_2} = \frac{(x_1 x_2 + y_1 y_2) + i(x_2 y_1 - x_1 y_2)}{a_2^2 + b_2^2}$$
(2.7)

$$\left|\frac{z_1}{z_2}\right| = \frac{|z_1|}{|z_2|}\tag{2.8}$$

2.3 Euler's Formula

$$z = re^{i\theta}$$
, where (2.9)

$$r = |z| \tag{2.10}$$

$$e^{i\theta} = \cos\theta + i\sin\theta \tag{2.11}$$

$$\theta = \arctan\left(\frac{y}{x}\right) \tag{2.12}$$

2.4 Trigonometric Ratios in Complex Form

$$e^{i\theta} + e^{-i\theta} = 2\cos\theta \tag{2.13}$$

$$\Rightarrow \cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2} \tag{2.14}$$

$$e^{i\theta} - e^{-i\theta} = 2\sin\theta \tag{2.15}$$

$$\Rightarrow \sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2} \tag{2.16}$$

2.5 De Moivre's Formula

According to DeMoivre's Formula:

$$(\cos \theta + i \sin \theta)^n = \cos(n\theta) + i \sin(n\theta) \tag{2.17}$$

Proof

$$\cos \theta + i \sin \theta = e^{i\theta}$$

$$\Rightarrow (\cos \theta + i \sin \theta)^n = e^{n(i\theta)}$$

$$= \cos(n\theta) + i \sin(n\theta)$$
Q.E.D.

2.6 Application of Euler's and De Moivre's Formula

For $z_1 = |r_1| e^{i\theta_1}$ and $z_2 = |r_2| e^{i\theta_2}$

$$z_1 z_2 = (r_1 r_2) e^{i(\theta_1 + \theta_2)}$$
(2.18)

$$\frac{z_1}{z_2} = \left(\frac{r_1}{r_2}\right) e^{i(\theta_1 - \theta_2)} \tag{2.19}$$

2.7 Roots of Unity

$$\sqrt[n]{1} = e^{i\frac{2k\pi}{n}}$$
, where $k \in [0, n-1]$ (2.20)

2.8 Important Relations of Complex Numbers

$$|z_1 + z_2| \le |z_1| + |z_2| \tag{2.21}$$

$$|z_1 - z_2| \le |z_1| + |z_2| \tag{2.22}$$

$$|z_1 - z_2| \ge |z_1| - |z_2| \tag{2.23}$$

$$|z_1 + z_2| \ge ||z_1| - |z_2|| \tag{2.24}$$

$$|z_1 + z_2|^2 = 2(|z_1|^2 + |z_2|^2)$$
 (2.25)

Progression

3.1 Arithmetic Progression (A.P.)

An arithmetic sequence is $a, a+n, a+2n, ...\infty$ or $t_n=a+(n-1)d$, where a is the first term, d is the common difference, and n is the n^{th} -term.

An arithmetic series is $a + (a + d) + (a + 2d) + ...\infty$.

3.1.1 Sum of A.P. Series

$$S_{n} = a + (a + d) + \dots + (a + \overline{n - 2}d) + (a + \overline{n - 1}d)$$

$$S_{n} = (a + \overline{n - 1}d) + (a + \overline{n - 2}d + \dots + (a + d) + a$$

$$\Rightarrow 2S_{n} = n(2a + \overline{n - 1}d)$$

$$\Rightarrow S_{n} = \frac{n}{2}(2a + \overline{n - 1}d)$$
(3.1)

3.1.2 Important Relation

If the three terms a, b, c are in A.P., then

$$2b = a + c \tag{3.2}$$

3.2 Geometric Progression (G.P.)

An geometric sequence is $a, ar, ar^2, ...\infty$ or $t_n = ar^{n-1}$, where a is the first term, r is the common ratio, and n is the n^{th} -term. An geometric series is $a + ar + ar^2 + ...\infty$.

3.2.1 The Value of 'r'

$$r = \frac{t_2}{t_1} = \frac{t_3}{t_2} = \dots = \frac{t_n}{t_{n-1}}$$
 (3.3)

3.2.2 Sum of a G.P. Series

For a definite G.P. series, where there are n terms in the series, the sum of the series is:

$$S_n = \frac{a|r^n - 1|}{|r - 1|} \tag{3.4}$$

For an infite G.P. series the sum of the series is defined for r < 1. Sum of such a series is:

$$S_{\infty} = \frac{a}{1 - r} \tag{3.5}$$

3.2.3 Important relations

If the three terms a, b, c are in G.P., then:

$$b^2 = ac (3.6)$$

3.3 Harmonic Progression (H.P.)

If a, b, c are terms of an H.P. then $\frac{1}{a}, \frac{1}{b}, \frac{1}{c}$ are in A.P.

$$\frac{2}{b} = \frac{1}{a} + \frac{1}{c} \tag{3.7}$$

$$\Rightarrow b = \frac{2ac}{a+c} \tag{3.8}$$

3.4 Arithmetico-Geometric Progression (A.G.P.)

Sequence $a, (a+d)r, (a+2d)r^2, ..., (a+\overline{n-1}d)r^{n-1}$, where $a \to \text{first term of A.G.P.}, d \to \text{common difference}$, and $r \to \text{common ratio}$.

3.4.1 Sum of A.G.P.:

For an infinite A.G.P. series, the sum is defined for r < 1:

$$S_{\infty} = \frac{a}{1-r} + \frac{dr}{(1-r)^2} \tag{3.9}$$

3.5 Special Series

For $n \in \mathbb{N}$

$$1 + 2 + 3 + \dots + (n-1) + n = \frac{n(n-1)}{2}$$
(3.10)

$$1^{2} + 2^{2} + 3^{2} + \dots + (n-1)^{2} + n^{2} = \frac{n(n+1)(2n+1)}{6}$$
(3.11)

$$1^{3} + 2^{3} + 3^{3} + \dots + (n-1)^{3} + n^{3} = \left[\frac{n(n-1)}{2}\right]^{2}$$
(3.12)

3.5.1 Riemann Zeta Function

$$\zeta(s) = \sum_{n=1}^{\infty} \frac{1}{n^s} \tag{3.13}$$

3.5.2 Riemann's Infinite Series as an Integration

$$\lim_{n \to \infty} \frac{1}{n} \sum_{i=r_1}^{r_2} f(\frac{i}{n}) = \int_{\frac{r_1}{n}}^{\frac{r_2}{n}} f(x) dx \tag{3.14}$$

Test of Convergence of Infinite Series

If $a_1, a_2, a_3, ..., a_n$ is a sequence by a_n and their sum of series is S_n , then the following apply.

4.1 Definition

If

$$\lim_{n\to\infty} S_n = l$$

where l is a finite value, the series S_n is said to converge. A non-convergent series is called a divergent series.

4.2 Tests of Convergence

4.2.1 Comparison Test

If u_n and v_n are two positive series, then:

- 1. (a) v_n converges
 - (b) $u_n \leq v_n \forall n$ Then u_n converges.
- 2. (a) v_n diverges
 - (b) $u_n \ge v_n \forall n$ Then u_n diverges.

4.2.2 Limit Form

If

$$\lim_{x \to \infty} \frac{u_n}{v_n} = l$$

where l is a finite quantity $\neq 0$, then u_n and v_n converge and diverge together.

4.2.3 Integral Test or Maclaurin-Cauchy Test

For a series

$$\sum_{i=N}^{\infty} f(x), \text{ where } N \in \mathbb{Z}$$
 (4.1)

will only converge if the improper integral

$$\int_{N}^{\infty} f(x)dx \tag{4.2}$$

is finite.

If the improper integral is finite, the upper and lower limit of the infinite series is given by:

$$\int_{N}^{\infty} f(x)dx \le \sum_{i=N}^{\infty} f(x) \le f(N) + \int_{N}^{\infty} f(x)dx \tag{4.3}$$

4.2.4 Ratio Test

If, for two series $\sum u_n$ and $\sum v_n$:

- 1. (a) $\sum v_n$ converges
 - (b) from or after a particular term $\frac{u_n}{u_{n+1}} > \frac{v_n}{v_{n+1}}$, then u_n converges.
- 2. (a) $\sum v_n$ diverges
 - (b) from or after a particular term $\frac{u_n}{u_{n+1}} < \frac{v_n}{v_{n+1}}$, then u_n diverges.

4.2.5 D'Alembert's Ratio Test

$$\lim_{n \to \infty} \frac{u_n}{u_{n+1}} = \lambda \tag{4.4}$$

- series converges if $\lambda < 1$
- series diverges if $\lambda > 1$
- fails if $\lambda = 1$

4.2.6 Rabbe's Test

$$\lim_{n \to \infty} n \left[\frac{u_n}{u_{n+1}} - 1 \right] = \kappa \tag{4.5}$$

- series converges if $\kappa < 1$
- series diverges if $\kappa > 1$
- fails if $\kappa = 1$

4.2.7 Cauchy's Root Test

$$\lim_{n \to \infty} |u_n| = \lambda \tag{4.6}$$

- series converges for $\lambda < 1$
- series diverges for $\lambda > 1$
- test fails for $\lambda = 1$

4.2.8 Logarithmic Test

$$\lim_{n \to \infty} n \log \left(\frac{u_n}{u_{n+1}} \right) = \kappa \tag{4.7}$$

- series converges for $\kappa < 1$
- series diverges for $\kappa > 1$
- test fails for $\kappa = 1$

Determinants

5.1 Definition

For a determinant:

$$\Delta = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & c_2 \\ b_3 & c_3 \end{vmatrix} - b_1 \begin{vmatrix} a_2 & c_2 \\ a_3 & c_3 \end{vmatrix} + c_1 \begin{vmatrix} a_2 & b_2 \\ a_3 & b_3 \end{vmatrix}$$
 (5.1)

5.1.1 Minor and Cofactor

For a third order determinant

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

Minor

$$M(a_{11}) = M_{11} = \begin{vmatrix} b_2 & c_2 \\ b_3 & c_3 \end{vmatrix}$$
 (5.2)

i.e., all the terms of determinant expect those in the same row and columns as the one of which the minor is being calculated.

Cofactor

$$C_{ij} = (-1)^{i+j} M_{ij} (5.3)$$

5.2 Properties of Determinants

1. Transposing a determinant does not alter its value.

$$\Delta = \Delta^T \tag{5.4}$$

2. If rows and columns are interchanges m times, the value of the new determinant is

$$\Delta' = (-1)^m \Delta \tag{5.5}$$

3. If two parallel lines are equal, then $\Delta = 0$

4. For
$$\Delta = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$
 and $\Delta_1 = \begin{vmatrix} ka_1 & kb_1 & kc_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$, then $\Delta_1 = k\Delta$

5. For
$$\Delta = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$
 and $\Delta_1 = \begin{vmatrix} ka_1 & b_1 & c_1 \\ ka_2 & b_2 & c_2 \\ ka_3 & b_3 & c_3 \end{vmatrix}$, then $\Delta_1 = k\Delta$

6. For
$$C_n \to k_1 C_l + k_2 C_m + k_3 C_n$$
 or $R_n \to k_1 R_l + k_2 R_m + k_3 R_n$, $\Delta' = \Delta$

5.3 Cramer's Rule

For a system of equations:

$$a_1x + b_1y + c_1z = d_1$$

 $a_2x + b_2y + c_2z = d_2$
 $a_3x + b_3y + c_3z = d_3$

the following determinants are defined:

$$D = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

$$D_x = \begin{vmatrix} d_1 & b_1 & c_1 \\ d_2 & b_2 & c_2 \\ d_3 & b_3 & c_3 \end{vmatrix}$$

$$D_y = \begin{vmatrix} a_1 & d_1 & c_1 \\ a_2 & d_2 & c_2 \\ a_3 & d_3 & c_3 \end{vmatrix}$$

$$D_z = \begin{vmatrix} a_1 & b_1 & d_1 \\ a_2 & b_2 & d_2 \\ a_3 & b_3 & d_3 \end{vmatrix}$$

The solution for the system of equations is:

$$x = \frac{D_x}{D} \tag{5.6}$$

$$y = \frac{D_y}{D} \tag{5.7}$$

$$z = \frac{D_z}{D} \tag{5.8}$$

5.3.1 Consistency Test

- 1. If $D \neq 0$, the system is consistent and has unique solutions.
- 2. If $D = D_x = D_y = D_z = 0$, the system may or may not be consisten and it will have infinite solutions and the system will be dependent.
- 3. If D=0 and at least one of D_x, D_y, D_z is non zero, the system is inconsistent

Matrices

For a matrix,

$$A_{m \times n} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

and where I_p is an identity matrix of the p^{th} order, the following relations are applicable.

6.1 Sum of Two Matrices

$$A_{m \times n} + B_{m \times n} = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \cdots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{21} & \cdots & a_{2n} + b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & a_{m2} + b_{m2} & \cdots & a_{mn} + b_{mn} \end{bmatrix}$$
(6.1)

6.2 Multiplication of Two Matrices

If

$$C_{m \times p} = A_{m \times n} \cdot B_{n \times p} \tag{6.2}$$

then,

$$c_{ik} = \sum_{j=1}^{n} a_{ij} \cdot b_{jk} \tag{6.3}$$

6.2.1 Multiplicative Properties

- 1. Multiplication of matrices is associative, hence (AB)C = A(BC).
- 2. AI = A

3.
$$A \cdot A^{-1} = I$$

4.
$$A \cdot (adjA) = (adjA) \cdot A = |A|I$$

5.
$$A^{-1} = \frac{1}{|A|} (adjA)^t$$

$$6. (AB)^t = B^t A^t$$

6.3 Adjoint of a Matrix

$$adjA = \begin{bmatrix} M_{11} & M_{12} & \cdots & M_{1n} \\ M_{21} & M_{22} & \cdots & M_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ M_{m1} & M_{m2} & \cdots & M_{mn} \end{bmatrix}^{t}, \text{ where } M_{ij} \text{ is the minor of } a_{ij}$$
(6.4)

6.4 Martin's Rule

For a system of equation,

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_n$$

The system can be written as:

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$(6.5)$$

$$\Rightarrow AX = B \tag{6.6}$$

$$\Rightarrow X = A^{-1}B \tag{6.7}$$

Binomial Theorem

For a binomial expansion $(a+b)^n$, there are (n+1) terms and $(a+b+c)^n$ has $\frac{(n+1)(n+2)}{2}$ terms.

7.1 Expansion of a binomial expression

$$(a+b)^{n} = {}^{n} C_{0} a^{n} b^{0} + {}^{n} C_{1} a^{n-1} b^{1} + {}^{n} C_{2} a^{n-2} b^{2} + \dots + {}^{n} C_{n} a^{0} b^{n}$$

$$= \sum_{i=0}^{n} {}^{n} C_{i} a^{n-i} b^{i}$$

$$\forall n \in \mathbb{N}$$

$$(a+b)^{n} = a^{n} b^{0} + n a^{n-1} b + \frac{n(n-1)}{2!} a^{n-2} b^{2} + \dots + \frac{n(n-1) \cdots 3 \cdot 2 \cdot 1}{n!} a^{0} b^{n} + \dots \infty$$

$$\forall n \in \mathbb{R}$$

$$(7.2)$$

7.2 Trinomial Expansion

For $(a+b+c)^n$:

$$(a+b+c+)^n = \sum_{i:j:k} \frac{n!}{i!j!k!} a^i b^j c^k$$

$$\forall (i+j+k) = n; i, j, k, n \in \mathbb{N}$$

$$(7.3)$$

7.3 Properties of Coefficients

Sum of Co-efficients:
$$C_0 + C_1 + C_2 + \dots + C_{n-1} + C_n = 2^n$$
 (7.4)

Sum of Odd Co-efficients:
$$C_0 + C_2 + C_4 + \dots + C_{2n-3} + C_{2n-1} = 2^{n-1}$$
 (7.5)

$$C_0 - C_1 + C_2 - \dots + C_{2n-1} - C_{2n} = 0 (7.6)$$

7.4 Pascal's Rule

For $1 \le k \le n$ and $k, n \in \mathbb{N}$:

$$\binom{n}{k} + \binom{n}{k-1} = \binom{n+1}{k} \tag{7.7}$$

-Chapter 8-

Boolean Algebra

Let B be a set of a, b, c with operations sum (+) and product (\cdot) . Then B is said to belong to the Boolean Structure if the following conditions are satisfied:

Table 8.1: Properties of Boolean Algebraic Structure

Property	Name of Property
$a+b \in B$	
$a \cdot b \in B$	Closure Property
a+b=b+a	
$a \cdot b = b \cdot a$	Associative Law
a(b+c) = ab + ac	
a + bc = (a+b)(a+c)	Commutative Law
$\{0,1\} \in B$	
a + 0 = a	
a + 1 = 1	
$a \cdot 0 = 0$	
$a \cdot 1 = a$	Laws of 1 and 0
a + ab = a	
a(a+b) = a	Absorption Law
(a+b)' = (a'b')	De'Morgan's Law

Remainder Theorems

9.1 Remainder Theorem

If a function f(x) is divided by a binomial x - a, then the remainder is provided by f(a).

$$\frac{f(x)}{x-a} \equiv f(a) \mod (x-a) \tag{9.1}$$

Worked Example

Find the remainder when $f(x) = x^3 - 4x^2 - 7x + 10$ is divided by (x - 2). The remainder:

$$R = (x^3 - 4x^2 - 7x + 10) \mod (x - 2)$$

is given by:

$$R = f(2) = (2)^3 - 4(2)^2 - 7(2) + 10$$
$$= 8 - 16 - 14 + 10 = -12$$

9.2 Euler's Remainder Theorem

According to Euler's Remainder Theorem, if x and n are two co-prime numbers:

$$x^{\varphi(n)} \equiv 1 \mod n, x, n \in \mathbb{Z}^+ \tag{9.2}$$

where, $\varphi(n)$ is Euler's totient function.

9.2.1 Euler's Totient Function

For a number defined as:

$$n = \prod_{i=1}^{r} a_r^{b_r} \tag{9.3}$$

then Euler's totient function is defined as:

$$\varphi(n) = n \cdot \left[\left(1 - \frac{1}{a_1} \right) \cdot \left(1 - \frac{1}{a_2} \right) \cdot \left(1 - \frac{1}{a_3} \right) \cdots \right]$$

$$= n \prod_{i=1}^r \left(1 - \frac{1}{a_r} \right)$$
(9.4)

Worked Example

Find the remainder if 3^{76} is divided by 35. Since:

$$35 = 5^1 \times 7^1$$

Hence the totient quotient of 35 is:

$$\varphi(35) = 35 \cdot \left(1 - \frac{1}{5}\right) \cdot \left(1 - \frac{1}{7}\right)$$
$$= 35 \times \frac{4}{5} \times \frac{6}{7}$$
$$= 24$$

Hence Euler's Theorem yields:

$$3^{24} \equiv 1 \mod 35$$

$$3^{76} \equiv 3^{24 \times 3 + 4}$$

$$\equiv (3^{24})^3 \times 3^4 \mod 35$$

$$\equiv (1)^3 \times 3^4 \mod 35$$

$$\equiv 81 \mod 35$$

$$\equiv 11 \mod 35$$

The remainder when 3^{76} is divided by 35 is 11.

9.3 Wilson Theorem

According to Wilson Theorem:

$$(n-1)! \equiv -1 \mod n \tag{9.5}$$

Worked Example

Find the remainder when 28! is divided by 31. By Wilson's Theorem:

$$30! \qquad \equiv -1 \mod 31$$

$$\Rightarrow 30 \cdot 29 \cdot 28! \qquad \equiv -1 \mod 31$$
Let 28! mod 31 \quad = x
$$\Rightarrow (-1) \cdot (-2) \cdot x \qquad \equiv 30 \mod 31$$

$$\Rightarrow 2x \qquad = 30$$

$$\Rightarrow x \qquad = 15$$

The remainder when 28! is divided by 31 is 15.

——Part II———Co-ordinate Geometry

2-D Co-ordinate Geometry

For the ordered pairs, $A(x_1, y_1)$ and $B(x_2, y_2)$:

$$AB = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$
(10.1)

Mid point of AB =
$$\left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}\right)$$
 (10.2)

Point C, which divides AB in the ratio
$$m: n = \left(\frac{nx_1 + mx_2}{m+n}, \frac{ny_1 + my_2}{m+n}\right)$$
 (10.3)

Triangles

For a triangle defined with three vertices $A(x_1, y_1), B(x_2, y_2), C(x_3, y_3)$ and corresponding sides of length a, b, c, then:

Centroid of
$$\triangle ABC = (\frac{x_1 + x_2 + x_3}{3}, \frac{y_1 + y_2 + y_3}{3})$$
 (11.1)

Area of
$$\triangle$$
 (11.2)

$$ABC = \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix}$$
 (11.3)

For a triangle, the semi-perimeter, s, is defined as:

$$s = \frac{a+b+c}{2}$$

Then the radius, r, and centre of incircle, o, is:

$$o = \left(\frac{ax_1 + bx_2 + cx_3}{a + b + c}, \frac{ay_1 + by_2 + cy_3}{a + b + c}\right)$$
(11.4)

$$r = \sqrt{\frac{(s-a)(s-b)(s-c)}{s}}$$
 (11.5)

(11.6)

The radius, R, and centre, O, of circumcircle is defined as:

$$O = \left(\frac{x_1 \sin 2A + x_2 \sin 2B + x_3 \sin 2C}{\sin 2A + \sin 2B + \sin 2C}, \frac{y_1 \sin 2A + y_2 \sin 2B + y_3 \sin 2C}{\sin 2A + \sin 2B + \sin 2C}\right)$$
(11.7)

$$2R = \frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C} \tag{11.8}$$

Straight Line

A straight line can be defined as:

$$y = mx + c \tag{12.1}$$

$$\frac{x}{a} + \frac{y}{b} = 1$$
, where a and b are the intercepts at x and y axes respectively (12.2)

$$x\cos\alpha + y\sin\alpha = p \text{ (Normal Form)}$$
 (12.3)

$$Ax + By + C = 0$$
 (General Form) (12.4)

12.1 Equation of Straight Line Passing Through (x_0, y_0) and Slope m

$$(y - y_0) = m(x - x_0) (12.5)$$

12.2 Distance Between Two Points on a Line

$$\frac{y_1 - y_2}{\sin \theta} = \frac{x_1 - x_2}{\cos \theta} = \gamma \tag{12.6}$$

$$\theta = \tan^{-1} m \tag{12.7}$$

12.3 Angle Between Two Lines

For two lines with slopes m_1, m_2 , the angle between them, θ :

$$\theta = \arctan\left(\frac{m_1 - m_2}{1 + m_1 m_2}\right) \tag{12.8}$$

Distance of a Point from a Line

Line: ax + by + c = 0 Point: (g, h)

$$S = \frac{ag + bh + c}{\sqrt{a^2 + b^2}} \tag{12.9}$$

Angle Bisector of a Line For the two lines: $a_1x + b_1y + c_1 = 0$ and $a_2x + b_2y + c_2 = 0$, the angle bisector is:

$$\frac{a_1x + b_1y + c_1}{\sqrt{a_1^2 + b_1^2}} = \frac{a_2x + b_2y + c_2}{\sqrt{a_2^2 + b_2^2}}$$
(12.10)

If the sign of c_1 and c_2 is the same, then the equation obtained is the internal bisector.

Equation of a Straight Line Passing through the Intersection of Two Lines

$$(a_1x + b_1y + c_1) + k(a_2x + b_2y + c_2) = 0 \ \forall k \in \mathbb{R}$$
 (12.11)

Relative Position of Points w.r.t. a Line For the points (x_1, y_1) and (x_2, y_2) :

$$k_1 = ax_1 + by_1 + c$$
$$k_2 = ax_2 + by_2 + c$$

If k_1 and k_2 have the same sign, they are on the same side of a line, otherwise on opposite sides.

Ratio of Division of Line Segment For any line, f(x,y) = 0, the ratio in which it divides (x_1, y_1) and (x_2, y_2) is given by:

$$r = -\frac{f(x_1, y_1)}{f(x_2, y_2)} \tag{12.12}$$

If $\begin{cases} r > 0, \text{ then division is internal} \\ r < 0, \text{ then division is external} \end{cases}$