Kalman-and-Bayesian-Filters-in-Python



Preface



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Mar 12th, 2022 https://github.com/duyongquan/LTSLAM



Outline

- Kalman and Bayesian Filters
- Motivation for this Book
- Reading Online
- PDF Version
- Downloading and Running the Book
- Jupyter
- SciPy, NumPy, and Matplotlib

Kalman and Bayesian Filters

卡尔曼和贝叶斯滤波

Kalman and Bayesian Filters

- Sensors are noisy
 - GPS in my car reports altitude, Each time pass the same point, it reports a slightly different altitude
 - Kitchen scale gives different readings weigh the same object twice.
 - Sensor is very noisy, environment makes data collection difficult. How can track?



Rudolf Emil Kálmán 鲁道夫·卡尔曼 匈牙利裔美国数学家

- Introduce
 - Apollo missions to the moon
- Aaircraft, submarines, cruise missiles

Medical imaging

Robots, IoT (Internet of Things), laboratory instruments

Motivation for this Book 书的目标

Motivation for this Book

- The theory is beautiful, but quite difficult to learn
 - signal processing
 - control theory
 - probability and statistics
- Ohter books quite difficult to learn
 - notation is introduced without explanation
 - books are almost devoid of examples or worked problems
 - no idea as to what real world phenomena these words and math were attempting to describe

Reading Online 在线阅读

Reading Online

- GitHub
 - https://github.com/rlabbe/Kalman-and-Bayesian-Filters-in-Python
- ninder
 - binder serves interactive notebooks online
 - http://mybinder.org/repo/rlabbe/Kalman-and-Bayesian-Filters-in-Python
- nbviewe
 - https://nbviewer.org/github/rlabbe/Kalman-and-Bayesian-Filters-in-Python/tree/master/

PDF Version PDF 版本

PDF Version





https://drive.google.com/file/d/0By SW19c1BfhSVFzNHc0SjduNzg/view?resourcekey=0-41olC9ht9xE3wQe2zHZ45A

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Downloading and Running the Book

下载和运行

Downloading and Running the Book

- Installation
 - http://nbviewer.ipython.org/github/rlabbe/Kalman-and-Bayesian-Filters-in-Python/blob/master/Appendix-A-Installation.ipynb

Introduce

This book is intended to be interactive and I recommend using it.

Its a little more effort to set up.

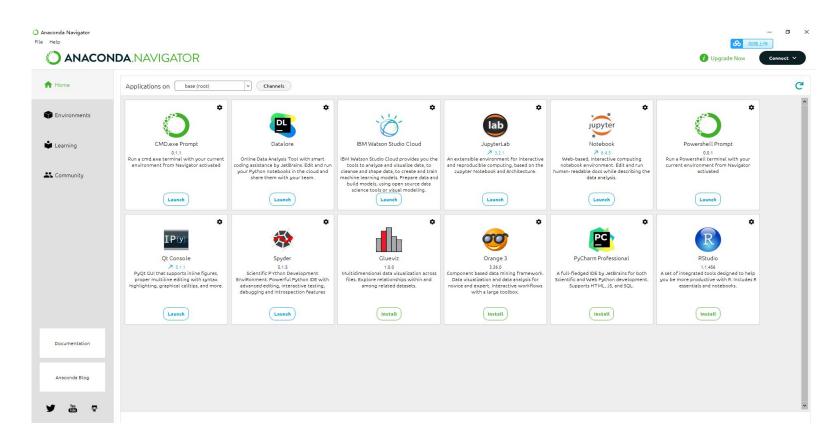
You can perform experiments, see how filters react to different data, see how different filters react to the same data, and so on

Jupyter 开发环境

Jupyter

jupyter notebook

安装Anaconda

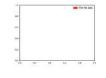


SciPy, NumPy, and Matplotlib Python库

- SciPy is a mathematic
 - array objects
 - linear algebra
 - random numbers
- NumPy
- Matplotlib
 - https://matplotlib.org/stable/tutorials/index









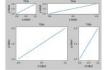


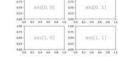
Artist tutorial

Legend guide

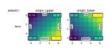
Styling with cycler

Constrained Layout Guide









Tight Layout guide

Arranging multiple Axes in a Figure

Autoscaling

origin and extent in imshow

onumpy.array implements a one or more dimensional array

numpy.array implements a one or more dimensional array

```
In [4]: x = np.array((4,5,6))
        x

Out[4]: array([4, 5, 6])
```

Create multidimensional arrays with nested brackets:

numpy.array implements a one or more dimensional array

You can access the array elements using subscript location:

- numpy.array implements a one or more dimensional array
 - You can access a column or row by using slices. A colon (:) used as a subscript is shorthand for all data in that row or column. So x[:,0] returns an array of all data in the first column (the 0 specifies the first column):

```
In [8]: x[:, 0]
Out[8]: array([1, 4])
We can get the second row with:
```

We can get the second row with:

```
In [9]: x[1, :]
Out[9]: array([4, 5, 6])
```

Get the last two elements of the second row with:

```
In [10]: x[1, 1:]
Out[10]: array([5, 6])
```

As with Python lists, you can use negative indexes to refer to the end of the array. -1 refers to the last index. So another way to get the last two elements of the second (last) row would be:

```
In [11]: x[-1, -2:]
Out[11]: array([5, 6])
```

You can perform matrix addition with the + operator, but matrix multiplication requires the dot method or function. The * operator performs element-wise multiplication, which is **not** what you want for linear algebra.

```
In [12]: x = np.array([[1., 2.]],
                     [3., 4.]])
        print('addition:\n', x + x)
        print('\nelement-wise multiplication\n', x * x)
        print('\nmultiplication\n', np.dot(x, x))
        print('\ndot is also a member of np.array\n', x.dot(x))
                                          multiplication
    addition:
                                            [[ 7. 10.]
     [[2. 4.]
                                            [15. 22.]]
      [6. 8.]]
                                          dot is also a member of np.array
    element-wise multiplication
                                            [[ 7. 10.]
     [[1. 4.]
                                            [15. 22.]]
     [ 9. 16.]]
```

Python 3.5 introduced the @ operator for matrix multiplication.

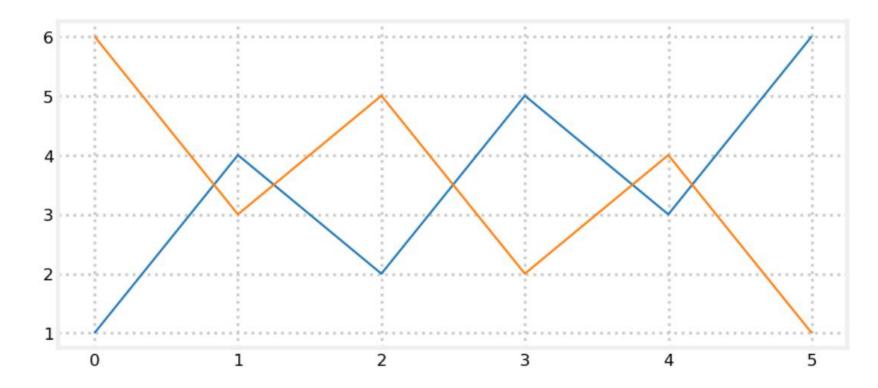
transpose and the inverse

zeros matrix, ones matrix, eye identity matrix

```
In [15]: print('zeros\n', np.zeros(7))
         print('\nzeros(3x2)\n', np.zeros((3, 2)))
         print('\neye\n', np.eye(3))
zeros
 [0. 0. 0. 0. 0. 0. 0.]
zeros(3x2)
 [[0. 0.]]
 [0. \ 0.]
 [0. \ 0.]]
eye
 [[1. 0. 0.]
 [0. 1. 0.]
 [0. 0. 1.]]
```

```
In [18]: import matplotlib.pyplot as plt
    a = np.array([6, 3, 5, 2, 4, 1])
    plt.plot([1, 4, 2, 5, 3, 6])
    plt.plot(a)
```

Out[18]: [<matplotlib.lines.Line2D at 0x298bcc7b4c8>]



SUNSPRING