Documentation msp430-arduino

version 1.2 by Alexandre BARRAT

Table of content

Constants	,	•	3
<pre>void pinMode(int pin, int mode)</pre>		•	3
<pre>void digitalWrite(int pin, int value)</pre>		•	3
<pre>int digitalRead(int pin)</pre>		•	3
<pre>void shiftOut(dataPin, clockPin, bitOrder, value)</pre>)		3

Constants

LOW	0
HIGH	1
INPUT	0
OUTPUT	1
INPUT_PULLUP	2
MSBFIRST	7
LSBFIRST	0
LED_BUILTIN	10

void pinMode(int pin, int mode)

Set the mode of a pin (INPUT/OUTPUT/INPUT_PULLUP)

Parameters

```
pin The pin to set the mode (10-17/20-27). mode The mode to set (INPUT/OUTPUT/INPUT_PULLUP)
```

Return

void digitalWrite(int pin, int value)

Write a digital value on a pin.

Parameters

pin The pin to modify (10-17/20-27). value The digital value to write (LOW/HIGH)

Return

int digitalRead(int pin)

Read the value of the given digital pin.

Parameters

pin The pin to read (10-17/20-27).

Return

value The digital value of the pin (0/1) or -1 if wrong pin.

void shiftOut(dataPin, clockPin, bitOrder, value)

Shifts out a byte of data one bit at a time.

Parameters

dataPin The pin to send data (10-17/20-27). clockPin The pin for the clock (10-17/20-27). bitOrder The first bit to shift: most or least significant (MSBFIRST/LSBFIRST).

Return