

GENERALISED LEAST SQUARES

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MIXED EFFECT MODELS

WHAT WE WILL TALK ABOUT TODAY

The basics of generalises Least Squares – the mathematical principle

Dealing with Heteroscedasticity – Solving non equal variance

- Modelling the model variance– Solving non-equal variances
- Autocorrelation- Solving non-independence

Model selection – Combing ML and RMEL

Any questions?

Ready to start?

A GENERAL LINEAR MODEL

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Fixed part Error part

A GENERAL LINEAR MODEL

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Random part

Normally distributed errors

$$\begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} : N(0, V)$$

Homogeneity of variances

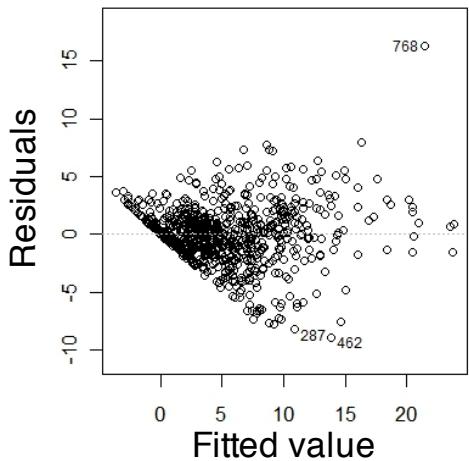
$$V = \begin{bmatrix} \sigma^2 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma^2 \end{bmatrix}$$

Variance-covariance matrix

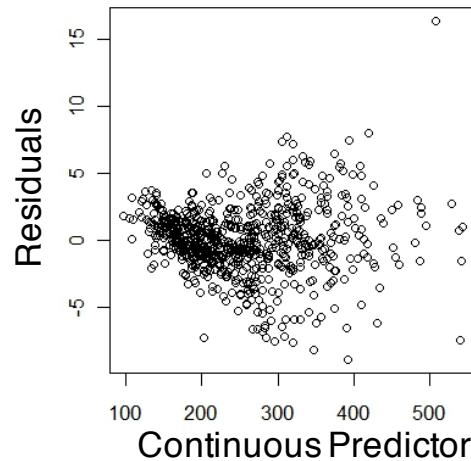
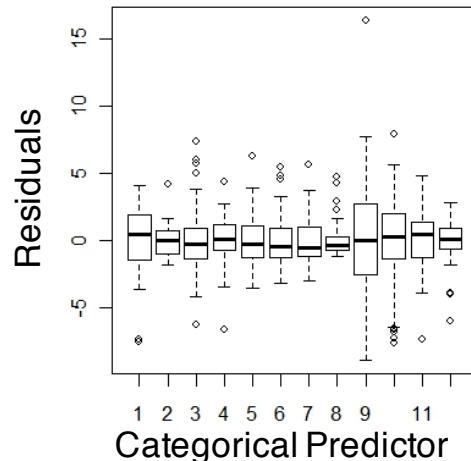
VIOLATING THE ASSUMPTIONS OF A GENERAL LINEAR MODEL

What problem is visualised here?

Homogeneity
of variances



Independence



The variance of error terms is not similar across the independent variable(s)
Heteroscedasticity

How can you see that problem in these figures?

VIOLATING THE HOMOGENEITY OF VARIANCES ASSUMPTION

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Random part

Variances are not equal across observations

Normally distributed errors

$$\begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} : N(0, V)$$

Variance heterogeneity

$$V = \begin{bmatrix} \sigma_{(1)}^2(X) & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \sigma_{(n)}^2(X) \end{bmatrix}$$

VIOLATING THE HOMOGENEITY OF VARIANCES ASSUMPTION

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Random part

However observations
are **still** independent

Normally distributed
errors

$$\begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} : N_{(0,V)}$$

Variance heterogeneity

$$V = \begin{bmatrix} \sigma_{(1)}^2(X) & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_{(n)}^2(X) \end{bmatrix}$$

MODELING VARIANCES IN R GLS NOT LM MODELS

Remember that in **basic** linear models parameters are estimated using **Ordinary least squares**.

But..

As we move to model the variance we need a method of estimation that:

- Model the fixed effects of the predictors
- Accounts for structure in the error term → how the variance changes!

Generalised Least Squares (GLS) is a method of estimation that allows accounting for structure in the error term

MODELING VARIANCES IN R WITH GLS

```
gls (y ~ x ,  
     weights = VAR.Fn  
     method = "ML/REML")
```

The syntax is almost the same as an lm but You can specify a description of the within-group heteroscedasticity structure as **weights**

MODELING VARIANCES IN R WITH GLS

```
gls (y ~ x ,  
      weights = VAR.Fn  
      method = "ML/REML" )
```

The general approach
Gaussian errors

```
MASS:::glmPQL (y ~ x ,  
      weights = VAR.Fn  
      family = "poisson" )
```

The generalised approach
Gaussian/binomial/Poisson errors

So far so good?

Any questions?

Ready to move on?

HOW TO DEAL WITH UNEQUAL VARIANCES

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$



Variance heterogeneity

$$\mathbf{V} = \begin{bmatrix} \sigma_{(1)}^2(\mathbf{X}) & \dots & 0 \\ \vdots & \vdots & \vdots \\ 0 & \dots & \sigma_{(n)}^2(\mathbf{X}) \end{bmatrix}$$

Build a model to describe how the variability changes as a function of the data



R does this by adding a weights to the variance of each observation

HOW TO DEAL WITH UNEQUAL VARIANCES

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Weights are included by defining a function to describe the change in variance between observations

Variance heterogeneity

$$V = \begin{bmatrix} \sigma_{(1)}^2(\mathbf{X}) & \dots & 0 \\ \vdots & \vdots & \vdots \\ 0 & \dots & \sigma_{(n)}^2(\mathbf{X}) \end{bmatrix}$$

$$\sigma_{(i)}^2 \sim \sigma_{(class_i)}^2$$

Variance depend on a category

$$\sigma_{(i)}^2 \sim \frac{\sigma^2}{x_i}$$

Variance proportional to a variance covariate

$$\sigma_{(i)}^2 \sim \sigma^2 F(x_i)$$

Variance as a function of a variance covariate

DIFFERENT VARIANCES PER STRATUM

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

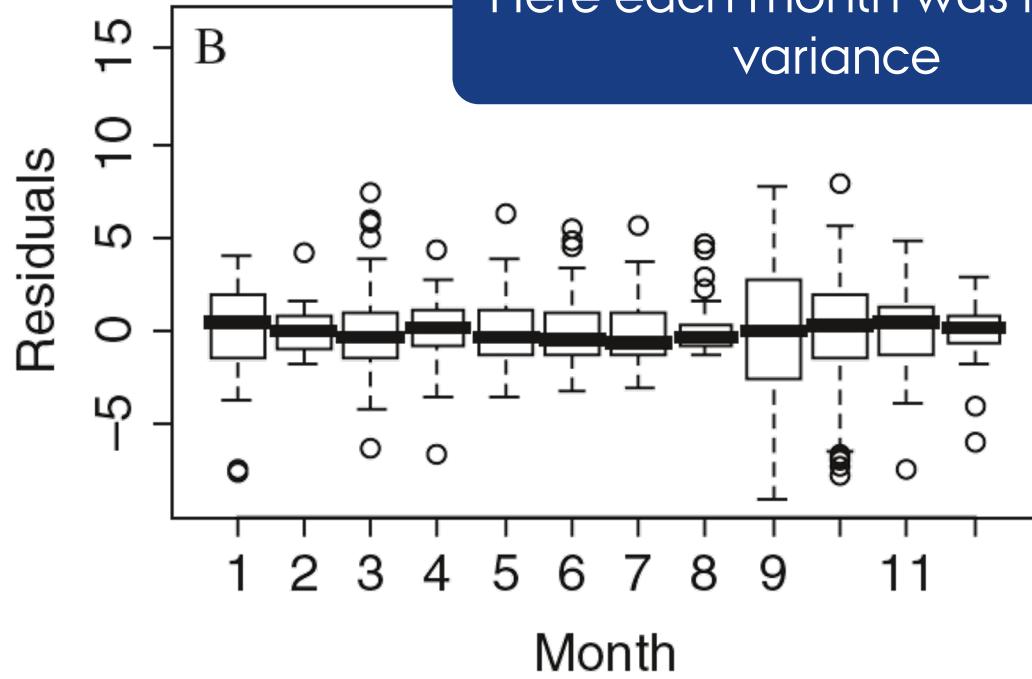
Variance heterogeneity

$$V = \begin{bmatrix} \sigma_{(1)}^2 X & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_{(n)}^2 X \end{bmatrix}$$

$$\sigma_{(i)}^2 \sim \sigma_{(class_i)}^2$$

Variance depend
on a category

Here each month was its own
variance



WEIGHTED VARIANCES

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

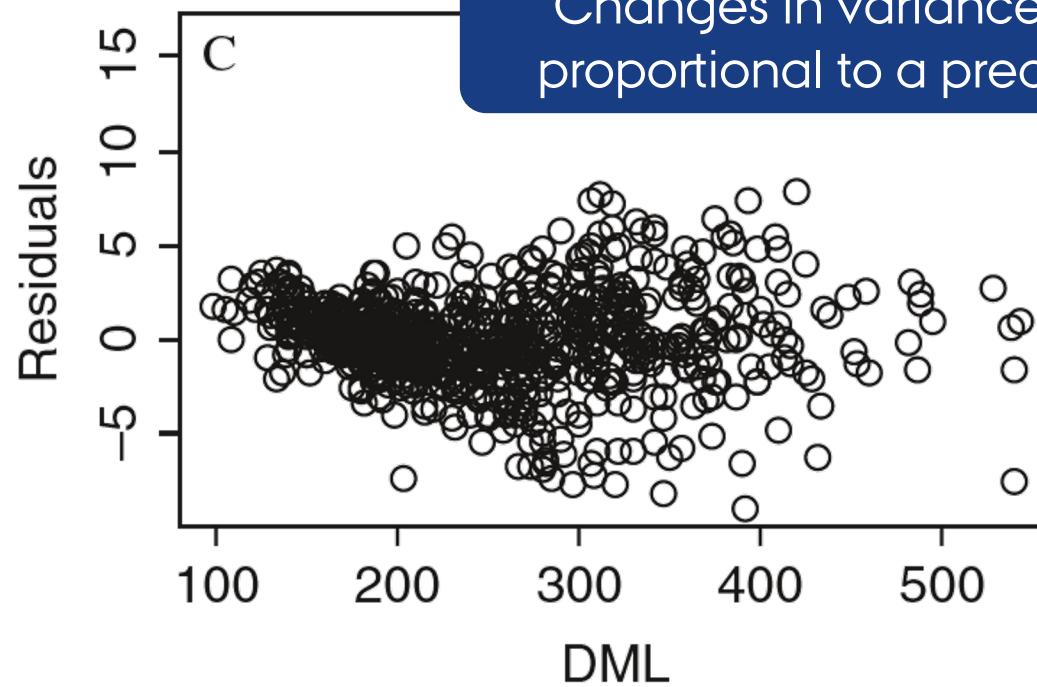
Variance heterogeneity

$$V = \begin{bmatrix} \sigma_{(1)}^2 X & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_{(n)}^2 X \end{bmatrix}$$

$$\sigma_{(i)}^2 \sim \frac{\sigma^2}{x_i}$$

Variance as a function of a predictor(s)

Changes in variance are proportional to a predictor



DIFFERENT VARIANCES PER STRATUM

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

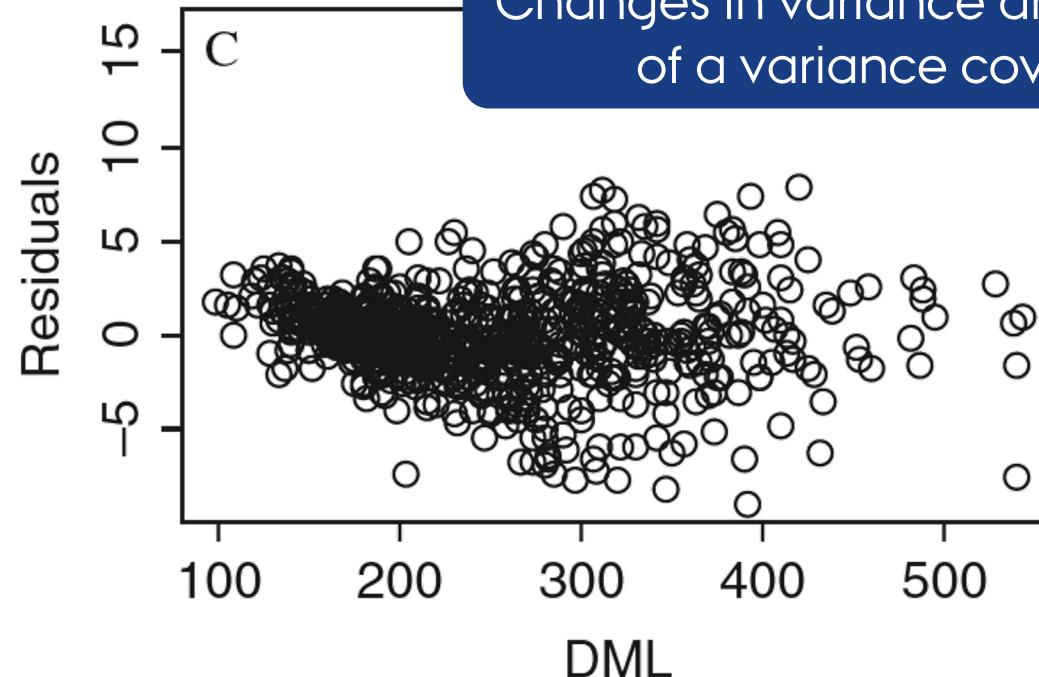
Variance heterogeneity

$$V = \begin{bmatrix} \sigma_{(1)}^2 X & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_{(n)}^2 X \end{bmatrix}$$

$$\sigma_{(i)}^2 \sim \sigma^2 F(x_i) \rightarrow$$

Variance as a function of a variance covariate

Changes in variance are a function of a variance covariate



VARIANCES AS A FUNCTION

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

$$\sigma_{(i)}^2 \sim \sigma^2 F(x_i) \rightarrow$$

Variance as a function
of a variance covariate

Functions can be of different types:

Variance heterogeneity

$$V = \begin{bmatrix} \sigma_{(1)}^2 X & \dots & 0 \\ \vdots & \vdots & \vdots \\ 0 & \dots & \sigma_{(n)}^2 X \end{bmatrix}$$

$$\sigma_{(i)}^2 \sim \sigma^2 \times |x_i|^{2\delta}$$

Power Function

$$\sigma_{(i)}^2 \sim \sigma^2 \times e^{2\delta \times x_i}$$

Exponential Function

$$\sigma_{(i)}^2 \sim \sigma^2 \times (\delta_1 + |x_i|^{2\delta_2})^2$$

Constant + Power Function

VARIANCES AS A FUNCTION

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Functions can combine categorical and continuous variance covariate(s)

Variance heterogeneity

$$V = \begin{bmatrix} \sigma_{(1)}^2 X & \dots & 0 \\ \vdots & \vdots & \vdots \\ 0 & \dots & \sigma_{(n)}^2 X \end{bmatrix}$$

$$\sigma_{(i)}^2 \sim \sigma^2 \times |x_i \times Class_i|^{2\delta} \quad \text{Power Function}$$

$$\sigma_{(i)}^2 \sim \sigma^2 \times e^{2\delta \times x_i \times Class_i} \quad \text{Exponential Function}$$

$$\sigma_{(i)}^2 \sim \sigma^2 \times (\delta_1 + |x_i \times Class_i|^{2\delta_2})^2 \quad \text{Constant + Power Function}$$

So far so good?

Any questions?

Ready to move on?

OVERVIEW OF ALL VARIANCE STRUCTURES

Name of the function in R	What does it do?
VarIdent	Different variances per stratum
VarFixed	Fixed variance
VarPower	Power of the variance covariate
VarExp	Exponential of the variance covariate
VarConstPower	Constant plus power of the variance covariate
VarComb	A combination of variance functions

Rather limited –
Problematic when
Variance-Convariance
takes negative Values

OVERVIEW OF ALL VARIANCE STRUCTURES

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VarConstPower	Constant plus power of the variance covariate
VarComb	A combination of variance functions

Flexible, but **do not** use if the variance covariate takes the value of zero

OVERVIEW OF ALL VARIANCE STRUCTURES

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Flexible, **can use** if the variance covariate takes the value of zero

So far so good?

Any questions?

Ready to move on?

MIXED EFFECTS MODELS

THE PROBLEM OF INDEPENDENCE

Observational/experiments can have:

- Spatial-Temporal-Evolutionary proximity
 - Autocorrelation → removes independence between samples
- A nested observational/experimental design
 - samples taken across different spatial-temporal-taxonomic scales

What does this mean?
Samples have “Pseudoreplication”

MIXED EFFECTS MODELS

(PSEUDO)REPLICATION

What is replication?

Independent observations of same measurement

What is
(Pseudo)replication?

Replicates are **not independent** (spatial-temporal), or
“treatments are truly **not replicated**”

What is independent?

Independent is when the value of one observation
does not affect the value of other observations

INDEPENDENCE OF OBSERVATIONS

What does it mean?

- Objects are sampled only once.
- The occurrence of one event doesn't change the probability for another.
- Sampling of one observation does not affect the choice of the second observation.

How can we ensure independence of observations?

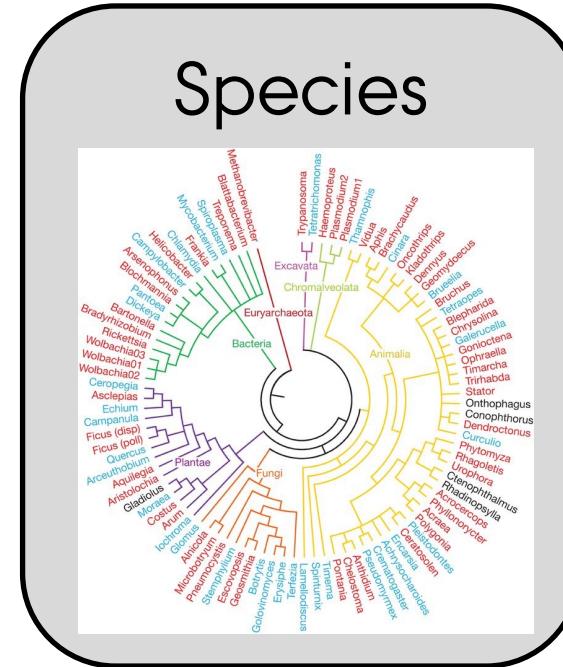
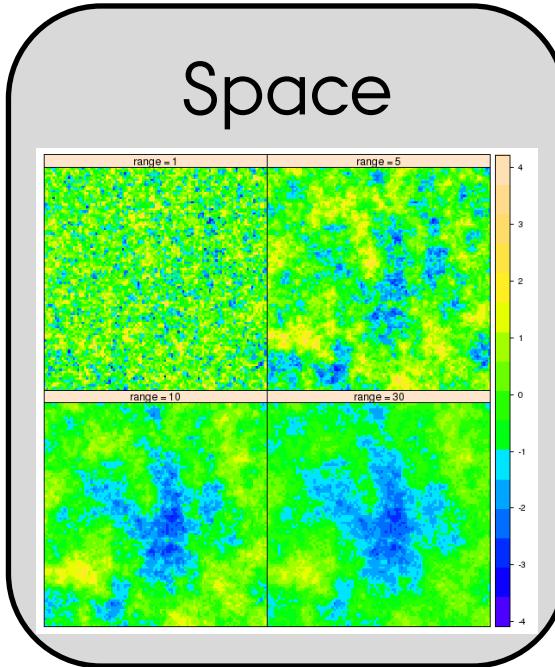
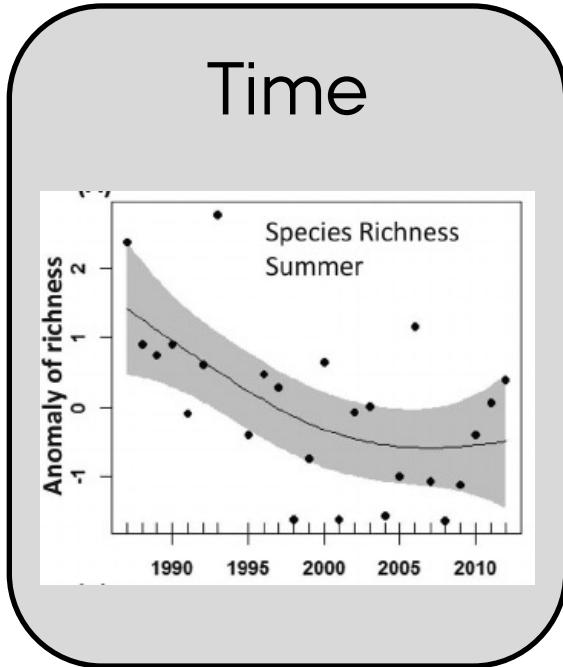
- Sample each object only once.
- Make sure that replicates have no relation → if they do, they are repetitions.
- Use a fully randomized design!!!

So far so good?

Any questions?

Ready to move on?

AUTOCORRELATION: A MORE COMPLEX VARIANCE STRUCTURE



AUTOCORRELATION

THE MATH BEHIND THE MODEL

$$\begin{bmatrix} \bar{y}_1 \\ \vdots \\ \bar{y}_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Random part

Normally distributed errors

$$\begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} : N(0, V)$$

Variance heterogeneity

$$V = \begin{bmatrix} \sigma_{(1,1)}^2 & & & \\ \vdots & \ddots & & \\ \sigma_{(1,n)}^2 & \dots & \dots & \sigma_{(j,1)}^2 \\ & \vdots & & \vdots \\ & \dots & \dots & \sigma_{(j,n)}^2 \end{bmatrix}$$

Observations are not independent

Variances are not equal across observations

MODELING CORRELATIONS IN R WITH GLS

```
gls (y ~ x ,  
     correlation = Cor.Fn,  
     method = "ML/REML")
```

```
MASS:::glmmPQL (y ~ x ,  
                  correlation = Cor.Fn,  
                  family = "poisson")
```

The syntax is almost the same as an `lm` but You can specify a description of the correlation between observations as a **correlation**

Name of the function in R	What does it do?
corAR1	autoregressive process of order 1
corARMA	autoregressive moving average process
corExp	exponential spatial correlation
corGaus	Gaussian spatial correlation
corLin	linear spatial correlation
corRatio	Rational quadratics spatial correlation
corSpher	spherical spatial correlation
corBrownian	Brownian motion mode
corPagel	The covariance matrix defined Freckleton et al. (2002)

So far so good?

Any questions?

Ready to move on?

TEMPORAL AUTOCORRELATION

THE MATH BEHIND THE MODEL

$$\varepsilon_s \sim N(0, \sigma^2)$$

$$cov(\varepsilon_s, \varepsilon_t) = \begin{cases} \sigma^2 & \text{if } s = t \\ h(\varepsilon_s, \varepsilon_{s+k}, \rho) & \text{else} \end{cases}$$

Correlation function

function that measures the spatial dependence between two sites

We assume stationarity

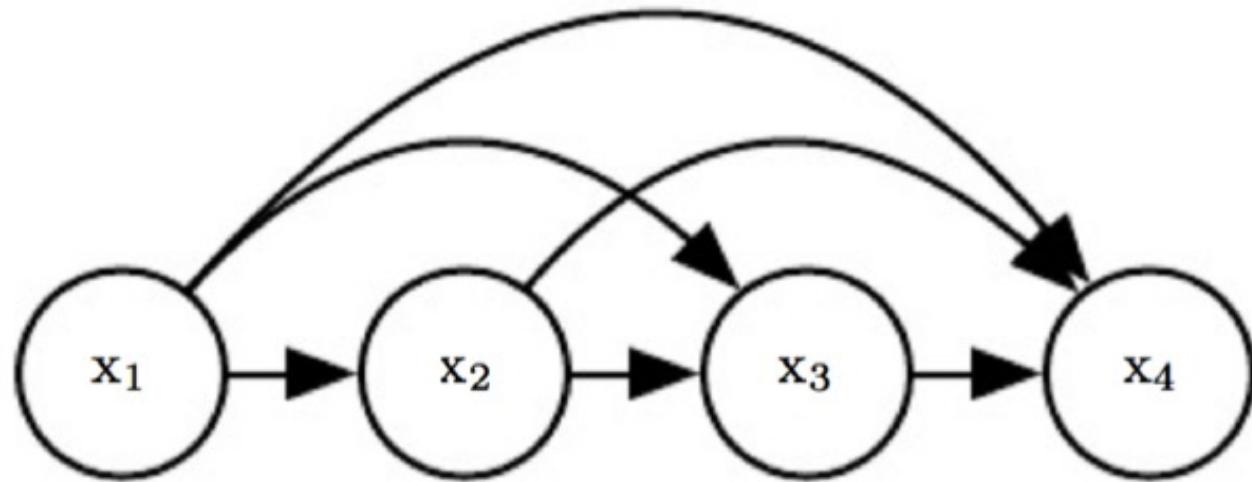
Correlation between the residuals ε_s and ε_t only depends on their time difference ($s - t$)

The goal

Find the best optimal parameterisation of the correlation function

TEMPORAL AUTOCORRELATION

THE TEMPORAL CASE



Output variable depends linearly on its own previous values

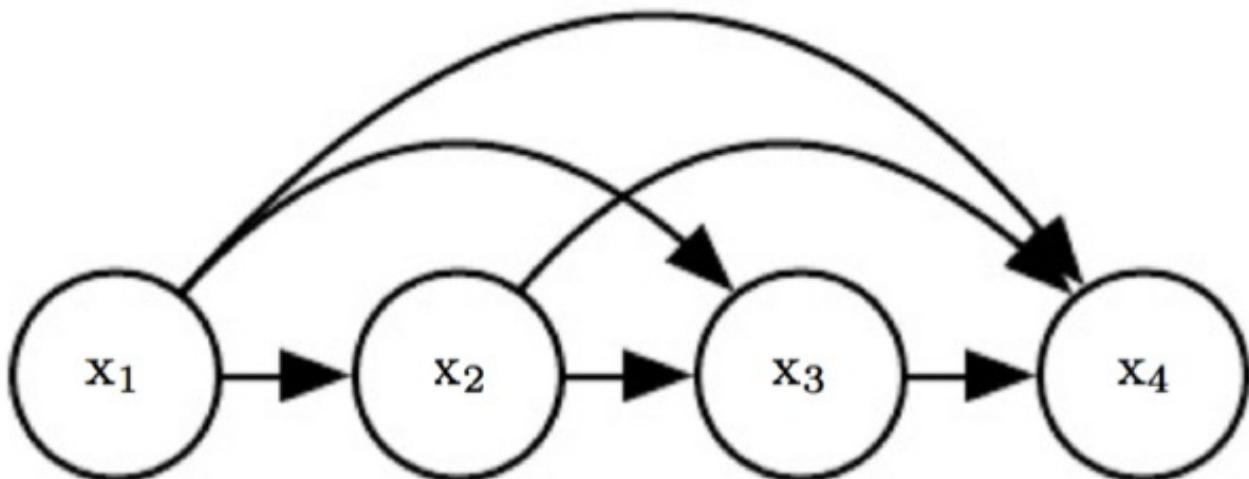
That means :

To estimate the response at time t_n we need to know the value/errors of the Predictor X_i at that time t_n AND the state of the response at time t_{n-1}



TEMPORAL AUTOCORRELATION

AUTOREGRESSIVE MODEL



Output variable depends linearly on its own previous values

If we **use the preceding value**, we call this an **Autoregressive model**

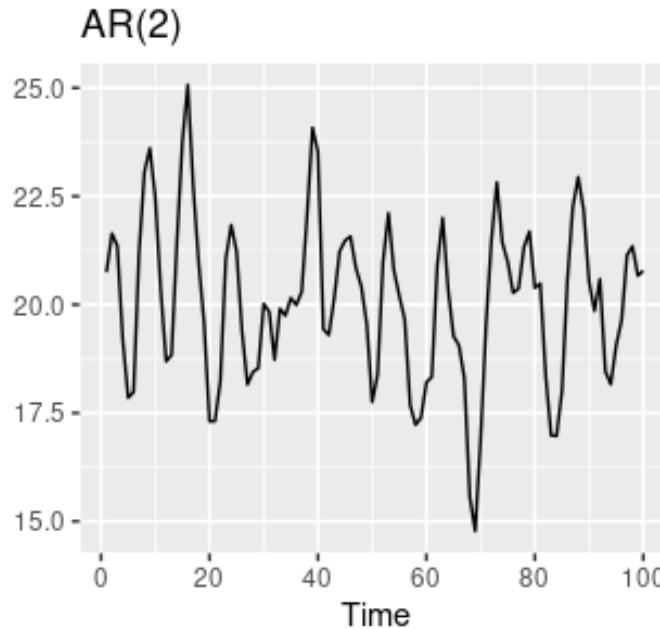
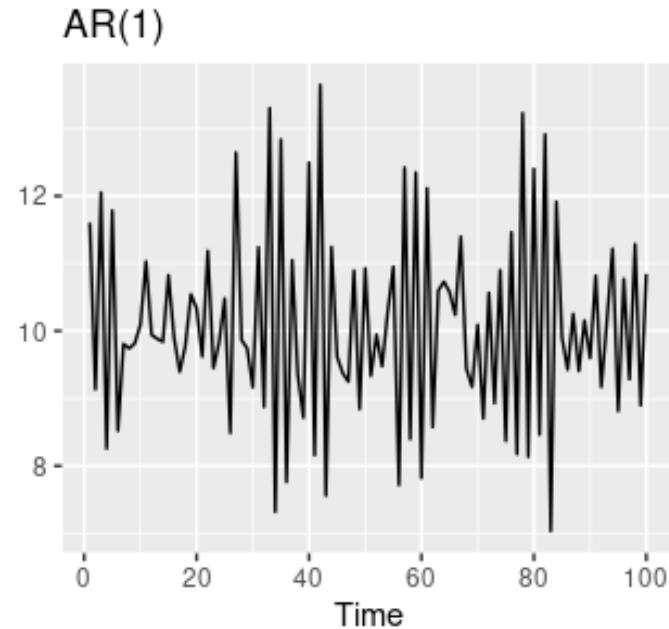
Autoregression = regression of the variable against itself.

$$X_t = \sum_{i=1}^p \varphi_i X_{t-i} + \varepsilon_t$$

TEMPORAL AUTOCORRELATION

AUTOREGRESSIVE MODEL

AR(1) process is one in which the current value is based on the immediately preceding value



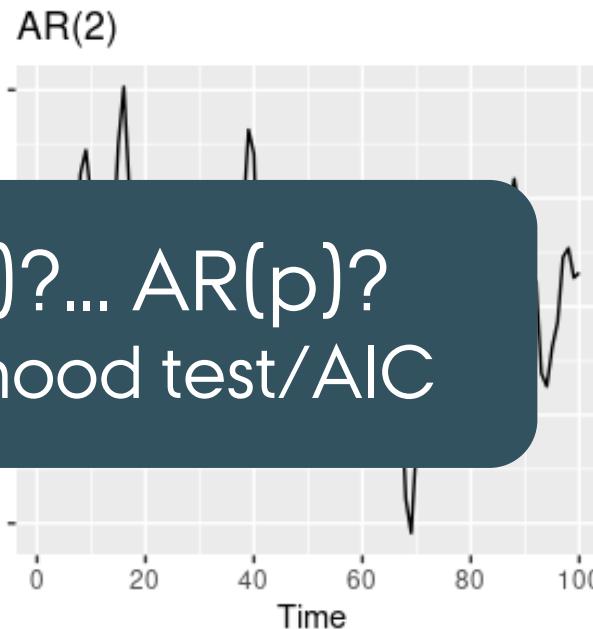
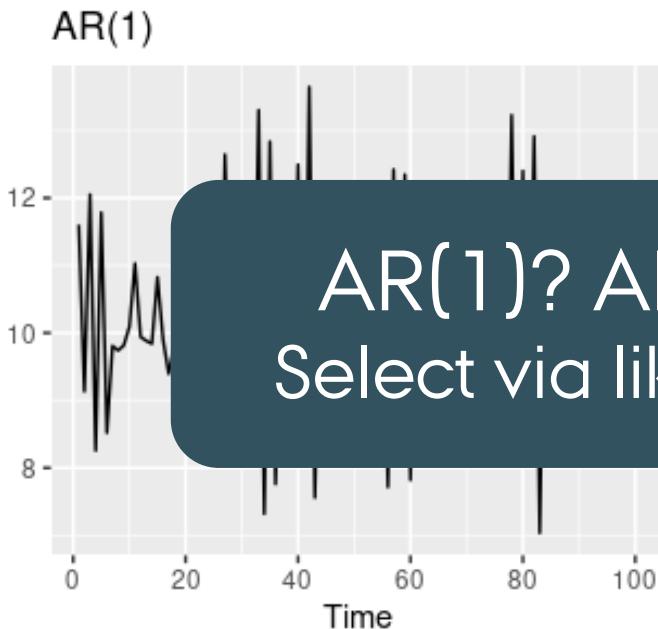
AR(2) process is one in which the current value is based on the previous two values

The correlation is uni-directional as past events affects future ones, not the other way

TEMPORAL AUTOCORRELATION

AUTOREGRESSIVE MODEL

AR(1) process is one in which the current value is based on the immediately preceding value



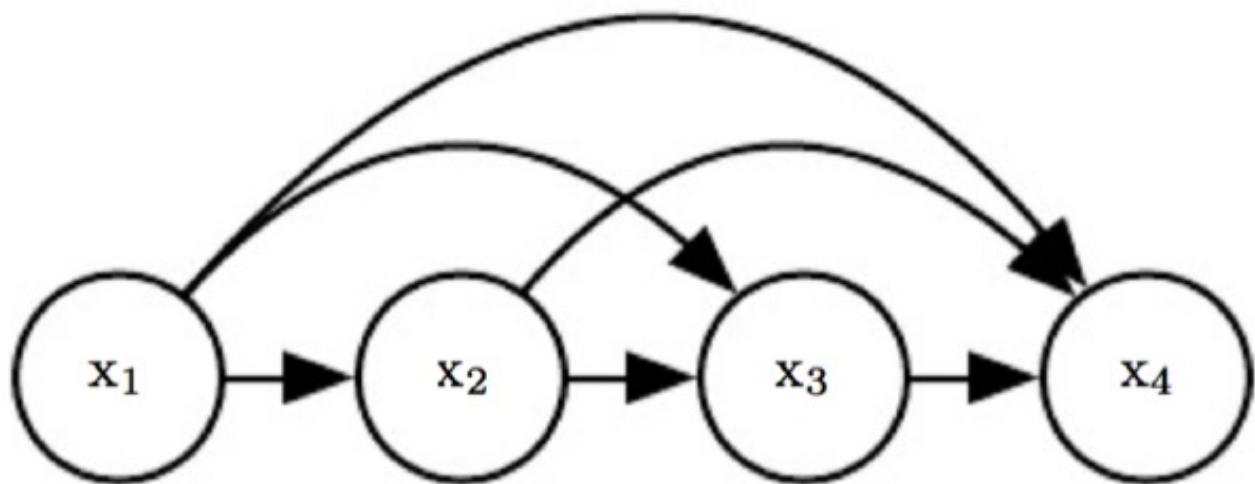
AR(1)? AR(2)?... AR(p)?
Select via likelihood test/AIC

AR(2) process is one in which the current value is based on the previous two values

The correlation is uni-directional as past events affects future ones, not the other way

TEMPORAL AUTOCORRELATION

MOVING AVERAGE MODEL



Output variable depends linearly on its own previous values

If we use the preceding error(s), we call this a **Moving average** model

Error defines the difference from the time series mean.

$$X_t = \mu + \sum_{i=1}^q \theta_i \varepsilon_{t-i} + \varepsilon_t$$

TEMPORAL AUTOCORRELATION

AUTOREGRESIVE + MOVIG AVERAGE

Autoregresive

Forcast based on the
observations

Moving average

Forcast based on the
Errors

ARMA

AutoRegressive
Moving Average

TEMPORAL AUTOCORRELATION

R – IMPLEMENTATION

autoregressive
parameters

Covariate
with time

```
corAR1 (value, form)
```

```
corARMA (value, form, p, q)
```

**autoregressive
&
moving
average
parameters**

Covariate
with time

autoregressive
and moving
average order

So far so good?

Any questions?

Ready to move on?

SPATIAL AUTOCORRELATION

THE MATH BEHIND THE MODEL

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Random part

Normally distributed errors

$$\begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} : N(0, V)$$

Variance heterogeneity

$$V = \begin{bmatrix} \sigma^2_{(1,1)} & \cdots & \sigma^2_{(j,1)} \\ \vdots & \ddots & \vdots \\ \sigma^2_{(1,n)} & \cdots & \sigma^2_{(j,n)} \end{bmatrix}$$

Observations are not independent

Variances are not equal across observations



SPATIAL AUTOCORRELATION

FITTING CORRELATION FUNCTIONS

**Exponential
correlation**
corExp

**Gaussian
correlation**
corGaus

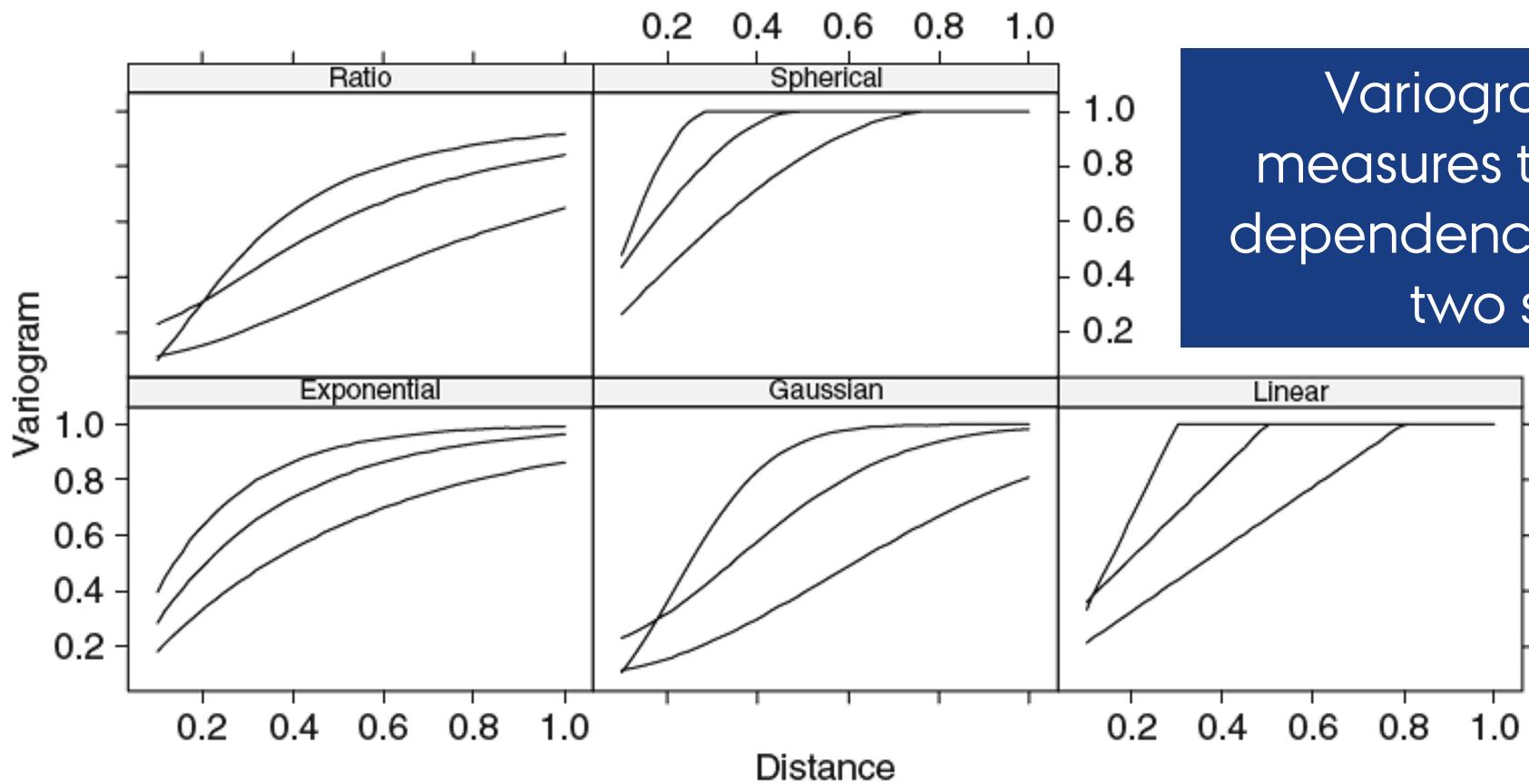
**Linear
correlation**
corLin

**Spherical
correlation**
corSpher

**Rational quadratic
correlation**
corRatio

SPATIAL AUTOCORRELATION

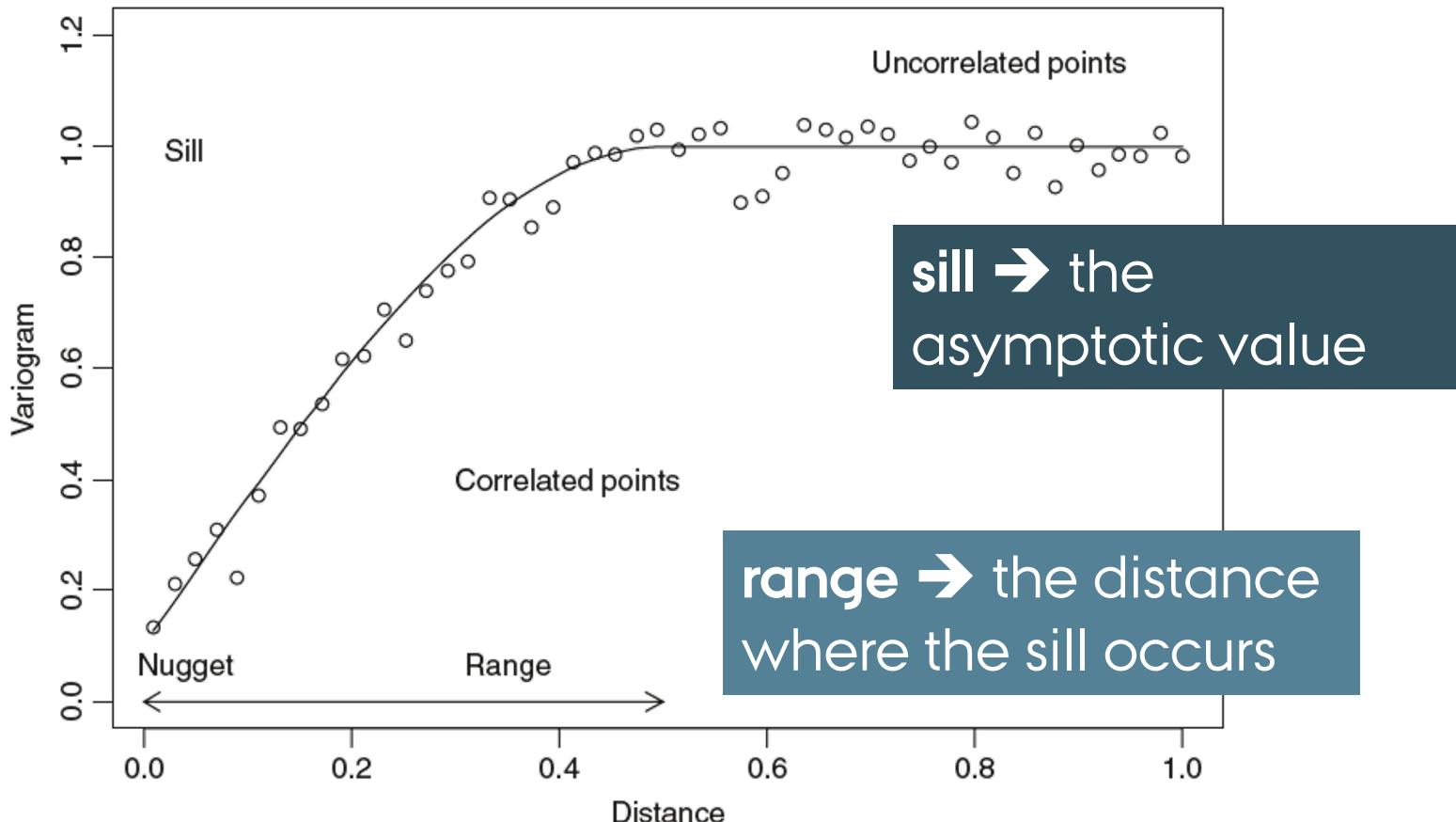
FITTING CORRELATION FUNCTIONS



SPATIAL AUTOCORRELATION

FITTING CORRELATION FUNCTIONS

nugget → the y-value when the distance is 0.



SPATIAL AUTOCORRELATION

R – IMPLEMENTATION

```
corSpher( form, nugget, metric)  
corLin ( form, nugget , metric)  
corRatio( form, nugget , metric)  
corGaus ( form, nugget , metric)  
corExp ( form, nugget , metric)
```

The spatial
covarianties
Lat/Long
x/y

Nugget
effect
Cor at lag dist =0

distance
metric
Euclidean?
Manhattan?

So far so good?

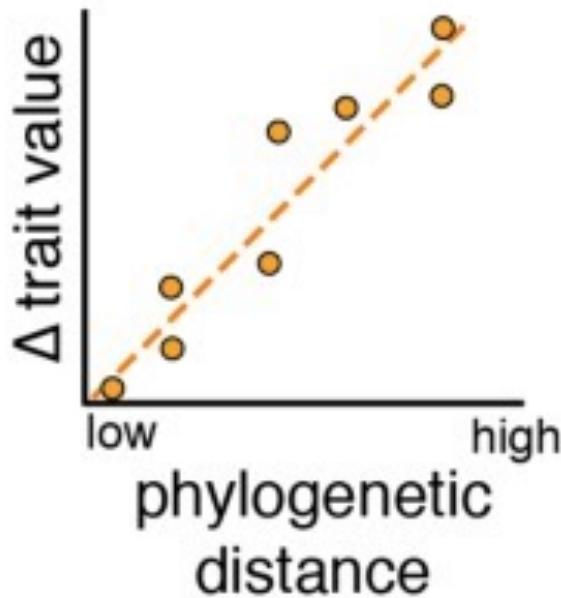
Any questions?

Ready to move on?

PHYLOGENETIC AUTOCORRELATION

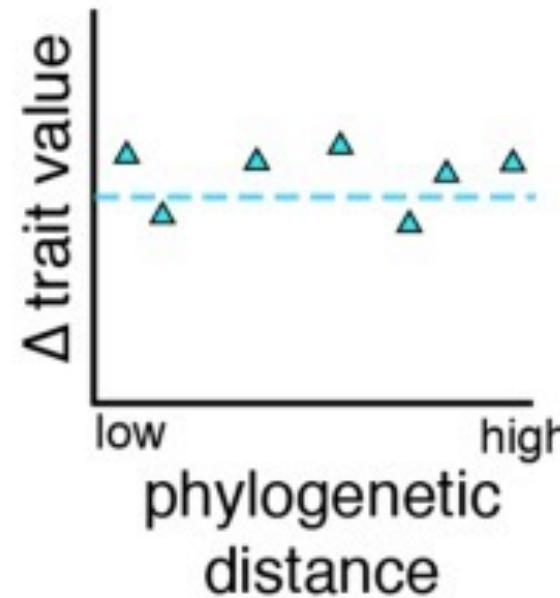
Positive Phylogenetic Autocorrelation

Evolutionary similarity means similar traits



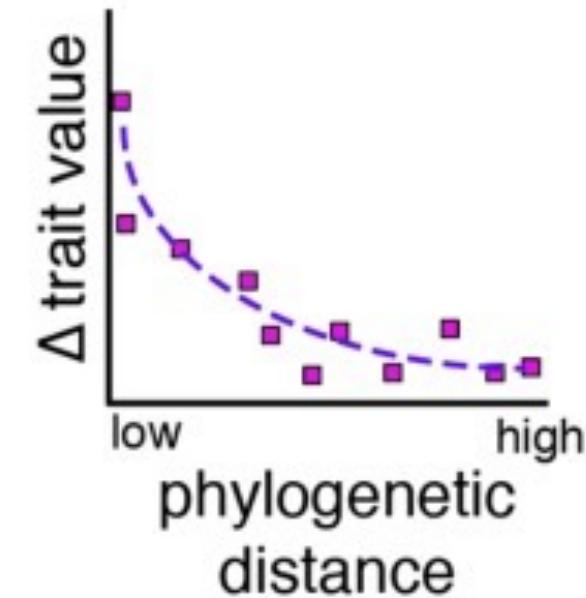
No Phylogenetic Autocorrelation

Evolutionary similarity does not affect trait similarity



Negative Phylogenetic Autocorrelation

Evolutionary Similarity means different traits



PHYLOGENETIC AUTOCORRELATION

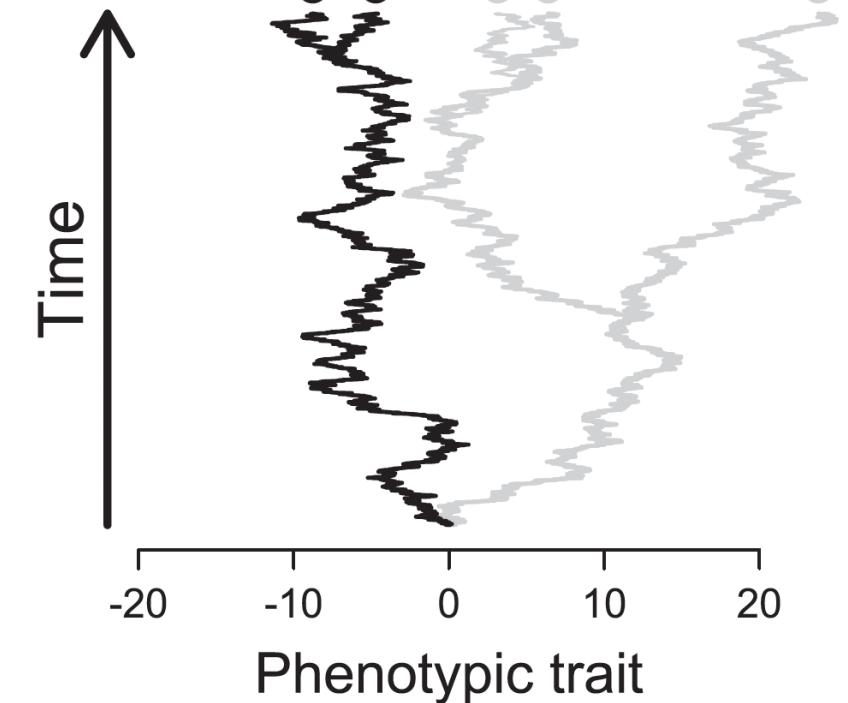
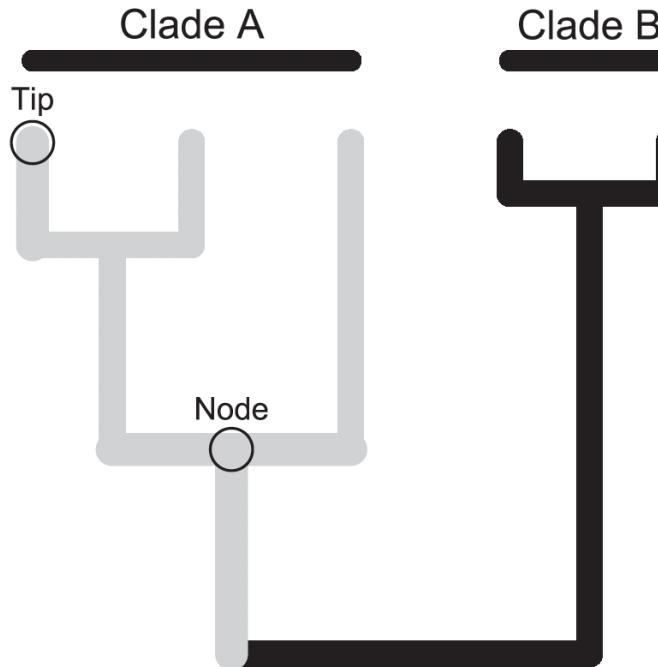
The correlation between species/nodes is determined by evolutionary:

Tempo

Amount of change per unit time

Mode

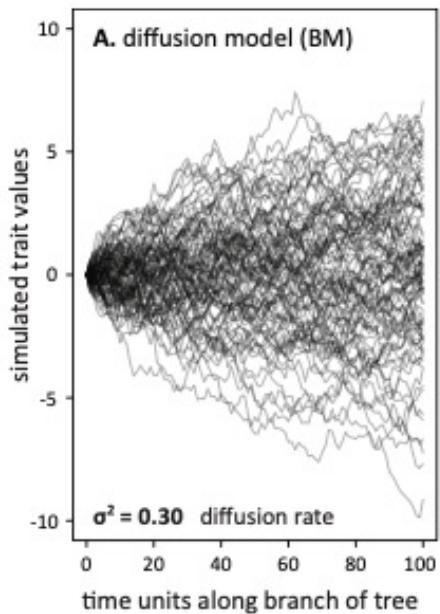
mechanisms responsible for evolution and their patterns



PHYLOGENETIC AUTOCORRELATION MODELS OF EVOLUTION

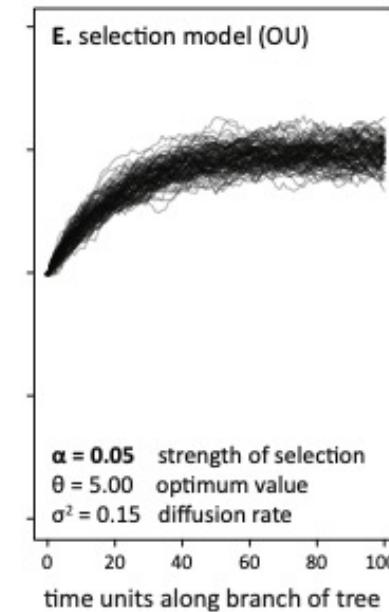
Brownian motion

Random drift and constant rate through time and across lineages



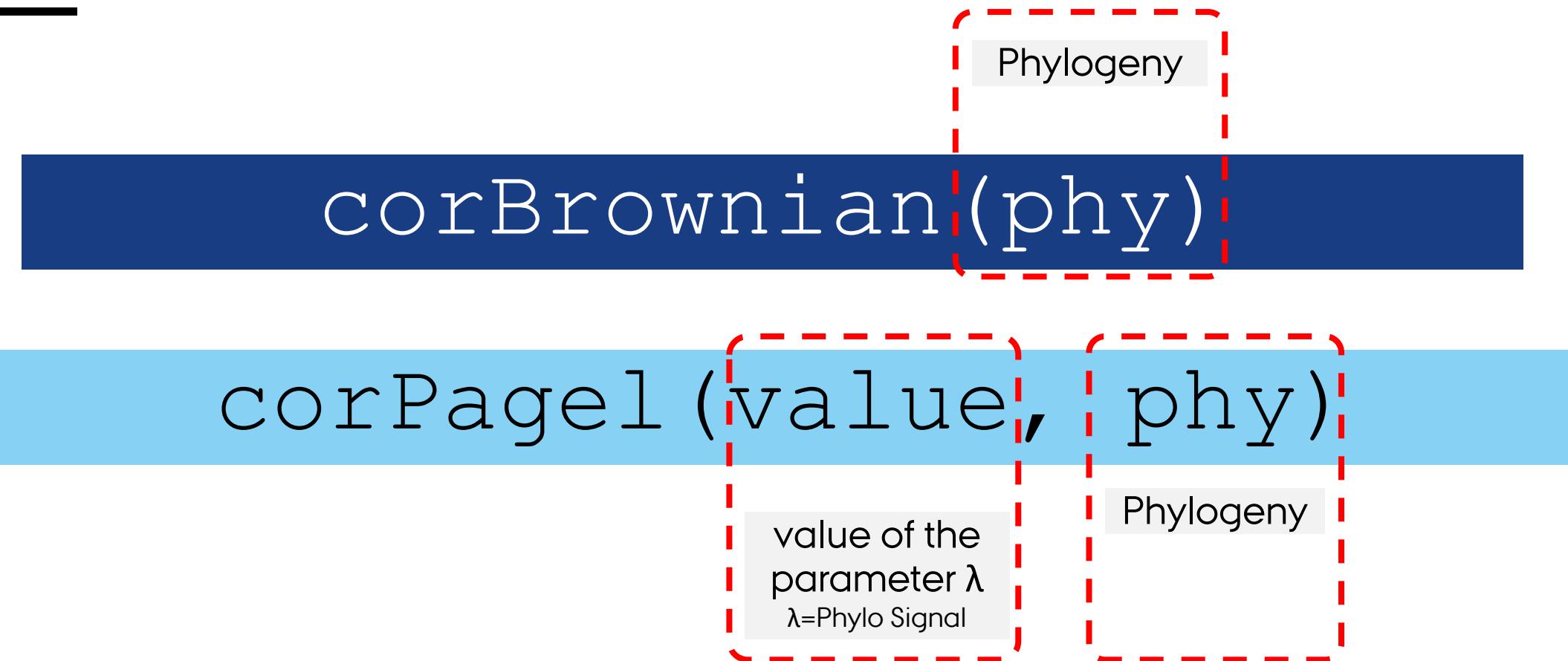
Ornstein–Uhlenbeck

Changes got towards a fitness optimum on an adaptive landscape



PHYLOGENETIC AUTOCORRELATION

R – IMPLEMENTATION [BROWNIAN]



PHYLOGENETIC AUTOCORRELATION

R-IMPLEMENTATION [ORNSTEIN-UHLENBECK]

```
corMartins(value, phy)
```

value of the
parameter α
 $\alpha=\text{optima}$

Phylogeny

So far so good?

Any questions?

Ready to move on?

MODEL SELECTION – TWO STEPS

Model selection is done in two stages:

1. Define the best variance/correlation structure.
 - Comapre a full model in fixed effects to one with a given variance/correlation structure.
 - Full and variance/correlation model are fitted using “REML”

2. Define the best fixed structure.
 - Reduce the pool of fixed effects from the model selected above
 - Models beeing reduced are build using “ML”.

MODEL SELECTION -STEP-1

Define the best variance/correlation structure

```
B1A<- gls(A ~ towns + region + Sex, data= eire.Dat,  
correlation=corSpher(form=~x + y, nugget=TRUE),  
method = 'REML')
```

One note of model Selection

If you need to include and the explanation of the (co)variance it is more important to have an expectation of it in your model than finding the “best” description.

```
method = 'REML')  
B1E <- gls(A ~ towns + region + Sex, data= eire.Dat,  
correlation=corExp(form=~x + y, nugget=TRUE) ,  
method = 'REML')
```

MODEL SELECTION -STEP-1

Define the best fixed structure.

```
B1EFull <- gls(A ~ towns + region + Sex, data= eire.Dat,  
                  correlation=corExp(form=~x + y, nugget=TRUE) ,  
                  method = 'ML')  
  
B1EMod1 <- gls(A ~ towns + region, data= eire.Dat,  
                  correlation=corExp(form=~x + y, nugget=TRUE) ,  
                  method = 'ML')  
  
B1EMod2 <- gls(A ~ towns + Sex, data= eire.Dat,  
                  correlation=corExp(form=~x + y, nugget=TRUE) ,  
                  method = 'ML')  
  
B1EMod3 <- gls(A ~ region + Sex, data= eire.Dat,  
                  correlation=corExp(form=~x + y, nugget=TRUE) ,  
                  method = 'ML')
```

RESTRICTED MAXIMUM LIKELIHOOD (REML) MAXIMUM LIKELIHOOD (ML) ANALYSIS

Maximum Likelihood (**ML**) Analysis

- Focused on getting the coefficients of the linear model right.
- That is the focus is predicting the mean correctly.

Restricted Maximum Likelihood (**REML**)

- Focused on getting the variances in the model right.
- That is the focus is predicting the variance correctly.

A good explanation of the diff between these is here:

<https://towardsdatascience.com/maxim...-reml-78cf79bef2cf>

So far so good?

Any questions?

Ready to finish?

IN SUMMARY

1. Generalized Least Squares is an approach that allows controlling for:
 - Heterogeneous variances: via modelling the variance using multiple strategies.
 - Autocorrelated Variables: Via the inclusion of correlation structures
 - Autoregresing / moving averages
 - Semivarigram/correlogram
 - Phylogenetic relatedness

IN SUMMARY

2. Model selection in mixed models is a two step process:
 - **Part one** – define the best variance/covariance structure
 - Models build using REML
 - **Part two** – define the best fixed effect structure
 - Models build using ML



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