08 Pose Estimation.

Q1. Prove
$$Y = P - qtytqt$$

$$y = \frac{1}{w} \stackrel{\mathcal{H}}{J}_{=1}^{m} w_{j} y_{j}$$
in which: $P = \frac{1}{w} \stackrel{\mathcal{H}}{J}_{=1}^{m} w_{j} P_{j}$

$$w = \stackrel{\mathcal{H}}{J}_{=1}^{m} w_{j}$$

we have:
$$q^{-1} \left[\sum w_j y_j^{\oplus} - \left(\sum w_j p_j - \sum w_j r \right)^{+} \right] q = 0$$
divide both side by $u = \sum w_j$

$$p = q + y + q - q = p - r$$

$$-\frac{1}{2}\sum_{j=1}^{N}w_{j}P_{j}^{OT}P_{j}^{O} = \begin{bmatrix} 1 & -P^{A} \\ P^{A} & -\frac{1}{2}\sum_{j=1}^{N}w_{j}P_{j}^{OT}P_{j}^{O} \end{bmatrix}$$

$$P = \frac{1}{2}\sum_{j=1}^{N}w_{j}P_{j}^{OT}W_{j}P_{j}^{OT}$$

$$-: M = \begin{bmatrix} 1 & p^{\prime} \\ -p^{\prime} & I - p^{\prime} \end{bmatrix}$$

$$I = -\frac{1}{4} \sum_{j=1}^{4} w_{j} (P_{j}^{1} P_{j}^{1} - P_{j}^{1} P_{j}^{2} - P_{j}^{1} P_{j}^{2} + P_{j}^{2} P_{j}^{2})$$

$$= -\frac{1}{4} \sum_{j=1}^{4} w_{j} P_{j}^{1} P_{j}^{1} + P_{j}^{2} P_{j}^{2}$$

Q3. Prove
$$w_{j=1}^{M}w_{j} z_{j}^{OT}(y_{j}-z_{j}) = \begin{bmatrix} y - C_{op}(p-k_{op}) \\ b-y^{C_{op}}(p-k_{op}) \end{bmatrix}$$

$$= \begin{bmatrix} C_{op} - C_{op} r_{op} \end{bmatrix} \begin{bmatrix} P_j \\ 1 \end{bmatrix} = \begin{bmatrix} C_{op} (P_j - r_{op}) \\ 1 \end{bmatrix} = \begin{bmatrix} I - [C_{op}(P_j - r_{op})]^{\lambda} \\ 0^T \end{bmatrix}$$

$$= \begin{bmatrix} y_j - C_{op}(P_j - r_{op}) \\ -y_j^{\wedge} C_{op}(P_j - r_{op}) \end{bmatrix}$$

$$-\frac{1}{2}\sum_{j=1}^{\infty}w_{j}\Gamma y_{j}-Cop(P_{j}-rop)]=\frac{1}{2}\sum_{j=1}^{\infty}w_{j}y_{j}-Cop(\overline{w}_{j=1}^{\infty}w_{j}P_{j}^{*}-h_{0}P_{0})=y-Cop(P_{0}-rop)$$

$$-\frac{1}{2}\sum_{j=1}^{2}w_{j}-y_{j}^{2}C_{op}(P_{j}-r_{op})=-\frac{1}{2}\sum_{j=1}^{2}w_{j}(y_{j}-y)^{2}C_{op}(P_{j}-P)-y^{2}C_{op}(P-v_{op})$$

The t-th element of
$$-\frac{1}{4}\sum_{j=1}^{2}w_{j}(y_{j}-y)^{2}Cop(P_{j}-P)$$
 is

 $1\sqrt{1}-\frac{1}{4}\sum_{j=1}^{2}w_{j}(y_{j}-y)^{2}Cop(P_{j}-P)=-\frac{1}{4}\sum_{j=1}^{2}w_{j}+r\{(op(P_{j}-P)[1\frac{1}{4}(y_{j}-y)^{2}]\}$
 $1\sqrt{1}-\frac{1}{4}\sum_{j=1}^{2}w_{j}(y_{j}-y)^{2}$
 $1\sqrt{1}-\frac{1}{4}\sum_{j=1}^{2}w_{j}(P_{j}-P)(y_{j}-y)^{2}$
 $1\sqrt{1}-\frac{1}{4}\sum_{j=1}^{2}w_{j}(P_{j}-P)(y_{j}-y)^{2}$
 $1\sqrt{1}-\frac{1}{4}\sum_{j=1}^{2}w_{j}(P_{j}-P)(y_{j}-y)^{2}$

=
$$tr[1^{\hat{i}} Cop W^{\dagger}], W^{\dagger} = w^{\underbrace{N}}_{j=1} w_{j} (P_{j} - P)(y_{j} - y_{j})^{\dagger}$$

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