



ORTA DOĞU TEKNİK ÜNİVERSİTESİ
MIDDLE EAST TECHNICAL UNIVERSITY

MATH 381 BONUS CODING HOMEWORK REPORT

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QUESTION 1:

Codes to solve a system of n linear equations and n unknowns using:

a) Jacobi iterative method

QUESTION 1

```
[28] # JACOBI method

import numpy as np

def Jacobi(n, M, x):
    A = M[:, :-1] # Extracting coefficient matrix A from augmented matrix M
    b = M[:, -1] # Extracting right hand side vector from augmented matrix M
    D = np.diag(A) # extract diagonal elements of A
    R = A - np.diagflat(D) # R = A - D
    print("\tk\tx(k)\tRelE") # print column headers
    k=1
    rele=1000000 # We create dummy rele variable and set it practically high enough so that we're able to execute first iteration, then we update rele accordingly after first iteration
    while rele>=10**(-3): # Let's use tolerance=0.001 as given in QUESTION 2
        if k>=11:
            # we stop here because we are required to print only first 10 iterations as output. Since we begin from k=0, k=10 would be 11th iteration, so we stop.
            break
        x_new = (b - np.dot(R, x)) / D # solution of Jacobi method
        rele = np.linalg.norm(x_new - x, ord=np.inf) / np.linalg.norm(x_new, ord=np.inf) # calculate relative error
        print("{}\t{}\t{}".format(k, x_new, rele)) # print iteration number, solution, and relative error
        x = x_new
        k=k+1
    return x
```

b) Gauss-Seidel method

```

# GAUSS-SEIDEL method

import numpy as np
def Gauss_Seidel(n, M, x):
    A = M[:, :-1] # Extracting coefficient matrix A from augmented matrix M
    b = M[:, -1] # Extracting right hand side vector from augmented matrix M
    L = np.tril(A) # Extract lower triangular part elements of A
    U = A - L
    print("k\tx(k)\tRele") # print column headers
    k=1
    rele=1000000 # We create dummy rele variable and set it practically high enough so that we're able to execute first iteration, then we update rele accordingly after first iteration
    while rele>=10**(-3): # Let's use tolerance=0.001 as given in QUESTION 2
        if k>=11:
            # we stop here because we are required to print only first 10 iterations as output. Since we begin from k=0, k=10 would be 11th iteration, so we stop.
            break
        x_neww = np.dot(np.linalg.inv(L), b - np.dot(U, x))
        rele = np.linalg.norm(x_neww - x, ord=np.inf) / np.linalg.norm(x_neww, ord=np.inf)
        print("{}\t{}\t{:.6f}".format(k, x_neww, rele)) # print iteration number, solution, and relative error
        x=x_neww
        k=k+1
    return x_neww

```

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QUESTION 1:

Results of tests our codes:

a) Jacobi method

```
✓ 0s # TESTING OUR RESULTS with Jacobi for the linear system given in QUESTION 1
M = np.array([[2., -1., 2., -1., -1],
              [2., 1., -2., -2., -2],
              [-1., 2., -4., 1., 1],
              [3.0, 0., 0., -3., -3]]) # Augmented matrix
x0 = np.array([1., 1., 1., 1.]) #LET'S START WITH STARTING VECTOR [1, 1, 1, 1]^T
x = Jacobi(4, M, x0);
print(x)
```

k	x(k)	Rele
1	[-0.5 0. 0.25 2.]	0.750000
2	[0.25 3.5 0.375 0.5]	1.000000
3	[1.125 -0.75 1.5625 1.25]	2.720000
4	[-1.8125 1.375 -0.59375 2.125]	1.382353
5	[1.84375 4.6875 1.421875 -0.8125]	0.780000
6	[0.015625 -4.46875 1.4296875 2.84375]	2.048951
7	[-2.7421875 6.515625 -1.77734375 1.015625]	1.685851
8	[5.04296875 1.9609375 3.94726562 -1.7421875]	1.543765
9	[-4.33789062 -7.67578125 -0.96582031 6.04296875]	1.255471
10	[-0.35058594 16.83007812 -1.49267578 -3.33789062]	1.456075

b) Gauss-Seidel method

```

[31] # TESTING OUR RESULTS with Gauss-Seidel for the linear system given in QUESTION 1
M = np.array([[2., -1., 2., -1., -1],
              [2., 1., -2., -2., -2],
              [-1., 2., -4., 1., 1],
              [3.0, 0., 0., -3., -3]]) # Augmented matrix
x0 = np.array([1., 1., 1., 1.]) # LET'S START WITH STARTING VECTOR [1, 1, 1, 1]^T
x = Gauss_Seidel(4, M, x0);
print(x)

```

k	x(k)	Rele
1	[-0.5 3. 1.625 0.5]	0.666667
2	[-0.375 3. 1.46875 0.625]	0.052083
3	[-0.15625 2.5 1.1953125 0.84375]	0.200000
4	[-0.0234375 2.125 1.02929688 0.9765625]	0.176471
5	[0.02148438 1.96875 0.97314453 1.02148438]	0.079365
6	[0.02197266 1.9453125 0.97253418 1.02197266]	0.012048
7	[0.0111084 1.96679688 0.9861145 1.0111084]	0.010924
8	[0.00283813 1.98876953 0.99645233 1.00283813]	0.011048
9	[-6.48498535e-04 1.99987793e+00 1.00081062e+00 9.99351501e-01]	0.005555
10	[-1.19590759e-03 2.00271606e+00 1.00149488e+00 9.98804092e-01]	0.001417

QUESTION 2:

In this example, 10 iterations are not enough to see whether Jacobi method converges. So, we use exact same code as in QUESTION 1, but this time with **50** iterations.

a) Jacobi method

QUESTION 2

```
# Jacobi method

import numpy as np

def Jacobi(n, M, x):
    A = M[:, :-1] # Extracting coefficient matrix A from augmented matrix M
    b = M[:, -1] # Extracting right hand side vector from augmented matrix M
    D = np.diag(A) # extract diagonal elements of A
    R = A - np.diagflat(D) # R = A - D
    print("k\tx(k)\tRele") # print column headers
    k=1
    rele=1000000 # We create dummy rele variable and set it practically high enough so that we're able to execute first iteration, then we update rele accordingly after first iteration
    while rele>10**(-3): # Let's use tolerance=0.001 as given in QUESTION 2
        if k>51: # printing only 50 iterations
            break
        x_new = (b - np.dot(R, x)) / D
        rele = np.linalg.norm(x_new - x, ord=np.inf) / np.linalg.norm(x_new, ord=np.inf) # calculate relative error
        print("{}\t{}\t{:0.6f}".format(k, x_new, rele)) # print iteration number, solution, and relative error
        x = x_new
        k=k+1
    return x
```

b) Gauss-Seidel method

```

✓ [33] # GAUSS-SEIDEL method
08
import numpy as np
def Gauss_Seidel(n, M, x):
    A = M[:, :-1] # Extracting coefficient matrix A from augmented matrix M
    b = M[:, -1] # Extracting right hand side vector from augmented matrix M
    L = np.tril(A) # Extract lower triangular part elements of A
    U = A - L
    print("k\tx(k)\tRele") # print column headers
    k=1
    rele=1000000 # We create dummy rele variable and set it practically high enough so that we're able to execute first iteration, then we update rele accordingly after first iteration
    while rele>10**(-3): # Let's use tolerance=0.001 as given in QUESTION 2
        if k>51:
            # printing only 50 iterations
            break
        x_neww = np.dot(np.linalg.inv(L), b - np.dot(U, x))
        rele = np.linalg.norm(x_neww - x, ord=np.inf) / np.linalg.norm(x_neww, ord=np.inf)
        print("{}\t{}\t{: .6f}".format(k, x_neww, rele)) # print iteration number, solution, and relative error
        x=x_neww
        k=k+1
    return x_neww

```

QUESTION 2:

Testing results of codes for given linear system

a) Jacobi method

So, we see results below that Jacobi method **converges** to solution $[1,1,1]^T$, which is indeed solution of the given linear system of equations.

0s		k	x(k)	Rele	
		1	[2. -0. -0.]	1.000000	
		2	[2. 2. 0.66666667]	1.000000	
		3	[1.33333333 2. 2.]	0.666667	
		4	[0. 1.33333333 1.77777778]	0.750000	
		5	[0.22222222 -0. 0.88888889]	1.500000	
		6	[1.11111111 0.22222222 0.07407407]	0.800000	
		7	[1.92592593 1.11111111 0.51851852]	0.461538	
		8	[1.48148148 1.92592593 1.38271605]	0.448718	
		9	[0.61728395 1.48148148 1.77777778]	0.486111	
		10	[0.22222222 0.61728395 1.19341564]	0.724138	
		11	[0.80658436 0.22222222 0.48559671]	0.877551	
		12	[1.51440329 0.80658436 0.4170096]	0.467391	
		13	[1.5829904 1.51440329 1.04252401]	0.447140	
		14	[0.95747599 1.5829904 1.53726566]	0.395147	
		15	[0.46273434 0.95747599 1.3744856]	0.455090	
		16	[0.6255144 0.46273434 0.79256211]	0.734231	
		17	[1.20743789 0.6255144 0.51699436]	0.481949	
		18	[1.48300564 1.20743789 0.8194889]	0.392395	
		19	[1.1805111 1.48300564 1.29929381]	0.323535	
		20	[0.70070619 1.1805111 1.38217413]	0.347138	
		21	[0.61782587 0.70070619 1.02057613]	0.470131	
		22	[0.97942387 0.61782587 0.67307942]	0.369195	
		23	[1.32692058 0.97942387 0.73835854]	0.272509	
		24	[1.26164146 1.32692058 1.09525611]	0.268967	
		25	[0.90474389 1.26164146 1.30516087]	0.273451	
		26	[0.69483913 0.90474389 1.14267561]	0.312335	
		27	[0.85732439 0.69483913 0.83477564]	0.359141	
		28	[1.16522436 0.85732439 0.74900088]	0.264241	
		29	[1.25099912 1.16522436 0.95995772]	0.246123	
		30	[1.04004228 1.25099912 1.19381595]	0.186937	
		31	[0.80618405 1.04004228 1.18068017]	0.198071	
		32	[0.81931983 0.80618405 0.96208954]	0.243073	
		33	[1.03791046 0.81931983 0.81056264]	0.210606	
		34	[1.18943736 1.03791046 0.89218337]	0.183776	
		35	[1.10781663 1.18943736 1.08841943]	0.164982	
		36	[0.91158057 1.10781663 1.16223045]	0.168844	
		37	[0.83776955 0.91158057 1.04240461]	0.188253	
		38	[0.95759539 0.83776955 0.8869769]	0.162310	
		39	[1.1130231 0.95759539 0.8777115]	0.139645	
		40	[1.1222885 1.1130231 1.00940463]	0.138492	
		41	[0.99059537 1.1222885 1.11611157]	0.117343	
		42	[0.88388843 0.99059537 1.07839079]	0.122120	
		43	[0.92160921 0.88388843 0.95502639]	0.129174	
		44	[1.04497361 0.92160921 0.89646202]	0.118055	
		45	[1.10353798 1.04497361 0.96273067]	0.111790	
		46	[1.03726933 1.10353798 1.06449506]	0.092216	
		47	[0.93550494 1.03726933 1.08144843]	0.094100	
		48	[0.91855157 0.93550494 1.00334786]	0.101425	
		49	[0.99665214 0.91855157 0.92985382]	0.078363	
		50	[1.07014618 0.99665214 0.9445851]	0.072981	

QUESTION 2:

Testing results of codes for given linear system

b) Gauss-Seidel method.

So, we can see from results below that Gauss-Seidel method **diverges** because solution at each iteration is either $[2,2,2]^T$ or $[0,0,0]^T$. Hence, this clearly means that solution **does not converge**, or it **diverges**

k	x(k)	Rel
1	[2. 2. 2.]	1.000000
2	[0. 0. 0.]	inf
3	[2. 2. 2.]	1.000000
4	[0. 0. 0.]	inf
5	[2. 2. 2.]	1.000000
6	[0. 0. 0.]	inf
7	[2. 2. 2.]	1.000000
8	[0. 0. 0.]	inf
9	[2. 2. 2.]	1.000000
10	[0. 0. 0.]	inf
11	[2. 2. 2.]	1.000000
12	[0. 0. 0.]	inf
13	[2. 2. 2.]	1.000000
14	[0. 0. 0.]	inf
15	[2. 2. 2.]	1.000000
16	[0. 0. 0.]	inf
17	[2. 2. 2.]	1.000000
18	[0. 0. 0.]	inf
19	[2. 2. 2.]	1.000000
20	[0. 0. 0.]	inf
21	[2. 2. 2.]	1.000000
22	[0. 0. 0.]	inf
23	[2. 2. 2.]	1.000000
24	[0. 0. 0.]	inf
25	[2. 2. 2.]	1.000000
26	[0. 0. 0.]	inf
27	[2. 2. 2.]	1.000000
28	[0. 0. 0.]	inf
29	[2. 2. 2.]	1.000000
30	[0. 0. 0.]	inf
31	[2. 2. 2.]	1.000000
32	[0. 0. 0.]	inf
33	[2. 2. 2.]	1.000000
34	[0. 0. 0.]	inf
35	[2. 2. 2.]	1.000000
36	[0. 0. 0.]	inf
37	[2. 2. 2.]	1.000000
38	[0. 0. 0.]	inf
39	[2. 2. 2.]	1.000000
40	[0. 0. 0.]	inf
41	[2. 2. 2.]	1.000000
42	[0. 0. 0.]	inf
43	[2. 2. 2.]	1.000000
44	[0. 0. 0.]	inf
45	[2. 2. 2.]	1.000000
46	[0. 0. 0.]	inf
47	[2. 2. 2.]	1.000000
48	[0. 0. 0.]	inf
49	[2. 2. 2.]	1.000000
50	[0. 0. 0.]	inf

