

Lesson 6.1 - Line Tracking Sensor Datalogging

Simulation of this lesson can be found at <https://makecode.microbit.org/57670-47999-45900-55680>

Note: (Robot construction must be completed before this Step)

Goal for this lesson

Learn to read the serial data from the line tracking photo diodes on the base of the Robot on a PC via USB

Hardware Required

PC will be required to log the serial data

1 x micro USB cable

1 x Smart Robot with micro:bit & battery installed

Step 1 As per Figure 1

- Goto URL <https://makecode.microbit.org/#>
- Create **"New Project"** & give it a name
- Press **Gear** symbol – top right
- Press Extensions
- Add repository found using link below
https://github.com/AltronicsAUKits/Z6454-Robot-Kit-v2_KS0426
- On start up both **"on start"** & **"forever"** will be in your work space, move **"forever"** block below **"on start"** block

Step 2 as per Figure 2

Moving forward we will only highlight the locations for the required modules to produce the desired code.

- We will be utilising the **"Basic"** Tab
- We will be utilising the **"Serial"** Tab under **"Advanced"** Tab
- We will be utilising the **"Pins"** Tab under **"Advanced"** Tab
- Download the code to the micro:bit

Expected Result!

- Once the code has been written to the micro:bit.
- Insert the micro:bit into the robot.
- Power on the robot and plug the USB lead into the micro:bit.
- On the Makecode website press **"Show data device"**
This will now begin to read the data on Pin 12 which is connected to the robots photo interrupter.
- Now if you move the robot over a black line on white paper several times you will see a digital signal readout and rolling data display up top
As per Figure 3.

Example Line Tracking Sensor Datalogging can be found at
<https://makecode.microbit.org/57670-47999-45900-55680>

STEM Smart Robot can be purchase from Altronics.

<https://www.altronics.com.au/p/z6454-stem-microbit-mini-smart-robot-car-v2.0/>

Scan QR code for Lesson 6.1 Simulation

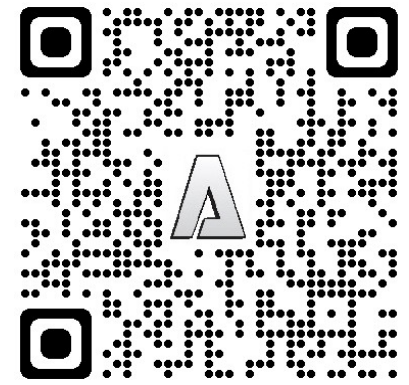


Figure 1



Figure 2

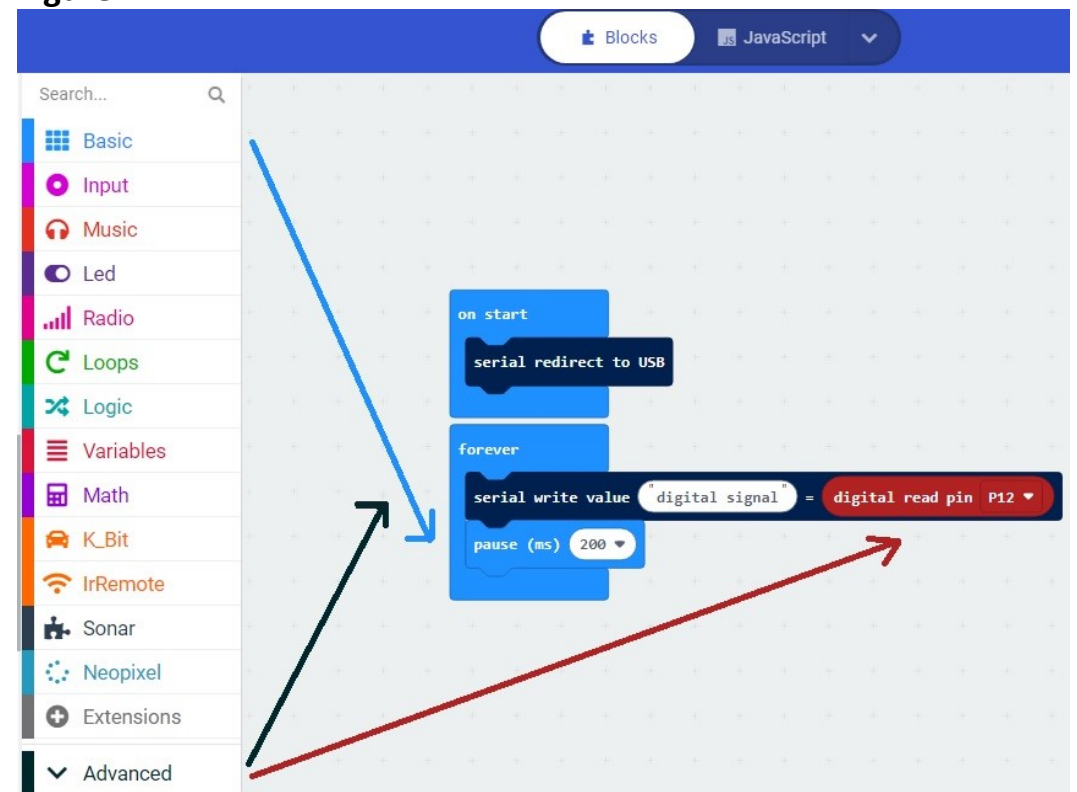


Figure 3

