

Lesson 8.2 - Infrared Obstacle Avoidance Display

Simulation of this lesson can be found at <https://makecode.microbit.org/86944-10749-06987-90752>

Note: (Robot construction must be completed before this Step)

Goal for this lesson

Learn how to use the obstacle avoidance sensors and produce an output on the micro:bit matrix display.

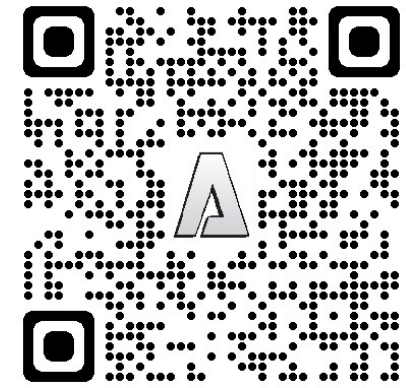
Hardware Required

PC or Tablet

1 x micro USB cable

1 x Smart Robot with micro:bit & battery installed

Scan QR code for Lesson 8.2 Simulation



Step 1 As per Figure 1

- Goto URL <https://makecode.microbit.org/#>
- Create **"New Project"** & give it a name
- Press **Gear** symbol – top right
- Press Extensions
- Add repository found using link below.
https://github.com/AltronicsAUKits/Z6454-Robot-Kit-v2_KS0426
- On start up both **"on start"** & **"forever"** will be in your work space, move **"forever"** block below **"on start"** block.

Step 2 as per Figure 2

Moving forward we will only highlight the locations for the required modules to produce the desired code.

- We will be utilising the **"Basic"** Tab
- We will be utilising the **"Led"** Tab
- We will be utilising the **"Logic"** Tab
- We will be utilising the **"K_Bit"** Tab
- Write the code to the micro:bit
- Download the code to the micro:bit

Expected Result!

- Insert the micro:bit into the robot & Power on.
- If the robot detects objects on both obstacle sensors the matrix display will show a smiley face.
- If the Right obstacle sensor detects an object the matrix display will display an arrow pointing left.
- If the Left obstacle sensor detects an object the matrix display will display an arrow pointing right.
- If no obstacles are detected on either sensor the display will show an arrow pointing forward.

Figure 1

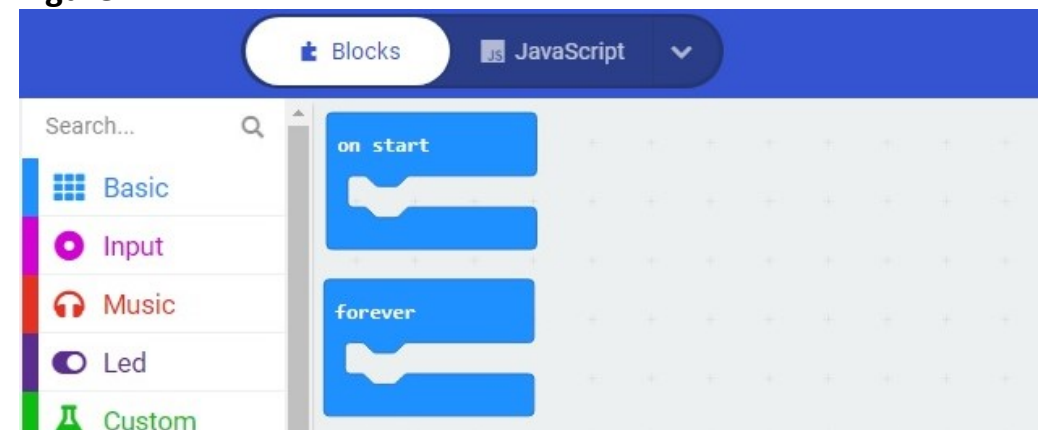
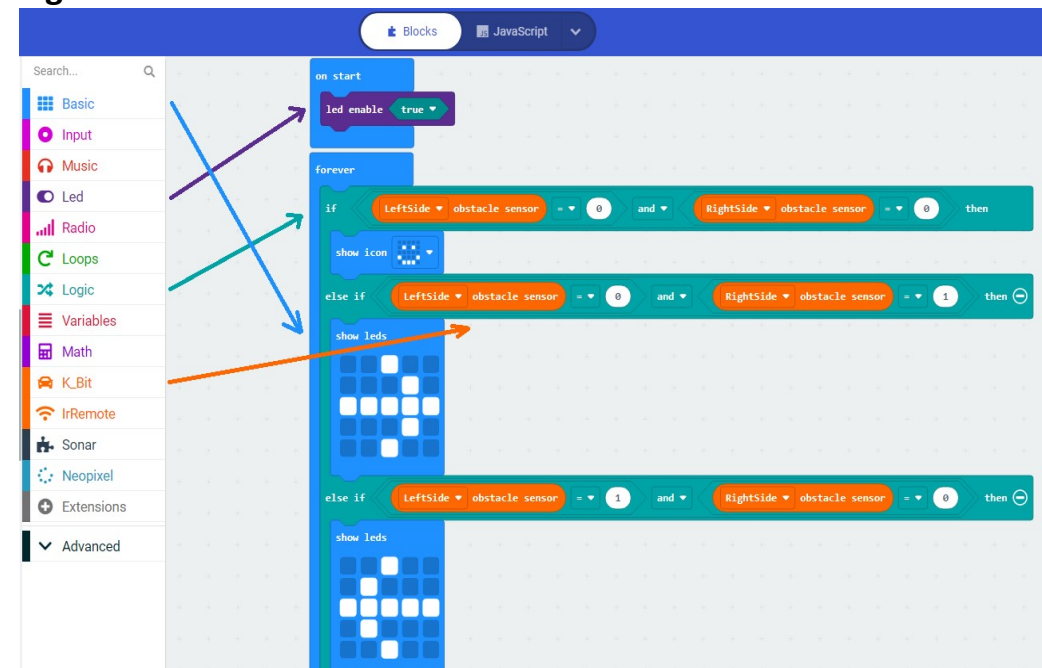


Figure 2



Example Infrared Obstacle Avoidance Display can be found at <https://makecode.microbit.org/86944-10749-06987-90752>

STEM Smart Robot can be purchase from Altronics.

<https://www.altronics.com.au/p/z6454-stem-microbit-mini-smart-robot-car-v2.0/>