

Lesson 1.0 - Passive Buzzer Control

Simulation of this lesson can be found at <https://makecode.microbit.org/18429-56003-51155-13829>

Note: (Robot construction must be completed before this Step)

Goal for this lesson

Learn to control the buzzer on the micro:bit, basic “blocks” coding & variable manipulation.

Hardware Required

PC or Tablet

1 x micro USB cable

1 x Smart Robot and micro:bit board

Step 1 As per Figure 1

- Goto URL <https://makecode.microbit.org/#>
- Create “+New Project” & give it a name
- Press **Gear** symbol – top right
- Press Extensions
- Add repository found using link below.
https://github.com/AltronicsAUKits/Z6454-Robot-Kit-v2_KS0426
- Press “Basic” Tab
- Drag “on start” into your work space “on the right hand side”
- Drag “forever” into work space

Step 2 As per Figure 2

- Press “... more” Tab – below the Led tab
- Drag “led enable false” into the “on start” field, ensure the variable is set to “false”

Step 3 As per Figure 3

- Press “Music” Tab
- Drag “play tone Middle C for 1 beat” into “forever” field
- Now in the work space press on “Middle C” and choose a different tone as below.



- Now press on “1 beat” and choose the length of the beat as below.



- Repeat **Step 3** and add additional tones to generate a tune.
- Download the code to the micro:bit.

Example tune can be found at.

<https://makecode.microbit.org/18429-56003-51155-13829>

STEM Smart Robot can be purchase from Altronics.

<https://www.altronics.com.au/p/z6454-stem-microbit-mini-smart-robot-car-v2.0/>

Scan QR code for Lesson 1.0 Simulation

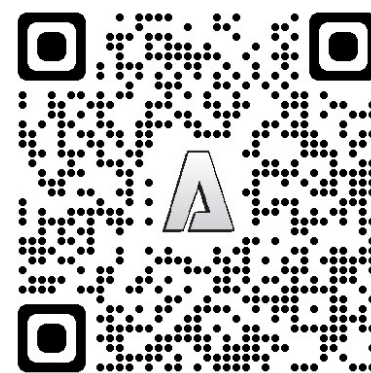


Figure 1

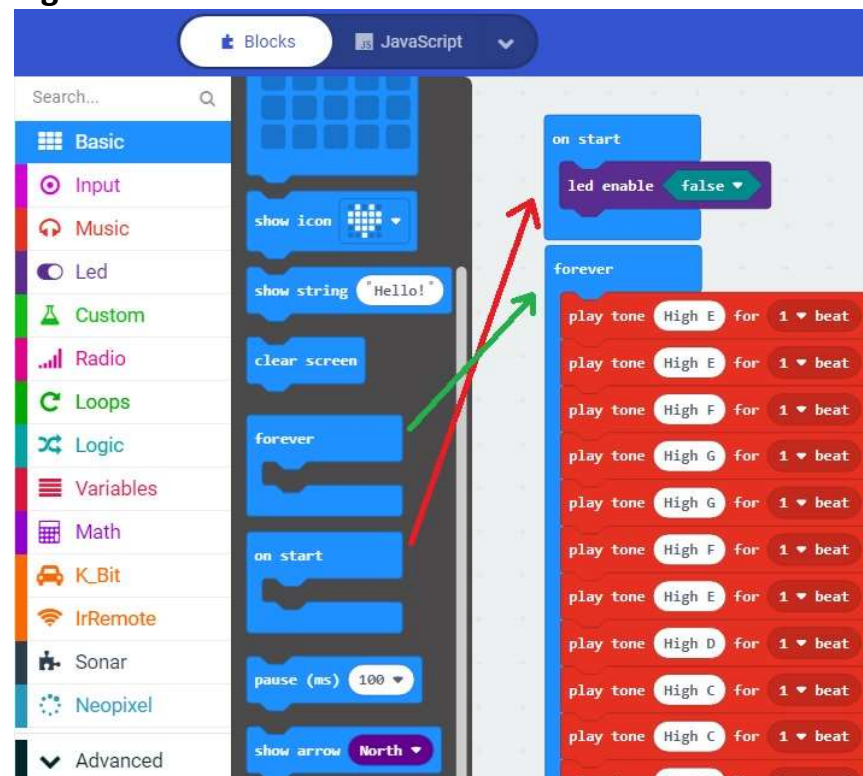


Figure 2

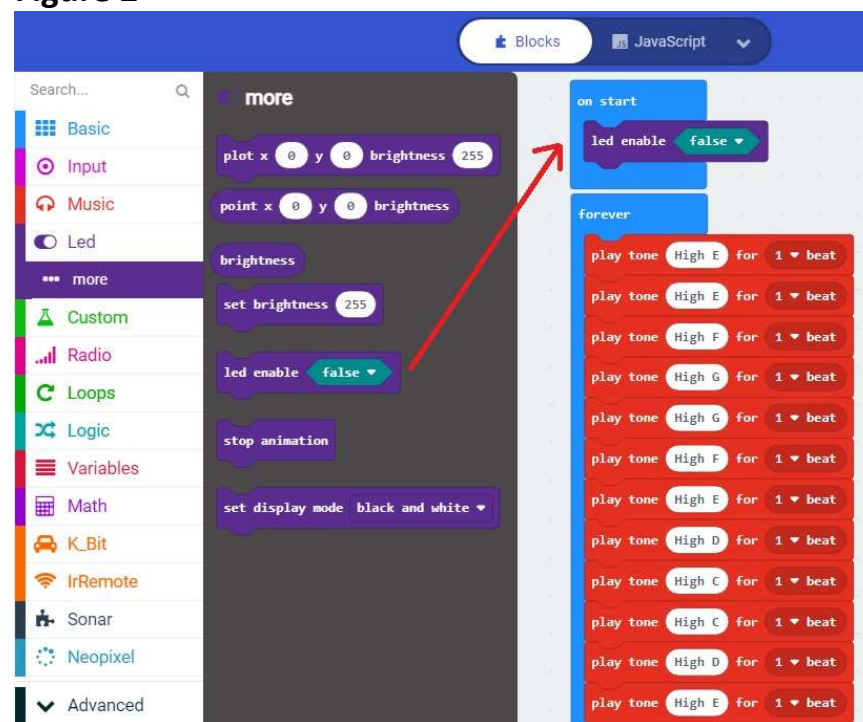


Figure 3

