

## Lesson 4.2 - Robot Photosensor Demo

Simulation of this lesson can be found at <https://makecode.microbit.org/70425-35912-57266-50967>

**Note:** (Robot construction must be completed before this Step)

### Goal for this lesson

Learn to control and utilise the onboard photo resistor, any changes read by the photo resistor will cause the Neopixel LED strip to change colour.

### Hardware Required

PC or Tablet

1 x micro USB cable

1 x Smart Robot with micro:bit & battery installed

### Step 1 as per Figure 1

- Goto URL <https://makecode.microbit.org/#>
- Create **"New Project"** & give it a name
- Press **Gear** symbol & Press **Extensions**
- Add repository [https://github.com/AltronicsAUKits/Z6454-Robot-Kit-v2\\_KS0426](https://github.com/AltronicsAUKits/Z6454-Robot-Kit-v2_KS0426)
- Move **"forever"** block below **"on start"** block.

### Step 2 as per Figure 2

- Press **"Variables"** Tab
- Press **"Make a Variable"**
- Create **"val"**
- Drag **"set val to 0"** into **"forever"**
- Press **"Math"** Tab
- Drag **"map 0 from low 0 high 1023 to low 0 high 4"** to **0** spot on **"set val to 0"**
- Adjust **"high 4"** to **"high 255"**
- Press **"K\_Bit"** Tab
- Drag **"photoresistor"** into **0** spot on **"map 0"**
- Press **"Neopixel"** Tab
- Drag **"strip show color red"** into **"forever"**
- Press **"Neopixel"** Tab, Press **"...more"** Tab
- Drag **"red 255 green 255 blue 255"** into **"color red"** position
- Press **"Math"** Tab
- Drag **"0 -v 0"** into **"red 255"** & Adjust **"0 -v 0"** to be **"255 -v 0"**
- Press **"Variables"** Tab
- Drag **"val"** into **0** location of **"red 255 -v 0"**
- Press **"Math"** Tab
- Drag **"0 -v 0"** into **"green 255"** & Adjust **"0 -v 0"** to be **"255 -v 0"**
- Press **"Variables"** Tab
- Drag **"val"** into **0** location of **"green 255 -v 0"**
- Press **"Math"** Tab
- Drag **"0 -v 0"** into **"blue 255"** & Adjust **"0 -v 0"** to be **"255 -v 0"**
- Press **"Variables"** Tab
- Drag **"val"** into **0** location of **"blue 255 -v 0"**
- Press **"Basic"** Tab
- aa. Drag **"pause (ms) 100"** into **"forever"** field

### Step 3 as per Figure 3

- Press **"Variables"** Tab
- Drag **"set strip to 0"** into **"on start"**, Change to **"strip"** to **"val"**
- Press **"Neopixel"** Tab
- Drag **"set strip to NeoPixel at pin P0 with 24 leds as RGB (GRB format)"** into **"on start"**  
Above item may read **"set strip 2"**, If need be change to **"set strip"**
- Adjust **pin P0** to **pin P5**, Adjust **24 leds** to **18 leds**
- Drag **"strip clear"** into **"on start"**
- Download the code to the micro:bit.

Example Photo sensor Demo can be found at

<https://makecode.microbit.org/70425-35912-57266-50967>

STEM Smart Robot can be purchase from Altronics.

<https://www.altronics.com.au/p/z6454-stem-microbit-mini-smart-robot-car-v2.0/>

Scan QR code for Lesson 4.2 Simulation

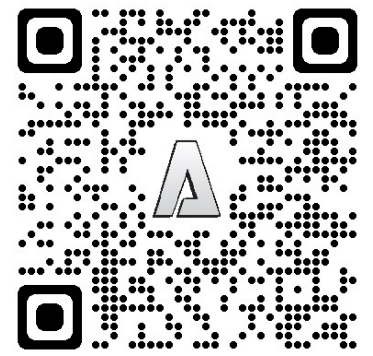


Figure 1

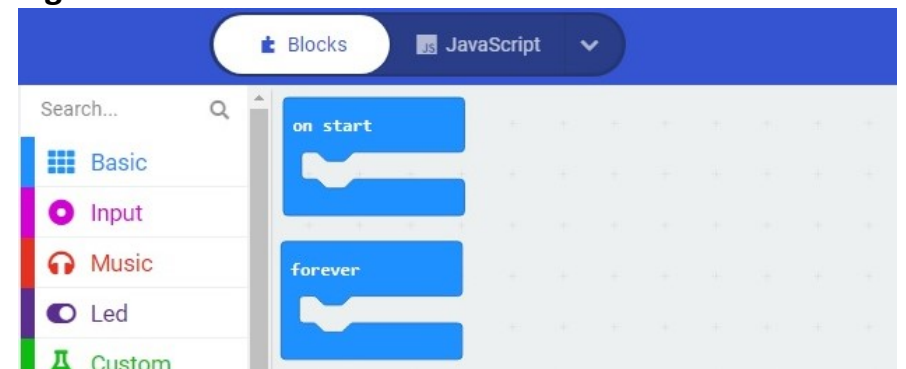


Figure 2

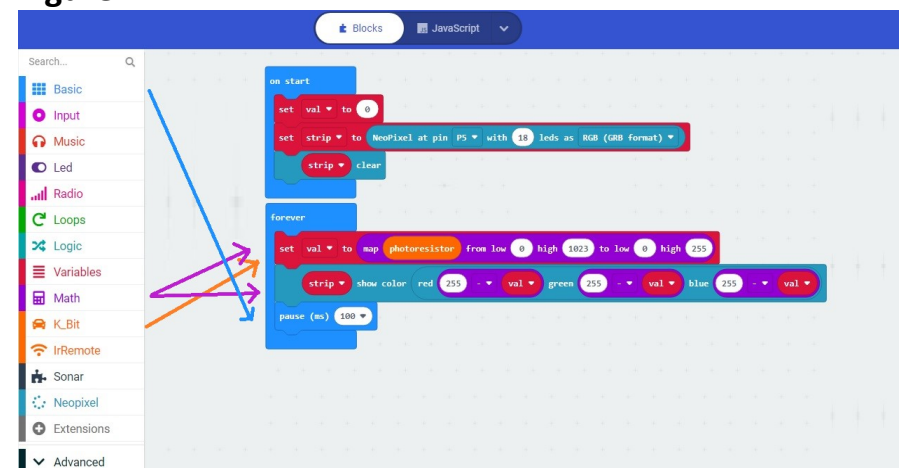


Figure 3

