T ☐ **T** - Smart Robot v2 - Altronics Z6454

Lesson 6.4 - **Line Tracking Smart Robot Demo**

Simulation of this lesson can be found at https://makecode.microbit.org/55144-14870-92905-74154

Note: (Robot construction must be completed before this Step)

Goal for this lesson

Learn to utilise the photo interrupter to control the motors and navigate a line, the NeoPixel LED will also illuminate based on the set variables.

Hardware Required

PC for data logging

1 x micro USB cable

1 x Smart Robot with micro:bit & battery installed

Step 1 As per Figure 1

- a. Goto URL https://makecode.microbit.org/#
- **b.** Create "+New Project" & give it a name
- c. Press Gear symbol top right
- d. Press Extensions
- e. Add repository found using link below. https://github.com/AltronicsAUKits/Z6454-Robot-Kit-v2_KS0426
- f. On start up both "on start" & "forever" will be in your work space, move "forever" block below "on start" block.

Step 2 as per Figure 2

Moving forward we will only highlight the locations for the required modules to produce the desired code.

- a. We will be utilising the "Logic" Tab
- b. We will be utilising the "Variables" Tab
- c. We will be utilising the "K_Bit" Tab
- d. We will be utilising the "NeoPixel" Tab
- e. Download the code to the micro:bit

Expected Result!

- a. When powered up a smiley face will appear on the matrix display and the NeoPixel Display will illuminate.
- b. With the robot placed over a black line on white paper it will begin to track the line by using the photo interrupters on the base.
- c. It will repeatedly check the logic and compare the photo interrupter outputs to continue to adjust the motors.

Scan QR code for Lesson 6.4 Simulation

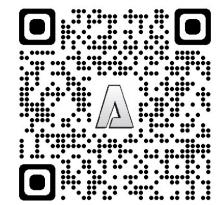
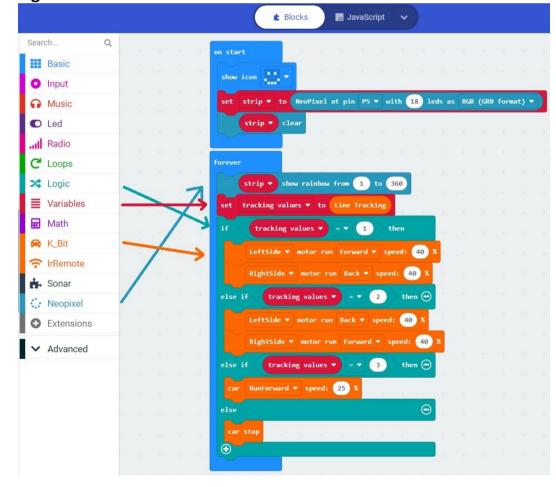




Figure 2



Example Line Tracking Smart Robot Demo can be found at https://makecode.microbit.org/55144-14870-92905-74154

STEM Smart Robot can be purchase from Altronics. https://www.altronics.com.au/p/z6454-stem-microbit-mini-smart-robot-car-v2.0/



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