### 4 صفر 1442 21 September 2020

### وَمَا أُوتِيتُوْ مِنَ الْعِلْمِ إِلَّا هَلِيلًا

Ain Shams University – Faculty of Engineering – ECE Dept. – Integrated Circuits Lab.

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### **Analog IC Design**

### Lab 11 (Mini Project 02)

### Fully-Differential Folded Cascode OTA

## **Intended Learning Objectives**

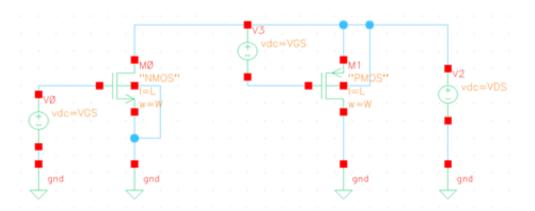
In this lab you will:

- Learn how to generate and use gm/ID design curves.
- Learn how to design a fully-differential folded-cascode OTA achieving given specifications.
- Learn how to simulate the open-loop characteristics of the fully-differential folded-cascode OTA.
- Learn how to simulate the closed-loop characteristics of the fully-differential folded-cascode OTA.
- Learn how to design the common-mode feedback circuit for the OTA.

## PART 1: gm/ID Design Charts

Use the following sweep ranges to characterize NMOS and PMOS transistors.

- W = 10um
- L = 0.2um:0.2um:5um → parametric sweep
- VGS ≈ (VTH-100m):5m:(VTH+VDD/3) → DCsweep
- VDS = VDD/3



Export simulation results to a csv file then import it in MATLAB.

→ Cadence Hint: In order to save OP point parameters vs DC sweep variable, create an empty text file and write the following statement (without quotes): "save \*:oppoint sigtype=dev". Add this text file in adexl (Setup -> Model Libraries). If you are using SPICE models (e.g., Arizona PTM models) you need to add this statement at the beginning of the text file to switch back to Spectre (without quotes): "simulator lang = spectre".

#### Plot the following design charts vs gm/ID for both PMOS and NMOS1:

- 1) gm\*ro
- 2) ID/W
- 3) gm/Cgg
- 4) VGS

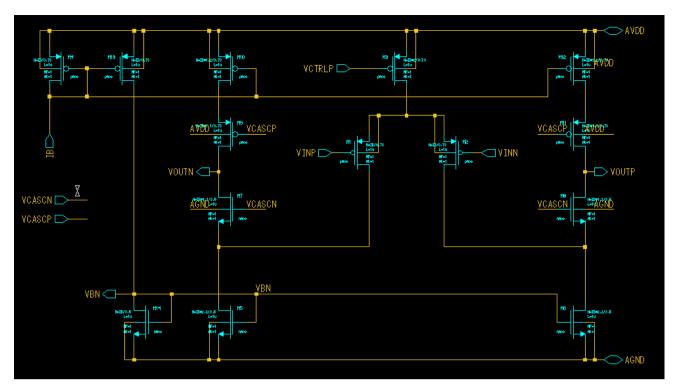
## PART 2: OTA Design

Design a fully-differential folded cascode OTA with capacitive feedback that meets the specifications below. The current consumed in the biasing branches (current mirrors) is not included in the specifications.

Technology	0.13um	0.18um
Supply voltage	1.2V	1.8V
Closed loop gain	2	2
Phase margin	>= <b>70</b> °	>= <b>70</b> °
OTA current	<= 80uA	<= 80uA
CMFB circuit current	<= 40uA	<= 40uA
CM input range – low	<= 0	<= 0
CM input range – high	>= 0.6V	>= 1.1V
Differential output swing	0.6Vpk-to-pk	1.2Vpk-to-pk
Load	1pF	1pF
DC Loop gain	50dB	60dB
Closed loop bandwidth	10MHz	10MHz

Note: The DC loop gain and closed loop bandwidth specs may be difficult to include (precisely) in the initial hand analysis. After following the suggested design procedure, you may tune the circuit on the simulator (while taking trade-offs into account) to achieve these specs.

<sup>&</sup>lt;sup>1</sup> While viewing MATLAB figure, use "View -> Plot Browser" to view the legend and enable or disable curves. While using the data cursor, right click on the cursor and select "Selection Style -> Mouse Position".



You can use the following ideal sources in your testbench:

- A single 20uA DC current source
- A DC voltage source for VDD
- Two DC voltage sources for biasing the cascode transistors (VCASCP and VCASCN)
- A DC voltage source for the CM output level (VREF)

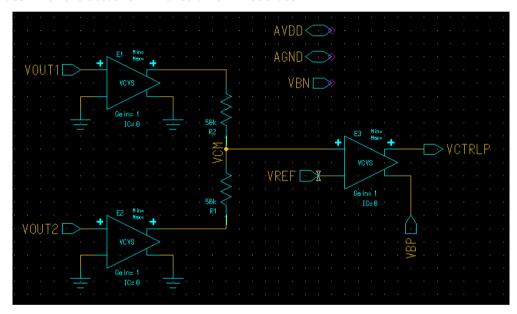
### **→** Suggested Design Procedure:

- 1) From the CMIR spec you will find that you need a PMOS input stage as shown in the schematic above.
- 2) The OTA current will be divided as follows: ISS = 40uA for the input pair (CS), and 40uA for the cascode branches (CG). The NMOS current sources in the bottom needs to sink 80uA (2 x 40uA). For more details on how to select the folded cascode current split check this paper: "Optimum Split Ratio for Folded Cascode OTA Bias Current: A Qualitative and Quantitative Study" DOI: 10.1109/ICM48031.2019.9021755.
- 3) Since this is a relatively difficult design, we will directly assume values for L and gm/ID (or V\*) based on designer's experience and folded cascode trade-offs matrix.
  - For the input pair use short L and bias it in MI or WI, e.g., L = 0.2um and gm/ID = 15. This maximizes the GBW (good efficiency) and minimizes the input capacitive loading (avoid reducing the DC LG).
     You will have to tune your gm/ID to achieve the CL bandwidth spec.
  - For the current source transistors use relatively long L and bias them in SI, e.g., L = 1um and gm/ID =
     10. These transistors contribute significant offset and noise. A large gm will not help the gain but will increase the noise.

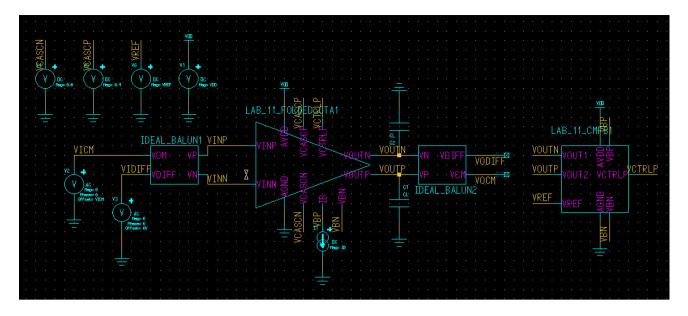
- For the cascode transistors use moderate L and bias them in MI or WI, e.g., L = 0.5um and gm/ID =
   15. These transistors do not contribute significant offset and noise, so they don't need to be large. A large gm helps the gain and doesn't increase the noise.
- These assumptions greatly simplify the design process and can be later tuned in simulations (taking the trade-offs matrix into consideration) to achieve exact specifications.
- 4) From the assumed L and  $gm/ID(V^*)$ , use the charts to find the sizing (W) of all transistors.
- 5) From the assumed V\*, select suitable biasing for the cascode transistors (VCASCP and VCASCN). Hint: Set VCASCN  $\approx$  VGSN + V\* and VCASCP  $\approx$  VDD |VGSP| V\*

## PART 3: Open-Loop OTA Simulation (Behavioral CMFB)

We will start with a behavioral CMFB network similar to the one shown below. We use ideal buffers to avoid loading the OTA output with the CM sensing resistors. Note that we don't need high gain in the CMFB loop (why?); thus, we use a gain = 1 in the error amplifier. We use dummy pins in the behavioral CMFB circuit to be "pin-accurate" with the actual CMFB circuit we will use later.



Create a testbench similar to the one shown below.



#### Report the following:

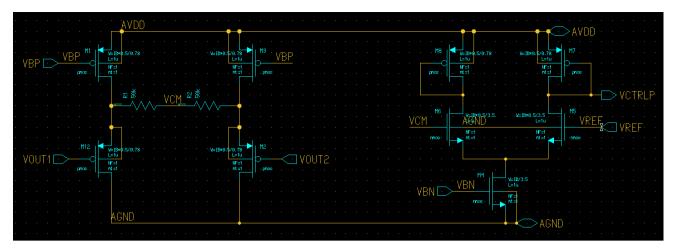
- 1) Schematic of the OTA and bias circuit with DC node voltages and transistors OP parameters (id, vgs, vds, vdsat, vth, gm, gds, region) clearly annotated.
  - Set VICM at the middle of the CMIR.
  - Select VREF to maximize the symmetrical output swing.
  - What is the CM level at the OTA output?
  - What are the differential input and output voltages of the error amplifier? What is the relation between them?
- 2) Diff small signal ccs:
  - Use AC analysis (1Hz:10Gz, logarithmic, 10 points/decade).
  - Set VIDAC = 1 and VICMAC = 0.
  - Set VICM at the middle of the CMIR.
  - Plot diff gain (magnitude in dB and phase) vs frequency.
  - Calculate circuit parameters (DC gain, BW, GBW, UGF, and PM).
- → Cadence Hint: Use Cadence calculator expressions to calculate circuit parameters (Ao, Ao in dB, BW, GBW, UGF). You may use Cadence calculator to create other useful expressions.

	Name	Type	Expression/Signal/File
	Ao	expr	ymax(mag(VF("/VOUT")))
	Ao_dB	expr	dB20(ymax(mag(VF("/VOUT"))))
	BW	expr	bandwidth(VF("/VOUT") 3 "low")
	fu	expr	unityGainFreq(VF("/VOUT"))
	GBW	expr	(Ao * BW)

 Compare simulation results with hand calculations in a table (use SS parameters from OP simulation in your hand analysis).

## PART 4: Open-Loop OTA Simulation (Actual CMFB)

Inside the CMFB cell, create a new schematic view for the actual CMFB circuit as shown below.



Note the following in the CMFB circuit design:

- The 40uA current is divided between the four CMFB branches. You may assume L = 1um and gm/ID = 15 for all transistors with unknown L or gm/ID for simplicity (note that L and gm/ID for some transistors are already known, why?).
- We need CD (source followers) to buffer the OTA output. This avoids loading the OTA with the sensing resistors<sup>2</sup>.
- The sensing resistors are chosen such that the max current flowing through them (when diff signal is max) is less than the CD bias current. This avoids starving the CD when the diff output signal has its maximum excursion.
- The CD introduces DC shift. Thus, the input to the error amplifier is not Vocm. Instead, it is Vocm + |VGSP|. Thus, you need to set VREF to VREF+ |VGSP|. A better approach is to apply VREF to an identical CD buffer, so that it experiences the same |VGSP| shift.
- The CMFB limits the output swing. Max Vout is VDD V\* |VGSP|. One reason why we selected PMOS CD is to avoid increasing VTH by body effect (increasing VTH will limit output swing even more).
- The output range now is from  $2V^*$  to  $VDD V^* |VGSP|$ . Select Vocm to be around the middle of this range to have maximum symmetric output swing (it will be different from the value selected in the behavioral model).
- The output of the CD buffer is close to VDD; thus, we select NMOS input for the error amplifier.
- The error amplifier is a simple differential amplifier with diode connected loads. We don't need high
  gain from the error amplifier, but we need low impedance nodes to avoid deteriorating the stability
  of the CMFB loop.
- The bias point output of the error amplifier is equal to VDD |VGSP|. That's why we use the error
  amplifier output to control the PMOS current source in the folded OTA rather than the NMOS
  current source.

<sup>&</sup>lt;sup>2</sup> Note that this type of CMFB will have a limited linear range and may affect the output swing specification.

 Note that we select the non-inverting error amplifier output to maintain -ve feedback in the CMFB loop.

Use hierarchy editor to change the model of the CMFB circuit to use the actual circuit instead of the behavioral one.

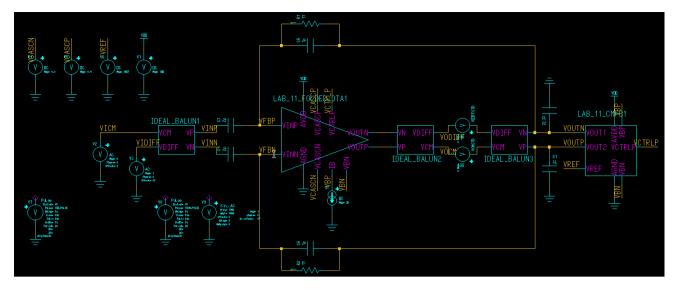
#### Report the following:

- 1) Schematic of the OTA and CMFB circuit with DC node voltages and transistors OP parameters (id, vgs, vds, vdsat, vth, gm, gds, region) clearly annotated.
  - Set VICM at the middle of the CMIR.
  - What is the CM level at the OTA output? Why?
  - What are the differential input and output voltages of the error amplifier? What is the relation between them?
- 2) Diff small signal ccs:
  - Use AC analysis (1Hz:10Gz, logarithmic, 10 points/decade).
  - Set VIDAC = 1 and VICMAC = 0.
  - Set VICM at the middle of the CMIR.
  - Plot diff gain (magnitude in dB and phase) vs frequency.
  - Calculate circuit parameters (DC gain, BW, GBW, UGF, and PM).

### PART 5: Closed Loop Simulation (AC and STB Analysis)

Create a new testbench with the OTA connected in closed-loop feedback configuration using capacitive feedback as shown below. Note that the CM DC level provided before the input balun is useless because it is blocked by the capacitor.

Note that we use two baluns at the output in order to allow stability analysis. We divide the output to diff and CM and break the diff/CM loops by 0V dc sources, then we combine them again to VOUTN and VOUTP to close the feedback loop. We use a 2pF input capacitance and 1pF feedback capacitance to provide a closed loop gain = 2. Note that you need to connect VOUTN to VINP and VOUTP to VINN to maintain negative feedback. We use large resistors across the feedback capacitance to close the loop in DC. This will set Vicm = Vocm.



→ Cadence Hint: Instead of using two baluns at output, you can use diffstbprobe (or cmdmprobe in older versions) to simulate LG of differential and CM loops.

#### Report the following:

- 1) Schematic of the OTA and the CMFB circuit with DC OP point clearly annotated in closed-loop configuration.
  - What is the CM level at the OTA output? Why?
  - What is the CM level at the OTA input? Why?
- 2) Differential closed-loop response:
  - Use AC analysis (1Hz:10Gz, logarithmic, 10 points/decade).
  - Set VIDAC = 1 and VICMAC = 0.
  - Plot VODIFF vs frequency
  - Use Measures or cursors to calculate circuit parameters (DC gain, CL BW, CL GBW)
- 3) Differential and CMFB loops stability (STB analysis):
  - Run STB analysis (in addition to AC analysis 1Hz:10Gz, logarithmic, 10 points/decade) **two times**: first using the OV source in the diff path, and second using the OV source in the CM path.
  - Plot loop gain in dB and phase vs frequency for the two simulations overlaid.
  - Compare GBW and PM of diff and CM loops. Comment.
  - Compare DC LG and GBW of the diff loop with those obtained from open-loop simulation.
     Comment

## PART 6: Closed Loop Simulation (Transient Analysis)

Use the same testbench as in Part 5, but change diff and CM input sources as explained below.

#### Report the following:

1) Differential and CMFB loops stability (transient analysis):

- Apply a differential input pulse (initial value = 0, pulse value = 100mV, delay = 1us, period = 2us, pulse width = 1us, rise = fall = 10ns).
- Run transient analysis for 3us with 10ns max step.
- Plot the transient signals at VINP, VINN, VOUTP, VOUTN, and VOCM overlaid in the same figure.
- Do you notice any differential/CM ringing? Are both loops stable with adequate PM?
- Set differential input to zero and apply the same previous pulse at the balun CM input.
- Run transient analysis for 3us to test the fully differential capacitive amplifier stability.
- Plot the transient signals at VINP, VINN, VOUTP, VOUTN, and VOCM overlaid in the same figure.
- Do you notice any differential/CM ringing? Are both loops stable with adequate PM?

#### 2) Output swing:

- Apply a differential sinusoidal input with freq = 100kHz and amplitude = 150mV.
- Run transient analysis for three periods (30us) with 0.1us max time step.
- Plot the transient signals at VINP, VINN, VOUTP, VOUTN, and VOCM overlaid in the same figure.
- Plot the transient signals at VIDIFF and VODIFF overlaid in the same figure.
- Calculate the diff input and output peak-to-peak swings and the closed loop gain.

### **Lab Summary**

- In Part 1 you learned:
  - How to generate and use gm/ID design curves.
- In Part 2 you learned:
  - How to design a fully-differential folded cascode OTA meeting desired specifications.
- In Part 3 you learned:
  - o How to set the CM output voltage of a fully-differential OTA with an ideal CMFB circuit.
  - How to simulate the small-signal differential characteristics of a fully-differential folded cascode OTA in open-loop configuration with an ideal CMFB circuit.
- In Part 4 you learned:
  - How to design a CMFB circuit.
  - o How to set the CM output voltage of a fully-differential OTA with an actual CMFB circuit.
  - o How to simulate the small-signal differential characteristics of a fully-differential folded cascode OTA in open-loop configuration with a real CMFB circuit.
- In Part 5 you learned:
  - How to simulate the small-signal differential gain of a fully-differential folded cascode OTA in closed-loop configuration with a real CMFB circuit.
  - How to simulate the stability of both the main OTA loop and the CMFB loop of a fullydifferential folded cascode OTA in closed-loop configuration.
- In Part 6 you learned:
  - How to simulate the stability of both the main OTA loop and the CMFB loop of a fullydifferential folded cascode OTA using transient simulation.
  - How to simulate the output swing of both the main OTA loop and the CMFB loop of a fullydifferential folded cascode OTA using transient simulation.

# Acknowledgements

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