Burgers' Equation

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Burgers' equation

- Burgers' equation
- Numerical Weather Prediction

- Burgers' equation
- Numerical Weather Prediction
- Explicit Approaches

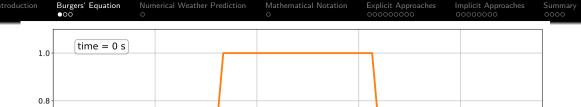
- Burgers' equation
- Numerical Weather Prediction
- Explicit Approaches
- Implicit Approaches

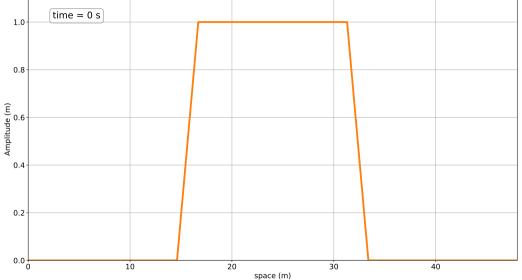
- Burgers' equation
- Numerical Weather Prediction
- Explicit Approaches
- Implicit Approaches
- Summary

Linear Convection

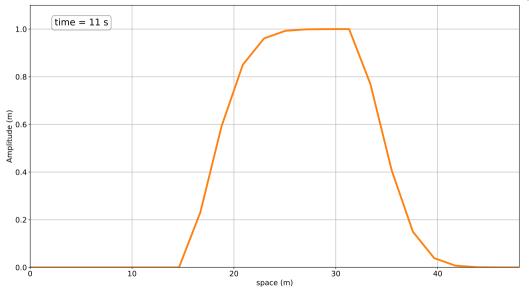
Propagation of a Wave with constant speed c

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = 0$$

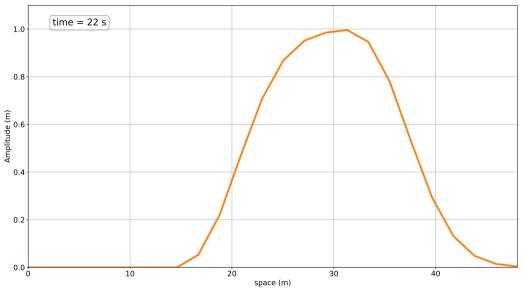




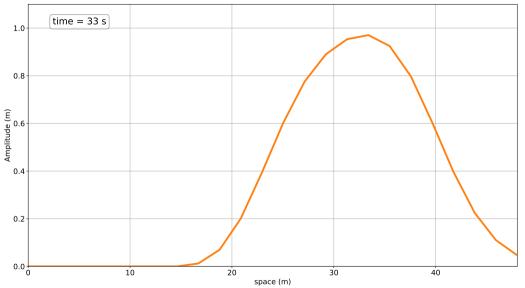




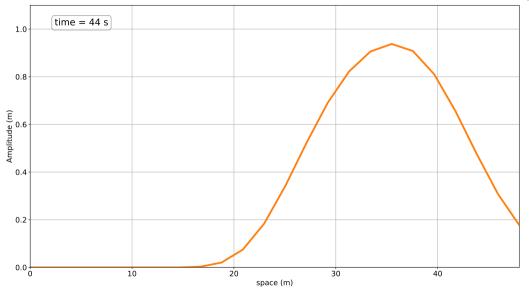




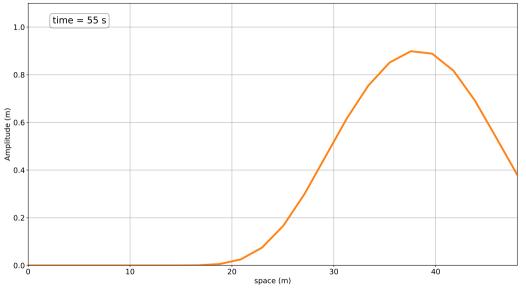




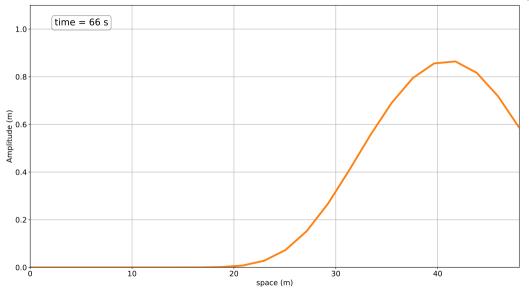




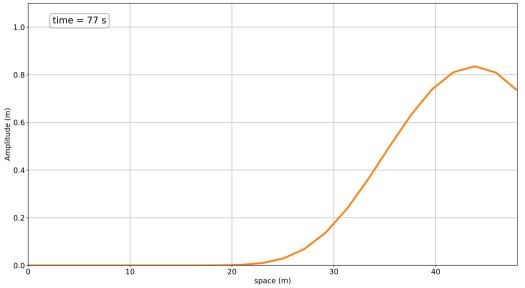




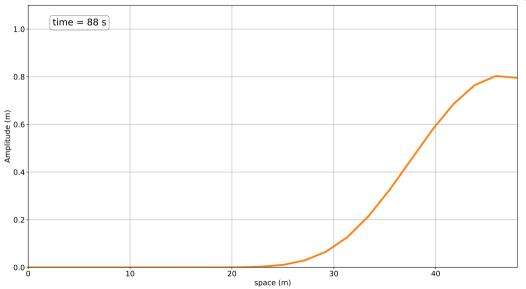


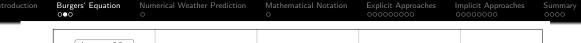


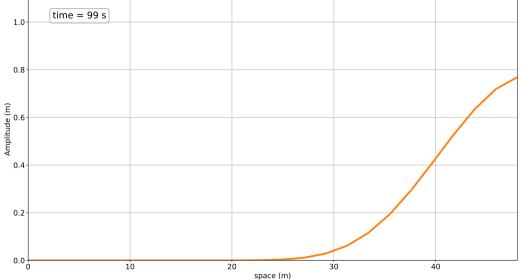












Viscous Burgers' equation

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = v \frac{\partial^2 u}{\partial x^2}$$

Viscous Burgers' equation

•

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = \nu \frac{\partial^2 u}{\partial x^2}$$

Inviscid Burgers' equation

•

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$$

Viscous Burgers' equation

•

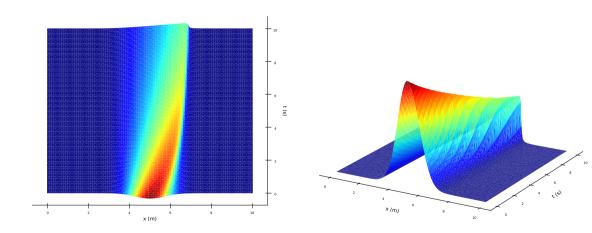
$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = v \frac{\partial^2 u}{\partial x^2}$$

Inviscid Burgers' equation

•

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$$

- Appears in
 - Fluid dynamics
 - Nonlinear acoustics
 - Traffic flow



duction Burgers' Equation Numerical Weather Prediction Mathematical Notation Explicit Approaches Implicit Approaches Summary

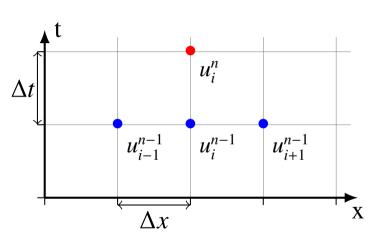
Numerical Weather Prediction



 $Reference: \ {\tt https://www.frontiersin.org/files/Articles/346275/fenvs-06-00013-HTML/image_m/fenvs-06-00013-g001.jpg}$

Mathematical Notation

- Discretization
 - u_i^n is the point to be calculated
 - i-1 is a step back in space
 - ullet n-1 is a step back in time
 - \bullet Δt is the step size in time
 - ullet Δx is the step size in space



Explicit Euler Method

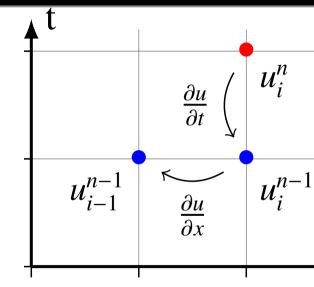
How to rewrtie our PDE?

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$$

Euler forwards

$$\frac{u_i^n - u_i^{n-1}}{\Delta t} + u_i^n \frac{u_i^{n-1} - u_{i-1}^{n-1}}{\Delta x} = 0$$

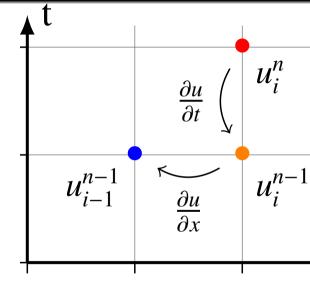
$$u_i^n = \frac{\Delta x \, u_i^{n-1}}{-\Delta t \, u_{i-1}^{n-1} + \Delta t \, u_i^{n-1} + \Delta x}$$



Euler forwards

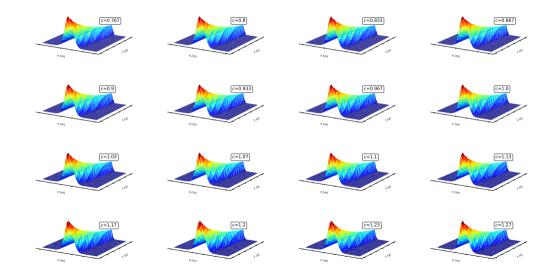
$$\frac{u_i^n - u_i^{n-1}}{\Delta t} + u_i^{n-1} \frac{u_i^{n-1} - u_{i-1}^{n-1}}{\Delta x} = 0$$

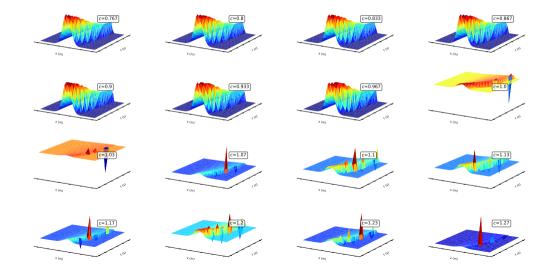
$$u_i^n = \frac{u_i^{n-1} \left(\Delta t \, u_{i-1}^{n-1} - \Delta t \, u_i^{n-1} + \Delta x \right)}{\Delta x}$$



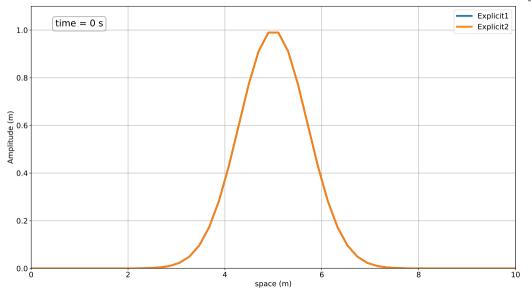
convergence condition by Courant–Friedrichs–Lewy

$$c = \frac{u \Delta t}{\Delta x} < 1$$

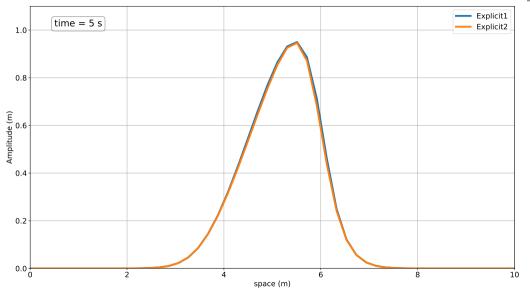




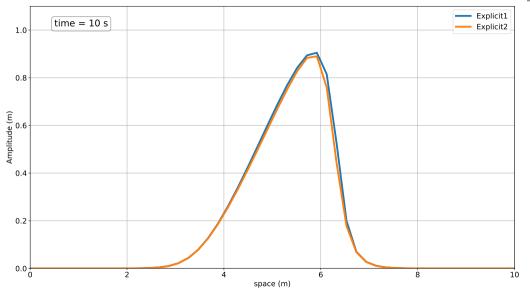




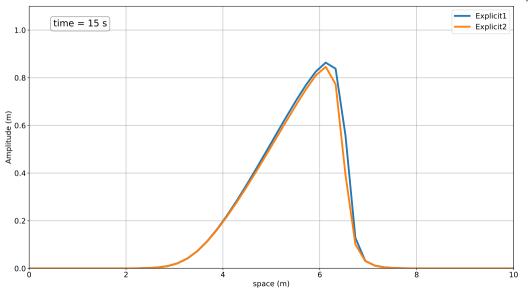




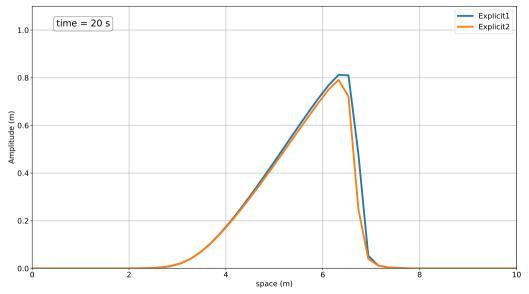




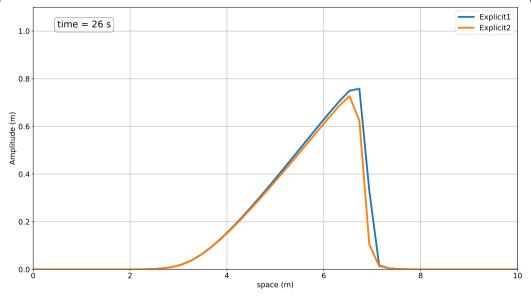




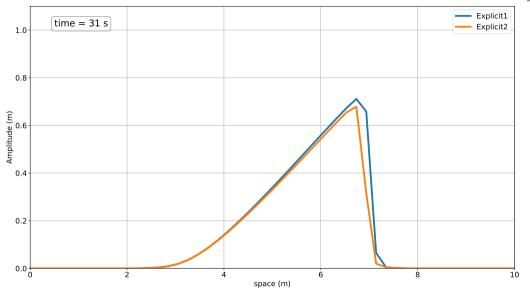




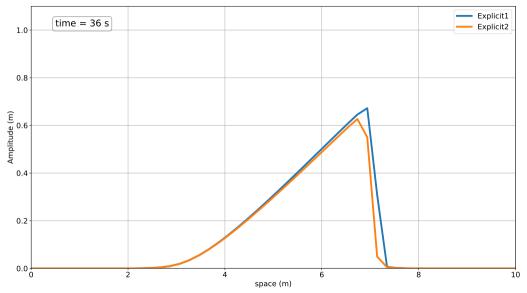




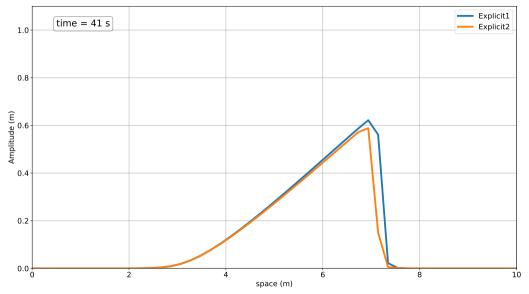




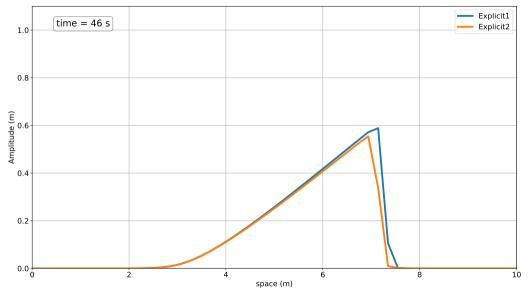




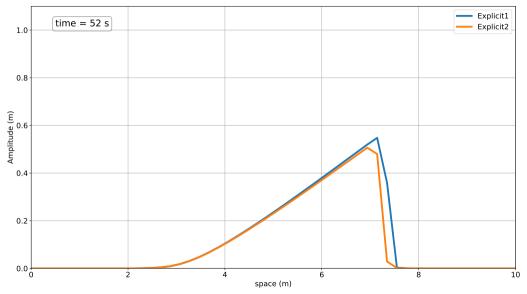




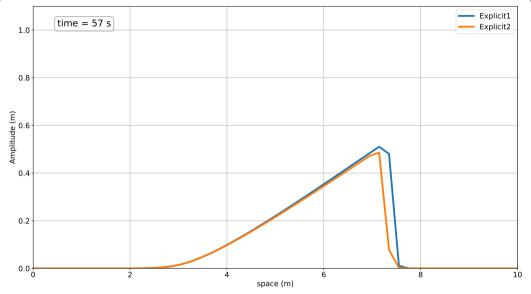




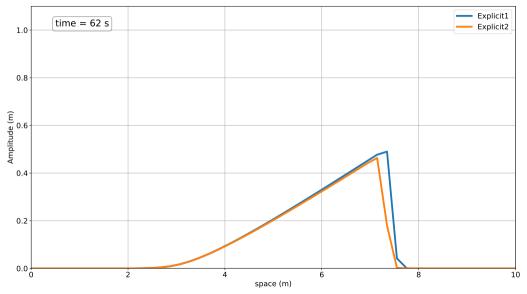




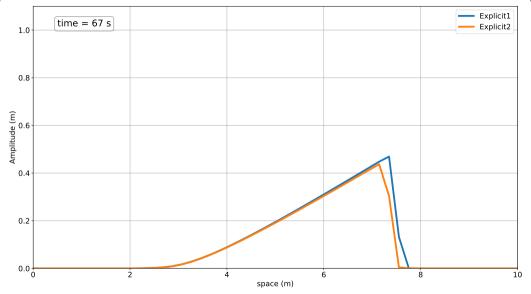




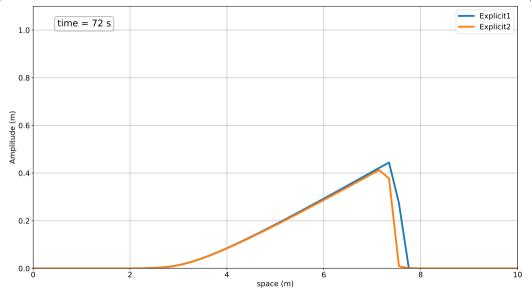




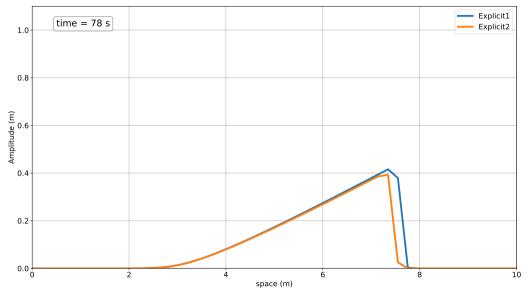




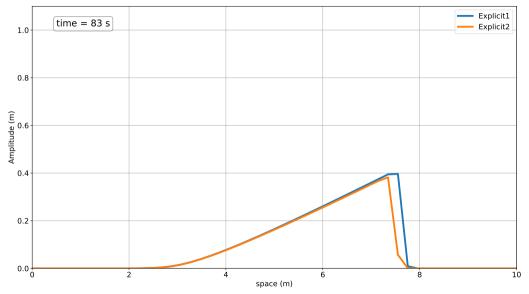




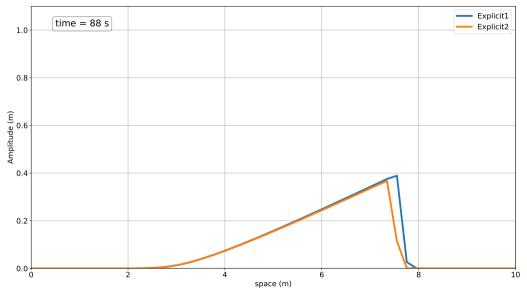




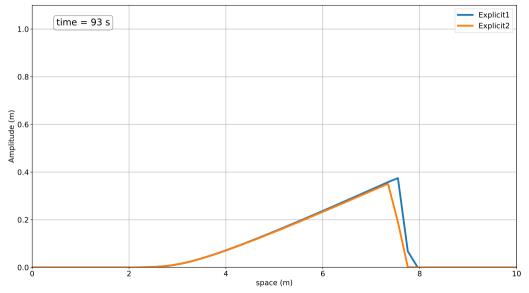




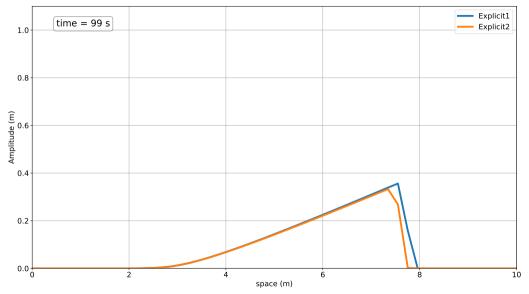


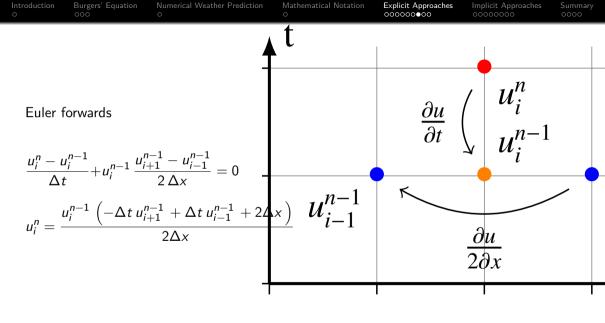








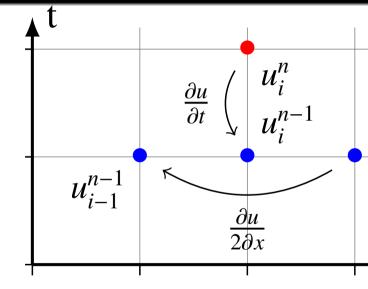




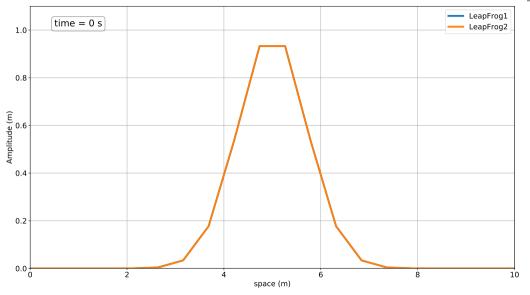
Euler forwards

$$\frac{u_i^n - u_i^{n-1}}{\Delta t} + u_i^n \frac{u_{i+1}^{n-1} - u_{i-1}^{n-1}}{2 \Delta x} = 0$$

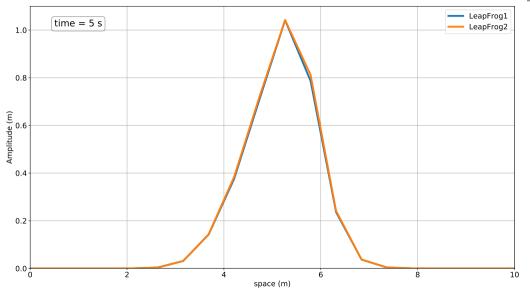
$$u_i^n = \frac{2\Delta x \, u_i^{n-1}}{\Delta t \, u_{i+1}^{n-1} - \Delta t \, u_{i-1}^{n-1} + 2\Delta x}$$



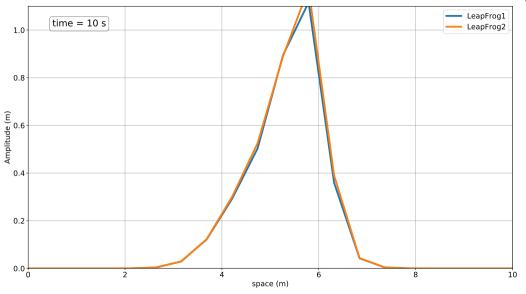




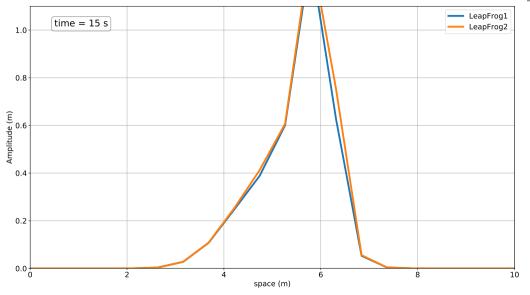




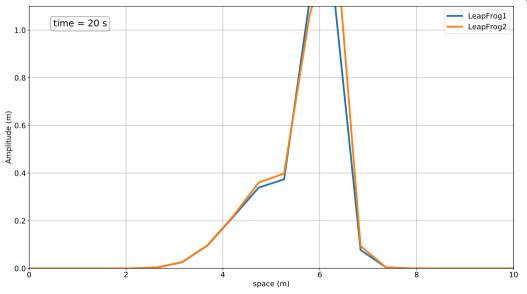




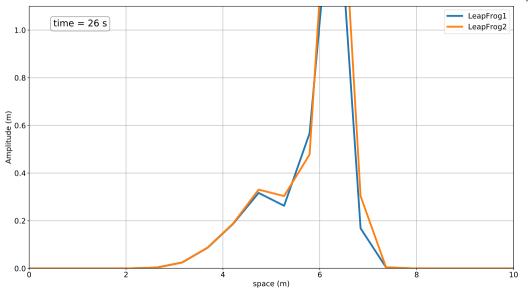




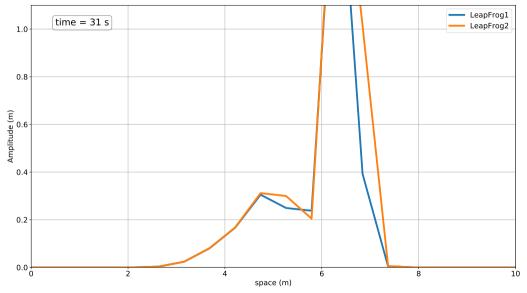




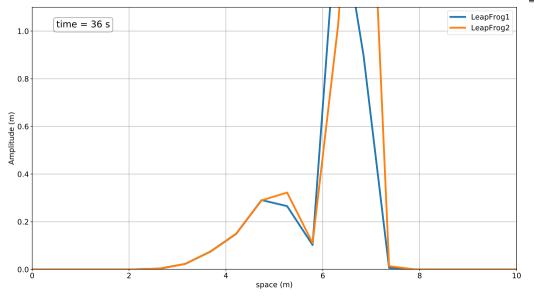




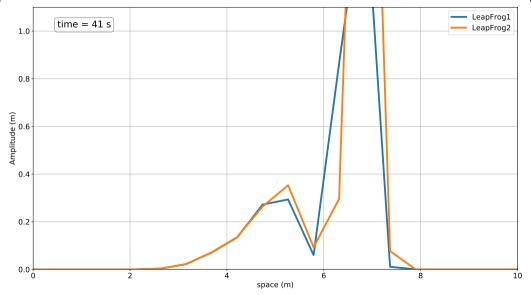




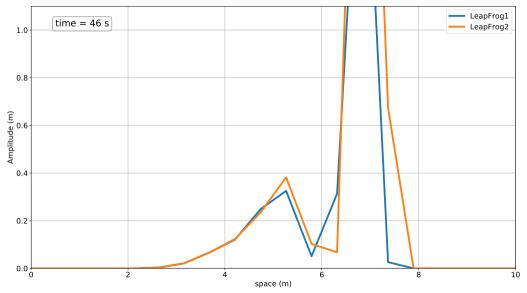


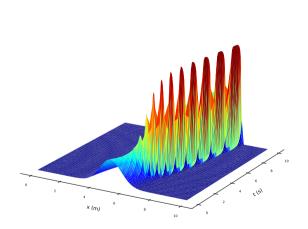


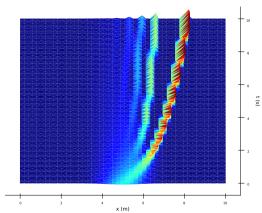








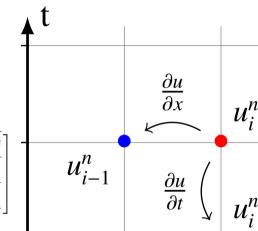




Euler backwards

$$\frac{u_i^n - u_i^{n-1}}{\Delta t} + u_i^n \frac{u_i^n - u_{i-1}^n}{\Delta x} = 0$$

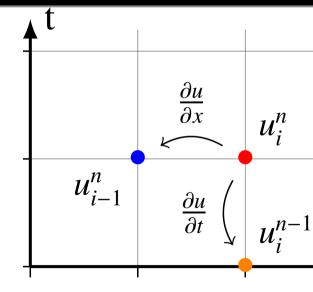
$$u_{i}^{n} = \begin{bmatrix} \Delta t \, u_{i-1}^{n} \, - \Delta x \, - \sqrt{\Delta t^{2} \left(u_{i-1}^{n}\right)^{2} + 4\Delta t \, \Delta x \, u_{i}^{n-1} \, - 2\Delta t \, \Delta x \, u_{i-1}^{n} \, + \Delta x^{2}} \\ \\ 2\Delta t \\ \\ \Delta t \, u_{i-1}^{n} \, - \Delta x \, + \sqrt{\Delta t^{2} \left(u_{i-1}^{n}\right)^{2} + 4\Delta t \, \Delta x \, u_{i}^{n-1} \, - 2\Delta t \, \Delta x \, u_{i-1}^{n} \, + \Delta x^{2}} \\ \\ 2\Delta t \end{bmatrix}$$



Euler backwards

$$\frac{u_i^n - u_i^{n-1}}{\Delta t} + u_i^{n-1} \frac{u_i^n - u_{i-1}^n}{\Delta x} = 0$$

$$u_i^n = \frac{u_i^{n-1} (\Delta t u_{i-1}^n + \Delta x)}{\Delta t u_i^{n-1} + \Delta x}$$



Implicit Euler method

Euler backwards $\frac{u_i^n - u_i^{n-1}}{\Delta t} + u_i^{n-1} \frac{u_{i+1}^n - u_{i-1}^n}{2 \Delta x} = 0$ $-u_i^{n-1} dt u_{i-1}^n + 2 dx u_i^n + u_i^{n-1} dt u_{i+1}^n = 2 dx u_i^{n-1}$

Implicit Euler method

$$-u_i^{n-1} dt u_{i-1}^n + 2 dx u_i^n + u_i^{n-1} dt u_{i+1}^n = 2 dx u_i^{n-1}$$

$$\begin{bmatrix} dx - u_1^n dt & u_1^n dt & 0 & 0 \\ -u_2^n dt & 2 dx & u_2^n dt & 0 \\ 0 & -u_3^n dt & 2 dx & \ddots & 0 \\ 0 & 0 & \ddots & \ddots & u_{M-1}^n dt \\ 0 & 0 & -u_M^n dt & dx + u_1^M dt \end{bmatrix} \begin{bmatrix} u_1^{n+1} \\ u_2^{n+1} \\ u_3^{n+1} \\ \vdots \\ u_M^{n+1} \end{bmatrix} = \begin{bmatrix} dx u_1^n \\ 2 dx u_2^n \\ 2 dx u_3^n \\ \vdots \\ dx u_M^n \end{bmatrix}$$

$$a_i x_{i-1} + b_i x_i + c_i x_{i+1} = d_i$$

$$\begin{bmatrix} b_1 & c_1 & & & & 0 \\ a_2 & b_2 & c_2 & & & \\ & a_3 & b_3 & \ddots & & \\ & & \ddots & \ddots & c_{n-1} \\ 0 & & & a_n & b_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \\ \vdots \\ d_n \end{bmatrix}$$

Algorithm 1 Tridiagonal matrix algorithm (Thomas algorithm)

1: function Thomas(a, b, c, d)

2:
$$\hat{c}_1 \leftarrow \frac{c}{b}$$

3:
$$\hat{d}_1 \leftarrow \frac{d_1}{b_1}$$

4: **for**
$$i = 2, 3, ..., n-1$$
 do

5:
$$\hat{c}_i \leftarrow \frac{c_i}{b_i - a_i \, \hat{c}_{i-1}}$$

$$\hat{d}_i \leftarrow \frac{d_i - a_i \, \hat{d}_{i-1}}{b_i - a_i \, \hat{c}_{i-1}}$$

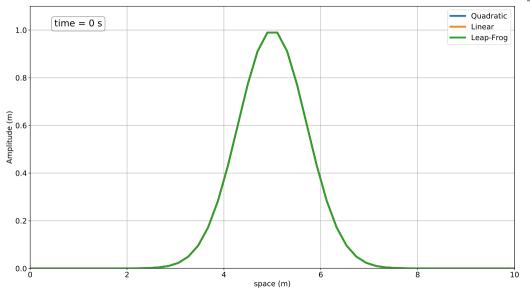
7:
$$x_n \leftarrow \hat{d}_n$$

8: **for**
$$i = n - 1, n - 2, ..., 1$$
 do

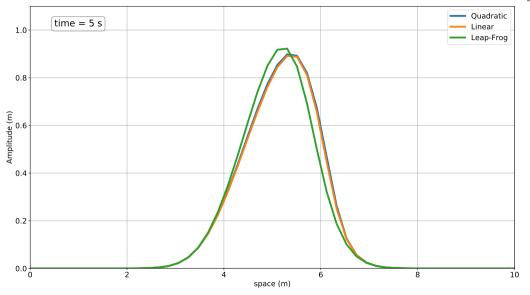
9:
$$x_i \leftarrow \hat{d}_i - \hat{c}_i x_{i+1}$$

▶ Backwards substitution

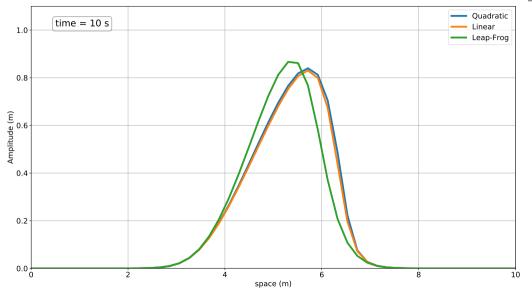




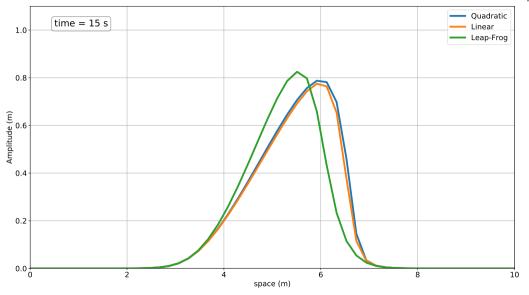




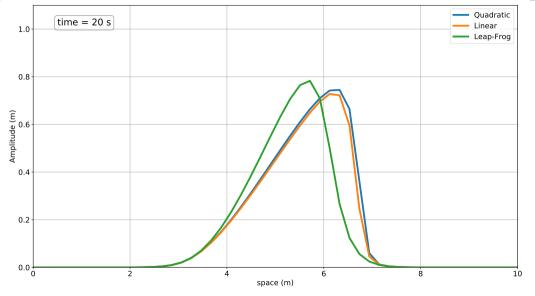




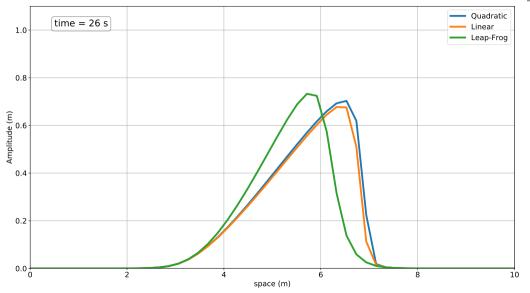




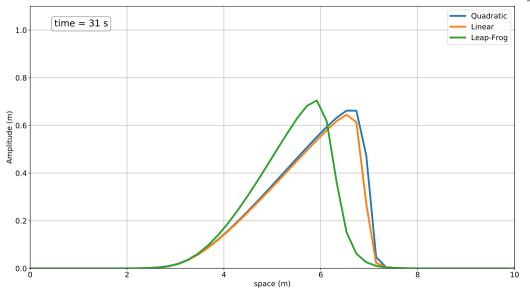




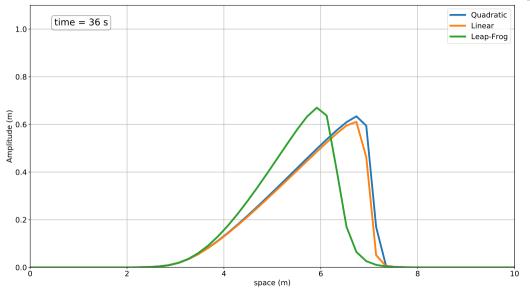




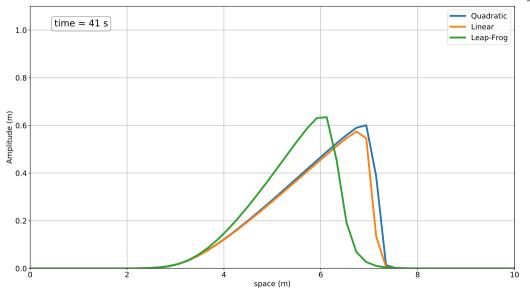




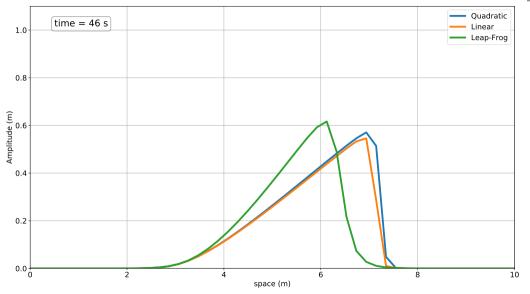




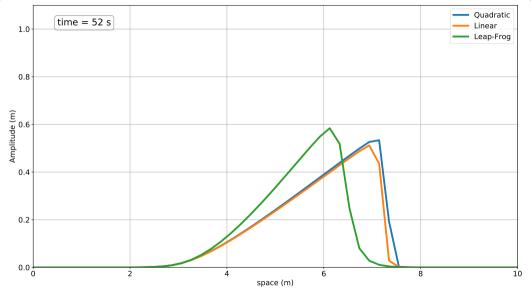




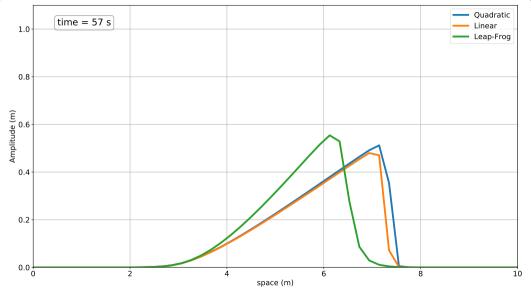




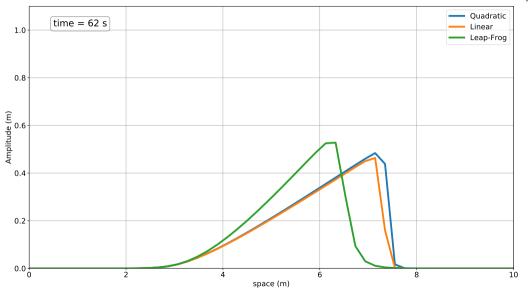




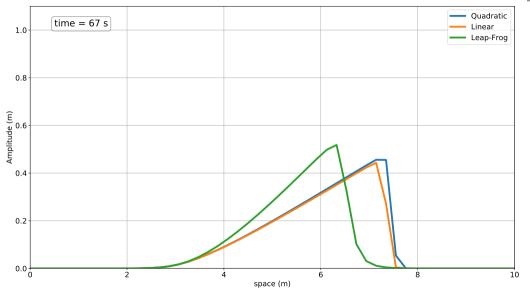




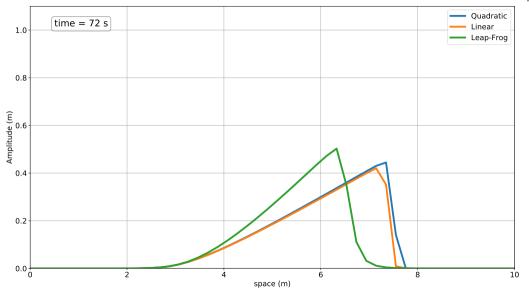




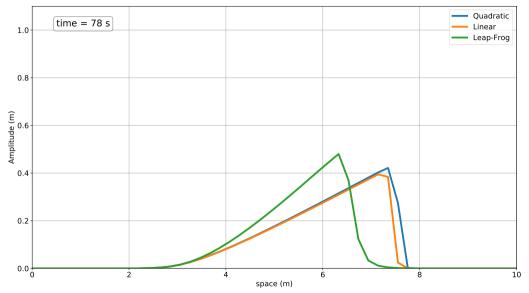




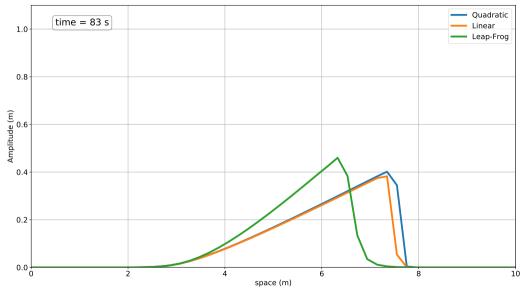




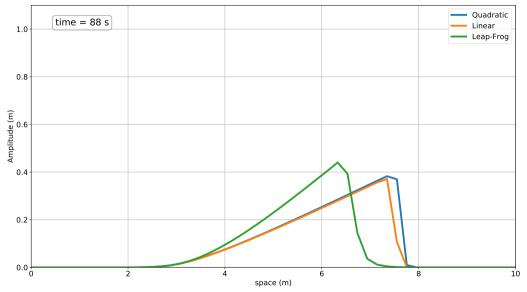




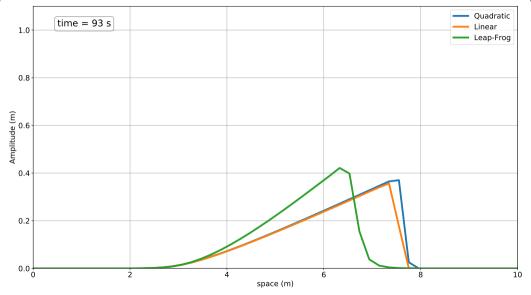




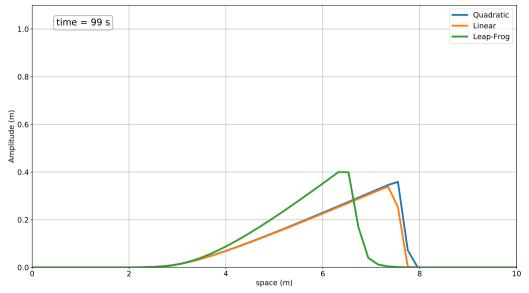


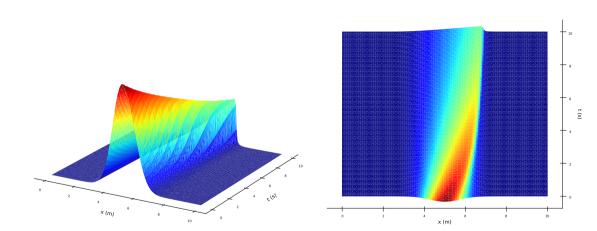












Convergence Condition

Stable!

Summary

- Explicit is risky
- Use implicit if possible
- Simple equation but nice curve

Tools used

- Latex
- Python, NumPy, Matplotlib, SymPy

Questions?

References

https:

//github.com/barbagroup/CFDPython