Deep Reinforcement Learning for Octree-Based Robotic Grasping

Learning Manipulation from 3D Observations

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Robotics

Master's Thesis

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Contents

Resumé 4

Preface 5

1 Introduction 6

2 Related Work 7

3 Background 8

4 Model-Free Reinforcement Learning 9

5 Problem Formulation 10

6 Network Architecture 11

7 Simulation Environment 12

8 Experimental Setup 13

9 Results 14

10 Ablation Studies 15

11 Discussion 16

12 Conclusion 17

13 Future Work 18

Bibliography 19

A Dataset 20

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Bibliography

Name, R. (2000). Fascinating title. *Journal of Testing 420*(69), 69–420.

A Dataset