

Deep Reinforcement Learning for Octree-Based Robotic Grasping

Learning Manipulation from 3D Observations

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Robotics

Master's Thesis





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STUDENT REPORT

Title:

Deep Reinforcement Learning for
Octree-Based Robotic Grasping

Abstract:

TODO: Abstract

Theme:

Master's Thesis

Programme:

Robotics

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Number of Pages:

15

Submission Date:

April 9, 2021

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Contents

Contents	iii
Resumé	iv
Preface	v
1 Introduction	1
2 Related Work	2
3 Background	3
4 Model-Free Reinforcement Learning	4
5 Problem Formulation	5
6 Network Architecture	6
7 Simulation Environment	7
8 Experimental Setup	8
9 Results	9
10 Ablation Studies	10
11 Discussion	11
12 Conclusion	12
13 Future Work	13
Bibliography	14
Appendices	15
A Dataset	15

Resumé

TODO: Resumé in Danish

Preface

TODO: Preface

Test citation (TODO: remove test citation): (Name, 2000)

Glossary

2D Two-dimensional
3D Three-dimensional

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7 Simulation Environment

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12 Conclusion

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Bibliography

Name, R. (2000). Fascinating title. *Journal of Testing* 420(69), 69–420.

Appendices

A Dataset