Deep Reinforcement Learning for Octree-Based Robotic Grasping

Learning Manipulation from 3D Observations

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Robotics

Master's Thesis

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AALBORG UNIVERSITY
STUDENT REPORT

Title:
Deep Reinforcement Learning for Octree-Based Robotic Grasping

Theme:
Master's Thesis

Programme:
Robotics

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Number of Pages:
15

Submission Date:
April 8, 2021

Abstract:

TODO: Abstract

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Resumé

TODO: Resumé in Danish

Preface

TODO: Preface

Test citation (TODO: remove test citation): (Name, 2000)

Glossary

2D Two-dimensional
3D Three-dimensional

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Bibliography

Name, R. (2000). Fascinating title. *Journal of Testing 420*(69), 69–420.

A Dataset