ROCKET THERMAL ANALYSIS					
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Abstract

For decades rocket groups have been using the THERMCAS software as a mean of initial estimations for the thermal analysis of a Solid Rocket Motor. Aiming to provide a better and more intuitive software, a new software was developed, Rocket Thermal Analysis (RTA). By applying the Finite Difference Method in analytical equations for convection and conduction, models for the casing and bulkhead heat distribution were successfully implemented inside RTA. The outputs showed good accordance with the expected values and the software is available for download on our Github repository.

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1 Software Purpose

The idea of developing RTA was brought to light by the Propulsion subsystem at the Latin America Space Challenge Cooperation 2021, during 2020. It was proposed a new software to replace the old THERMCAS [4], created by Richard Nakka. During the RTA development it was always in our mind that the software needed to be easy to execute and run a simulation and should have more features than THERMCAS does. This is why in RTA a bulkhead analysis is able to be conducted as well as two Finite Difference Methods for the casing thermal distribution. It is planned the insertion of many material properties for the user to choose, since now only EPDM and Aluminium 6061-T6 are available.

2 Software Explanation

2.1 Casing

For a thin cylinder of length to radius ratio of about 10, an infinite cylinder having only one dimension for conduction can be assume as an approximation [1], since the only considerable heat conduction path is radially. Solid Rocket Motors usually have a length to diameter ratio of 10 [2], so it is suitable to apply such an idealization in these applications.

Inside the rocket chamber the insulator area most exposed to hot gases are in the sections between grains. These areas will be receiving heat for a longer time than any other along the casing and by having so it is the critical point for heat insulation. Having said that, the heat exposure time will be set as the combustion time and an even thickness will be assumed throughout the insulator.

At first, heat will enter the system through convection by the hot gases provenient from the propellant burning. In order to have an estimation of the convective heat coefficient, an expression for convection in tube with turbulent flow can be used [1], it is shown in the Annex I. The convective heat will then be calculated utilizing Newton's Law of Cooling, considering the chamber and wall temperature.

After that, the boundary condition is set by applying the Energy Balance Equation at the first node, all the expressions are present in Annex I. The heats entering are from conduction from the posterior node and convection by the gases.

Then, conduction is taken within the materials. For that, a one-dimensional transient Fourier Law is applied, giving the care to change between the properties of the insulator and the casing structural material. The initial temperature of the materials composing the wall are set as the ambient temperature through all of its extent.

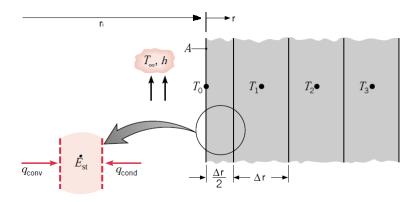


Figure 1: Discretization of the 1-D model. Adapted from [1].

2.2 Bulkhead

In order to tackle the bulkhead temperature distribution a two-dimensional model was addopted, it was based on cylindrical coordinates assuming symmetry along the angular coordinate. The bulkhead is considered here as a cylinder that is receiving heat on one of its circular surfaces. At the bulkhead side that is within the chamber an insulator of radius equal to that of the chamber is adopted.

The same equations used for the casing convective heat were used for the bulkhead scheme now for all the first line of nodes, see Annex II. For conduction the equations were used in two dimensions, going radially from Δr to the outer radius and in height from zero to the bulkhead thickness, see Annex II.

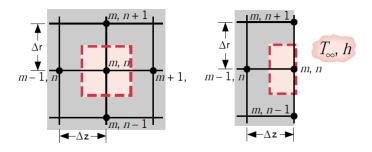


Figure 2: Discretization of the 2-D model. Adapted from [1].

2.3 Solution Methods

The method chosen to solve the partial differential equations was the Finite Difference Method because of its simplicity and fairly good results. For the casing an explicit and implicit form of the method was developed, but for the bulkhead only the explicit version was successfully implemented. The reason for this is that to solve the equation implicitly it was required to solve simultaneously for nodes varying in r and z, which could not be done by the ease it was done in the one-dimension scheme.

In the Explicit Finite Difference Method the future temperature of a node was only dependent on previously known temperatures in its surroundings [1], so it was possible to program the code to solve the temperature for each node at a given time, see Annex I and II. This process is computationally costly and is able to not converge which is a downside. But it can achieve the objective once one is capable of accepting these faults.

In the other hand the Implicit Finite Difference Method created a system of algebraic equations that gave the previous temperature at the node based on the future temperature of the node and its surroundings [1], see Annex I. In order to solve this system the inverse matrix of the coefficients multiplying the new temperatures was calculated and then multiplied with the known temperatures vector to achieve the new temperature vector.

2.4 Graphical Resources

The RTA software has three options of graphs to be generate, those are:

Casing Temperature Distribution: a graph showing the temperature at each location of the casing wall at the end time.

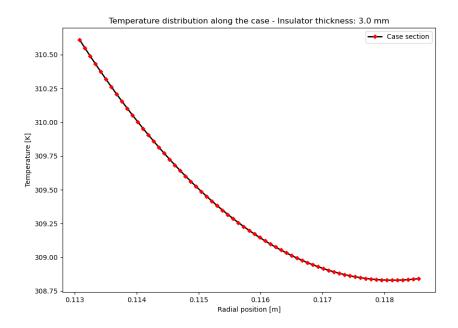


Figure 3: Graph of the casing temperature distribution.

Casing and Insulator Temperature Distribution: it is generated a graph showing the temperature distribution across all of the spatial domain at the end time.

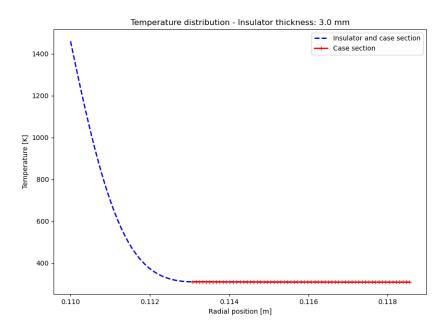


Figure 4: Graph of the casing and insulator temperature distribution.

Temperature Distribution at different times: the plot will show the temperature distribution at the last node for times going from 0 to 100% of the total burn time, with a pace of 25%.

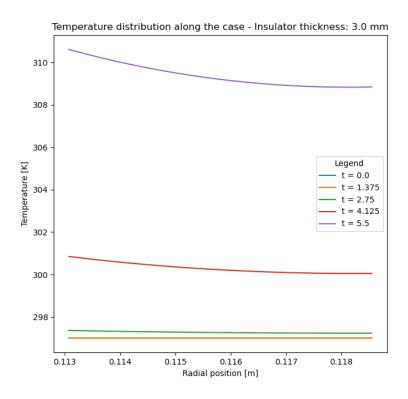


Figure 5: Temperature Distribution at different times.

2.5 Output File

RTA provides an optional output text file in which it provides in details the principal inputs for the analysis and of course a data frame which contains the results, but there are several differences between the output file of the implicit and of the explicit method and also with respect to bulkhead resultant file, the differences are shown below.

2.5.1 Case output file for implicit method

- · It has detailed information about the inputs;
- It displays a dataframe with the results;
- If time or radial steps exceed 1000 it will generate a resumed file.

It is possible to see a typical output file below

```
| Page of analysis | Case temperature distribution | Case | Case
```

Figure 6: Typical implicit method output file.

2.5.2 Case output file for explicit method

- · It has detailed information about the inputs;
- It displays a dataframe with the results;
- The dataframe contains 10 values for time steps represeting a percentage of the burning time.

It is possible to see a typical output file below

Figure 7: Typical explicit method output file.

2.5.3 Bulkhead output file

Unfortunately for this first release it will be unavailable to generate an output file for the bulkhead.

3 Stability Analysis

Solving a Partial Differential Equation by the Finite Difference Method and utilizing an Explicit approach requires a stability criterion to be respected for the solution to converge. This criterion, for a parabollic PDE, is, according to the Von Neumann necessary condition for stability, that the coefficient of the associated node of interest at the previous time is greater than or equal to zero [3].

For the 1-D solution, applied to the casing model, this condition gives the following relation between the finite step in time and the finite step in space.

$$\Delta t \le \frac{(\Delta r)^2}{2\alpha} \tag{1}$$

It happens to be that the above expression is equivalent to the criterion of having a fourier number smaller than 0.5, so when the user is putting the data in RTA, the software will ask for you to get down its value until the Fourier Number reaches a number below 0.5. The same criteria was analyses for the 2-D solution of the bulkhead model. In that case, the expression is

$$\Delta t \le \frac{(\Delta z \Delta r)^2}{2\alpha(\Delta r^2 + \Delta z^2)} \tag{2}$$

An exemple of how the solution behaves when the time and spatial steps are changed can be seen in Figure 1. Fixing the number of time steps in $n_t=120$ in the right hand side and fixig the spatial steps in $n_r=120$ for the left hand side.

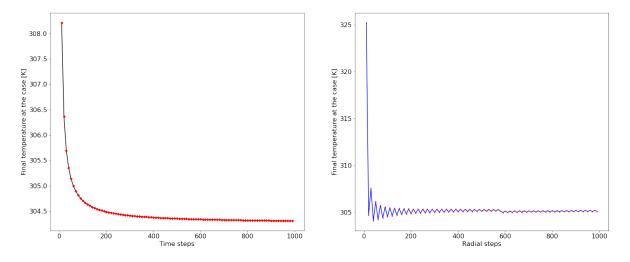


Figure 8: Convergence of the solution varying time and space steps.

As can be seen in the Figure 8, for 200 time steps the solution already has a good precision, being it deviated by 0.1 from the limit result at that point. For the amplitude of the radial steps temperature oscillation to remain approximately constant it is required about 300 steps, the result will be approximately 0.5 Kelvin deviated from the limit result.

4 Results Comparison

In order to have a comparison between the explicit, implicit and THERMCAS outputs, a simulation was conducted in the three of them, all with the same values. Because THERMCAS has a limit of 10 radial points, the same amount was used in the RTA. The values used are listed in the table below.

Variable	Description	Insulator	Casing
C_p	Specific Heat $[J/kgK]$	2000	896
ρ	Specific Mass $[kg/m^3]$	860	2700
k	Thermal Conductivity $[W/mK]$	0.2	167
tk_0	Casing thickness $[mm]$	5.55	
tk_0	Insulator thickness $[mm]$	3	
r_i	Inner radius $[m]$	0.11	
t	Burn time [s]	5	
n_t	Number of time steps	250	
n_r	Number of radial points	10	
Δr	Radial step $[mm]$	0.555	
Δt	Time step [s]	0.02	
h_m	Convection Coefficient $[W/m^2K]$	1295	
T_i	Initial Temperature $[K]$	297	
T_c	Combustion Temperature $[K]$	1600	

Table 1: Values used in the simulations.

From the simulation run, the plots shown below were obtained. In it, one can identify the clear difference between THERMCAS and RTA, both explicit and implicit methods showed good accordance, but in the other way, THERMCAS got smaller and constant values.

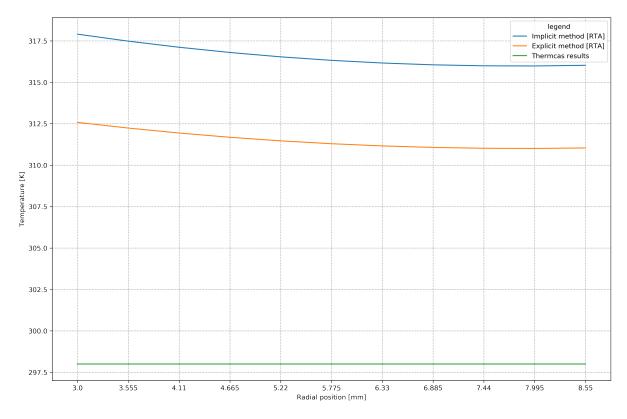


Figure 9: Casing temperature distribution after 5 seconds.

In THERMCAS, the outputs are rounded, so for the first point of the casing to the last temperature did not change one degree Celsius. This seems unreasonable for the inputs provided.

These clearly different results came from the fact that the two approches to the problem are different. THERMCAS considers the coordinate as cartesian, an evidence is that the software does not ask for the radius of the combustion chamber, so its model is an infinite plane. In the other way, at RTA the coordinate system is cylindrical, so the model is an infinite cylinder.

5 Conclusion

The results were within the expected values and they revealed to have a resonable physical behavior for the SRM thermal problem. For the future, it is needed a inverse problem test to be conducted in order for RTA to be validated. While this does not occur, RTA is presented here with promising results and a image of the final user interface of the sofware can be seen below.

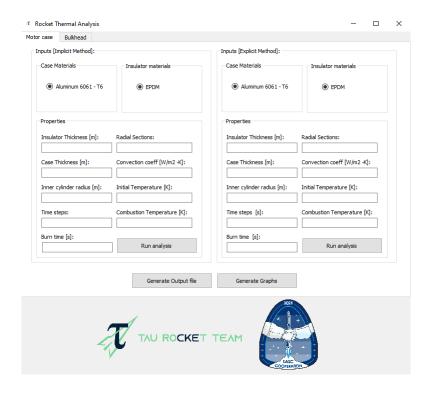


Figure 10: Main graphical user interface of RTA

References

- [1] T. L. B. A. S. L. Frank P. Incropera, David P. DeWitt. *Fundamentals of Heat and Mass Transfer.* John Wiley & Sons, 6^{th} edition, 2006.
- [2] O. B. George Paul Sutton. *Rocket Propulsion Elements*. John Wiley & Sons, 9^{th} edition, 2010.
- [3] D. M. K. W. Morton. *Numerical Solution of Partial Differential Equations*. Cambridge University Press, 2^{nd} edition, 2005.
- [4] R. Nakka. Richard nakka's experimental rocketry web site, October 19, 2020. Access in 24 october, 2020. URL: http://www.nakka-rocketry.net/.

Annex I - Casing Model

Analytical Equations

1-D Cylindrical Heat Cunduction Equation

$$\frac{1}{\alpha} \frac{\partial T}{\partial t} = \frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r}$$

1-D Conservation of Energy Equation with Convection

$$\rho c_p \frac{\partial T}{\partial t} = k \left. \frac{\partial T}{\partial r} \right|_{back} + h_m (T_c - T_w)$$

Newton's Law of cooling

$$q" = h_m(T_c - T_w)$$

Convective Heat Coefficent in Circular Tube with Turbulent Flow

$$h_m = 0.023 \frac{k}{D} Re_D^{0.8} Pr^{0.3}$$

Discrete Equations

Implicit Discretization

First r node

$$\rho c_p \left(\frac{T_j^{i+1} - T_j^i}{\Delta t} \right) = k \left(\frac{T_{j+1}^{i+1} - T_j^{i+1}}{\Delta r} \right) + h_m (T_c - T_j^i)$$

$$\left(1 - \frac{h_m \Delta t}{\rho c_p} \right) T_j^i + \frac{h_m \Delta t T_c}{\rho c_p} = \left(1 + \frac{k \Delta t}{\rho c_p \Delta r} \right) T_j^{i+1} + \left(\frac{-k \Delta t}{\rho c_p \Delta r} \right) T_{j+1}^{i+1}$$

Inner r node

$$\frac{1}{\alpha} \frac{T_{j}^{i+1} - T_{j}^{i}}{\Delta t} = \frac{T_{j+1}^{i+1} + T_{j-1}^{i+1} - 2T_{j}^{i+1}}{(\Delta r)^{2}} + \frac{T_{j+1}^{i+1} - T_{j-1}^{i+1}}{2r\Delta r}$$

$$T_{j}^{i} = \left(1 + \frac{2\alpha\Delta t}{(\Delta r)^{2}}\right) T_{j}^{i+1} + \left(\frac{\alpha\Delta t}{2r\Delta r} - \frac{\alpha\Delta t}{(\Delta r)^{2}}\right) T_{j-1}^{i+1} + \left(\frac{-\alpha\Delta t}{2r\Delta r} - \frac{\alpha\Delta t}{(\Delta r)^{2}}\right) T_{j+1}^{i+1}$$

Last r node

$$\frac{1}{\alpha} \frac{T_{j}^{i+1} - T_{j}^{i}}{\Delta t} = \frac{T_{j+2}^{i+1} + T_{j}^{i+1} - 2T_{j+1}^{i+1}}{(\Delta r)^{2}} + \frac{T_{j+1}^{i+1} - T_{j}^{i+1}}{r\Delta r}$$

$$T_{j}^{i} = \left(1 - \frac{\alpha \Delta t}{(\Delta r)^{2}} + \frac{\alpha \Delta t}{r\Delta r}\right) T_{j}^{i+1} + \left(\frac{-\alpha \Delta t}{(\Delta r)^{2}}\right) T_{j+2}^{i+1} + \left(\frac{2\alpha \Delta t}{(\Delta r)^{2}} - \frac{\alpha \Delta t}{r\Delta r}\right) T_{j+1}^{i+1}$$

Explicit Discretization

First r node

$$\rho c_p \left(\frac{T_j^{i+1} - T_j^i}{\Delta t} \right) = k \left(\frac{T_{j+1}^i - T_j^i}{\Delta r} \right) + h(T_c - T_j^i)$$

$$T_j^{i+1} = \left(1 - \frac{k\Delta t}{\rho c_p \Delta r} - \frac{h_m \Delta t}{\rho c_p} \right) T_j^i + \left(\frac{k\Delta t}{\rho c_p \Delta r} \right) T_{j+1}^i + \frac{h_m T_c \Delta t}{\rho c_p}$$

Inner r node

$$\frac{1}{\alpha} \frac{T_{j}^{i+1} - T_{j}^{i}}{\Delta t} = \frac{T_{j+1}^{i} + T_{j-1}^{i} - 2T_{j}^{i}}{(\Delta r)^{2}} + \frac{T_{j+1}^{i} - T_{j-1}^{i}}{2r\Delta r}$$

$$T_{j}^{i+1} = \left(1 - \frac{2\alpha\Delta t}{(\Delta r)^{2}}\right) T_{j}^{i} + \left(\frac{\alpha\Delta t}{(\Delta r)^{2}} - \frac{\alpha\Delta t}{2r\Delta r}\right) T_{j-1}^{i} + \left(\frac{\alpha\Delta t}{2r\Delta r} + \frac{\alpha\Delta t}{(\Delta r)^{2}}\right) T_{j+1}^{i}$$

Last r node

$$\frac{1}{\alpha} \frac{T_j^{i+1} - T_j^i}{\Delta t} = \frac{T_{j+2}^i + T_j^i - 2T_{j+1}^i}{(\Delta r)^2} + \frac{T_{j+1}^i - T_j^i}{r\Delta r}$$

$$T_j^{i+1} = \left(1 + \frac{\alpha \Delta t}{(\Delta r)^2} - \frac{\alpha \Delta t}{r\Delta r}\right) T_j^i + \left(\frac{\alpha \Delta t}{(\Delta r)^2}\right) T_{j+2}^i + \left(\frac{\alpha \Delta t}{r\Delta r} - \frac{2\alpha \Delta t}{(\Delta r)^2}\right) T_{j+1}^i$$

Annex II - Bulkhead Model

Analytical Equations

2-D Cylindrical Heat Conduction Equation

$$\frac{1}{\alpha}\frac{\partial T}{\partial t} = \frac{\partial^2 T}{\partial r^2} + \frac{1}{r}\frac{\partial T}{\partial r} + \frac{\partial^2 T}{\partial z^2}$$

2-D Conservation of Energy Equation with Convection

$$\frac{\rho c_p \Delta r \Delta z}{2} \frac{\partial T}{\partial t} = \frac{k \Delta z}{2} \left. \frac{\partial T}{\partial r} \right|_{uv} + \frac{k \Delta z}{2} \left. \frac{\partial T}{\partial r} \right|_{down} + \frac{k \Delta r}{2} \left. \frac{\partial T}{\partial z} \right|_{back} + h \Delta r (T_c - T_w)$$

Discrete Equations

Explicit Discretization

First z and first r node

$$\begin{split} \frac{\rho c_p \Delta r \Delta z}{2} \left(\frac{T_{j,l}^{i+1} - T_{j,l}^i}{\Delta t} \right) &= \frac{k \Delta z}{2} \left(\frac{T_{j+1,l}^i - T_{j,l}^i}{\Delta r} \right) + \frac{k \Delta r}{2} \left(\frac{T_{j,l+1}^i - T_{j,l}^i}{\Delta z} \right) + h_m \Delta r (T_c - T_{j,l}^i) \\ T_{j,l}^{i+1} &= \frac{2h_m \Delta t (T_c)}{\rho c_p \Delta z} + \left(1 - \frac{k \Delta t}{\rho c_p \Delta r^2} - \frac{k \Delta t}{\rho c_p \Delta z^2} - \frac{2h_m \Delta t}{\rho c_p \Delta z} \right) T_{j,l}^i + \left(\frac{k \Delta t}{\rho c_p \Delta r^2} \right) T_{j+1,l}^i \\ &\quad + \left(\frac{k \Delta t}{\rho c_p \Delta z^2} \right) T_{j,l+1}^i \end{split}$$

First z and inner r node

$$\frac{\rho c_p \Delta r \Delta z}{2} \left(\frac{T_{j,l}^{i+1} - T_{j,l}^i}{\Delta t} \right) = \frac{k \Delta z}{2} \left(\frac{T_{j+1,l}^i - T_{j,l}^i}{\Delta r} \right) + \frac{k \Delta z}{2} \left(\frac{T_{j,l}^i - T_{j-1,l}^i}{\Delta r} \right) + \frac{k \Delta r}{2} \left(\frac{T_{j,l+1}^i - T_{j,l}^i}{\Delta z} \right) + h_m dr(T_c - T_{j,l}^i)$$

$$T_{j,l}^{i+1} = \frac{2h_m\Delta t(T_c)}{\rho c_p\Delta z} + \left(1 - \frac{k\Delta t}{\rho c_p\Delta z^2} - \frac{2h_m\Delta t}{\rho c_p\Delta z}\right)T_{j,l}^i + \left(\frac{k\Delta t}{\rho c_p\Delta r^2}\right)T_{j+1,l}^i + \left(\frac{-k\Delta t}{\rho c_p\Delta r^2}\right)T_{j-1,l}^i + \left(\frac{k\Delta t}{\rho c_p\Delta z^2}\right)T_{j,l+1}^i$$

First z and last r node

$$\frac{\rho c_p \Delta r \Delta z}{2} \left(\frac{T_{j,l}^{i+1} - T_{j,l}^i}{\Delta t} \right) = \frac{k \Delta z}{2} \left(\frac{T_{j,l}^i - T_{j-1,l}^i}{\Delta r} \right) + \frac{k \Delta r}{2} \left(\frac{T_{j,l+1}^i - T_{j,l}^i}{\Delta z} \right) + h_m \Delta r (T_c - T_{j,l}^i)$$

$$T_{j,l}^{i+1} = \frac{2h_m \Delta t (T_c)}{\rho c_p \Delta z} + \left(1 + \frac{k \Delta t}{\rho c_p \Delta r^2} - \frac{k \Delta t}{\rho c_p \Delta z^2} - \frac{2h_m \Delta t}{\rho c_p \Delta z} \right) T_{j,l}^i + \left(\frac{-k \Delta t}{\rho c_p \Delta r^2} \right) T_{j-1,l}^i$$

$$\left(\frac{k \Delta t}{\rho c_p \Delta z^2} \right) T_{j,l+1}^i$$

Inner z and first r node

$$\begin{split} \frac{1}{\alpha} \frac{T^{i+1}_{j,l} - T^{i}_{j,l}}{\Delta t} &= \frac{T^{i}_{j+2,l} + T^{i}_{j,l} - 2T^{i}_{j+1,l}}{(\Delta r)^{2}} + \frac{T^{i}_{j+1,l} - T^{i}_{j,l}}{r\Delta r} + \frac{T^{i}_{j,l+1} + T^{i}_{j,l-1} - 2T^{i}_{j,l}}{(\Delta z)^{2}} \\ T^{i+1}_{j,l} &= \left(1 - \frac{\alpha \Delta t}{r\Delta r} + \frac{\alpha \Delta t}{(\Delta r)^{2}} - \frac{2\alpha \Delta t}{(\Delta z)^{2}}\right) T^{i}_{j,l} + \left(\frac{\alpha \Delta t}{r\Delta r} - \frac{2\alpha \Delta t}{(\Delta r)^{2}}\right) T^{i}_{j+1,l} + \left(\frac{\alpha \Delta t}{(\Delta r)^{2}}\right) T^{i}_{j+2,l} + \\ &\left(\frac{\alpha \Delta t}{(\Delta z)^{2}}\right) T^{i}_{j,l-1} + \left(\frac{\alpha \Delta t}{(\Delta z)^{2}}\right) T^{i}_{j,l+1} \end{split}$$

Inner z and inner r node

$$\frac{1}{\alpha} \frac{T_{j,l}^{i+1} - T_{j,l}^{i}}{\Delta t} = \frac{T_{j+1,l}^{i} + T_{j-1,l}^{i} - 2T_{j,l}^{i}}{(\Delta r)^{2}} + \frac{T_{j+1,l}^{i} - T_{j-1,l}^{i}}{2r\Delta r} + \frac{T_{j,l+1}^{i} + T_{j,l-1}^{i} - 2T_{j,l}^{i}}{(\Delta z)^{2}}$$

$$T_{j,l}^{i+1} = \left(1 - \frac{2\alpha\Delta t}{(\Delta r)^{2}} - \frac{2\alpha\Delta t}{(\Delta z)^{2}}\right) T_{j,l}^{i} + \left(\frac{\alpha\Delta t}{(\Delta r)^{2}} - \frac{\alpha\Delta t}{2r\Delta r}\right) T_{j-1,l}^{i} + \left(\frac{\alpha\Delta t}{2r\Delta r} + \frac{\alpha\Delta t}{(\Delta r)^{2}}\right) T_{j+1,l}^{i} + \left(\frac{\alpha\Delta t}{(\Delta z)^{2}}\right) T_{j,l-1}^{i} + \left(\frac{\alpha\Delta t}{(\Delta z)^{2}}\right) T_{j,l+1}^{i}$$

Inner z and last r node

$$\begin{split} \frac{1}{\alpha} \frac{T^{i+1}_{j,l} - T^i_{j,l}}{\Delta t} &= \frac{T^i_{j-2,l} + T^i_{j,l} - 2T^i_{j-1,l}}{(\Delta r)^2} + \frac{T^i_{j,l} - T^i_{j-1,l}}{r\Delta r} + \frac{T^i_{j,l+1} + T^i_{j,l-1} - 2T^i_{j,l}}{(\Delta z)^2} \\ T^{i+1}_{j,l} &= \left(1 + \frac{\alpha \Delta t}{r\Delta r} + \frac{\alpha \Delta t}{(\Delta r)^2} - \frac{2\alpha \Delta t}{(\Delta z)^2}\right) T^i_{j,l} + \left(\frac{-2\alpha \Delta t}{(\Delta r)^2} - \frac{\alpha \Delta t}{r\Delta r}\right) T^i_{j-1,l} + \left(\frac{\alpha \Delta t}{(\Delta r)^2}\right) T^i_{j-2,l} + \\ & \left(\frac{\alpha \Delta t}{(\Delta z)^2}\right) T^i_{j,l-1} + \left(\frac{\alpha \Delta t}{(\Delta z)^2}\right) T^i_{j,l+1} \end{split}$$

Final z and first r node

$$\begin{split} \frac{1}{\alpha} \frac{T_{j,l}^{i+1} - T_{j,l}^{i}}{\Delta t} &= \frac{T_{j+2,l}^{i} + T_{j,l}^{i} - 2T_{j+1,l}^{i}}{(\Delta r)^{2}} + \frac{T_{j+1,l}^{i} - T_{j,l}^{i}}{r\Delta r} + \frac{T_{j,l-2}^{i} + T_{j,l}^{i} - 2T_{j,l-1}^{i}}{(\Delta z)^{2}} \\ T_{j,l}^{i+1} &= \left(1 - \frac{\alpha \Delta t}{r\Delta r} + \frac{\alpha \Delta t}{(\Delta r)^{2}} + \frac{\alpha \Delta t}{(\Delta z)^{2}}\right) T_{j,l}^{i} + \left(\frac{\alpha \Delta t}{r\Delta r} - \frac{2\alpha \Delta t}{(\Delta r)^{2}}\right) T_{j+1,l}^{i} + \left(\frac{\alpha \Delta t}{(\Delta r)^{2}}\right) T_{j+2,l}^{i} + \\ \left(\frac{-2\alpha \Delta t}{(\Delta z)^{2}}\right) T_{j,l-1}^{i} + \left(\frac{\alpha \Delta t}{(\Delta z)^{2}}\right) T_{j,l-2}^{i} \end{split}$$

Final z and inner r node

$$\begin{split} \frac{1}{\alpha} \frac{T_{j,l}^{i+1} - T_{j,l}^{i}}{\Delta t} &= \frac{T_{j+1,l}^{i} + T_{j-1,l}^{i} - 2T_{j,l}^{i}}{(\Delta r)^{2}} + \frac{T_{j+1,l}^{i} - T_{j-1,l}^{i}}{2r\Delta r} + \frac{T_{j,l-2}^{i} + T_{j,l}^{i} - 2T_{j,l-1}^{i}}{(\Delta z)^{2}} \\ T_{j,l}^{i+1} &= \left(1 - \frac{2\alpha\Delta t}{(\Delta r)^{2}} + \frac{\alpha\Delta t}{(\Delta z)^{2}}\right)T_{j,l}^{i} + \left(\frac{\alpha\Delta t}{(\Delta r)^{2}} - \frac{\alpha\Delta t}{2r\Delta r}\right)T_{j-1,l}^{i} + \left(\frac{\alpha\Delta t}{2r\Delta r} + \frac{\alpha\Delta t}{(\Delta r)^{2}}\right)T_{j+1,l}^{i} + \\ \left(\frac{-2\alpha\Delta t}{(\Delta z)^{2}}\right)T_{j,l-1}^{i} + \left(\frac{\alpha\Delta t}{(\Delta z)^{2}}\right)T_{j,l-2}^{i} \end{split}$$

Final z and last r node

$$\frac{1}{\alpha} \frac{T_{j,l}^{i+1} - T_{j,l}^{i}}{\Delta t} = \frac{T_{j-2,l}^{i} + T_{j,l}^{i} - 2T_{j-1,l}^{i}}{(\Delta r)^{2}} + \frac{T_{j,l}^{i} - T_{j-1,l}^{i}}{r\Delta r} + \frac{T_{j,l-2}^{i} + T_{j,l}^{i} - 2T_{j,l-1}^{i}}{(\Delta z)^{2}}$$

$$T_{j,l}^{i+1} = \left(1 + \frac{\alpha \Delta t}{r\Delta r} + \frac{\alpha \Delta t}{(\Delta r)^{2}} + \frac{\alpha \Delta t}{(\Delta z)^{2}}\right) T_{j,l}^{i} + \left(\frac{-2\alpha \Delta t}{(\Delta r)^{2}} - \frac{\alpha \Delta t}{r\Delta r}\right) T_{j-1,l}^{i} + \left(\frac{\alpha \Delta t}{(\Delta r)^{2}}\right) T_{j-2,l}^{i} + \left(\frac{-2\alpha \Delta t}{(\Delta z)^{2}}\right) T_{j,l-1}^{i} + \left(\frac{\alpha \Delta t}{(\Delta z)^{2}}\right) T_{j,l-2}^{i}$$