FÍSICA II (62.03, 62.04 y 82.02) Primer Cuatrimestre de 2020 (última versión: 1° C. 2018)



Guía 1: Electrostática en el vacío

Campo electrostático

9. Plantear la expresión para el cálculo del campo eléctrico, en todo punto del espacio, producido por una distribución esférica de carga de radio R y de densidad volumétrica $ho=
ho_0\cos\varphi$

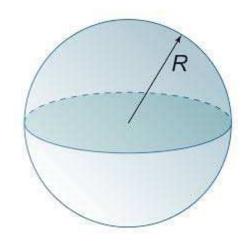
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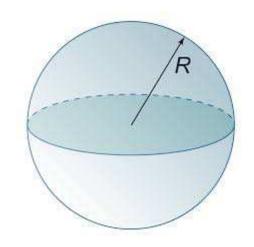
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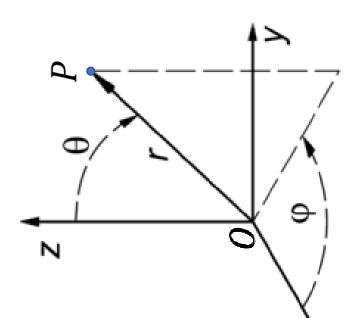
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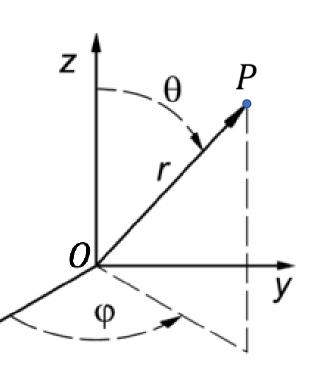
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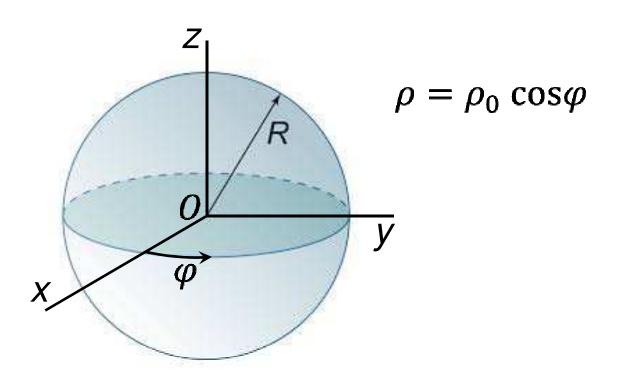
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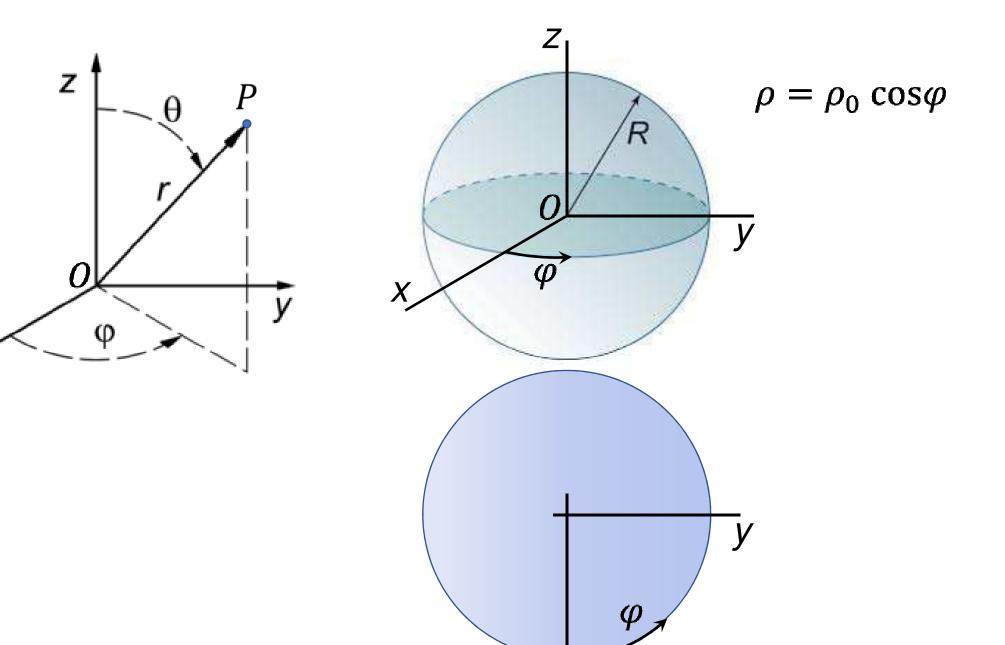


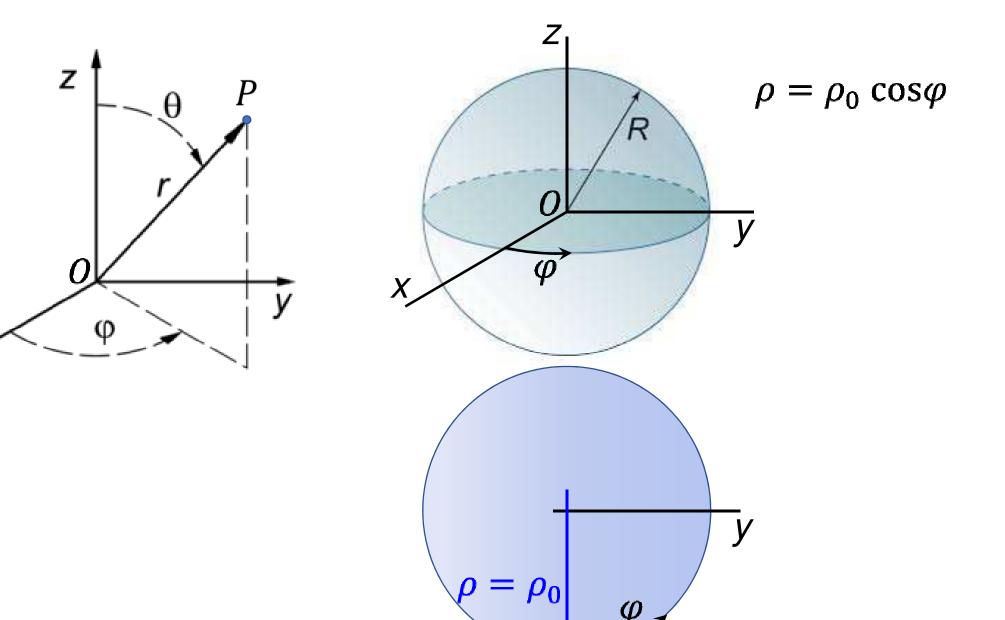
Coordenadas esféricas: r, θ, φ

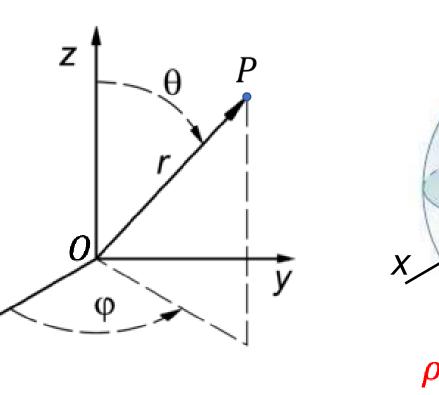


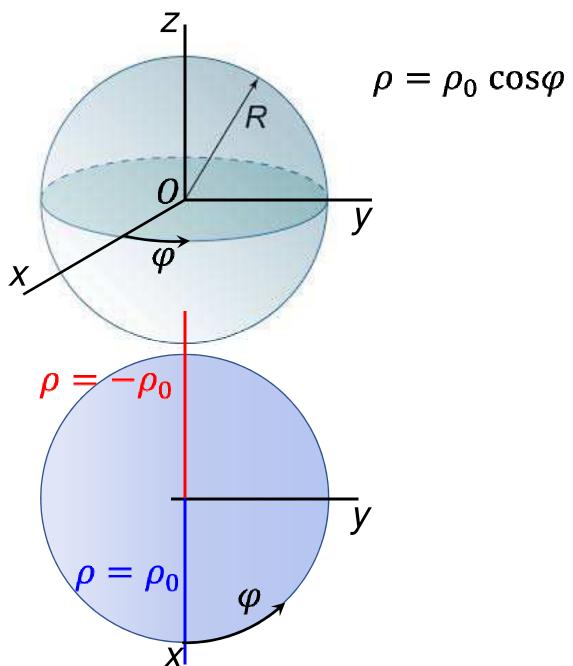


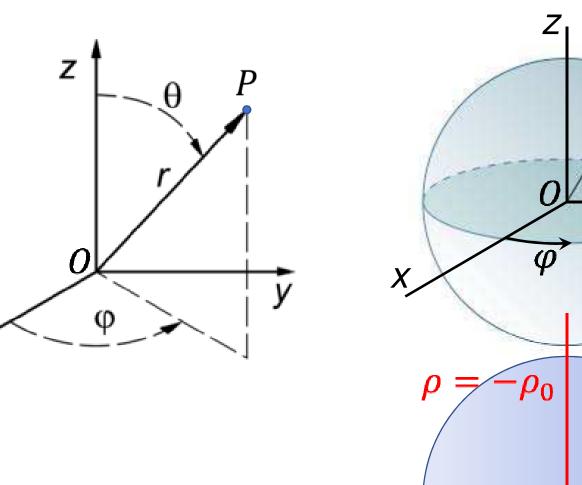


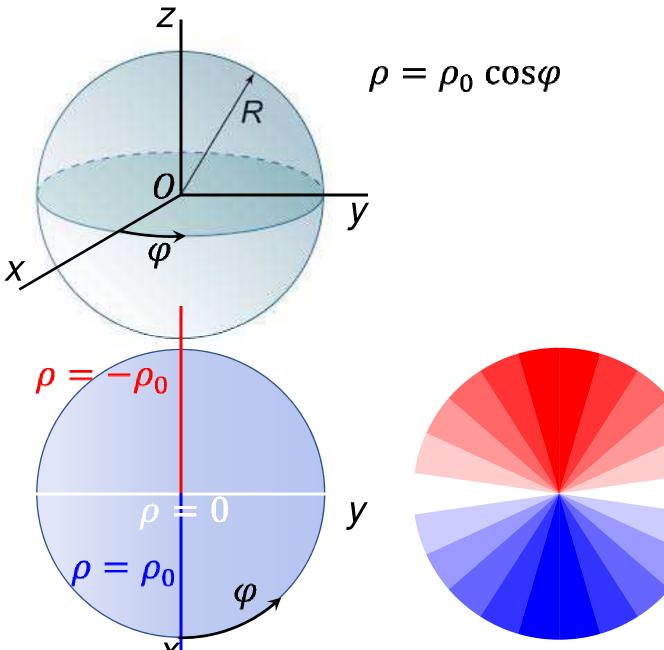


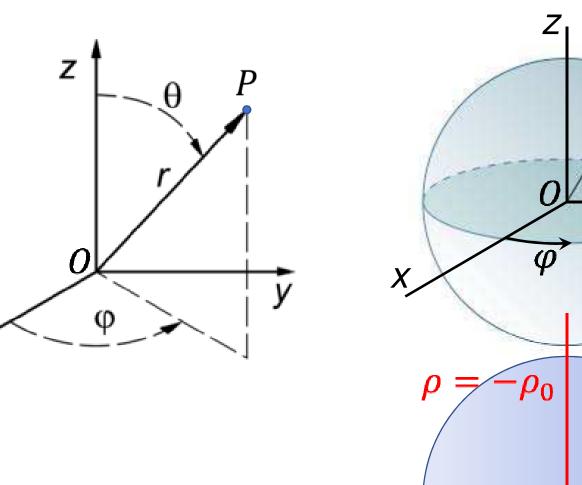


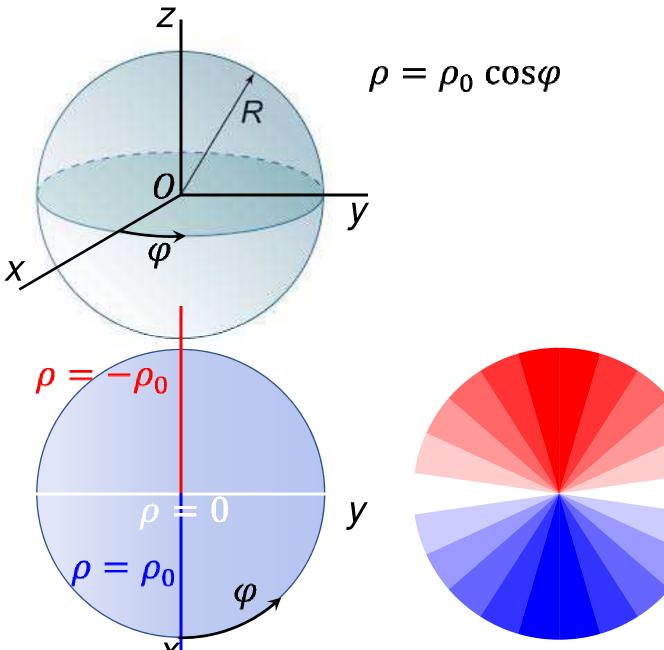




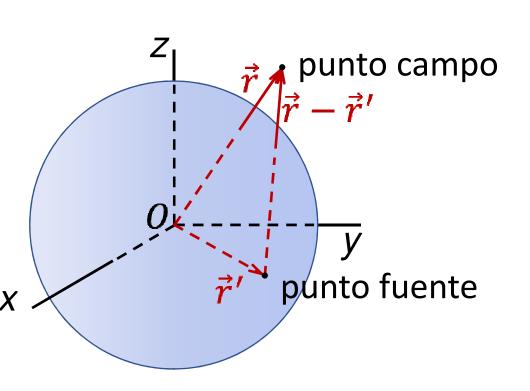




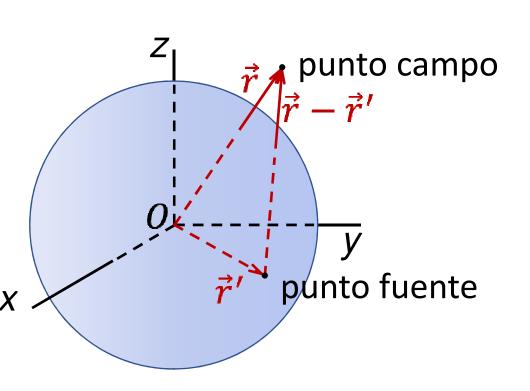




$$\vec{E}(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}')dV'}{|\vec{r} - \vec{r}'|^3}$$

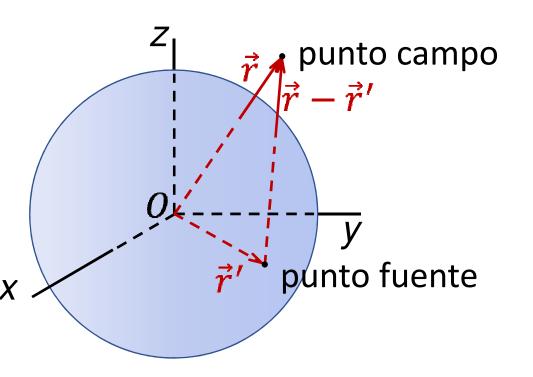


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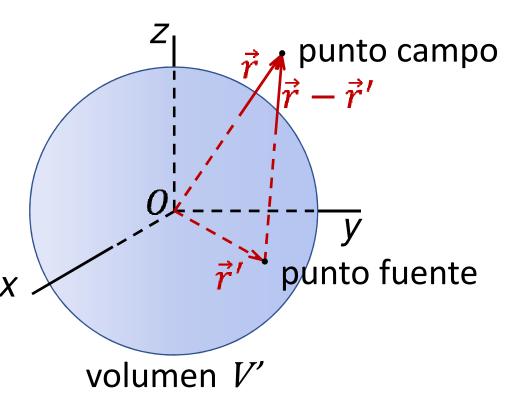
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$$\rho(\vec{r}') = \rho_0 \cos \varphi'$$



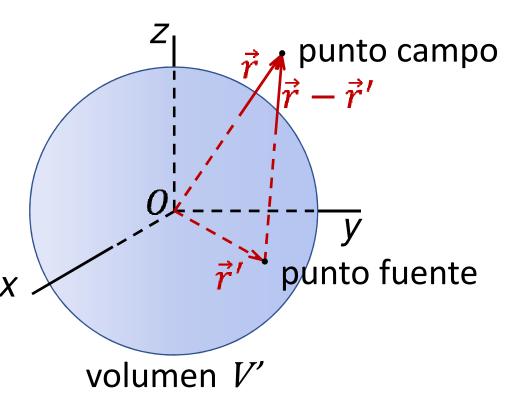
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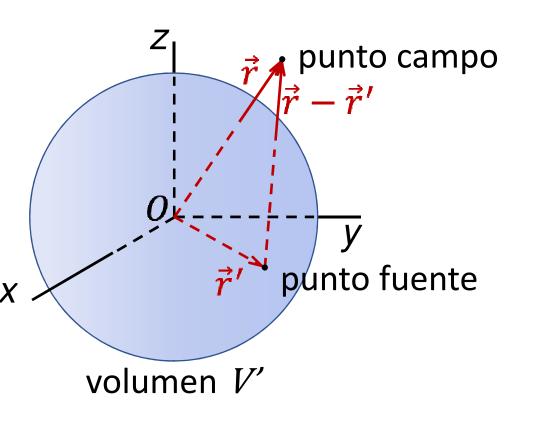
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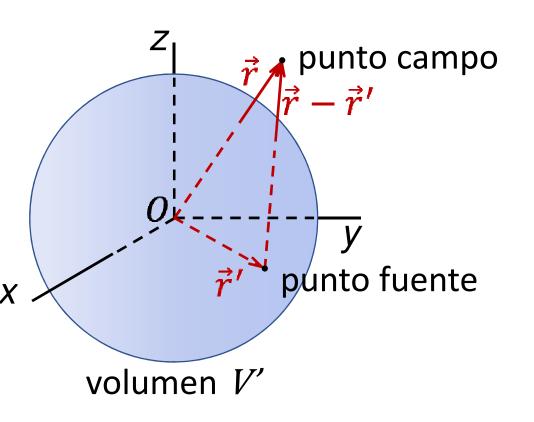


Pasos

- 1. dV'
- 2. \vec{r}'
- $3. \quad \vec{r}$
- 4. $\vec{r} \vec{r}'$
- 5. $|\vec{r} \vec{r}'|$

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}')dV'}{|\vec{r} - \vec{r}'|^3}$$

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Pasos

- 1. dV'
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$$\vec{\xi}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}') dV'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos \varphi'$$

 $dV' = r'^2 \operatorname{sen}\theta' dr' d\theta' d\varphi'$

$$\frac{dV}{r}$$

$$\vec{z}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}') dV'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos \varphi'$$

orientación en el espacio, coordenadas y versores $ec{r}'=ec{r}'(r', heta',arphi')$ vector con valor numérico y

AF

$$\vec{z}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}') dV'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos \varphi'$$

orientación en el espacio, coordenadas y versores $ec{r}'=ec{r}'(r', heta',arphi')$ vector con valor numérico y

 $^{\prime}\Lambda$ F

$$\vec{r}' = x' \hat{1} + y' \hat{j} + z' \hat{k}$$

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}')dV'}{|\vec{r} - \vec{r}'|^3} \qquad \qquad \rho(\vec{r}') = \rho_0 \cos\varphi'$$

$$ec{r}'$$
 $ec{r}'$
 $ec{r}'$
 $ec{r}'$
orientación en el espacio, coordenadas y versores
 $ec{r}-ec{r}'$
 $ec{r}'=x'\;\hat{\mathbf{1}}+y'\;\hat{\mathbf{j}}+z'\hat{\mathbf{k}}$

 $\vec{r}' = r' \operatorname{sen} \theta' \operatorname{cos} \varphi' \hat{\mathbf{i}} + r' \operatorname{sen} \theta' \operatorname{sen} \varphi' \hat{\mathbf{j}} + r' \operatorname{cos} \theta' \hat{\mathbf{k}}$ mantenemos los versores cartesianos

$$\vec{z}(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}') \mathrm{d}V'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos \varphi'$$

 $\vec{r} = r \operatorname{sen}\theta \cos \varphi \, \hat{\imath} + r \operatorname{sen}\theta \operatorname{sen}\varphi \, \hat{\jmath} + r \cos \theta \, \hat{k}$

$$\begin{vmatrix} \vec{r} \\ \vec{r} - \vec{r}' \\ |\vec{r} - \vec{r}'| \end{vmatrix}$$

 ηN_{\prime}

$$\vec{\vec{\tau}}(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}')\mathrm{d}V'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos\varphi'$$

4N'

$$\vec{r} = r \operatorname{sen}\theta \operatorname{cos}\varphi \, \hat{\mathbf{i}} + r \operatorname{sen}\theta \operatorname{sen}\varphi \, \hat{\mathbf{j}} + r \operatorname{cos}\theta \, \hat{\mathbf{k}}$$

$$\vec{r}' = r' \operatorname{sen}\theta' \operatorname{cos}\varphi' \, \hat{\mathbf{i}} + r' \operatorname{sen}\theta' \operatorname{sen}\varphi' \, \hat{\mathbf{j}} + r' \operatorname{cos}\theta' \hat{\mathbf{k}}$$

$$\vec{r} - \vec{r}' = (r \operatorname{sen}\theta \operatorname{cos}\varphi - r' \operatorname{sen}\theta' \operatorname{cos}\varphi') \, \hat{\mathbf{i}} + (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi') \, \hat{\mathbf{j}} + (r \operatorname{cos}\theta - r' \operatorname{cos}\theta') \, \hat{\mathbf{k}}$$

$$\vec{z}(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}')\mathrm{d}V'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos\varphi'$$

$$\vec{r} - \vec{r}' = (r \operatorname{sen}\theta \cos \varphi - r' \operatorname{sen}\theta' \cos \varphi') \hat{\imath} + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi') \hat{\jmath} + \\ (r \cos \theta - r' \cos \theta') \hat{k} \\ |\vec{r} - \vec{r}'| = [(r \operatorname{sen}\theta \cos \varphi - r' \operatorname{sen}\theta' \cos \varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\varphi' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi' - r' \operatorname{sen}\varphi' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\theta \operatorname{sen}\varphi' - r' \operatorname{sen}\varphi')^2 + \\ (r \operatorname{sen}\varphi')^2 +$$

4N'

 $(r\cos\theta - r'\cos\theta')^2|^{1/2}$

$$\vec{z}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}') dV'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos \varphi'$$

$$\vec{r} - \vec{r}' = (r \operatorname{sen}\theta \cos \varphi - r' \operatorname{sen}\theta' \cos \varphi') \hat{\imath} + (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi') \hat{\jmath} + (r \cos \theta - r' \cos \theta') \hat{k}$$

4N'

$$|\vec{r} - \vec{r}'| = \left[(r \operatorname{sen}\theta \cos \varphi - r' \operatorname{sen}\theta' \cos \varphi')^2 + (r \operatorname{sen}\theta \operatorname{sen}\varphi - r' \operatorname{sen}\theta' \operatorname{sen}\varphi')^2 + (r \cos \theta - r' \cos \theta')^2 \right]^{1/2}$$

rollando, agrupando, con sen $^2lpha+\cos^2eta=1$ y $\coslpha\coslpha$ $+ senlpha seneta=\cos(lpha$ -

$$\vec{z}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}') dV'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos \varphi'$$

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4N'

$$|\vec{r} - \vec{r}'| = \left[(r \operatorname{sen}\theta \operatorname{cos}\phi - r' \operatorname{sen}\theta' \operatorname{cos}\phi')^2 + (r \operatorname{sen}\theta \operatorname{sen}\phi - r' \operatorname{sen}\theta' \operatorname{sen}\phi')^2 + (r \operatorname{cos}\theta - r' \operatorname{cos}\theta')^2 \right]^{1/2}$$

rollando, agrupando, con sen $^2lpha+\cos^2eta=1$ y $\coslpha\coslpha$ + $senlpha seneta=\cos(lpha$ -

$$\vec{r} - \vec{r}' | = [r^2 + r'^2 - 2rr' \operatorname{sen}\theta \operatorname{sen}\theta' \cos(\varphi - \varphi') - 2rr' \cos\theta \cos\theta']^{1}$$

$$\rho(\vec{r}') = \rho_0 \cos \varphi'$$

$$\vec{z}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}') dV'}{|\vec{r} - \vec{r}'|^3}$$

$$\frac{dV'}{r'} < \frac{r'}{r'} < \frac{r'}{r'} < \frac{r'}{r'} < \frac{r'}{r'} - \frac{r'}{r'} < \frac{r'}{r'} - \frac{r'}{r'} < \frac{r$$

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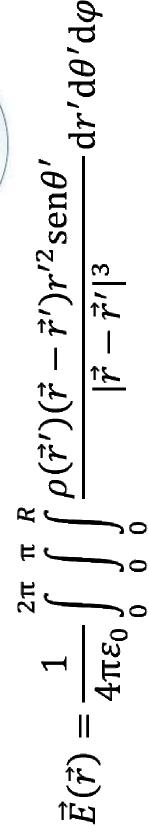
 $\rho(\vec{r}') = \rho_0 \cos \varphi'$

•
$$0 \le \varphi' \le 2\pi$$

$$\vec{\xi}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}') dV'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos \varphi'$$

$$\bullet \quad 0 \leq \theta' \leq \pi$$

•
$$0 \le \varphi' \le 2\pi$$



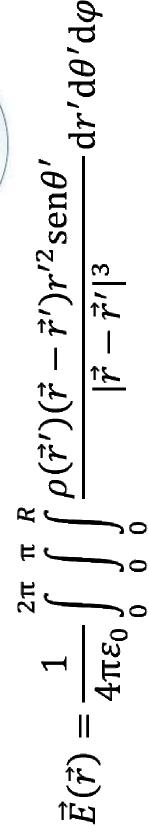
 $|\vec{r}-\vec{r}'| \prec$

 $\vec{r} - \vec{r}' \checkmark$

$$\vec{\xi}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho(\vec{r}')(\vec{r} - \vec{r}') dV'}{|\vec{r} - \vec{r}'|^3} \qquad \rho(\vec{r}') = \rho_0 \cos \varphi'$$

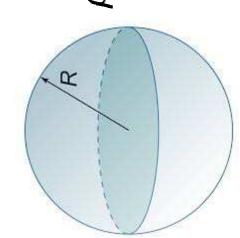
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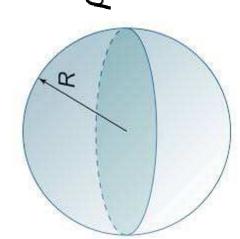
 $|\vec{r}-\vec{r}'| \prec$

 $\vec{r} - \vec{r}' \checkmark$



$$\rho(\vec{r}) = \rho_0 \cos \varphi$$

$$\vec{E}(\vec{r}) = E_x(r,\theta,\varphi) \hat{1} + E_y(r,\theta,\varphi) \hat{1} + E_z(r,\theta,\varphi)$$



$$\rho(\vec{r}) = \rho_0 \cos \varphi$$

$$\vec{E}(\vec{r}) = E_x(r,\theta,\varphi)\,\hat{\mathbf{i}} + E_y(r,\theta,\varphi)\,\hat{\mathbf{j}} + E_z(r,\theta,\varphi)$$

$$(r, \theta, \varphi) = \frac{\rho_0}{4\pi\varepsilon_0} \int_{0}^{\infty} \int_{0}^{\infty} \int_{0}^{\infty} \frac{c}{[r^2]}$$

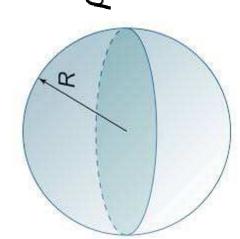
$$(x, \theta, \varphi) = \frac{2\pi}{4\pi\epsilon_0} \int_0^{2\pi} \int_0^{\pi} \frac{\cos\varphi'(r \sin\theta \cos\varphi - r' \sin\theta' \cos\varphi') r'^2 \sin\theta' dr' d\theta' dr'}{[r^2 + r'^2 - 2rr' \sin\theta \sin\theta' \cos(\varphi - \varphi') - 2rr' \cos\theta \cos\theta']}$$

$$(\theta, \varphi) = \frac{\rho_0}{4\pi\epsilon_0} \int_{-\infty}^{\infty} \int_{-\infty}^{$$

$$(r, \theta, \varphi) = \frac{2\pi \pi R}{4\pi\epsilon_0} \int_{0}^{2\pi} \int_{0}^{\pi} \int_{0}^{R} \frac{\cos\varphi'(r \sin\theta \sin\varphi - r' \sin\theta' \sin\varphi') r'^2 \sin\theta' dr' d\theta' dr'}{[r^2 + r'^2 - 2rr' \sin\theta \sin\theta' \cos(\varphi - \varphi') - 2rr' \cos\theta \cos\theta']}$$

$$=\frac{2\pi \pi R}{4\pi\epsilon_0}\int_{1}^{2\pi}\int_{1}^{$$

$$(r, \theta, \varphi) = \frac{\rho_0}{4\pi\epsilon_0} \int_0^{2\pi} \int_0^{\pi} \int_0^{R} \frac{\cos\varphi'(r\cos\theta - r'\cos\theta') r'^2 \sin\theta' dr' d\theta' d\varphi'}{[r^2 + r'^2 - 2rr' \sin\theta \sin\theta'\cos(\varphi - \varphi') - 2rr'\cos\theta\cos\theta']}$$



$$\rho(\vec{r}) = \rho_0 \cos \varphi$$

$$\vec{E}(\vec{r}) = E_x(r,\theta,\varphi)\,\hat{\mathbf{i}} + E_y(r,\theta,\varphi)\,\hat{\mathbf{j}} + E_z(r,\theta,\varphi)$$

$$(r, \theta, \varphi) = \frac{\rho_0}{4\pi\varepsilon_0} \int_{0}^{\infty} \int_{0}^{\infty} \int_{0}^{\infty} \frac{c}{[r^2]}$$

$$(x, \theta, \varphi) = \frac{2\pi}{4\pi\epsilon_0} \int_0^{2\pi} \int_0^{\pi} \frac{\cos\varphi'(r \sin\theta \cos\varphi - r' \sin\theta' \cos\varphi') r'^2 \sin\theta' dr' d\theta' dr'}{[r^2 + r'^2 - 2rr' \sin\theta \sin\theta' \cos(\varphi - \varphi') - 2rr' \cos\theta \cos\theta']}$$

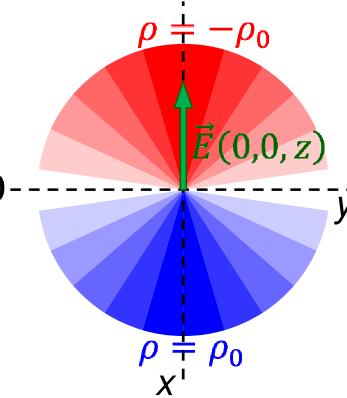
$$(\theta, \varphi) = \frac{\rho_0}{4\pi\epsilon_0} \int_{-\infty}^{\infty} \int_{-\infty}^{$$

$$(r, \theta, \varphi) = \frac{2\pi \pi R}{4\pi\epsilon_0} \int_{0}^{2\pi} \int_{0}^{\pi} \int_{0}^{R} \frac{\cos\varphi'(r \sin\theta \sin\varphi - r' \sin\theta' \sin\varphi') r'^2 \sin\theta' dr' d\theta' dr'}{[r^2 + r'^2 - 2rr' \sin\theta \sin\theta' \cos(\varphi - \varphi') - 2rr' \cos\theta \cos\theta']}$$

$$=\frac{2\pi \pi R}{4\pi\epsilon_0}\int_{1}^{2\pi}\int_{1}^{$$

$$(r, \theta, \varphi) = \frac{\rho_0}{4\pi\epsilon_0} \int_0^{2\pi} \int_0^{\pi} \int_0^{R} \frac{\cos\varphi'(r\cos\theta - r'\cos\theta') r'^2 \sin\theta' dr' d\theta' d\varphi'}{[r^2 + r'^2 - 2rr' \sin\theta \sin\theta'\cos(\varphi - \varphi') - 2rr'\cos\theta\cos\theta']}$$

$$\rho(\vec{r}) = \rho_0 \cos \varphi$$



Por la forma de $\rho(\varphi)$, podemos deducir que en los puntos del eje z:

$$\vec{E}(0,0,z) = -|E|\hat{1}$$

Esto se puede obtener demostrando que las integrales

$$E_{y}(r,\theta,\varphi) = \frac{\rho_{0}}{4\pi\varepsilon_{0}} \int_{0}^{2\pi} \int_{0}^{\pi} \int_{0}^{R} \frac{\cos\varphi'(r\sin\theta\,\sin\varphi - r'\sin\theta'\sin\varphi')\,r'^{2}\sin\theta'dr'\varphi'}{[r^{2} + r'^{2} - 2rr'\sin\theta\sin\theta'\cos(\varphi - \varphi') - 2rr'\cos\theta\varphi']}$$

$$E_z(r,\theta,\varphi) = \frac{\rho_0}{4\pi\varepsilon_0} \int_0^{2\pi} \int_0^{\pi} \int_0^R \frac{\cos\varphi'(r\cos\theta - r'\cos\theta') r'^2 \sin\theta' dr' d\theta' d\varphi'}{[r^2 + r'^2 - 2rr'\sin\theta\sin\theta'\cos(\varphi - \varphi') - 2rr'\cos\thetac']}$$

dan resultado 0 cuando $\theta=0$ o $\theta=0$

Este problema resuelto es un material previo a las clases a distancia de Física II de la FIUBA. Por supuesto que en ese espacio podemos seguir hablando acerca de lo que acabo de contarles.

Gracias y saludos.

Rodolfo Aparicio