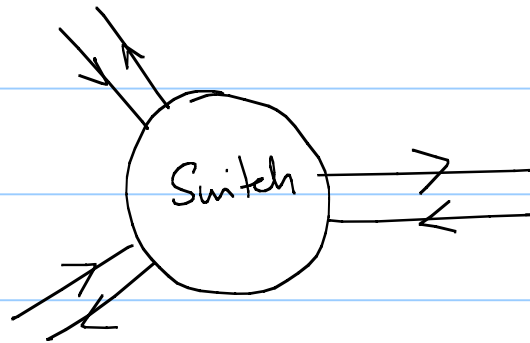


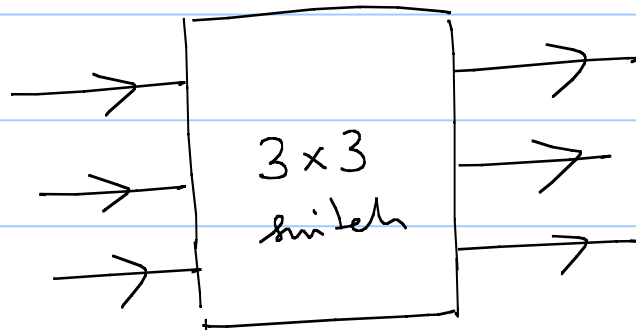
06. High-speed Switches

Note Title

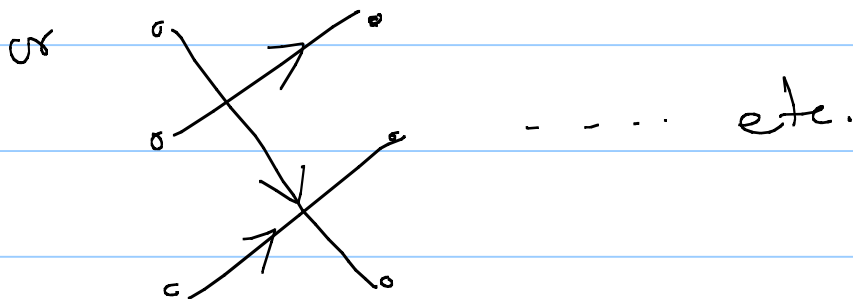
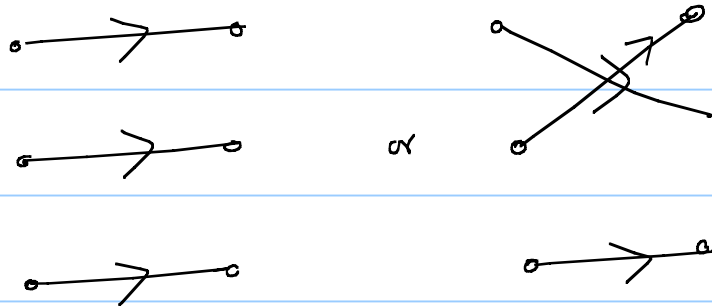
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- Each link connected to a switch consists of an incoming wire and an outgoing wire
- They are interconnected using a switch fabric: the switch can connect each input to only one output at each time and each output can be connected to only one input at a time.
- $N \times N$ switch: N input ports and N output ports



Possible input-output connections:



In general, in an $N \times N$ switch, there are $N!$ possible

schedules (interconnections). Each schedule is a matching in a bipartite graph.

In matrix form, each schedule can be represented by a permutation matrix: exactly one 1 in each row and column


$$= \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Capacity region or throughput region (e)

Let $M_1, M_2, \dots, M_{N!}$ be the set of permutation matrices for

an $N \times N$ switch. Let λ_{ij} be the arrival rate of packets from input i to output j . The matrix λ is supportable only if

$$\lambda \leq \sum_i \alpha_i M_i$$

for some $\alpha_i \geq 0$, $\sum_i \alpha_i = 1$.

□

Question: Can the queues be stabilized without knowing λ but only knowing that $\lambda(1+\epsilon) \in \mathcal{C}$ for some $\epsilon > 0$?

We will use Foster-Lyapunov theory to answer this question.

Assume $a_{ij}(u) = \text{Ber}(\lambda_{ij})$

$$V = \sum_{i,j} q_{ij}^2$$

$$E(V(k+1) - V(k) \mid q(k) = q)$$

$$\leq E\left(\sum_{i,j} (q_{ij} + a_{ij} - s_{ij})^2 - q_{ij}^2\right)$$

$$\leq 2 \sum_{i,j} q_{ij} (\lambda_{ij} - s_{ij}) + K$$

choose $\{s_{ij}\} \in \underbrace{\{M_1, M_2, \dots, M_N\}}_{\triangleq \mathcal{M}}$
to solve

$$\max_{s \in \mathcal{M}} \sum_{i,j} q_{ij} s_{ij}$$

Useful insight: Recall

$\mathcal{C} = \mathcal{C}_0(\mathcal{M})$, where \mathcal{C}_0 is

the convex hull.

$$\max_{s \in \mathcal{M}} \sum_{i,j} q_{ij} s_{ij} = \max_{s \in \mathcal{C}} \sum_{i,j} q_{ij} s_{ij}$$

Why? if $s \in \mathcal{L}$, then

$$s = \sum_e \alpha_e M_e$$

$$\Rightarrow s_{ij} = \sum_e \alpha_e M_e(i, j)$$

$$\sum_{i,j} q_{ij} s_{ij} = \sum_{i,j} q_{ij} \sum_e \alpha_e M_e(i, j)$$

$$= \sum_e \alpha_e \sum_{i,j} q_{ij} M_e(i, j)$$

Thus, we will make $\alpha_e = 1$

for M_e which maximizes

$$\sum_{i,j} q_{ij} M_e(i, j).$$

Back to derivation: since

$$\lambda(1+\epsilon) \in \mathcal{L}$$

$$\sum_{i,j} \lambda_{ij} (1+\epsilon) q_{ij} \leq \sum_{i,j} s_{ij} q_{ij}$$

Thus, expected drift is

$$-\epsilon E\left(\sum_{ij} \lambda_{ij} q_{ij}\right) + K$$

which is negative for large q . By Foster-Lyapunov, the system is stable.

Scheduling algorithm (MaxWeight)

$$\max_{M_e \in M} \sum_{ij} q_{ij} M_e(i, j)$$

Birkhoff-von Neumann theorem

Any $\{\lambda_{ij}\}$ s.t.

$$\sum_i \lambda_{ij} \leq 1$$

$$\text{and } \sum_j \lambda_{ij} \leq 1$$

} - (I)

can be written as

$$\Lambda = \sum_x \alpha_x M_x$$

for some

$$\alpha_x \geq 0, \quad \sum_x \alpha_x = 1$$

□

Thus, (I) is another characterization of the capacity region.