Mastering Embedded System Online Diploma

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First Term (Final Project 1)

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Pressure Detection Project

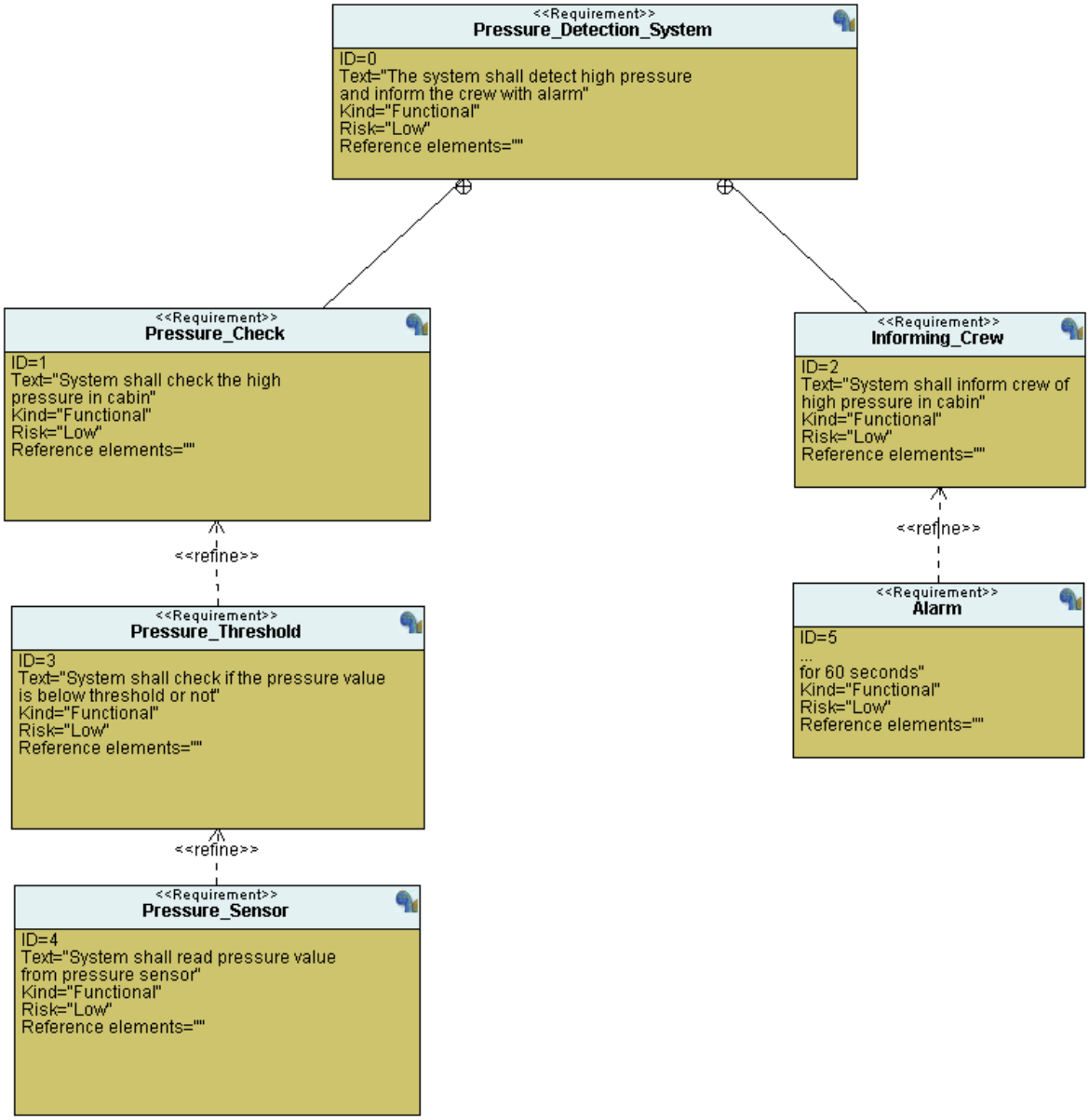
Case Study:-

- A Pressure controller that monitors the pressure level in a cabin with an alarm
- If the pressure exceeds **20 bars** in the cabin the alarm goes off for **60 seconds**

Assumptions:-

- Controller set up and shutdown procedures are not modeled
- Controller maintenance is not modeled
- Pressure sensor used never fails
- Alarm never fails
- No power cut

Requirement diagram:-

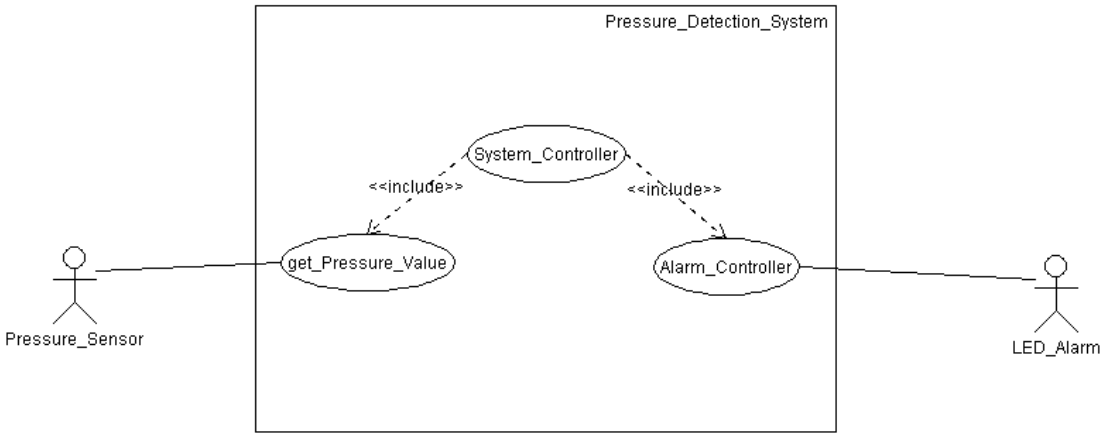


Space Exploration:-

- This is a simple project , it only needs one ECU which will be **STM32**

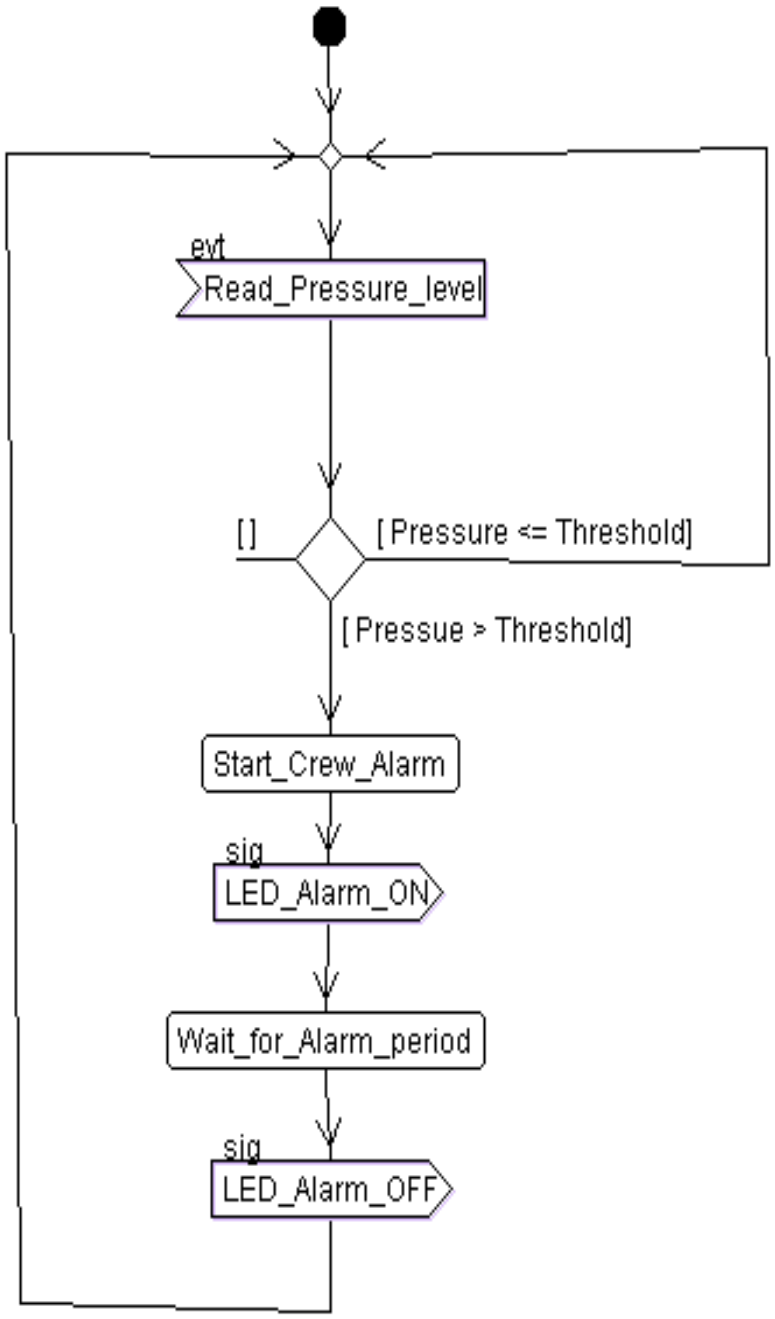
System Analysis:-

- **Use Case Diagram:-**

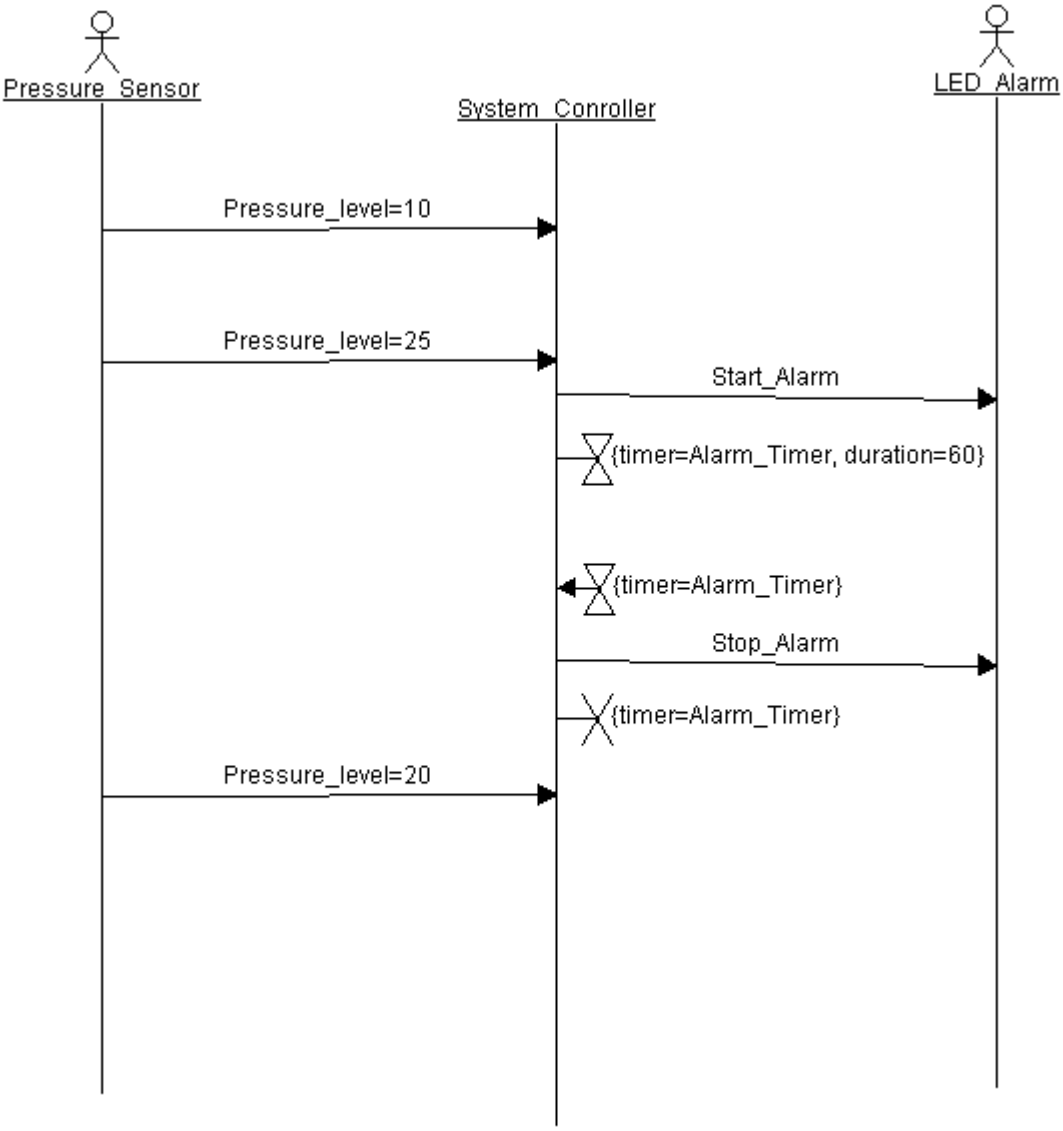


1. get_Pressure_Value reads the pressure level from Pressure Sensor
2. System_Controller compares the pressure level with the threshold "20 bar" , if it exceeds the threshold it send a signal to Alarm_Controller
3. Alarm_Controller manges the LED_Alarm whether to turn it on for 60 second or to turn it off

- **Activity Diagram:-**



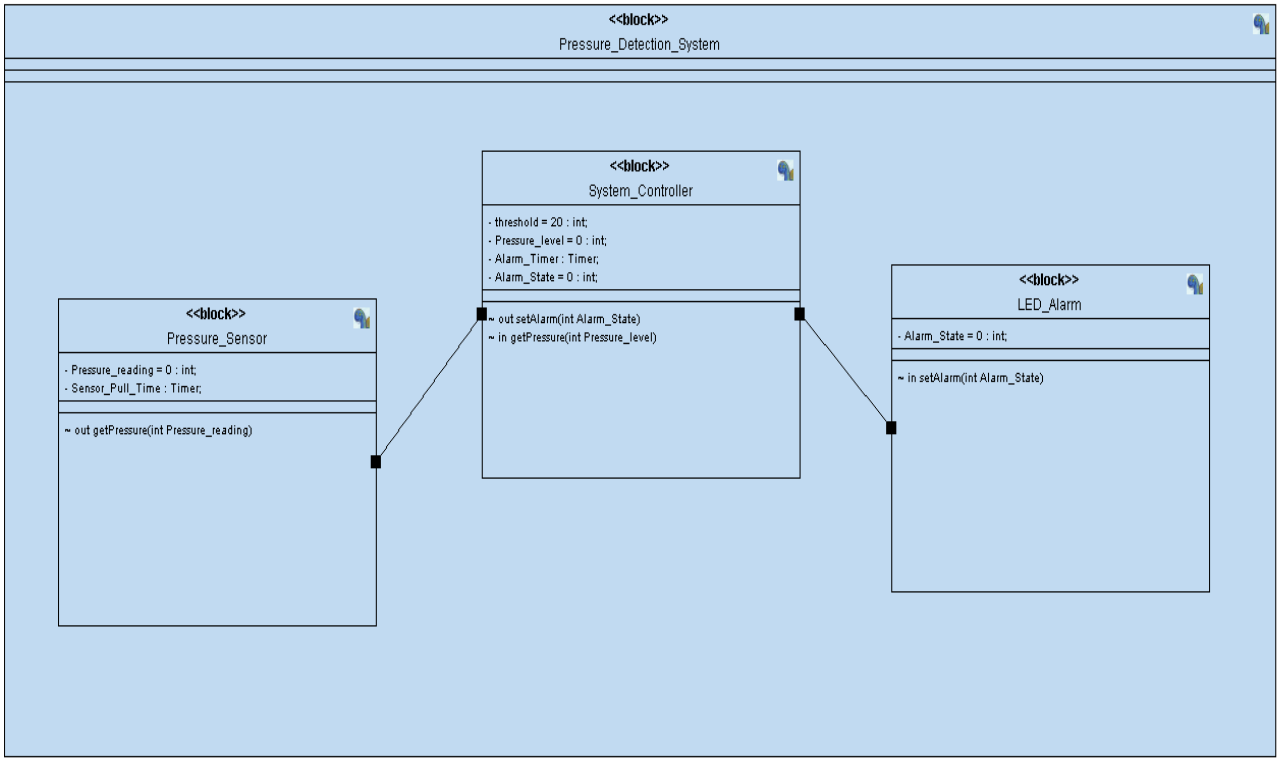
- **Sequence Diagram:-**



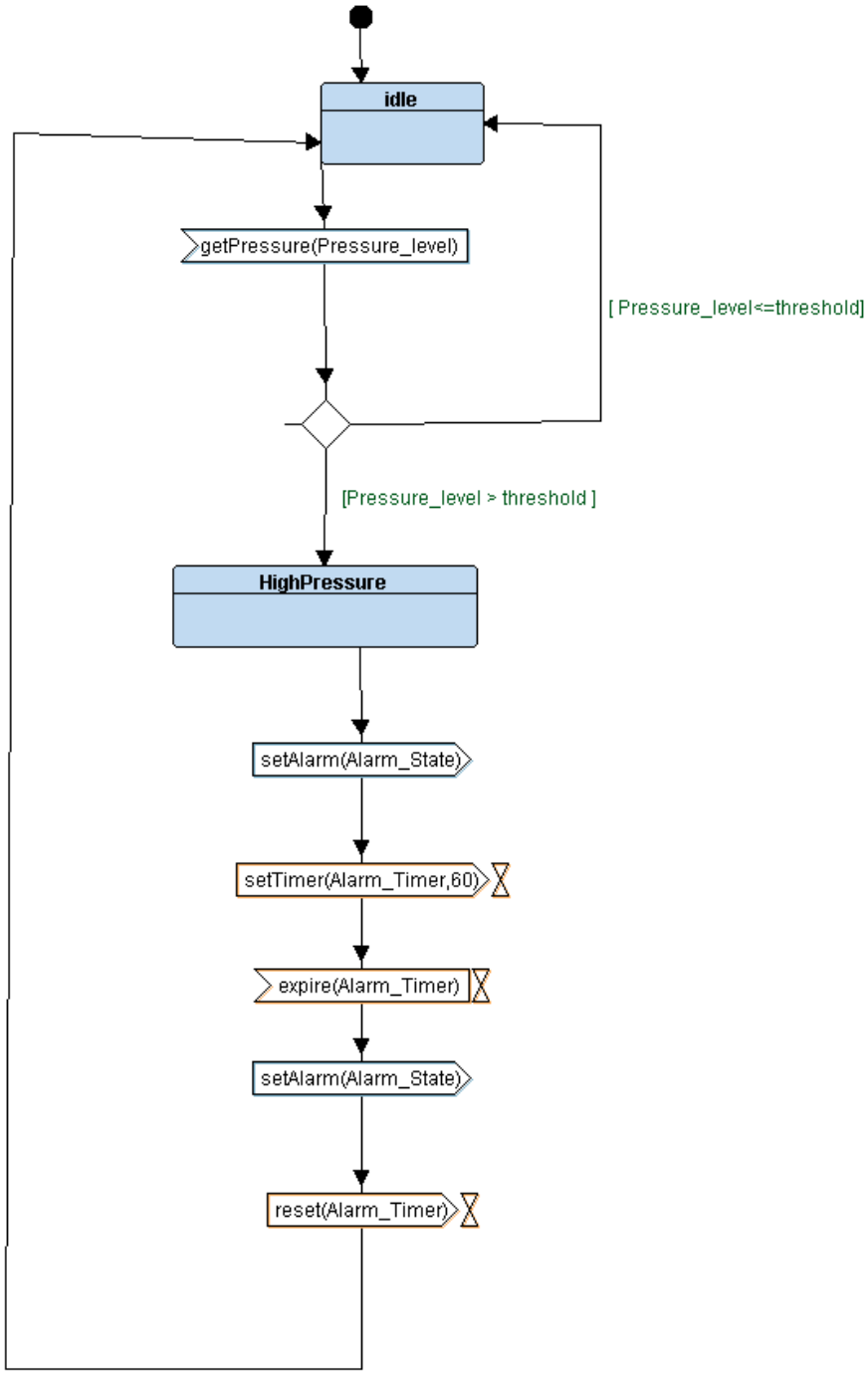
Here we notice the when pressure_level=20 nothing happens , since in algorithm it will be defined as less than threshold case

System Design:-

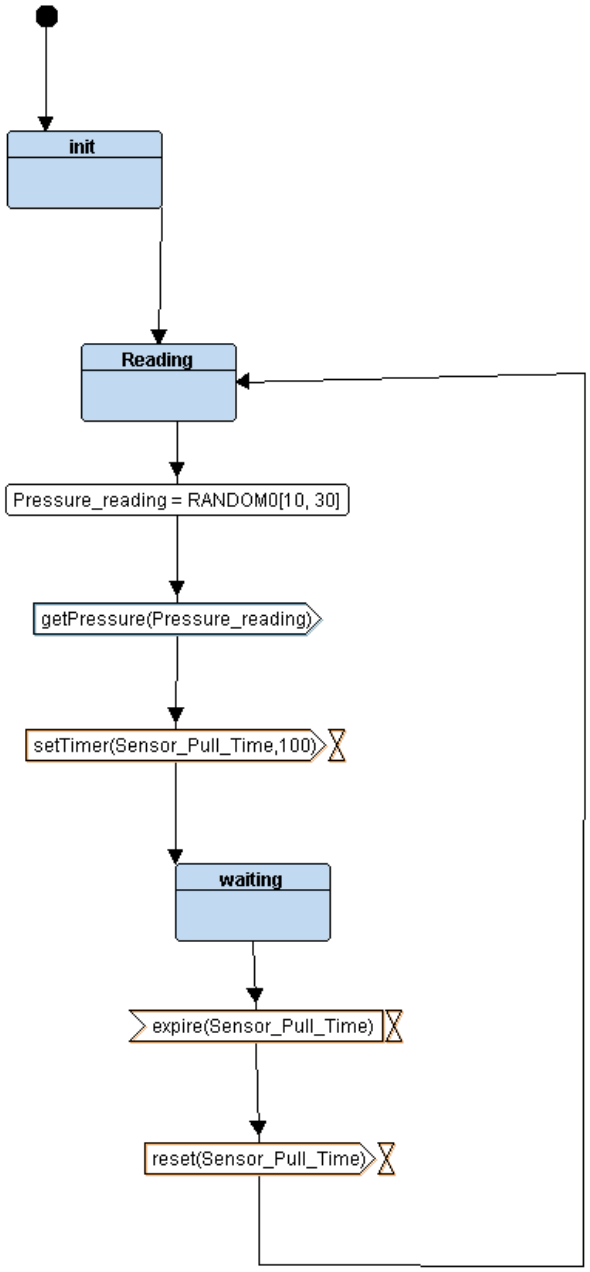
- **Block Diagram:-**



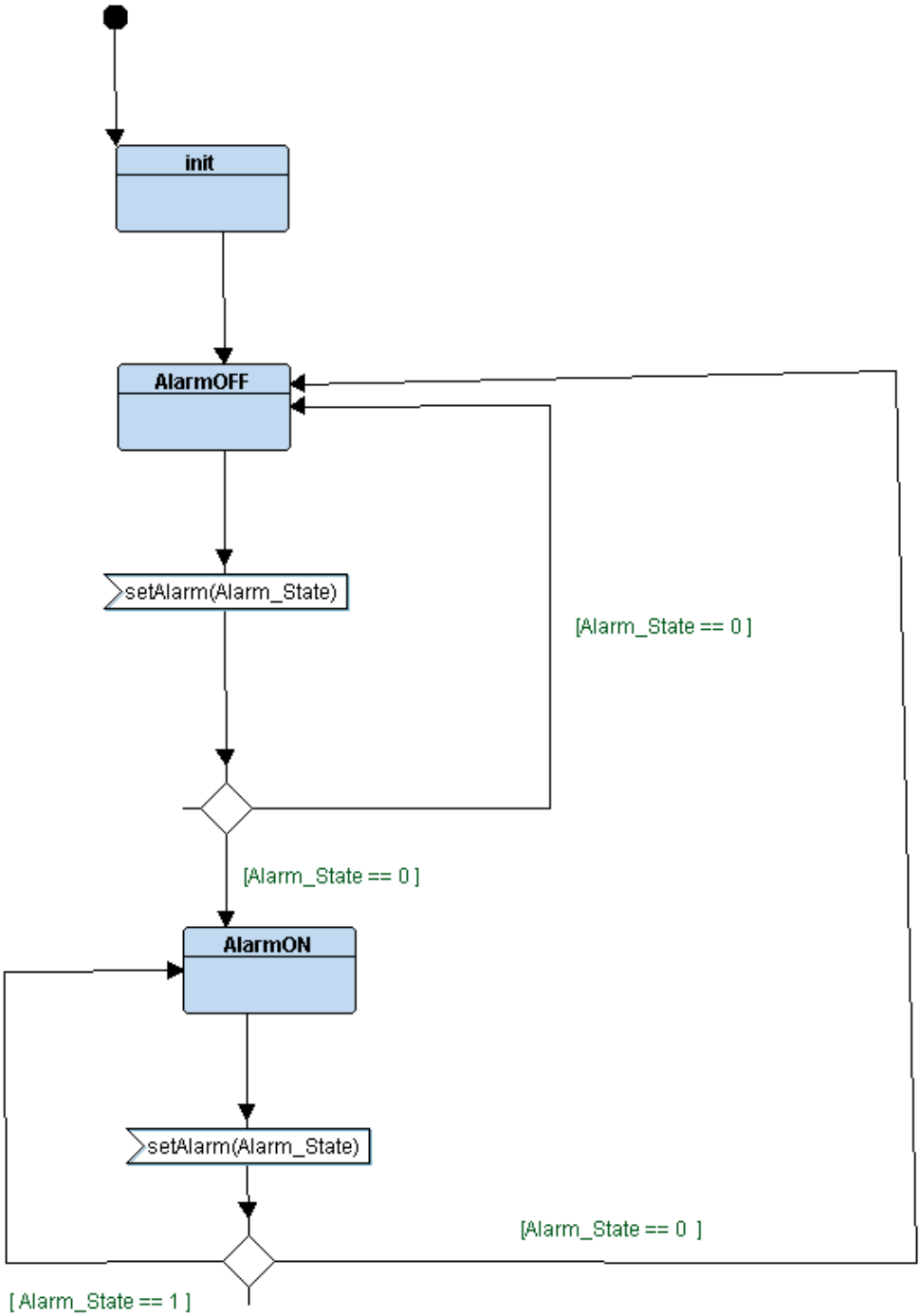
- **State machine System_Controller:-**



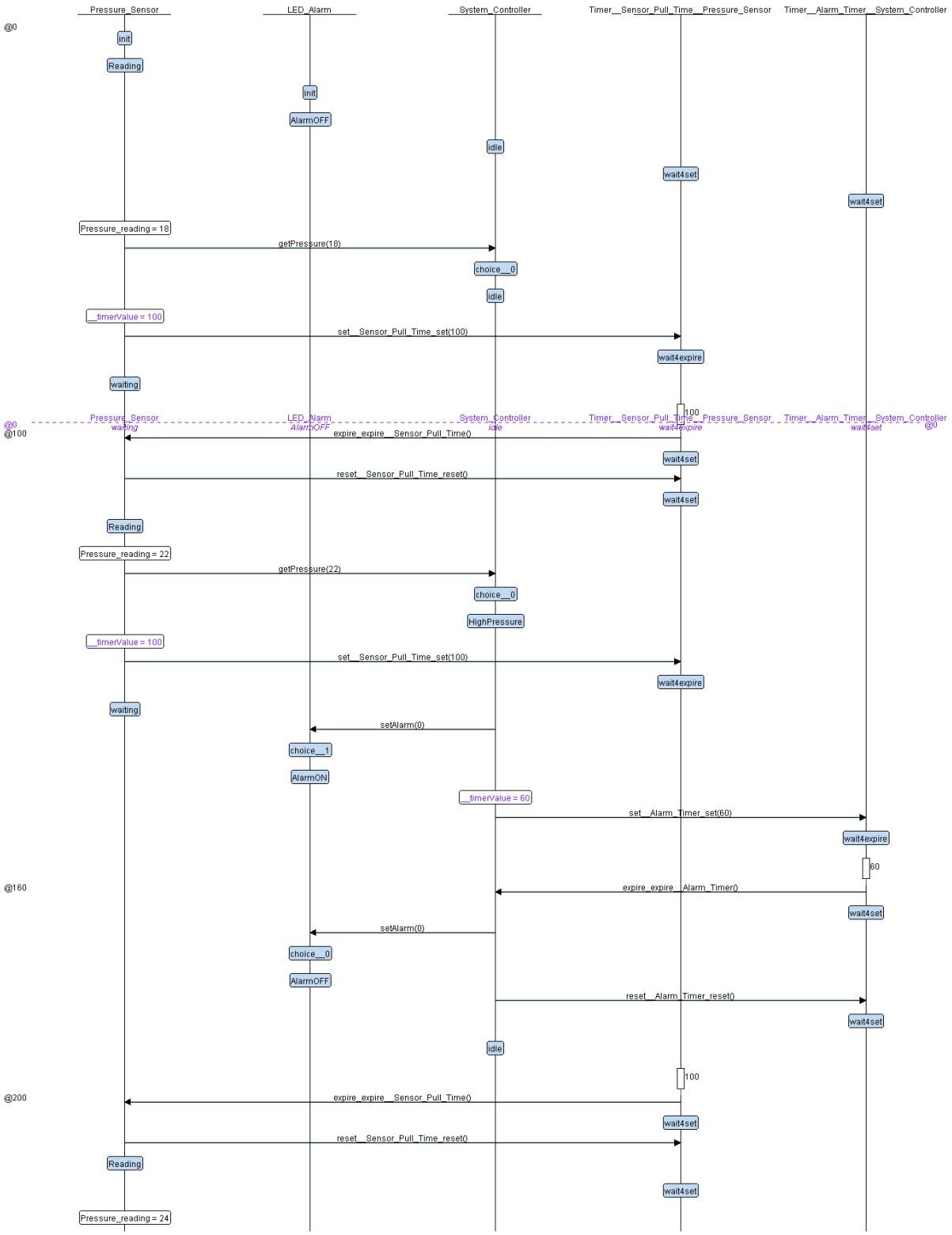
- **State machine Pressure_Sensor:-**



- **State machine LED_Alarm:-**



- **Verification of logic using trace:-**



Software of each module:-

- **Main.c**

```c
#include <stdint.h>
#include <stdio.h>

#include "driver.h"
#include "Alarm.h"
#include "Controller.h"
#include "states.h"
#include "pSensor.h"

void setup()
{
    GPIO_INITIALIZATION();
    pSensor_State=STATE(reading);
    Controller_State=STATE(idle);
    Alarm_State=STATE(AlarmOFF);
}
int main (){
    volatile int i;
    setup();
    while (1)
    {
        pSensor_State();
        Controller_State();
        Alarm_State();
        for(i=1;i<1000;i++);
    }

}
```

- **Controller.c**

```c
 */
#include"driver.h"
#include"Controller.h"
#include"Alarm.h"
#include"pSensor.h"
#include"states.h"
#define threshold 20
unsigned int Pressure_level=0;
unsigned int Alarm_Condition=1;
void(*Controller_State)();

void getPressure(int p)
{
    Pressure_level = p;
    (Pressure_level<=threshold) ? (Controller_State=STATE(idle)) : (Controller_State=STATE(HighPressure));
}

STATE_define(idle)
{
    Controller_State_ID=idle;
    Alarm_Condition=1;
    setAlarm(Alarm_Condition);
}


STATE_define(HighPressure)
{
    Controller_State_ID=HighPressure;
    Alarm_Condition=0;
    setAlarm(Alarm_Condition);
}
```

- **Controller.h**

```c
/*
 * Controller.h
 *
 *  Created on: Aug 22, 2021
 *      Author: Arshy
 */

#ifndef CONTROLLER_H_
#define CONTROLLER_H_
#include"states.h"
enum{
    idle,
    HighPressure
}Controller_State_ID;

STATE_define(idle);
STATE_define(HighPressure);

extern void (*Controller_State)();

#endif /* CONTROLLER_H_ */
```

- **Pressure Sensor.c**

```c
/*
 * pSensor.c
 *
 *  Created on: Aug 22, 2021
 *      Author: Arshy
 */

#include"pSensor.h"
#include"driver.h"

int Pressure_reading=0;
void(*pSensor_State)();

STATE_define(reading)
{
    pSensor_State_ID=reading;
    Pressure_reading=getPressureVal();
    getPressure(Pressure_reading);
    pSensor_State = STATE(reading);
}
```

- **Pressure Sensor.h**

```c
/*
 * pSensor.h
 *
 *  Created on: Aug 22, 2021
 *      Author: Arshy
 */

#ifndef PSENSOR_H_
#define PSENSOR_H_
#include"states.h"
#include"driver.h"
enum{
    reading
}pSensor_State_ID;

STATE_define(reading);

extern void (*pSensor_State)();


#endif /* PSENSOR_H_ */

```

- **Alarm.c**

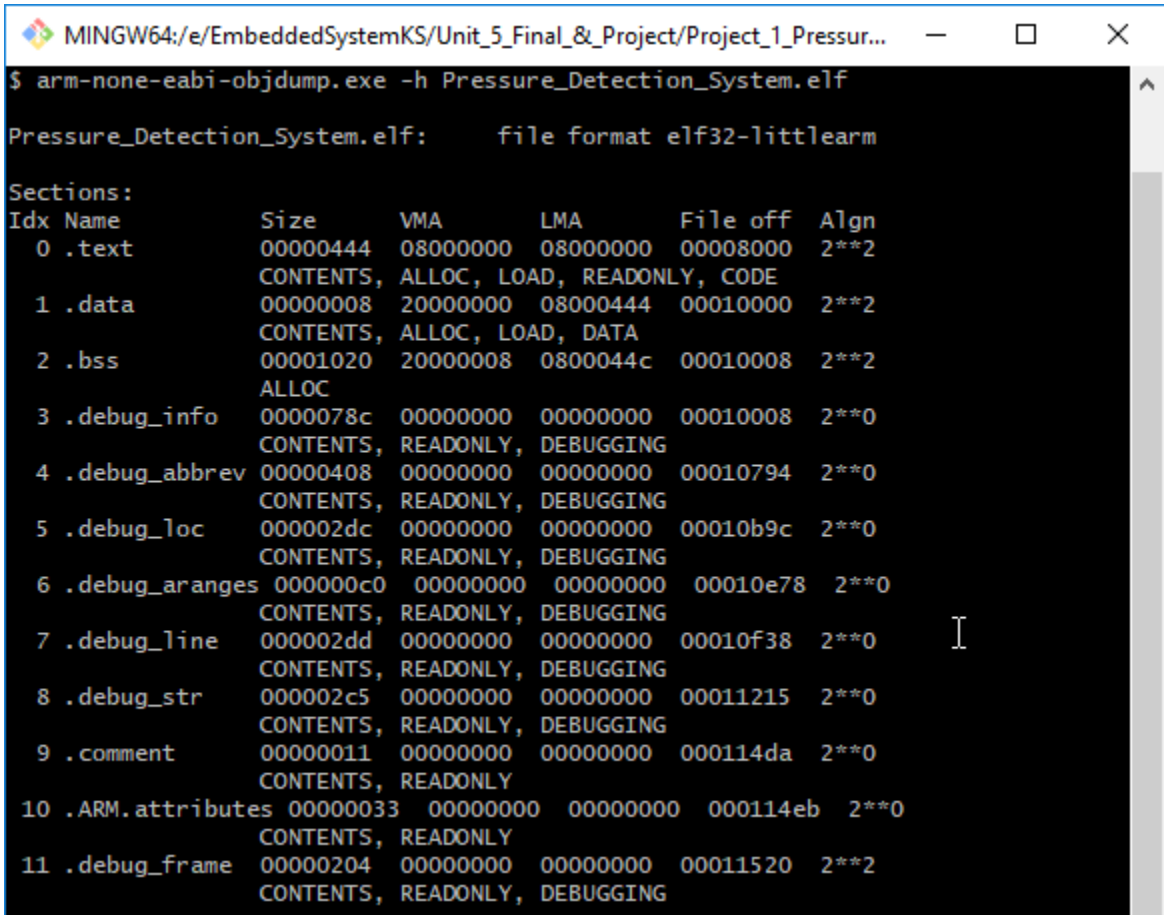
```c
/*
 * Alarm.c
 *
 *  Created on: Aug 22, 2021
 *      Author: Arshy
 */
#include"driver.h"
#include"Alarm.h"

int Alarm=1;

void (*Alarm_State)();
void setAlarm(int a)
{
    Alarm = a;
    (Alarm==1) ? (Alarm_State=STATE(AlarmOFF)) : (Alarm_State=STATE(AlarmON));
}

STATE_define(AlarmOFF)
{
    Alarm_State_ID=AlarmOFF;
    Set_Alarm_actuator(1);

}

STATE_define(AlarmON)
{
    Alarm_State_ID=AlarmON;
    Set_Alarm_actuator(0);
    Delay(2000);//assume 2000 = 60sec
}

```

- **Alarm.h**

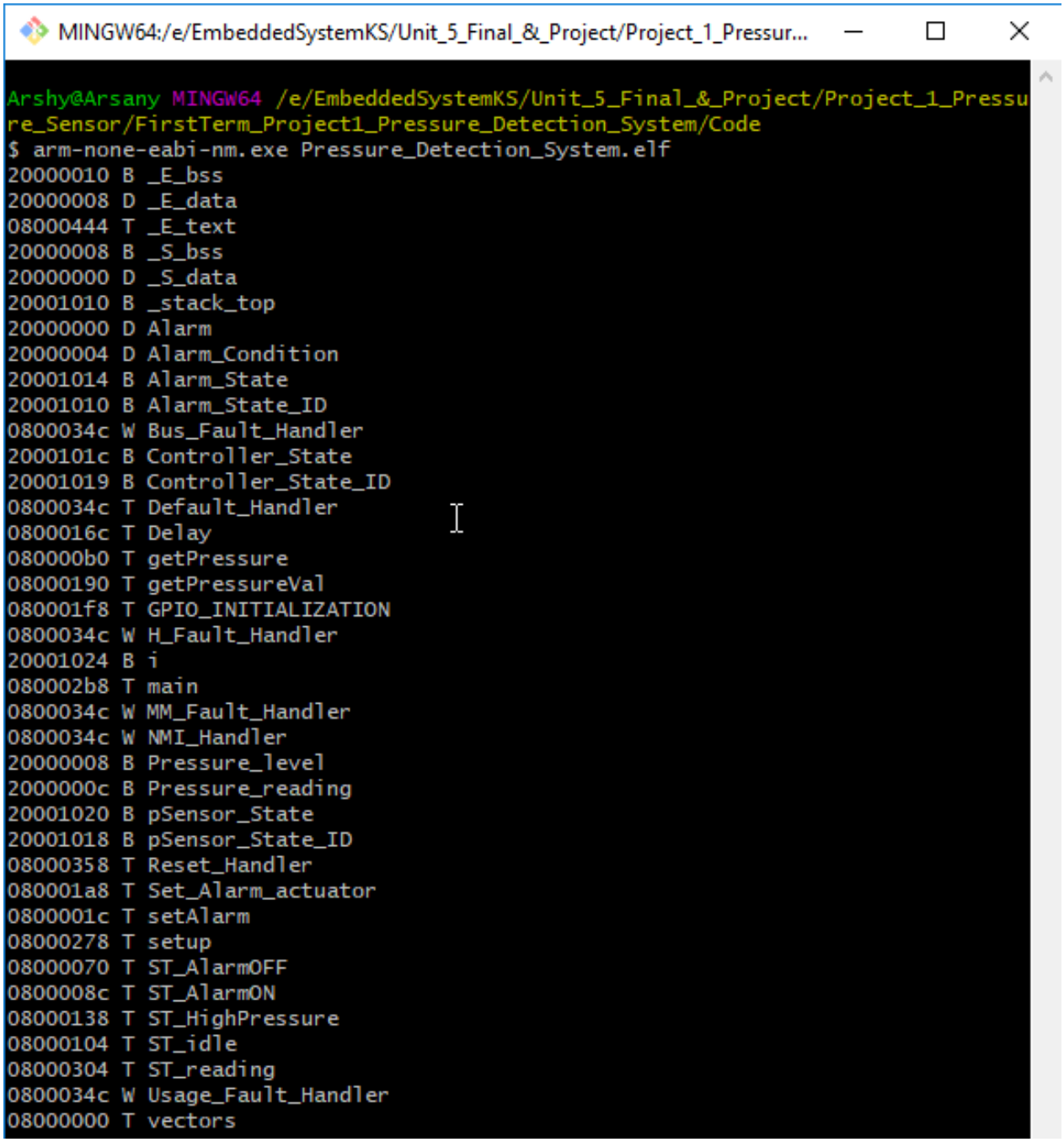
```c
/*
 * Alarm.h
 *
 *  Created on: Aug 22, 2021
 *      Author: Arshy
 */

#ifndef ALARM_H_
#define ALARM_H_
#include"states.h"
#include"driver.h"
enum{
    AlarmOFF,
    AlarmON
}Alarm_State_ID;

STATE_define(AlarmOFF);
STATE_define(AlarmON);

extern void (*Alarm_State)();

#endif /* ALARM_H_ */

```

Software Analysis:-

- **Section Table**



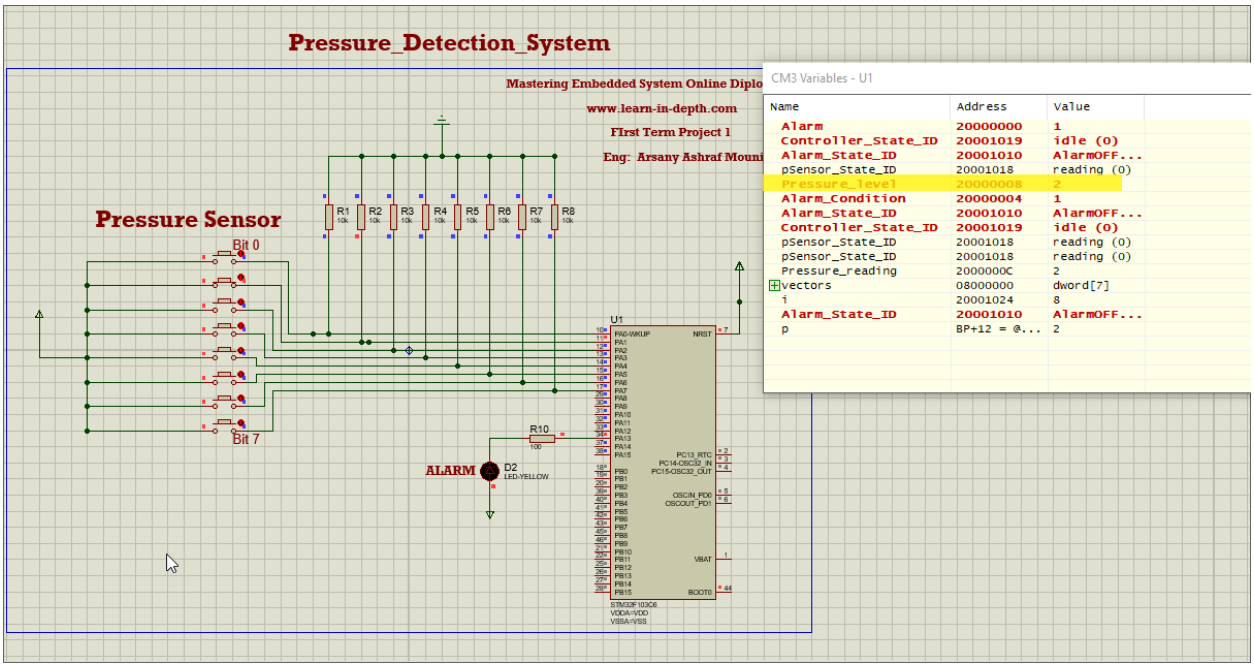
- **Symbol Table**



- **Map file**

```
Allocating common symbols
Common symbol       size              file

pSensor_State_ID    0x1               Controller.o
Alarm_State_ID      0x1               Alarm.o
Controller_State_ID
                    0x1               Controller.o
i                   0x4               startup.o
Alarm_State         0x4               Alarm.o
Controller_State    0x4               Controller.o
pSensor_State       0x4               pSensor.o

Memory Configuration

Name             Origin             Length             Attributes
flash            0x08000000         0x00020000         xr
sram             0x20000000         0x00005000         xrw
*default*        0x00000000         0xffffffff

Linker script and memory map


.text           0x08000000      0x444
 *(.vectors*)
 .vectors       0x08000000       0x1c startup.o
                0x08000000                vectors
 *(.rodata*)
 *(.text*)
 .text          0x0800001c       0x94 Alarm.o
                0x0800001c                setAlarm
                0x08000070                ST_AlarmOFF
                0x0800008c                ST_AlarmON
 .text          0x080000b0       0xbc Controller.o
                0x080000b0                getPressure
                0x08000104                ST_idle
                0x08000138                ST_HighPressure
 .text          0x0800016c      0x10c driver.o
                0x0800016c                Delay
                0x08000190                getPressureVal
                0x080001a8                Set_Alarm_actuator
                0x080001f8                GPIO_INITIALIZATION
 .text          0x08000278       0x8c main.o
                0x08000278                setup
                0x080002b8                main
 .text          0x08000304       0x48 pSensor.o
                0x08000304                ST_reading
 .text          0x0800034c       0xf8 startup.o
                0x0800034c                Bus_Fault_Handler
                0x0800034c                H_Fault_Handler
                0x0800034c                MM_Fault_Handler
                0x0800034c                Usage_Fault_Handler
                0x0800034c                Default_Handler
                0x0800034c                NMI_Handler
                0x08000358                Reset_Handler
                0x08000444                _E_text = .
```

Simulation:-


Pressure_Detection_System
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FIrst Term Project 1
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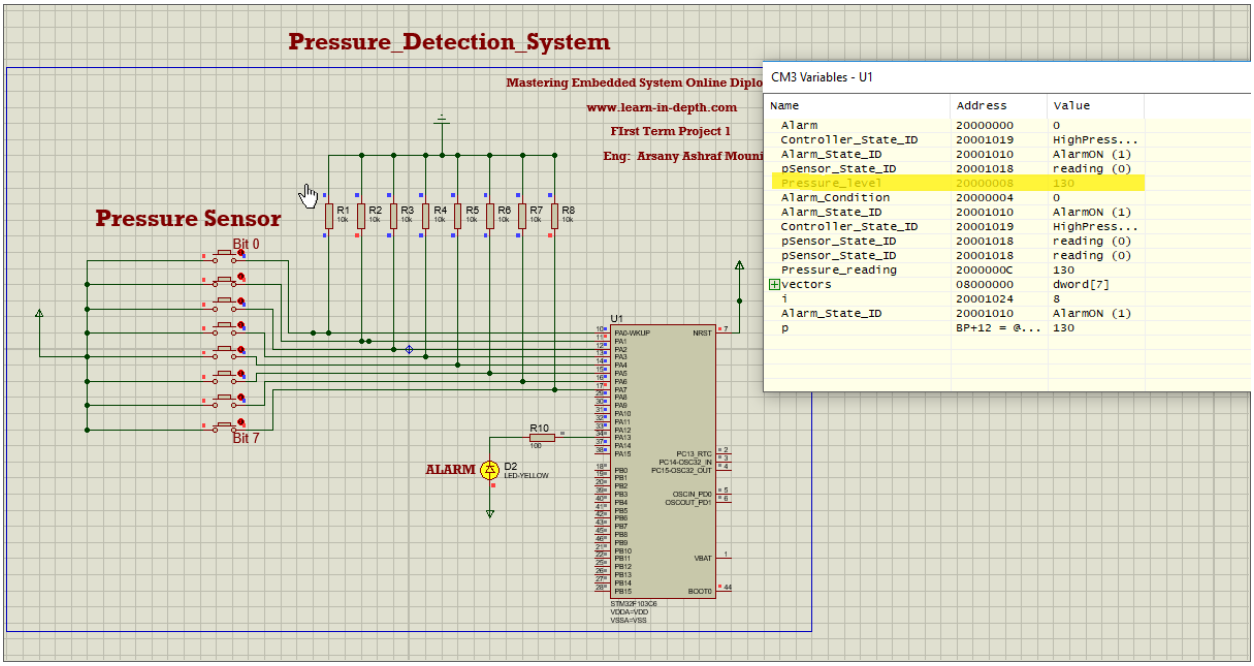
Pressure Sensor
Bit 0
Bit 7
R1
R2
R3
R4
R5
R6
R7
R8
R10
ALARM
D2
LED-YELLOW
U1
CM3 Variables - U1
Name
Address
Value
Alarm 20000000 1
Controller_State_ID 20001019 idle (0)
Alarm_State_ID 20001010 AlarmOFF...
pSensor_State_ID 20001018 reading (0)
Pressure_level 20000008 2
Alarm_Condition 20000004 1
Alarm_State_ID 20001010 AlarmOFF...
Controller_State_ID 20001019 idle (0)
pSensor_State_ID 20001018 reading (0)
pSensor_State_ID 20001018 reading (0)
Pressure_reading 2000000C 2
vectors 08000000 dword[7]
i 20001024 8
Alarm_State_ID 20001010 AlarmOFF...
p BP+12 = @... 2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FIrst Term Project 1
Eng: Arsany Ashraf Mouni
Pressure Sensor
Bit 0
Bit 7
R1
R2
R3
R4
R5
R6
R7
R8
R10
ALARM
D2
LED-YELLOW
U1
CM3 Variables - U1
Name
Address
Value
Alarm 20000000 0
Controller_State_ID 20001019 HighPress...
Alarm_State_ID 20001010 AlarmON (1)
pSensor_State_ID 20001018 reading (0)
Pressure_level 20000008 130
Alarm_Condition 20000004 0
Alarm_State_ID 20001010 AlarmON (1)
Controller_State_ID 20001019 HighPress...
pSensor_State_ID 20001018 reading (0)
pSensor_State_ID 20001018 reading (0)
Pressure_reading 2000000C 130
vectors 08000000 dword[7]
i 20001024 8
Alarm_State_ID 20001010 AlarmON (1)
p BP+12 = @... 130