

This is a part of SFQED-Loops script collection  
developed for calculating loop processes in  
Strong-Field Quantum Electrodynamics.  
The scripts are available on <https://github.com/ArsenyMironov/SFQED-Loops>

If you use this script in your research, please, consider  
citing our papers:

- A. A. Mironov, S. Meuren, and A. M. Fedotov, PRD 102, 053005 (2020),  
<https://doi.org/10.1103/PhysRevD.102.053005>
- A. A. Mironov, A. M. Fedotov, arXiv:2109.00634 (2021)

If you have any questions, please, don't hesitate to contact:  
[mironov.hep@gmail.com](mailto:mironov.hep@gmail.com)

Copyright (C) 2021 Arseny Mironov, <https://scholar.google.ru/citations?user=GQwNEuwAAAAJ>

This program is free software: you can redistribute it and/or modify  
it under the terms of the GNU General Public License as published by  
the Free Software Foundation, either version 3 of the License, or  
(at your option) any later version.

This program is distributed in the hope that it will be useful,  
but WITHOUT ANY WARRANTY; without even the implied warranty of  
MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the  
GNU General Public License for more details.

You should have received a copy of the GNU General Public License  
along with this program. If not, see <https://www.gnu.org/licenses/>.

$$\text{wavy line with shaded circle} = \text{wavy line} + \text{wavy line with } 1\text{PI} + \text{wavy line with } 1\text{PI} \text{ } 1\text{PI} + \dots$$

`NotebookEvaluate[NotebookOpen[NotebookDirectory[] <> "definitions.nb"]]`

**FeynCalc** 9.2.0. For help, use the documentation center, check out the wiki or write to the mailing list.

See also the supplied examples. If you use FeynCalc in your research, please cite

- V. Shtabovenko, R. Mertig and F. Orellana,  
Comput. Phys. Commun., 207C, 432–444, 2016, arXiv:1601.01167
- R. Mertig, M. Böhm, and A. Denner, Comput. Phys. Commun., 64, 345–359, 1991.

### Exact photon propagator in momentum representation

$$D_{\mu\nu}^c(l) =$$

$$D_0(l^2, \chi_l) g_{\mu\nu} + D_1(l^2, \chi_l) \epsilon_{\mu}^{(1)}(l) \epsilon_{\nu}^{(1)}(l) + D_2(l^2, \chi_l) \epsilon_{\mu}^{(2)}(l) \epsilon_{\nu}^{(2)}(l);$$

$l^{\mu}$  – the photon propagator 4 – momentum;

$$\chi_l = \frac{e}{m^3} \sqrt{-(F_{\mu\nu} l^{\nu})^2};$$

$$\epsilon_{\mu}^{(1)}(l) = \frac{e F_{\mu\nu} l^{\nu}}{m^3 \chi_l};$$

$$\epsilon_{\mu}^{(2)}(l) = \frac{e F_{\mu\nu}^* l^{\nu}}{m^3 \chi_l}; \quad F^{*\mu\nu} = \frac{1}{2} \epsilon^{\mu\nu\delta\lambda} F_{\delta\lambda};$$

$$(\epsilon^{(i)}(l))^2 = -1;$$

$$D_0(l^2, \chi_l) = \frac{-i}{l^2 - l^2 \hat{\Pi}}, \quad D_{1,2}(l^2, \chi_l) = \frac{i \Pi_{1,2}}{(l^2 - l^2 \hat{\Pi})(l^2 - l^2 \hat{\Pi} - \Pi_{1,2})};$$

$$l^2 \hat{\Pi} = l^2 \hat{\Pi}(l^2, \chi_l),$$

$\Pi_{1,2} = \Pi_{1,2}(l^2, \chi_l)$  – polarization operator eigenfunctions;

**Our goal : exact photon propagator in coordinate representation**

$$D_{\mu\nu}^c(x) = \frac{\Lambda^{4-D}}{(2\pi)^D} \int d^D l D_{\mu\nu}^c(l) e^{-ilx};$$

**Let's define photon momentum and the coordinate variables**

NewMomentum["l"]

NewCoordinate["x"]

$$\left\{ l^{\alpha}, l^2, k \cdot l, F l^{\alpha}, F F l^{\alpha}, F D l^{\alpha}, a \cdot l, 0, 0, 0, -a^2 (k \cdot l), 0, 0, -\frac{m^6 \chi l^2}{e^2}, -\frac{m^6 \chi l^2}{e^2}, \frac{m^6 \chi l^2}{e^2}, 0, 0, 0, 0, 0, 0 \right\}$$

$$\left\{ x^{\alpha}, x^2, k \cdot x, a \cdot x, F x^{\alpha}, F F x^{\alpha}, F D x^{\alpha}, k \cdot x, 0, 0, 0, -a^2 (k \cdot x), 0, 0, -\frac{m^2 \xi^2 (k \cdot x)^2}{e^2}, -\frac{m^2 \xi^2 (k \cdot x)^2}{e^2}, \frac{m^2 \xi^2 (k \cdot x)^2}{e^2}, 0, 0, 0, 0, 0, 0 \right\}$$

**Eigenvectors and tensor structures**

We intentionally leave tensors and vectors uncontracted

```

e1[μ_, ν_] = e Ft[μ, ν] lν[ν] / m^3 / χl
e2[μ_, ν_] = e FDt[μ, ν] lν[ν] / m^3 / χl
T0[μ_, ν_] = MTD[μ, ν]
T1[μ_, ν_] = e1[μ, α] e1[ν, β]
T2[μ_, ν_] = e2[μ, α] e2[ν, β]
Contract[Contract[T1[μ, μ]] /. FieldSubstitutions]
Contract[Contract[T2[μ, μ]] /. FieldSubstitutions]

$$\frac{e l^\nu F(\mu, \nu)}{m^3 \chi l}$$


$$\frac{e l^\nu FD(\mu, \nu)}{m^3 \chi l}$$


$$g^{\mu \nu}$$


$$\frac{e^2 l^\alpha l^\beta F(\alpha, \mu) F(\beta, \nu)}{m^6 \chi l^2}$$


$$\frac{e^2 l^\alpha l^\beta FD(\alpha, \mu) FD(\beta, \nu)}{m^6 \chi l^2}$$

-1
-1

```

We write  $D^c_{\mu\nu}$  in the following form

$$\int d^D l \left[ \text{Coeff} * \text{Matrix} * \text{Exp} (i \text{ Phase}) \right],$$

where

Coeff – is a general multiplier for all terms,

Matrix – tensor part,

Phase – total phase of the expression,

We assume

$$Dk = Dk (l^2, \chi l)$$

$$\text{Coeff} = \Lambda^{4-D} / (2\pi)^D$$

$$\text{Matrix} = D0 * T0[\mu, \nu] + D1 * T1[\mu, \nu] + D2 * T2[\mu, \nu]$$

$$\text{Phase} = -\text{Contract}[xv[\alpha] \, lv[\alpha]]$$

$$(2\pi)^{-D} \Lambda^{4-D}$$

$$\frac{D1 \, e^2 \, l^\alpha \, l^\beta \, F(\alpha, \mu) \, F(\beta, \nu)}{m^6 \, \chi l^2} + \frac{D2 \, e^2 \, l^\alpha \, l^\beta \, FD(\alpha, \mu) \, FD(\beta, \nu)}{m^6 \, \chi l^2} + D0 \, g^{\mu\nu}$$

$$-(l \cdot x)$$

**We need to calculate the integrals of two types**

$$\int d^D l \, D_0(l^2, \chi l) \, e^{-i l x};$$

and

$$\int d^D l \, l_\alpha \, l_\beta \, D_{1,2}(l^2, \chi l) \, e^{-i l x} = i \frac{\partial}{\partial x^\alpha} i \frac{\partial}{\partial x^\beta} \int d^D l \, D_{1,2}(l^2, \chi l) \, e^{-i l x};$$

Symbol  $d_{\alpha,\beta}$  means that we need to differentiate the expression later

**Let us now change the variables**

$$l_m = l_- = l_0 - l_3;$$

$$l_p = l_+ = \frac{l_0 + l_3}{2};$$

$$l_t = l_{\perp} \quad \text{transverse components of } l \text{ (in } D=4 \text{ } l_{\perp} = (l_1, l_2));$$

$$l_2 = l^2$$

$$l^2 = 2 l_- l_+ - l_{\perp}^2;$$

**Proper time**

$$s = x_- / 2 l_- = kx / 2 kl;$$

$$l_- = x_- / 2 s;$$

$$l_+ = (l^2 + l_{\perp}^2) / 2 l_- = s (l^2 + l_{\perp}^2) / x_- \quad \text{-- expressed via } l^2;$$

**Hereinafter**

$$x_m = x_- = x_0 - x_3;$$

$$x_p = x_+ = \frac{x_0 + x_3}{2};$$

$$x_t = x_{\perp}$$

**Change of variables**

$$l^{\mu} \rightarrow \{l_-, l_+, l_{\perp}\} = \left\{ \frac{x_-}{2s}, \frac{s}{x_-} (l^2 + l_{\perp}^2), l_{\perp} \right\} \rightarrow \{s, l^2, l_{\perp}\}$$

**New integration measure**

$$d^D l \dots = \frac{ds}{2|s|} dl^2 d^{D-2} l_{\perp}$$

**(\*Checking Jacobian\*)**

$$D[\{x_m/2/s, s(l^2 + l_{\perp}^2)/x_m\}, \{\{s, l^2\}\}]$$

$$\text{Jac} = \text{Abs}[\text{Det}[\%]]$$

$$\begin{pmatrix} -\frac{x_m}{2s^2} & 0 \\ \frac{l^2 + l_{\perp}^2}{x_m} & \frac{s}{x_m} \end{pmatrix}$$

$$\frac{1}{2|s|}$$

**Coeff1 = Coeff \* Jac**

**Matrix1 = Matrix /. {lv[α\_] → d<sub>α</sub>}**

**Phase1 = Phase;**

$$\frac{2^{-D-1} \pi^{-D} \Lambda^{4-D}}{|s|}$$

$$\frac{D1 \, e^2 \, d_\alpha \, d_\beta \, F(\alpha, \mu) \, F(\beta, \nu)}{m^6 \, \chi l^2} + \frac{D2 \, e^2 \, d_\alpha \, d_\beta \, FD(\alpha, \mu) \, FD(\beta, \nu)}{m^6 \, \chi l^2} + D0 \, g^{\mu \nu}$$

### Integration over

$$\int d^{D-2} l_\perp \dots$$

$$\begin{aligned} I_\theta &= \int d^{D-2} l_\perp \text{Exp} \left[ -I \, A \, l_\perp^2 + I \, (J \cdot l_\perp) \right] = \\ &= \text{Exp} \left[ -I \, \frac{\pi}{2} \, \frac{D-2}{2} \right] \pi^{\frac{D-2}{2}} (\det A)^{-\frac{1}{2}} \text{Exp} \left[ I \, \frac{1}{4} \, J \cdot A^{-1} \cdot J \right] \end{aligned}$$

where

$$A = s,$$

$$J = x_\perp,$$

$$\det A = s^{D-2},$$

$$A^{-1} = 1 / s$$

In effect,

integration results into multiplication of Coeff by  $I_\theta$  and changing Phase

**Coeff2 = Coeff1;**

**Matrix2 = Matrix1;**

**Phase2 =**

$$\text{Expand} \left[ \text{Phase1} /. \{ \text{Pair}[\text{Momentum}[x, D], \text{Momentum}[l, D]] \rightarrow x_m l_p + x_p l_m - x_t l_t \} /. \right. \\ \left. \{ l_m \rightarrow x_m / 2 / s, l_p \rightarrow s (l_v^2 + l_t^2) / x_m \} /. \{ x_p \rightarrow (x_v^2 + x_t^2) / 2 / x_m \} \right]$$

$$-l^2 s + l t^2 (-s) + l t x_t - \frac{x^2}{4 s} - \frac{x t^2}{4 s}$$

**Amatr = -Coefficient[Phase2, lt^2]**

**J = Coefficient[Phase2, lt]**

**CI0 = Exp[-I Pi / 2 (D / 2 - 1)] Pi ^ (D / 2 - 1) / Amatr ^ (D / 2 - 1)**

**s**

**xt**

$$e^{-\frac{1}{2} i \pi \left( \frac{D-1}{2} \right)} \pi^{\frac{D-1}{2}} s^{1-\frac{D}{2}}$$

**Coeff3 = Coeff2 \* CI0**

**Matrix3 = Matrix2;**

**Phase3 = Expand[ ( (Phase2 /. {lt -> 0}) + 1 / 4 J^2 / Amatr ) ]**

$$\frac{2^{-D-1} e^{-\frac{1}{2} i \pi \left(\frac{D}{2}-1\right)} \pi^{-\frac{D}{2}-1} \Lambda^{4-D} s^{1-\frac{D}{2}}}{|s|}$$

$$\ell^2(-s) - \frac{x^2}{4s}$$

### The integrals

$$\int_{-\infty}^{\infty} \frac{ds}{2|s|} e^{-i \frac{x^2}{4s}} \int_{-\infty}^{\infty} dl^2 D_k(l^2, \chi_l) e^{-i l^2 s}$$

will remain

Let us introduce

$$J_k = J_k(s) =$$

$$-i \int_{-\infty}^{\infty} dl^2 D_k(l^2, \chi_l) e^{-i l^2 s} \text{ - note that this integral is dimensionless}$$

It can be shown that  $J_k(s \leq 0) = 0$

**Coeff4 = Simplify[Coeff3 \* I, Assumptions -> {s > 0}]**

**Matrix4 = Matrix3 /. {D0 -> J0, D1 -> J1, D2 -> J2}**

**Phase4 = Phase3 /. {lv2 -> 0}**

$$-2^{-D-1} e^{-\frac{1}{4} i \pi D} \pi^{-\frac{D}{2}-1} \Lambda^{4-D} s^{-D/2}$$

$$\frac{e^2 J_1 d_\alpha d_\beta F(\alpha, \mu) F(\beta, \nu)}{m^6 \chi l^2} + \frac{e^2 J_2 d_\alpha d_\beta FD(\alpha, \mu) FD(\beta, \nu)}{m^6 \chi l^2} + J_0 g^{\mu \nu}$$

$$-\frac{x^2}{4s}$$

### Calculation of the tensor structure

Let us perform the remaining differentiation

and contract the resulting vectors and tensors

```

Expand[Simplify[
  I FourDivergence[I FourDivergence[Exp[I Phase4], xv[α]], xv[β]] Exp[-I Phase4]]]
Matrix4 /. {dα dβ → %}
Matrix5 = Collect[
  Contract[Contract[%] /. FieldSubstitutions /. FieldSubstitutions], {J0, J1, J2}]
Coeff5 = Coeff4
Phase5 = Phase4

$$\frac{x^\alpha x^\beta}{4 s^2} + \frac{i g^{\alpha\beta}}{2 s}$$


$$\frac{e^2 J1 F(\alpha, \mu) F(\beta, \nu) \left( \frac{x^\alpha x^\beta}{4 s^2} + \frac{i g^{\alpha\beta}}{2 s} \right)}{m^6 \chi l^2} + \frac{e^2 J2 FD(\alpha, \mu) FD(\beta, \nu) \left( \frac{x^\alpha x^\beta}{4 s^2} + \frac{i g^{\alpha\beta}}{2 s} \right)}{m^6 \chi l^2} + J0 g^{\mu\nu}$$


$$J2 \left( \frac{e^2 FDx^\mu FDx^\nu}{4 m^6 s^2 \chi l^2} - \frac{i e^2 FF(\mu, \nu)}{2 m^6 s \chi l^2} \right) + J1 \left( \frac{e^2 Fx^\mu Fx^\nu}{4 m^6 s^2 \chi l^2} - \frac{i e^2 FF(\mu, \nu)}{2 m^6 s \chi l^2} \right) + J0 g^{\mu\nu}$$


$$-2^{-D-1} e^{-\frac{1}{4} i \pi D} \pi^{-\frac{D}{2}-1} \Lambda^{4-D} s^{-D/2}$$


$$-\frac{x^2}{4 s}$$


```

### Change to dimensionless proper time

```

Coeff6 = Simplify[Coeff5 / m^2 /. {s → t / m^2}, Assumptions → {m > 0}]
Matrix6 = Matrix5 /. {χ l → ξ k l / m^2} /. {k l → k x / 2 / s} /. {k x → φ} /.
  {FFt[μ, ν] → -av2 kv[μ] kv[ν]} /. {av2 → -m^2 ξ^2 / e^2} /. {s → t / m^2}
Phase6 = Phase5 /. {s → t / m^2}

$$-2^{-D-1} e^{-\frac{1}{4} i \pi D} \pi^{-\frac{D}{2}-1} \Lambda^{4-D} m^{D-2} t^{-D/2}$$


$$J2 \left( \frac{e^2 FDx^\mu FDx^\nu}{m^2 \xi^2 \phi^2} - \frac{2 i t k^\mu k^\nu}{m^2 \phi^2} \right) + J1 \left( \frac{e^2 Fx^\mu Fx^\nu}{m^2 \xi^2 \phi^2} - \frac{2 i t k^\mu k^\nu}{m^2 \phi^2} \right) + J0 g^{\mu\nu}$$


$$-\frac{m^2 x^2}{4 t}$$


```

## Final result



$$\begin{aligned}
D^c_{\mu\nu}(x) &= \frac{\Lambda^{4-D}}{(2\pi)^D} \int d^D l D^c_{\mu\nu}(l) e^{-ilx} = \\
&= \text{Exp} \left[ -i \frac{\pi}{2} \left( \frac{D}{2} - 2 \right) \right] \frac{\Lambda^{4-D}}{2^{D+1} \pi^{D/2+1}} \\
&\quad \int_0^\infty \frac{ds}{s^{D/2}} e^{-i \frac{x^2}{4s}} \left\{ g_{\mu\nu} J_0(s) - i \frac{1}{2s m^6 \chi_1^2} \left( e^2 (F^2)_{\mu\nu} + i \frac{1}{2s} e^2 Fx_\mu Fx_\nu \right) J_1(s) \right. \\
&\quad \left. - i \frac{1}{2s m^6 \chi_1^2} \left( e^2 (F^2)_{\mu\nu} + i \frac{1}{2s} e^2 FDx_\mu FDx_\nu \right) J_2(s) \right\} = \\
&= \text{Exp} \left[ -i \frac{\pi}{2} \left( \frac{D}{2} - 2 \right) \right] \frac{1}{2^{D+1} \pi^{D/2+1}} \frac{\Lambda^{4-D}}{m^{2-D}} \\
&\quad \int_0^\infty \frac{dt}{t^{D/2}} e^{-i \frac{m^2 x^2}{4t}} \left\{ g_{\mu\nu} J_0(m^{-2}t) + \left( -2i t \frac{k_\mu k_\nu}{m^2 \phi^2} + \frac{e^2 Fx_\mu Fx_\nu}{m^2 \xi^2 \phi^2} \right) J_1(m^{-2}t) \right. \\
&\quad \left. + \left( -2i t \frac{k_\mu k_\nu}{m^2 \phi^2} + \frac{e^2 FDx_\mu FDx_\nu}{m^2 \xi^2 \phi^2} \right) J_2(m^{-2}t) \right\}; \\
J_k(s, \chi_1) &= -i \int_{-\infty}^\infty dl^2 D_k(l^2, \chi_1) e^{-il^2 s}; \\
\phi &= kx; \\
\chi_1 &= \xi k l / m^2 = \xi \phi / 2 m^2 s = \xi \phi / 2 t; \\
\xi^2 &= -e^2 a^2 / m^2; \\
Fx_\mu &= F_{\mu\nu} x^\nu; \\
FDx_\mu &= F^*_{\mu\nu} x^\nu;
\end{aligned}$$