AI - LAB Assignment-5 Report

GAME PLAYING - OTHELLO

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1 Introduction

Othello or Reversi is a strategy board game for two players, played on an 8×8 uncheckered board. Players take turns placing disks on the board with their assigned color facing up.

During a play, any disks of the opponent's color that are in a straight line and bounded by the disk just placed and another disk of the current player's color are turned over to the current player's color.

Player with more number of disks at the end is the winner.

Given a board configuration of othello, we have to return an optimal move which ensures the probability of winning using minmax algorithm and alphabeta pruning with k-ply search .

2 Minimax Algorithm

2.1 Definition

Mini-max algorithm is a recursive or backtracking algorithm which is used in decision-making and game theory. It provides an optimal move for the player assuming that opponent is also playing optimally.

Since there is a time constraint of 2 seconds for each move, we are using k-ply search with **3 depth**. Once it reaches the depth, it returns the heuristic for the last node.

2.2 Pseudo code:

```
def minimax(node, depth, player):
  if depth is 0 then
    return heuristic(node)
  if player is maximizing then
    best_val = -infinity
    for each child_node of node do
    val= minimax(child, depth-1, minimizing)
    best_val= max(best_val,val)
```

else

```
best_val = infinity
for each child_node of node do
  val= minimax(child, depth-1, maximizing)
  best_val= min(best_val,val)
return best_val
```

3 Alpha Beta Pruning

3.1 Definition

Alpha-beta pruning is a modified version of the minimax algorithm. It is an optimization technique for the minimax algorithm. Alpha-beta pruning can be applied at any depth of a tree, and sometimes it not only prune the tree leaves but also entire sub-tree. The main condition which required for alphabeta pruning is $\alpha \geq \beta$.

We are applying k-ply search till depth 4.

3.2 Pseudo code:

```
if depth is 0 then
    return heuristic(node)

if player is maximizing then

best_val = -infinity

for each child_node of node do

val= minimax(child, depth-1, minimizing)

best_val= max(best_val,val)

alpha= max(best_val,alpha)

if alpha ≥ beta then
```

def alphabeta(node, depth, player, alpha, beta):

break

else

```
best_val = infinity

for each child_node of node do

val= minimax(child, depth-1, maximizing)

best_val= min(best_val,val)

beta= min(best_val,beta)

if alpha ≥ beta then

break
```

4 Heuristic Function

4.1 Definition

 $\mathbf{return}\ \mathrm{best_val}$

We are calculating heuristic based on four conditions:

- Lead: Assigning positive value for difference between the total number of disks of the player and opponent.
- Valid moves: Assigning positive value for difference between number of valid moves between player and opponent.
- Corner position: Assigning corner value as 1000 for player as it increases the chances of winning.
- Next to corner: The position surrounded by corner cells are assigned as -500 as it increases the chances of winning for opponent.

4.2 Pseudo code:

```
def heuristic():
```

```
\mathrm{heur}=0
```

heur += no_of_dics_diff

 $diff_in_moves = mypossibleMoves - opponentMoves$

 $\mathbf{heur} += 5^*(\mathbf{diff_in_moves})$

 $\mathbf{if} \ \mathrm{position} \ \mathrm{is} \ \mathrm{corner} \ \mathbf{do}$

heur += 1000

 $\mathbf{if} \ \mathrm{position} \ \mathrm{is} \ \mathrm{next} \ \mathrm{to} \ \mathrm{corner} \ \mathbf{do}$

heur = 500

return heur

5 Results

5.1 Minimax vs RandomBot

Trial No. 🔻	Score 🔻	Won
1	44	12 times
2	8	
3	47	
4	32	Average score
5	48	32.71428571
6	0	
7	28	
8	50	Lost
9	52	1
10	26	
11	63	Drawn
12	-6	1
13	26	
14	40	

5.2 AlphaBeta vs RandomBot

Trial No. 🔻	Score 🔻	Won
1	30	13 times
2	49	
3	30	
4	46	Average score
5	24	31.35714286
6	46	
7	28	
8	28	Lost
9	42	0
10	12	
11	54	Drawn
12	22	1
13	28	
14	0 .	

6 Minimax vs AlphaBeta

6.1 Results

With Minimax bot, AlphaBeta bot is winning all the time (i.e. while playing first or second).

AlphaBeta bot playing first (BLACK)



AlphaBeta bot playing second (RED)



6.2 Comparision

- When there is no time constraint, both algorithm performs ideally same. But here we are given with a time constraint of 2 seconds for each move. So Minimax algorithm can only search upto depth 3. Alpha beta algorithm can prune some subtrees and can search upto depth 4 in some cases, thereby improving chances of winning.
- This is the reason being minimax is losing to Alpha beta bot even it starts first.
- In terms of **space and time complexity** both are exponential in terms of branching factor. So we are applying k-ply search for both with k values 3 and 4 respectively for minimax and alpha beta.
- Winning criteria: When played against random bot both performs very good but alpha beta won many times compared to minimax bot.
- So when there is time constraint, alphabeta pruning algorithm performs well with k-ply search.