# Containers: Priority Queues

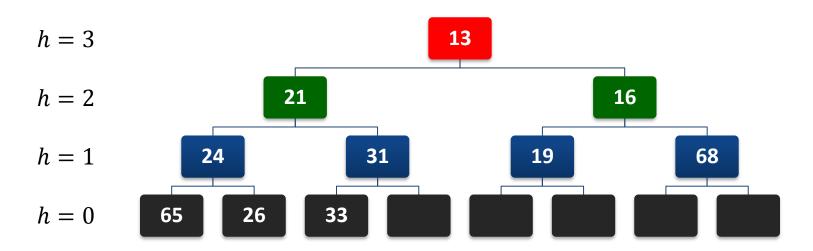


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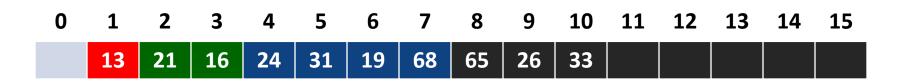
#### A priority queue

- A priority queue is a queue in which each element has a priority.
- Elements with higher priority are served before elements with lower priority.
- It can be implemented as a vector or a linked list. For a queue with n elements:
  - Insertion is O(n).
  - Extraction is O(1).
- A more efficient implementation can be proposed in which insertion and extraction are  $O(\log n)$ : **binary heap**.

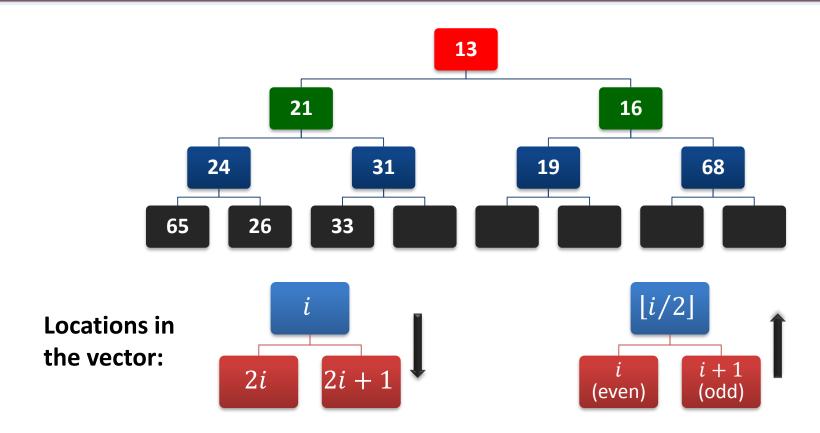
### Binary Heap



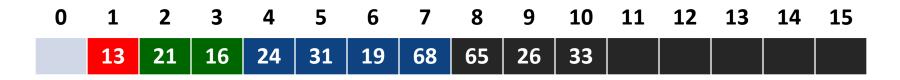
- Complete binary tree (except at the bottom level).
- Height h: between  $2^h$  and  $2^{h+1} 1$  nodes.
- For N nodes, the height is  $O(\log N)$ .
- It can be represented in a vector.



#### Binary Heap

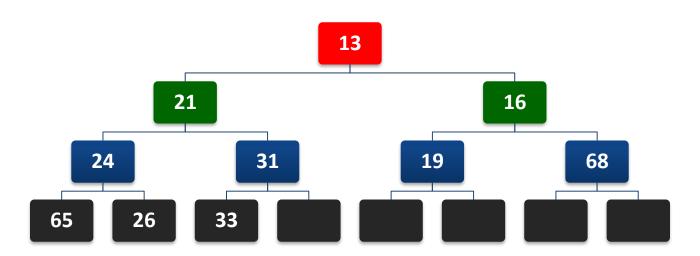


**Heap-Order Property:** the key of the parent of X is smaller than (or equal to) the key in X.



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#### Binary Heap



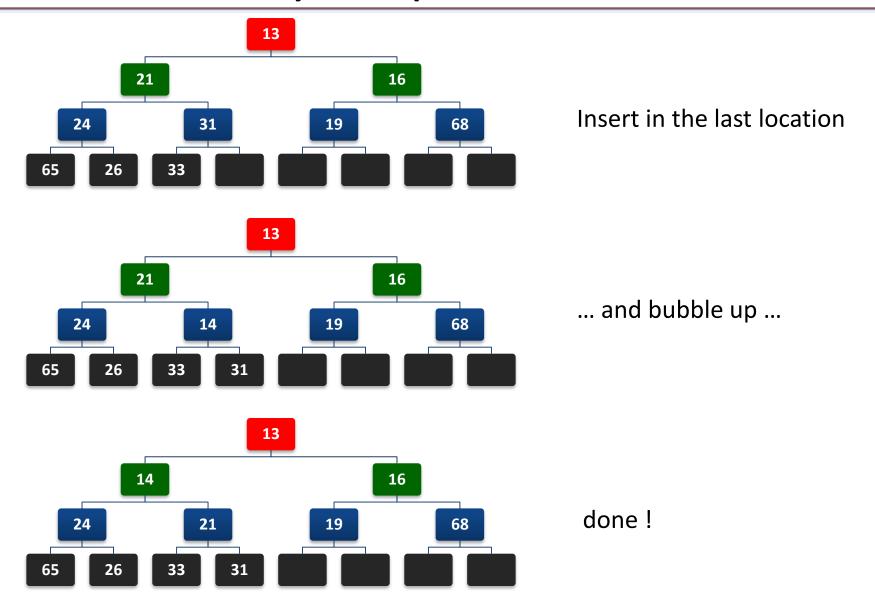
Two main operations on a binary heap:

- Insert a new element
- Remove the min element

Both operations must preserve the properties of the binary heap:

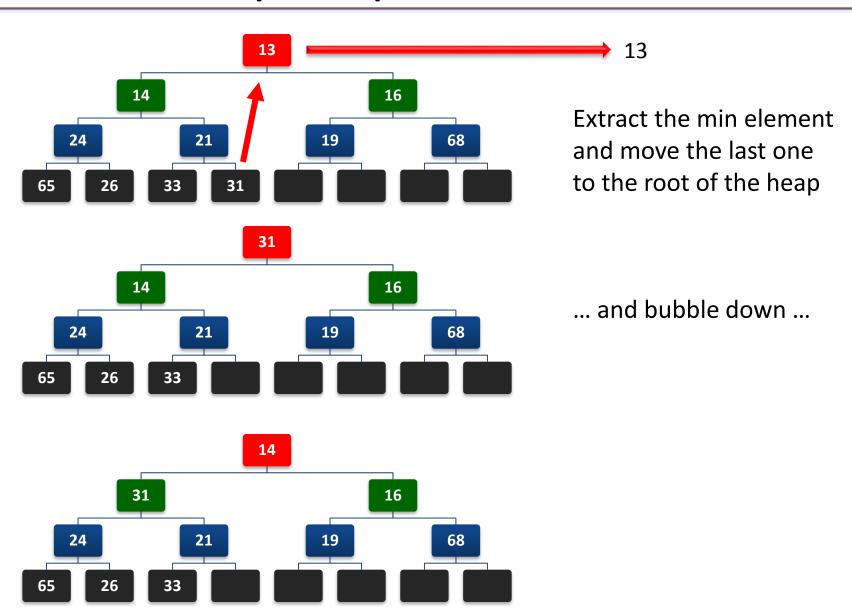
- Completeness
- Heap-Order property

## Binary Heap: insert 14

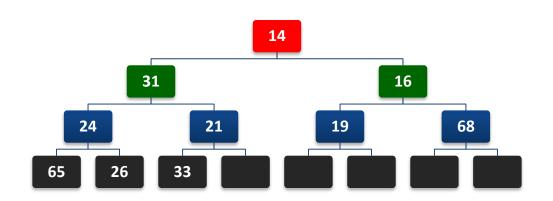


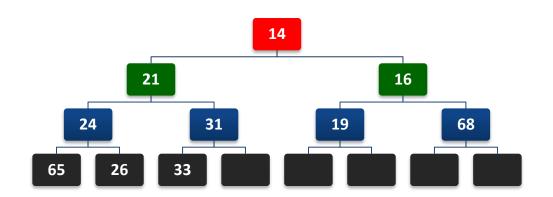
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#### Binary Heap: remove min



### Binary Heap: remove min





done!

### Binary Heap: complexity

• Bubble up/down operations do at most h swaps, where h is the height of the tree and

$$h = \lfloor \log_2 N \rfloor$$

- Therefore:
  - Getting the min element is O(1)
  - Inserting a new element is  $O(\log N)$
  - Removing the min element is  $O(\log N)$

### Binary Heap: other operations

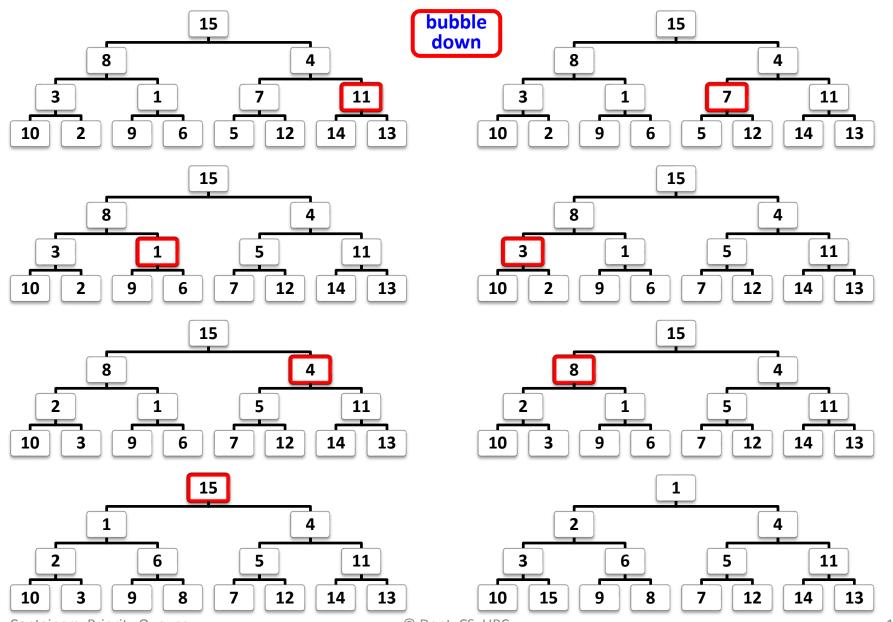
 Let us assume that we have a method to know the location of every key in the heap.

- Increase/decrease key:
  - Modify the value of one element in the middle of the heap.
  - If decreased  $\rightarrow$  bubble up.
  - If increased  $\rightarrow$  bubble down.
- Remove one element:
  - Set value to  $-\infty$ , bubble up and remove min element.

### Building a heap from a set of elements

- Heaps are sometimes constructed from an initial collection of N elements. How much does it cost to create the heap?
  - Obvious method: do N insert operations.
  - Complexity:  $O(N \log N)$
- Can it be done more efficiently?

### Building a heap from a set of elements



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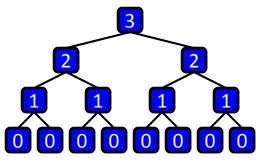
### Building a heap: implementation

```
// Constructor from a collection of items
BinaryHeap(const vector<Elem>& items) {
   v.push_back(Elem()); // v is the vector holding the elements
   for (auto& e: items) v.push_back(e);
   for (int i = size()/2; i > 0; --i) bubble_down(i);
}
```

v:

Sum of the heights of all nodes:

- 1 node with height h
- 2 nodes with height h-1
- 4 nodes with height h-2
- $2^i$  nodes with height h-i



$$S = \sum_{i=0}^{h-1} 2^i (h-i)$$

$$S = h + 2(h - 1) + 4(h - 2) + 8(h - 3) + 16(h - 4) + \dots + 2^{h-1}(1)$$

$$2S = 2h + 4(h - 1) + 8(h - 2) + 16(h - 3) + \dots + 2^{h}(1)$$
Subtract the two equations:
$$S = -h + 2 + 4 + 8 + \dots + 2^{h-1} + 2^{h} = (2^{h+1} - 1) - (h + 1) = 0(N)$$

A heap can be built from a collection of items in linear time.

#### Heap sort

```
template <typename T>
void HeapSort(vector<T>& v) {
   BinaryHeap<T> heap(v);
   for (T& e: v) e = heap.remove_min();
}
```

- Complexity:  $O(n \log n)$ 
  - Building the heap: O(n)
  - Each removal is  $O(\log n)$ , executed n times.

#### **EXERCISES**

#### Exercise: insert/remove element

Given the binary heap implemented in the following vector, draw the tree represented by the vector.

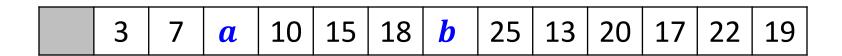
Execute the following sequence of operations

```
insert(8); remove_min(); insert(6); insert(18); remove_min();
```

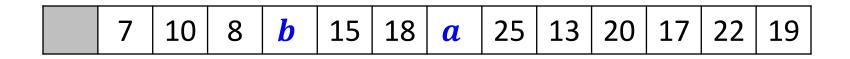
and draw the tree after the execution of each operation.

### Exercise: guess a and b

Consider the binary heap of integer keys implemented by the following vector:



After executing the operations **insert(8)** and **remove\_min()** the contents of the binary heap is:



Discuss about the possible values of a and b. Assume there can never be two identical keys in the heap.

#### Exercise: the *k*-th element

The k-th element of n sorted vectors.

Let us consider n vectors sorted in ascending order.

Design an algorithm with cost  $\Theta(k \log n + n)$  that finds the k-th global smallest element.

#### Exercise: bubble-up/down

Consider the following declaration for a Binary Heap:

```
template <typename T> // T must be a comparable type
class BinaryHeap {
private:
    vector<Elem> v; // Table for the heap (location 0 not used)

// Bubbles up the element at location i
    void bubble_up(int i);

// Bubbles down the element at location i
    void bubble_down(int i);
```

Give an implementation for the methods **bubble\_up** and **bubble\_down**.