Distributed GraphLab: A Framework for Machine Learning and Data Mining in the Cloud

Problem:

Existing *distributed* graph computation systems perform poorly on **Natural Graphs**.



GraphLab can....

- Expresses asynchronous
- Dynamic, graph-parallel computation
- Ensure data-consistency and high degree of parallelism



- ➤ Common properties and Limitations
- >Implementing the distributed execution model
- > Fault tolerance
- > Application Example



2 MLDM Algorithm Properties

- ➤ Graph Structured Computation
- > Asynchronous Iterative Computation
- > Dynamic Computation
- ➤ Serializability



2.1 Graph Structured Computation

- Dependency between data
- ➤ Product recommendations
- > Supported by MapReduce not efficient.



2.1 Graph Structured Computation

For GraphLab.....

- ➤ Vertex-centric model (computation is defined as kernels that run on each vertex)
- ➤ Sequential shared memory (each vertex can read and write to data on adjacent vertices and edges)



2 MLDM Algorithm Properties

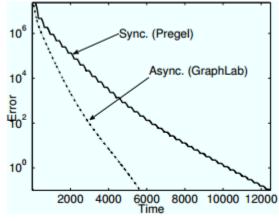
- ➤ Graph Structured Computation
- > Asynchronous Iterative Computation
- > Dynamic Computation
- ➤ Serializability

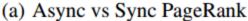


2.2 Asynchronous Iterative Computation

- ➤ Update using the *most recent* parameter values as input
- Providing many MLDM algorithm with benefits

(Eg: Linear systems can converge faster)







2.2 Asynchronous Iterative Computation

Disadvantages for synchronous computation:

- ➤ Incurs performance penalties (slowest machine, load & network imbalance)
- ➤ Individual vertex kernels produce more variability

(Even graph is partitioned uniformly)



2.2 Asynchronous Iterative Computation

For GraphLab.....

➤ Designed to efficiently and naturally express the asynchronous iterative algorithms to advance MLDM



2 MLDM Algorithm Properties

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2.3 Dynamic Computation

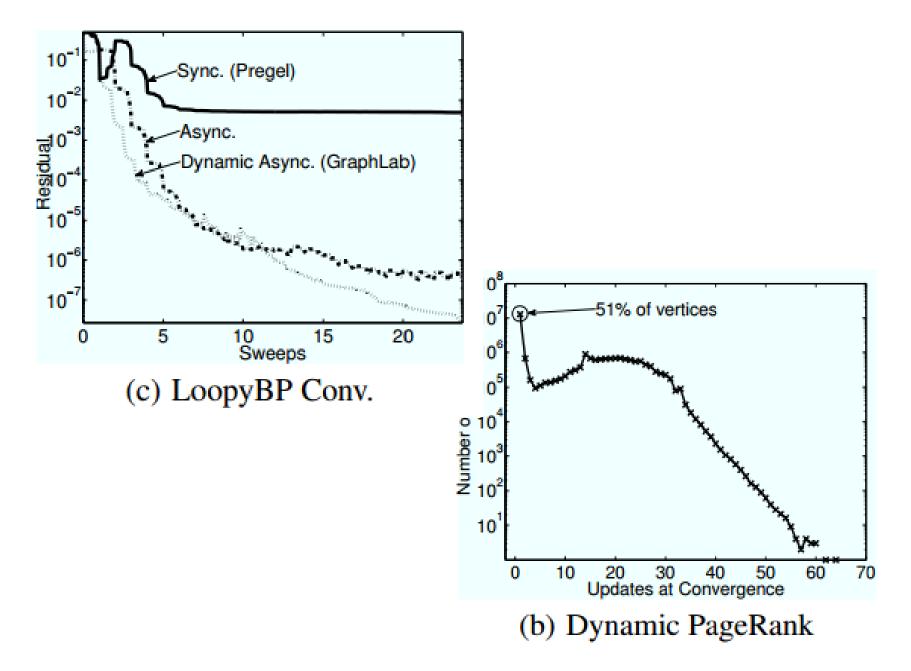
In many MLDM alg, iterative computation converges asymmetrically

(Eg: parameter optimization)

➤ Prioritizing computation can further accelerate convergence

```
(wasting time if upgrade equally, b/c recomputing params converge efficiently)
```





2.3 Dynamic Computation

For GraphLab.....

 Only GraphLab permits prioritization as well as the ability to adaptively pull information from adjacent vertices.



2 MLDM Algorithm Properties

- ➤ Graph Structured Computation
- > Asynchronous Iterative Computation
- > Dynamic Computation
- **≻** Serializability

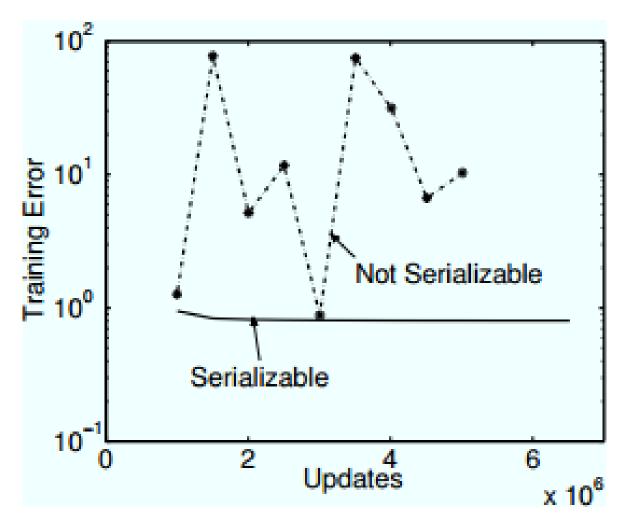


2.4 Serializability

- > Eliminates many challenges
 - (ensuring all parallel executions have an equivalent sequential execution)
- ➤ Converge faster
- ➤ Some algorithms require serializability for correctness

(Eg:Dynamic ALS (Sec. 5.1) is unstable when allowed to race)





(d) ALS Consistency

2.4 Serializability

For GraphLab.....

 GraphLab supports a broad range of consistency settings, allowing a program to choose the level of consistency needed for correctness



- ➤ Data Graph
- ➤ Update Function
- ➤ Sync operation



➤ Data Graph

---- represents program state, and stores both the mutable user-defined data and encodes the sparse computational dependencies



- ➤ Update function
- ---- represents the user computation and operate on the data graph



- ➤ Sync operation
- ---- represents and maintains global aggregates



$$R(v) = \frac{a}{n} + (1 - a) \sum_{\text{u links to v}} w_{u,v} \times R(u)$$

Rank of webpage v

Weighted sum of neighbors' ranks

- Update ranks in parallel
- Iterate until convergence

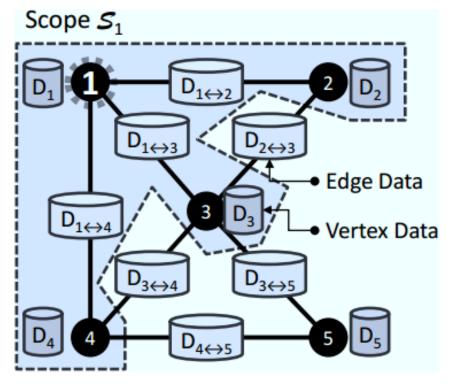


Part 1 : Data Graph

D(v)

R(v)

 $D_{u \to v}$



(a) Data Graph



Part 2 : Update Functions

- A stateless procedure that modifies the data within the scope of a vertex
- Schedules the future execution

Update:
$$f(v, S_v) \rightarrow (S_v, \tau)$$

Define update functions with complete freedom



Algorithm 1: PageRank update function

```
Input: Vertex data \mathbf{R}(v) from \mathcal{S}_v
Input: Edge data \{w_{u,v}: u \in \mathbf{N}[v]\} from \mathcal{S}_v
Input: Neighbor vertex data \{\mathbf{R}(u): u \in \mathbf{N}[v]\} from S_v
\mathbf{R}_{\mathrm{old}}(v) \leftarrow \mathbf{R}(v) // Save old PageRank
\mathbf{R}(v) \leftarrow \alpha/n
\mathbf{R}(v) \leftarrow \mathbf{R}(v) + (1-\alpha) * w_{u,v} * \mathbf{R}(u)
// If the PageRank changes sufficiently
if |R(v) - R_{old}(v)| > \epsilon then
   // Schedule neighbors to be updated return \{u:u\in {\bf N}[v]\}
Output: Modified scope S_v with new \mathbf{R}(v)
```



For GraphLab:

Algorithm 2: GraphLab Execution Model

```
Input: Data Graph G = (V, E, D)

Input: Initial vertex set \mathcal{T} = \{v_1, v_2, ...\}

while \mathcal{T} is not Empty do

\begin{array}{c|c} \mathbf{1} & v \leftarrow \texttt{RemoveNext}(\mathcal{T}) \\ \mathbf{2} & (\mathcal{T}', \mathcal{S}_v) \leftarrow f(v, \mathcal{S}_v) \\ \mathbf{3} & \mathcal{T} \leftarrow \mathcal{T} \cup \mathcal{T}' \\ \end{array}
Output: Modified Data Graph G = (V, E, D')
```

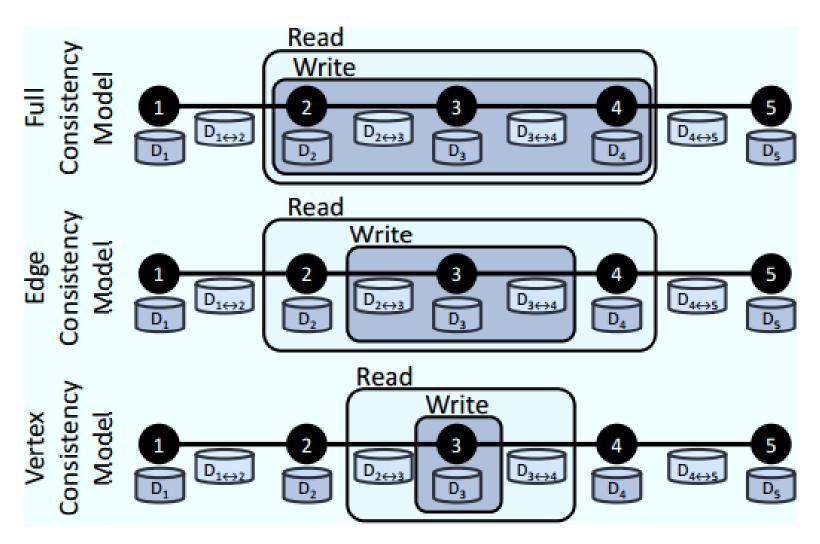
➤ **Notice**: Allow runtime to determine the best order to execute vertices



Ensuring Serializability

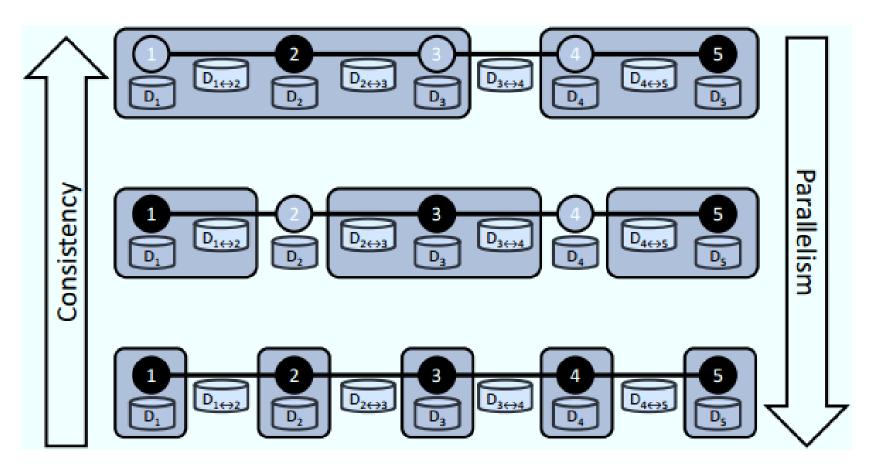
- A serializable execution implies that there exists a serial schedule of update functions that when executed by Alg. 2 produces the same values.
- Scope of update functions do not overlap i.e. the *full consistency model*





(b) Consistency Models





(c) Consistency and Parallelism

