

MECH201 ENGINEERING ANALYSIS

Lecture Notes (Week 5)

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Consultation: Appointment by email

Week 2 – Roots of equations

Week 3 - Linear Algebraic Equations

Week 4 - Optimization

MATLAB example scripts

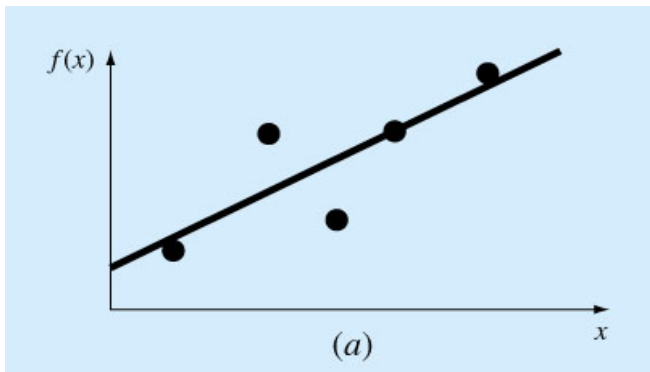
All lecture scripts uploaded weekly to:

<https://github.com/AzdiarGazder/MECH201>

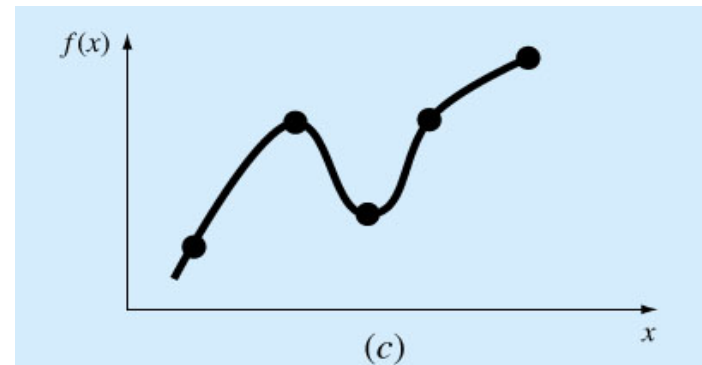
Please follow the instructions posted there to download and run your local copy of the scripts.

Curve Fitting and Interpolation

- There are two approaches: **curve fitting & interpolation**
- Curve fitting by least-squares regression:** When the data exhibits a **significant degree of error**, then the strategy is to derive a single curve that represents the **general trend** of the data.
- Interpolation:** when the data is known to be **precise**, the approach is to fit a curve or a series of curves that pass **directly through each of the points**. Estimation of values between well-known discrete points is called interpolation.



Curve fitting



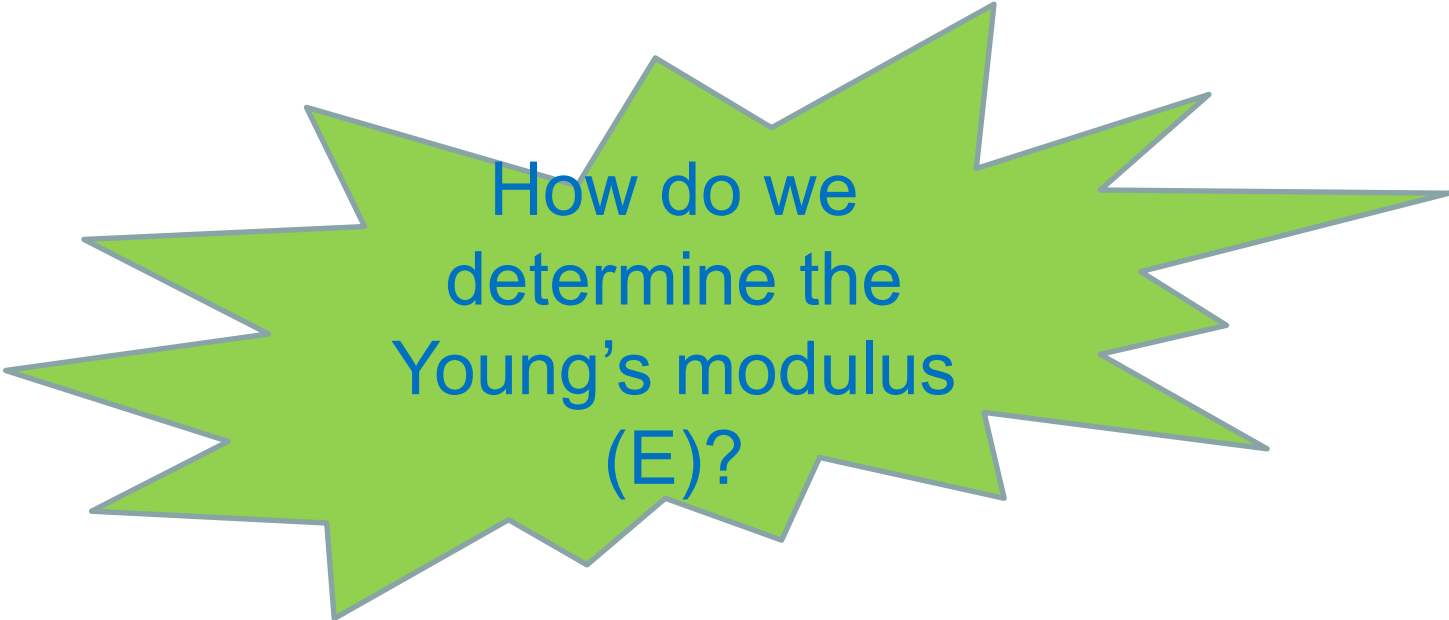
Interpolation

Curve fitting by Least-Squares Regression

Example – Young's modulus

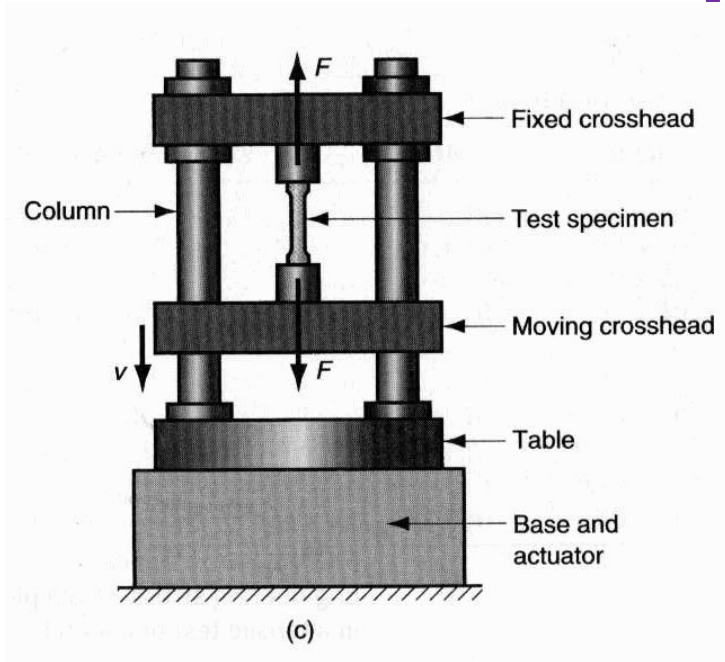
Hooke's law:

$$\sigma = E\varepsilon$$

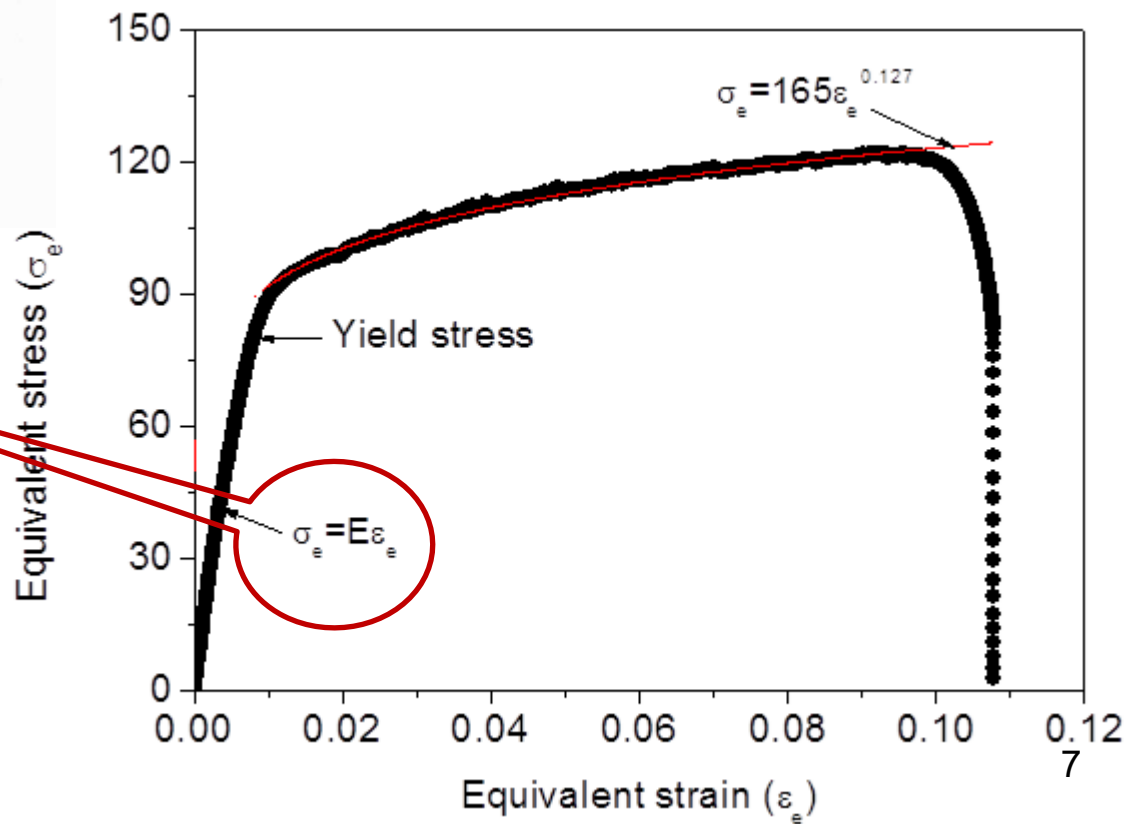


How do we
determine the
Young's modulus
(E)?

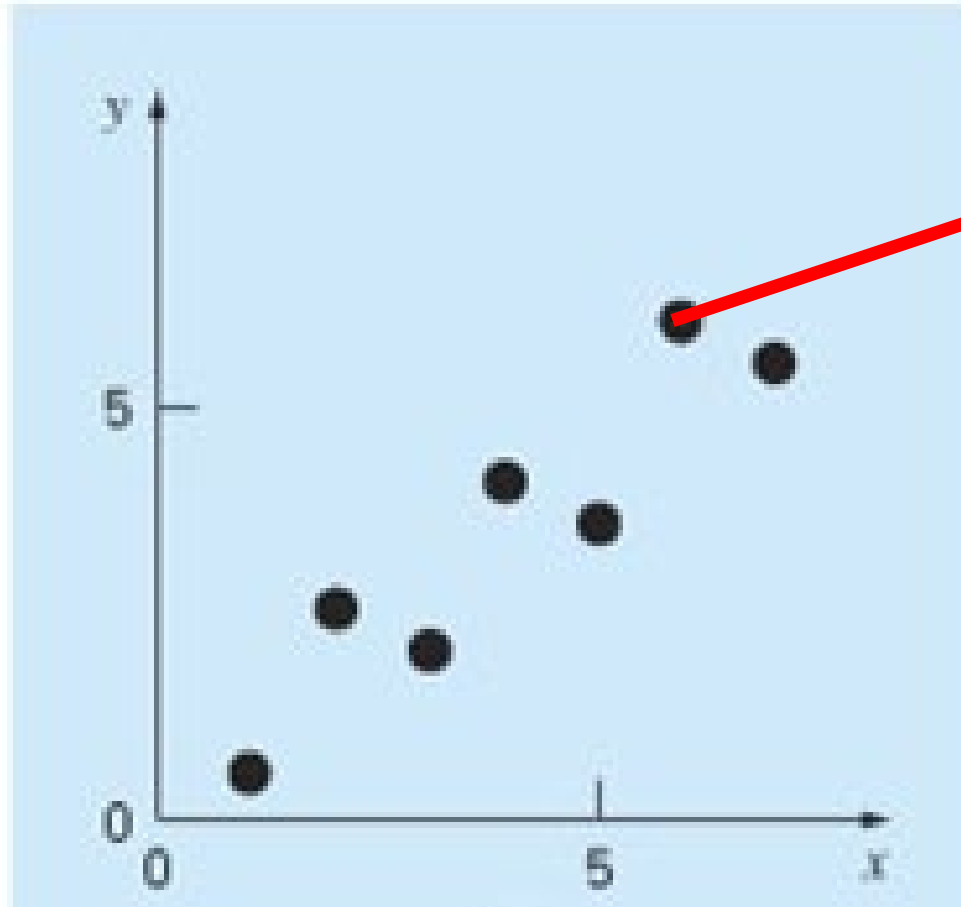
Tensile test



In the elastic region, E is determined by regression.



Experimental data (solid points):
 $(x_1, y_1), (x_2, y_2), \dots, (x_i, y_i), \dots (x_n, y_n)$.

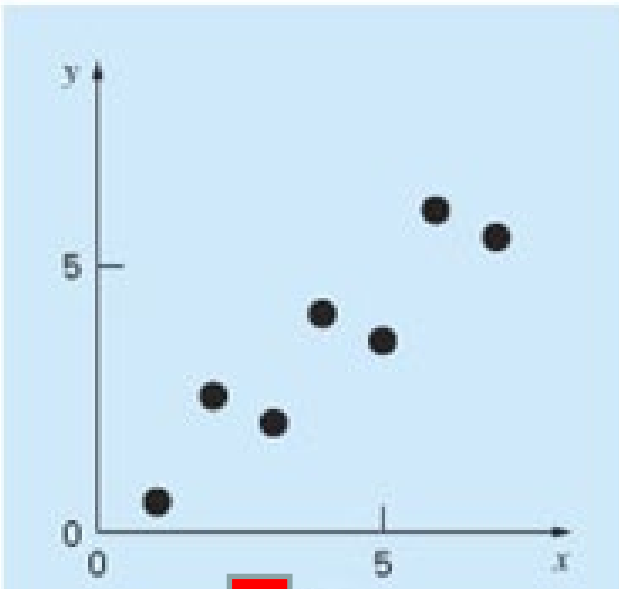


(x_i, y_i)

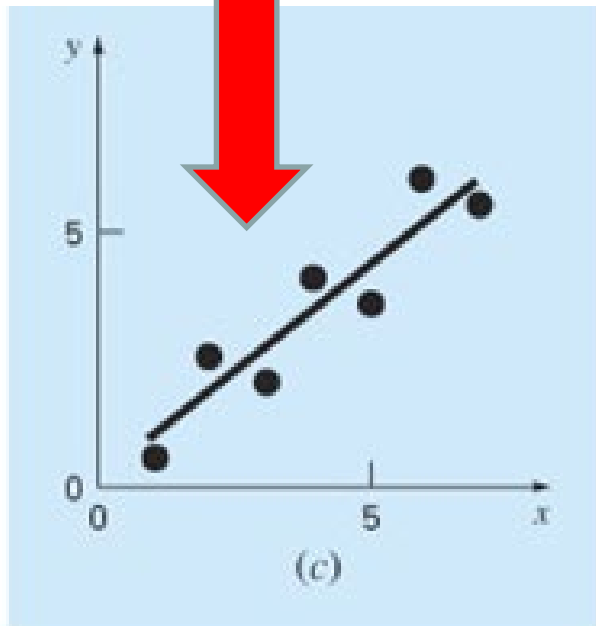
are known then...

$$y = f(x)?$$

Experimental data



Visual inspection

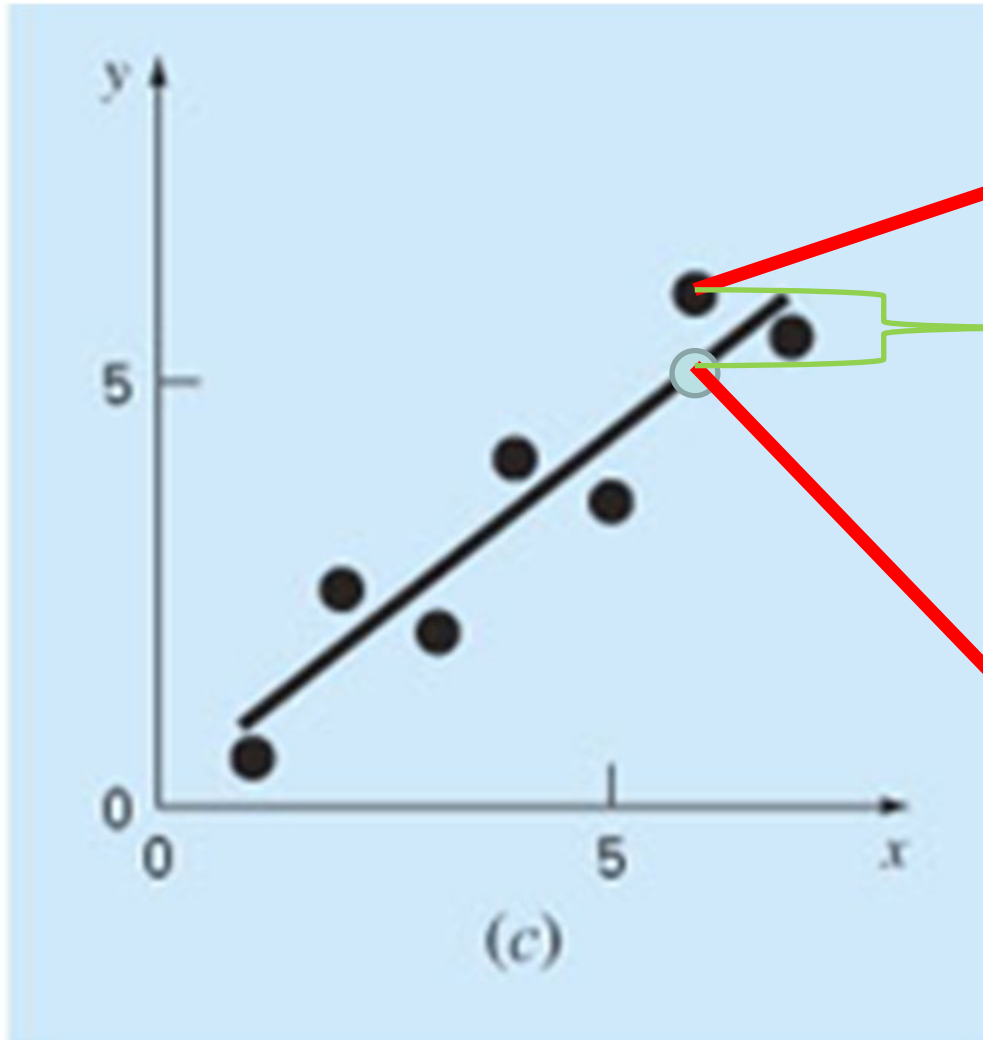


Linear relationship

$$y = a_0 + a_1 x$$

But how do
we determine
 a_0, a_1 ?

Experimental data (solid points):
 $(x_1, y_1), (x_2, y_2), \dots, (x_i, y_i), \dots (x_n, y_n)$.



(x_i, y_i)

Error (residual):

$$e_i = y_i - a_0 - a_1 x_i$$

Point on the line:

$(x_i, a_0 + a_1 x_i)$

n is the total number of data.

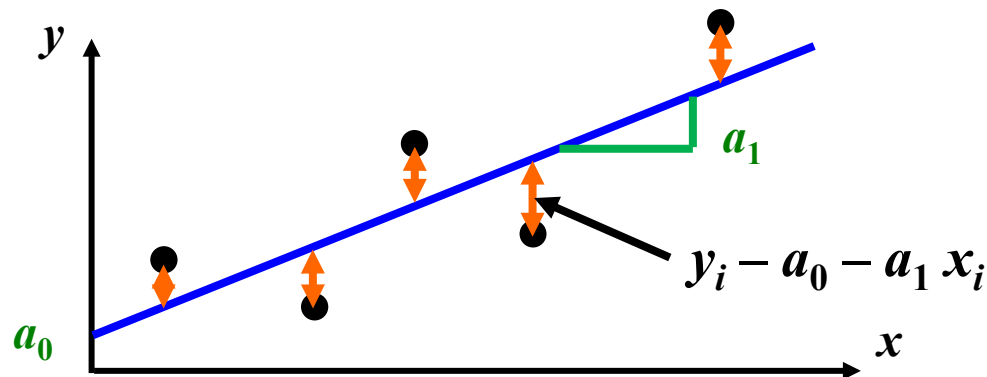
“Best fit” – Least-Squares Regression

(determination of a_0 and a_1)

The strategy is to **minimise the sum of the squares of the residual errors** between the **measured y_i** and the **calculated y** with the linear model ($a_0 + a_1 x_i$).

Minimise

$$S_r = \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_{i,\text{measured}} - y_{i,\text{model}})^2 = \sum_{i=1}^n (y_{i,\text{measured}} - a_0 - a_1 x_i)^2$$



Determination of a_0 and a_1



minimize $S_r = \sum_{i=1}^n (y_i - a_0 - a_1 x_i)^2$



where,
 a_0 and a_1 are unknowns

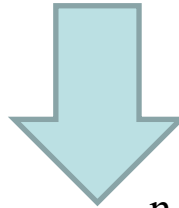
The first derivatives are equal to zero.

$$\frac{\partial S_r}{\partial a_0} = -2 \sum_{i=1}^n (y_i - a_0 - a_1 x_i) = 0$$

$$\frac{\partial S_r}{\partial a_1} = -2 \sum_{i=1}^n ((y_i - a_0 - a_1 x_i) x_i) = 0$$

$$\frac{\partial S_r}{\partial a_0} = -2 \sum_{i=1}^n (y_i - a_0 - a_1 x_i) = 0$$

$$\frac{\partial S_r}{\partial a_1} = -2 \sum_{i=1}^n ((y_i - a_0 - a_1 x_i) x_i) = 0$$



$$\sum_{i=1}^n y_i - \sum_{i=1}^n a_0 - \sum_{i=1}^n a_1 x_i = 0$$

$$\sum_{i=1}^n y_i x_i - \sum_{i=1}^n a_0 x_i - \sum_{i=1}^n a_1 x_i^2 = 0$$



$$na_0 + \left(\sum_{i=1}^n x_i \right) a_1 = \sum_{i=1}^n y_i$$

$$\left(\sum_{i=1}^n x_i \right) a_0 + \left(\sum_{i=1}^n x_i^2 \right) a_1 = \sum_{i=1}^n x_i y_i$$



Solution:

$$a_0 = \bar{y} - a_1 \bar{x}$$

$$\bar{x} = \frac{\sum_{i=1}^n x_i}{n}$$

$$a_1 = \frac{n \sum_{i=1}^n (x_i y_i) - \sum_{i=1}^n x_i \sum_{i=1}^n y_i}{n \sum_{i=1}^n (x_i^2) - \left(\sum_{i=1}^n x_i \right)^2}$$

$$\bar{y} = \frac{\sum_{i=1}^n y_i}{n}$$

Quantification of error

1) Standard error of the estimate:

$$S_{y/x} = \sqrt{\frac{S_r}{n-2}} \quad S_r = \sum_{i=1}^n (y_i - a_0 - a_1 x_i)^2$$

$S_{y/x} = 0$ indicates a perfect fit.

$n-2$ because 2 degrees of freedom are lost.

2) Correlation coefficient (coefficient of determination):

$$r = \sqrt{\frac{S_1 - S_r}{S_1}} \quad S_1 = \sum_{i=1}^n (y_i - \bar{y})^2$$

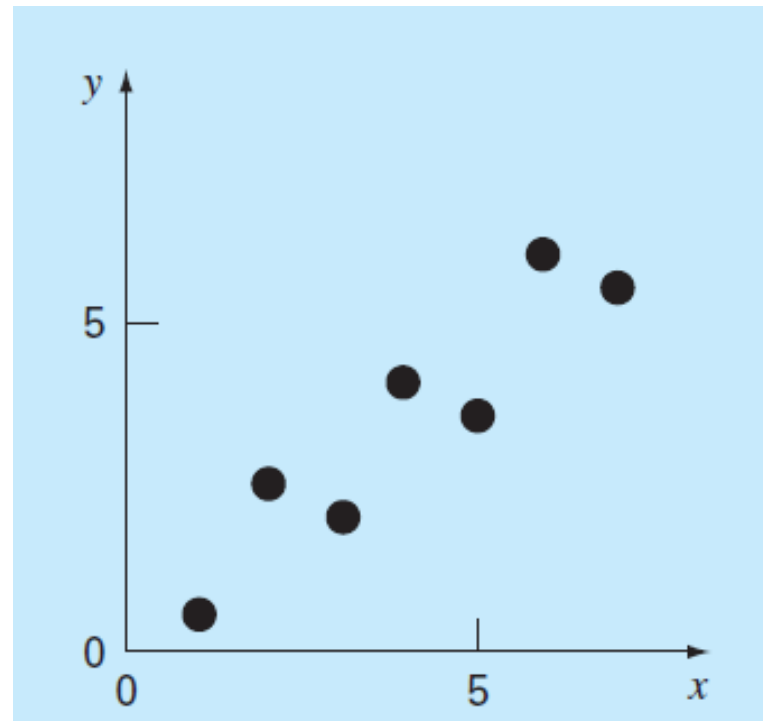
$r = 1$ signifies a perfect fit with the line explaining 100% of data variability.

If $r = r^2 = 0$, $S_r = S_t$, the fit represents no improvement.

Example – Least-Squares Regression

Fit a straight line to the x and y values given in the following table.

x_i	y_i
1	0.5
2	2.5
3	2.0
4	4.0
5	3.5
6	6.0
7	5.5



Solution

x_i	y_i
1	0.5
2	2.5
3	2.0
4	4.0
5	3.5
6	6.0
7	5.5

$$n = 7$$

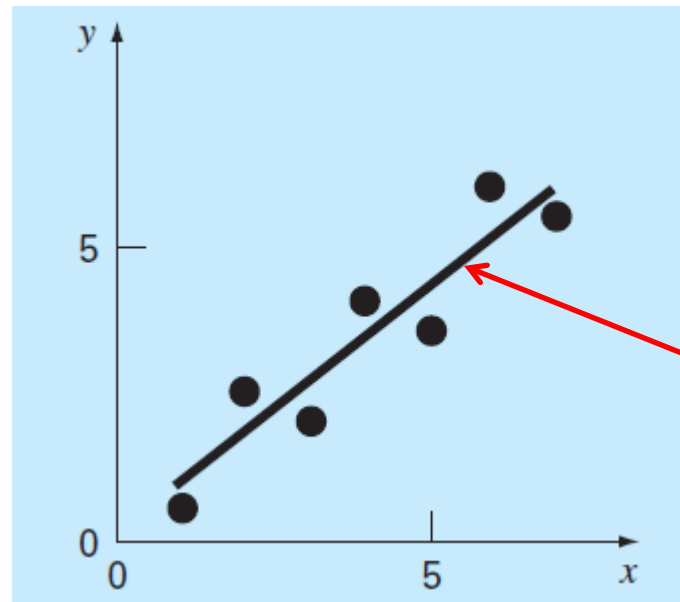
$$\sum_{i=1}^7 (x_i y_i) = 119.5, \quad \sum_{i=1}^7 (x_i^2) = 140$$

$$\sum_{i=1}^7 x_i = 28, \quad \sum_{i=1}^7 y_i = 24$$

$$\bar{x} = \frac{\sum_{i=1}^7 x_i}{7} = 4, \quad \bar{y} = \frac{\sum_{i=1}^7 y_i}{7} = 3.4286$$

$$a_1 = \frac{n \sum_{i=1}^n (x_i y_i) - \sum_{i=1}^n x_i \sum_{i=1}^n y_i}{n \sum_{i=1}^n (x_i^2) - \left(\sum_{i=1}^n x_i \right)^2} = \frac{7(119.5) - 28(24)}{7(140) - (28)^2} = 0.8393$$

$$a_0 = \bar{y} - a_1 \bar{x} = 3.4286 - 0.8393(4) = 0.0714$$



$$y = a_0 + a_1 x$$

TABLE 17.1 Computations for an error analysis of the linear fit.

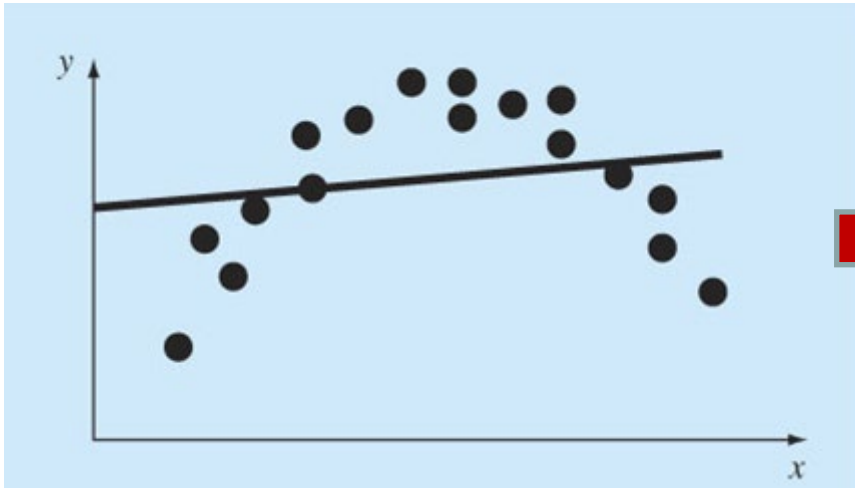
x_i	y_i	$(y_i - \bar{y})^2$	$(y_i - a_0 - a_1 x_i)^2$
1	0.5	8.5765	0.1687
2	2.5	0.8622	0.5625
3	2.0	2.0408	0.3473
4	4.0	0.3265	0.3265
5	3.5	0.0051	0.5896
6	6.0	6.6122	0.7972
7	5.5	4.2908	0.1993
Σ	24.0	22.7143	2.9911

$$S_r = \sum_{i=1}^7 (y_i - a_0 - a_1 x_i)^2 = 2.9911 \quad S_1 = \sum_{i=1}^7 (y_i - \bar{y})^2 = 22.7143$$

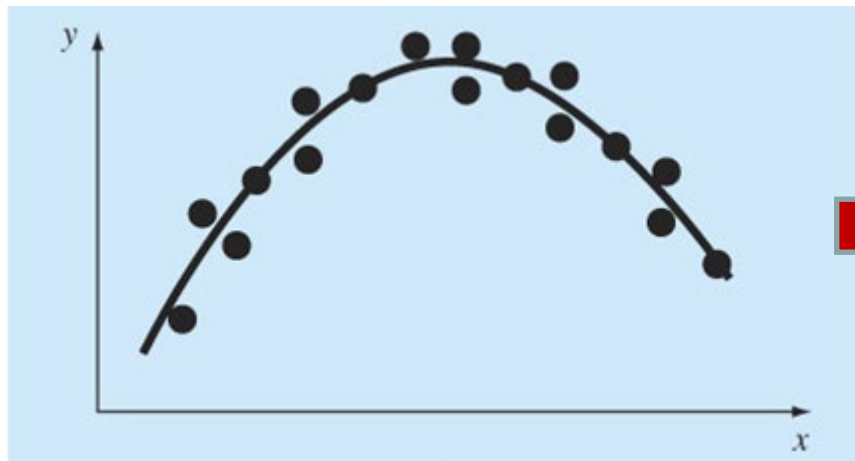
$$s_{y/x} = \sqrt{\frac{S_r}{n-2}} = \sqrt{\frac{2.9911}{7-2}} = 0.7735$$

$$r = \sqrt{\frac{S_1 - S_r}{S_1}} = \sqrt{\frac{22.7143 - 2.9911}{22.7143}} = 0.932$$

Non-linear relationships



Not a good fit



Is a good fit

How do we
determine the
coefficients of
a non-linear
relationship?

Determination of non-linear relationships

Step 1: Linearize a nonlinear relationship.

Step 2: Determine the coefficients of the linearized relationship in Step 1.

Step 3: Substitute the coefficients back into the nonlinear relationship.

Linearization of nonlinear relationships

(1) Power function:

$$y = \alpha_2 x^{\beta_2}$$

applying log10 or natural log
on both sides

$$\log(y) = \log(\alpha_2) + \beta_2 \log(x)$$

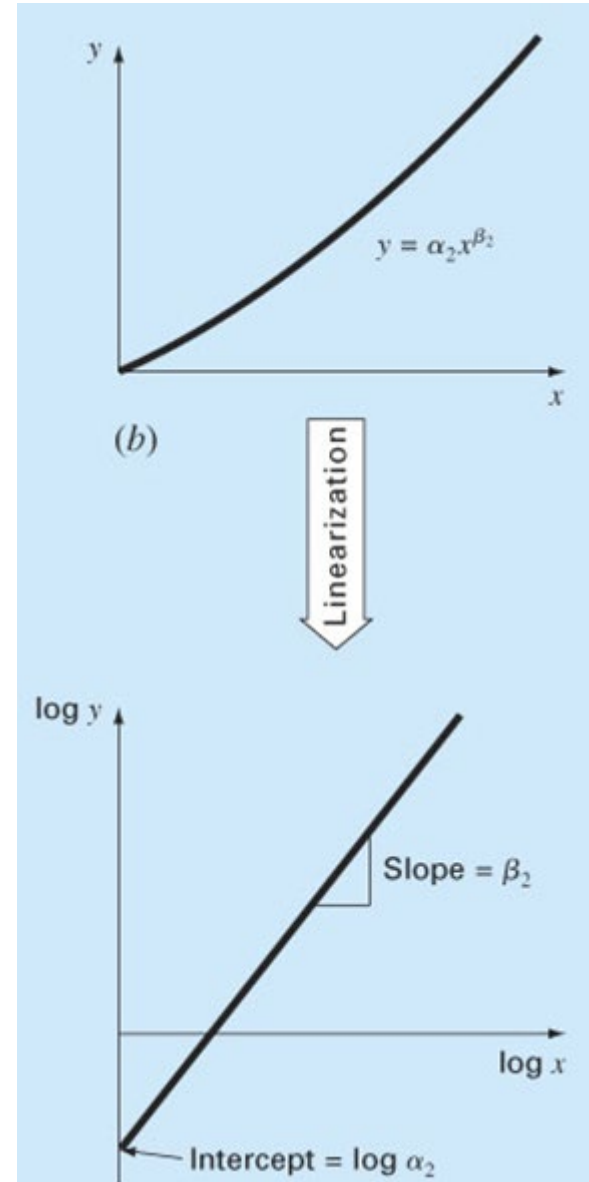
$$Y = a_0 + a_1 X$$

Linear relationship
between X and Y

$$X = \log(x); Y = \log(y)$$
$$a_0 = \log(\alpha_2); a_1 = \beta_2$$

Determine a_0 and a_1 by linear regression

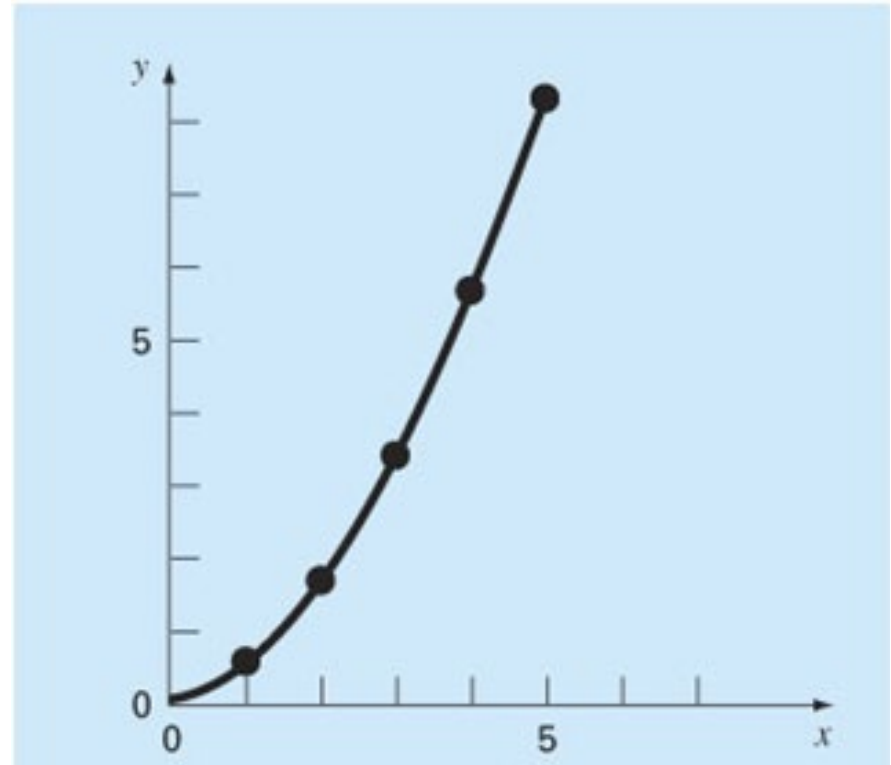
$$\alpha_2 = 10^{a_0} \quad \beta_2 = a_1$$



Example - Linearization of nonlinear relationships

Fit a power equation to the (x, y) data.

x	y
1	0.5
2	1.7
3	3.4
4	5.7
5	8.4



Solution

Power law relationship: $y = \alpha x^\beta$

Linearise by applying log10 to both sides:

$$\log(y) = \log(\alpha) + \beta \log(x)$$

Linear relationship between $\log(y)$ and $\log(x)$:

$$\log(y) = a_0 + a_1 \log(x)$$

$$a_0 = \log(\alpha)$$

$$a_1 = \beta$$

Y		X	
x	y	log x	log y
1	0.5	0	-0.301
2	1.7	0.301	0.226
3	3.4	0.477	0.534
4	5.7	0.602	0.753
5	8.4	0.699	0.922

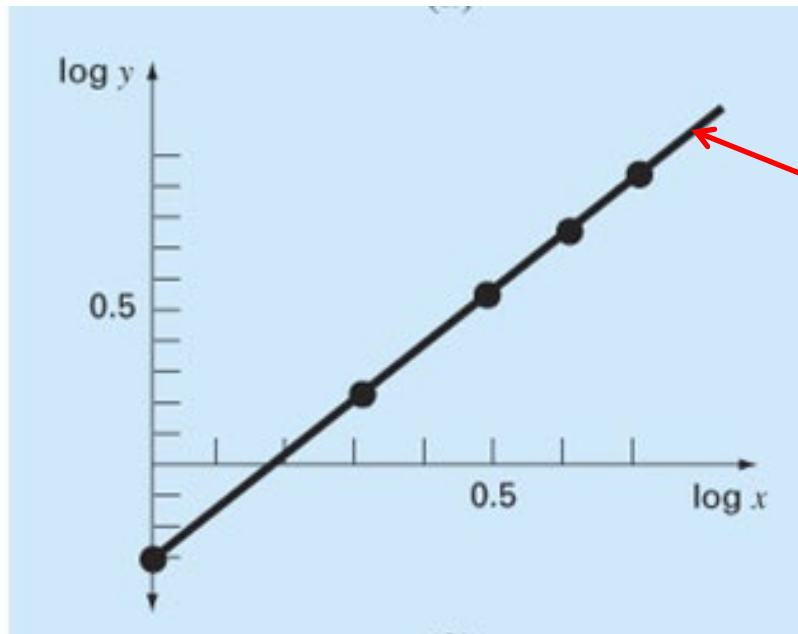
$$\overset{\text{Y}}{\log(y)} = a_0 + a_1 \overset{\text{X}}{\log(x)}$$

Least-squares regression:

$$a_0 = -0.3$$

$$a_1 = 1.75$$

$\log x$	$\log y$
0	-0.301
0.301	0.226
0.477	0.534
0.602	0.753
0.699	0.922



$$\log(y) = -0.3 + 1.75 \log(x)$$

$$a_0 = \log(\alpha)$$

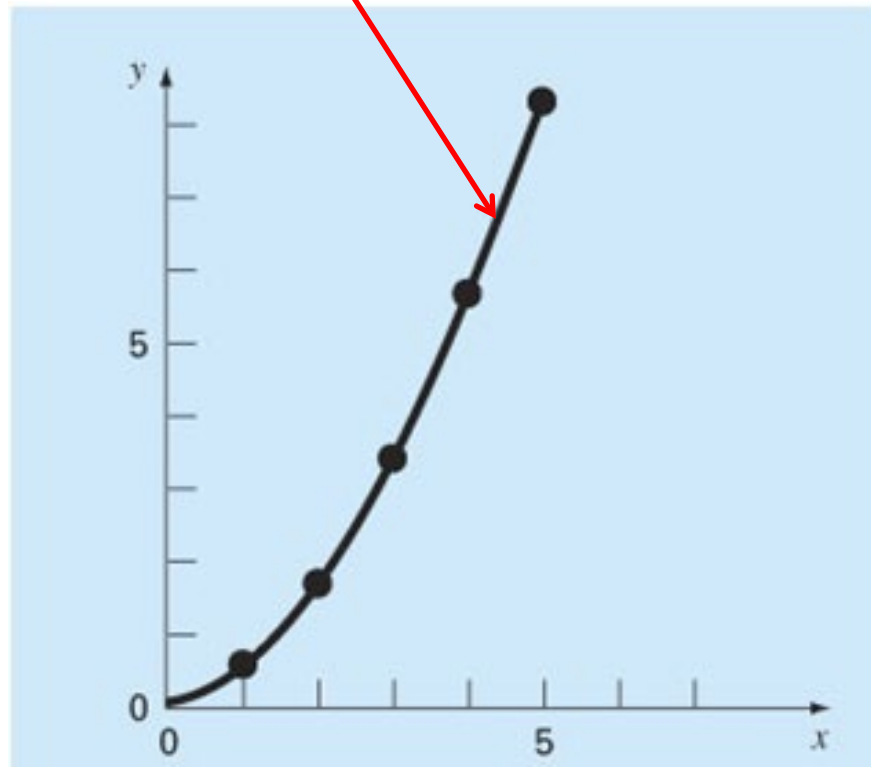
$$a_1 = \beta$$



$$\alpha = 10^{a_0} = 0.5$$

$$\beta = a_1 = 1.75$$

$$y = 0.5x^{1.75}$$



Linearization of other nonlinear relationships

(2) Exponential function:

$$y = \alpha_1 e^{\beta_1 x}$$



applying natural log on both sides

$$\ln(y) = \ln(\alpha_1) + \beta_1 * x$$



$$Y = a_0 + a_1 X$$

Linear relationship
between X and Y.

$$X = x; Y = \ln(y)$$
$$a_0 = \ln(\alpha_1), a_1 = \beta_1$$

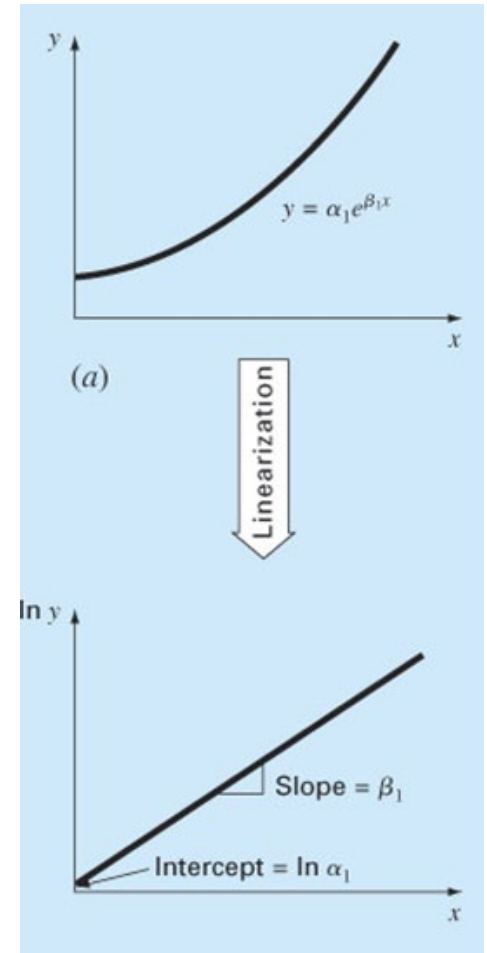


Determine a_0 and a_1 by linear regression



$$\alpha_1 = e^{a_0}$$

$$\beta_1 = a_1$$



(3) Saturation growth rate function:

$$y = \alpha_3 \frac{x}{\beta_3 + x}$$

invert

$$\frac{1}{y} = \frac{\beta_3}{\alpha_3} \frac{1}{x} + \frac{1}{\alpha_3}$$



$$Y = a_0 + a_1 X$$



Determine a_0 and a_1 by linear regression

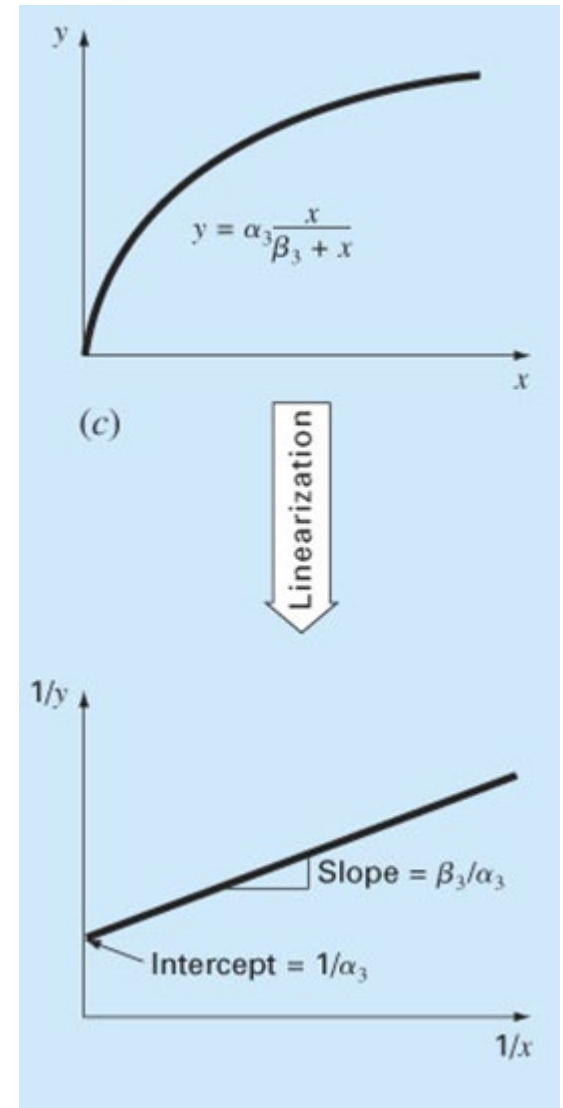


$$\alpha_3 = 1/a_0 \quad \beta_3 = a_1 \alpha_3$$

Linear relationship
between X and Y

$$X = \frac{1}{x}; \quad Y = \frac{1}{y}$$

$$a_0 = \frac{1}{\alpha_3}; \quad a_1 = \frac{\beta_3}{\alpha_3}$$



Curve fitting by Polynomial Regression

Polynomial (non-linear) regression (single x, 2nd order)

If we fit a second-order polynomial or quadratic equation:

$$y = a_0 + a_1x + a_2x^2$$

Coefficients a_0 , a_1 and a_2 can be determined by minimizing:

$$S_r = \sum_{i=1}^n (y_i - a_0 - a_1x_i - a_2x_i^2)^2$$

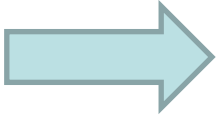
$$\frac{\partial S_r}{\partial a_0} = -2 \sum_{i=1}^n (y_i - a_0 - a_1x_i - a_2x_i^2) = 0$$



$$\frac{\partial S_r}{\partial a_1} = -2 \sum_{i=1}^n x_i (y_i - a_0 - a_1x_i - a_2x_i^2) = 0$$

$$\frac{\partial S_r}{\partial a_2} = -2 \sum_{i=1}^n x_i^2 (y_i - a_0 - a_1x_i - a_2x_i^2) = 0$$

$$(n)a_0 + \left(\sum_{i=1}^n x_i \right) a_1 + \left(\sum_{i=1}^n x_i^2 \right) a_2 = \left(\sum_{i=1}^n y_i \right)$$



$$\left(\sum_{i=1}^n x_i \right) a_0 + \left(\sum_{i=1}^n x_i^2 \right) a_1 + \left(\sum_{i=1}^n x_i^3 \right) a_2 = \left(\sum_{i=1}^n x_i y_i \right)$$

$$\left(\sum_{i=1}^n x_i^2 \right) a_0 + \left(\sum_{i=1}^n x_i^3 \right) a_1 + \left(\sum_{i=1}^n x_i^4 \right) a_2 = \left(\sum_{i=1}^n x_i^2 y_i \right)$$

This is familiar!

**Use Gauss elimination
or LU decomposition, or
Gauss-Seidel iteration
from week 3.**



$$\mathbf{A}\mathbf{X} = \mathbf{B}$$

$$\mathbf{A} = \begin{pmatrix} n & \left(\sum_{i=1}^n x_i \right) & \left(\sum_{i=1}^n x_i^2 \right) \\ \left(\sum_{i=1}^n x_i \right) & \left(\sum_{i=1}^n x_i^2 \right) & \left(\sum_{i=1}^n x_i^3 \right) \\ \left(\sum_{i=1}^n x_i^2 \right) & \left(\sum_{i=1}^n x_i^3 \right) & \left(\sum_{i=1}^n x_i^4 \right) \end{pmatrix}$$

$$\mathbf{X} = \begin{pmatrix} a_0 \\ a_1 \\ a_2 \end{pmatrix}$$

$$\mathbf{B} = \begin{pmatrix} \left(\sum_{i=1}^n y_i \right) \\ \left(\sum_{i=1}^n x_i y_i \right) \\ \left(\sum_{i=1}^n x_i^2 y_i \right) \end{pmatrix}$$

Solving $\mathbf{AX} = \mathbf{B}$ yields the coefficients a_0 , a_1 & a_2

1) Standard error of the estimate:

$$S_{y/x} = \sqrt{\frac{S_r}{n - (m + 1)}} \quad S_r = \sum_{i=1}^n (y_i - a_0 - a_1 x_i - a_2 x_i^2)^2$$

m is the order of polynomial; $m = 2$ for a quadratic equation.

$n - (m + 1)$ because $m + 1$ degrees of freedom lost for a_0 , a_1 and a_2 ...etc

2) Correlation coefficient :

$$r = \sqrt{\frac{S_1 - S_r}{S_1}}$$

$$S_1 = \sum_{i=1}^n (y_i - \bar{y})^2$$

Example - Polynomial regression

Fit a second-order polynomial to the data below.
(single x, 2nd order)

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TABLE 17.4 Computations for an error analysis of the quadratic least-squares fit.

x_i	y_i	$(y_i - \bar{y})^2$	$(y_i - a_0 - a_1x_i - a_2x_i^2)^2$
0	2.1	544.44	0.14332
1	7.7	314.47	1.00286
2	13.6	140.03	1.08158
3	27.2	3.12	0.80491
4	40.9	239.22	0.61951
5	61.1	1272.11	0.09439
Σ	152.6	2513.39	3.74657

$$y = a_0 + a_1x + a_2x^2$$

$$\mathbf{A} = \begin{pmatrix} n & \left(\sum_{i=1}^n x_i\right) & \left(\sum_{i=1}^n x_i^2\right) \\ \left(\sum_{i=1}^n x_i\right) & \left(\sum_{i=1}^n x_i^2\right) & \left(\sum_{i=1}^n x_i^3\right) \\ \left(\sum_{i=1}^n x_i^2\right) & \left(\sum_{i=1}^n x_i^3\right) & \left(\sum_{i=1}^n x_i^4\right) \end{pmatrix} = \begin{pmatrix} 6 & 15 & 55 \\ 15 & 55 & 225 \\ 55 & 225 & 979 \end{pmatrix}$$

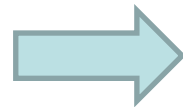
$$\mathbf{B} = \begin{pmatrix} \left(\sum_{i=1}^n y_i\right) \\ \left(\sum_{i=1}^n x_i y_i\right) \\ \left(\sum_{i=1}^n x_i^2 y_i\right) \end{pmatrix} = \begin{pmatrix} 152.6 \\ 585.6 \\ 2488.8 \end{pmatrix}$$

Solving $\mathbf{AX} = \mathbf{B}$ by Gauss elimination.

$$a_0 = 2.47857$$

$$a_1 = 2.35929$$

$$a_2 = 1.86071$$



$$y = 2.47857 + 2.35929x + 1.86071x^2$$

$$S_r = \sum_{i=1}^n (y_i - a_0 - a_1 x_i - a_2 x_i^2)^2 = 3.74657$$

$$S_1 = \sum_{i=1}^n (y_i - \bar{y})^2 = 2513.39$$



$$s_{y/x} = \sqrt{\frac{S_r}{6 - (2 + 1)}} = 1.12$$

$$r = \sqrt{\frac{S_1 - S_r}{S_1}} = 0.99851$$

Multiple linear regression

($\mathbf{x}_1, \mathbf{x}_2, \dots$, first order)

For example, y might be a linear function of \mathbf{x}_1 and \mathbf{x}_2 :

$$y = a_0 + a_1 x_1 + a_2 x_2$$

Coefficients a_0 , a_1 and a_2 can be determined by minimizing:

$$S_r = \sum_{i=1}^n (y_i - a_0 - a_1 x_{1i} - a_2 x_{2i})^2$$

$$\frac{\partial S_r}{\partial a_0} = -2 \sum_{i=1}^n (y_i - a_0 - a_1 x_{1i} - a_2 x_{2i}) = 0$$




$$\frac{\partial S_r}{\partial a_1} = -2 \sum_{i=1}^n x_{1i} (y_i - a_0 - a_1 x_{1i} - a_2 x_{2i}) = 0$$

$$\frac{\partial S_r}{\partial a_2} = -2 \sum_{i=1}^n x_{2i} (y_i - a_0 - a_1 x_{1i} - a_2 x_{2i}) = 0$$

$$(n)a_0 + \left(\sum_{i=1}^n x_{1i} \right) a_1 + \left(\sum_{i=1}^n x_{2i} \right) a_2 = \left(\sum_{i=1}^n y_i \right)$$


This is familiar!



$$\left(\sum_{i=1}^n x_{1i} \right) a_0 + \left(\sum_{i=1}^n x_{1i}^2 \right) a_1 + \left(\sum_{i=1}^n x_{1i} x_{2i} \right) a_2 = \left(\sum_{i=1}^n x_{1i} y_i \right)$$

$$\left(\sum_{i=1}^n x_{2i} \right) a_0 + \left(\sum_{i=1}^n x_{1i} x_{2i} \right) a_1 + \left(\sum_{i=1}^n x_{2i}^2 \right) a_2 = \left(\sum_{i=1}^n x_{2i} y_i \right)$$

**Use Gauss
elimination or LU
decomposition, or
Gauss-Seidel
iteration from
week 3.**



$$\mathbf{A}\mathbf{X} = \mathbf{B}$$

$$\mathbf{A} = \begin{pmatrix} n & \left(\sum_{i=1}^n x_{1i} \right) & \left(\sum_{i=1}^n x_{2i} \right) \\ \left(\sum_{i=1}^n x_{1i} \right) & \left(\sum_{i=1}^n x_{1i}^2 \right) & \left(\sum_{i=1}^n x_{1i} x_{2i} \right) \\ \left(\sum_{i=1}^n x_{2i} \right) & \left(\sum_{i=1}^n x_{1i} x_{2i} \right) & \left(\sum_{i=1}^n x_{2i}^2 \right) \end{pmatrix} \quad \mathbf{X} = \begin{pmatrix} a_0 \\ a_1 \\ a_2 \end{pmatrix} \quad \mathbf{B} = \begin{pmatrix} \left(\sum_{i=1}^n y_i \right) \\ \left(\sum_{i=1}^n x_{1i} y_i \right) \\ \left(\sum_{i=1}^n x_{2i} y_i \right) \end{pmatrix}$$

Solving $\mathbf{AX} = \mathbf{B}$ yields the coefficients a_0 , a_1 & a_2 .

1) Standard error of the estimate:

$$S_{y/x} = \sqrt{\frac{S_r}{n - (m + 1)}} \quad S_r = \sum_{i=1}^n (y_i - a_0 - a_1 x_{1i} - a_2 x_{2i})^2$$

m is the dimensionality, $m = 2$ for the above problem.

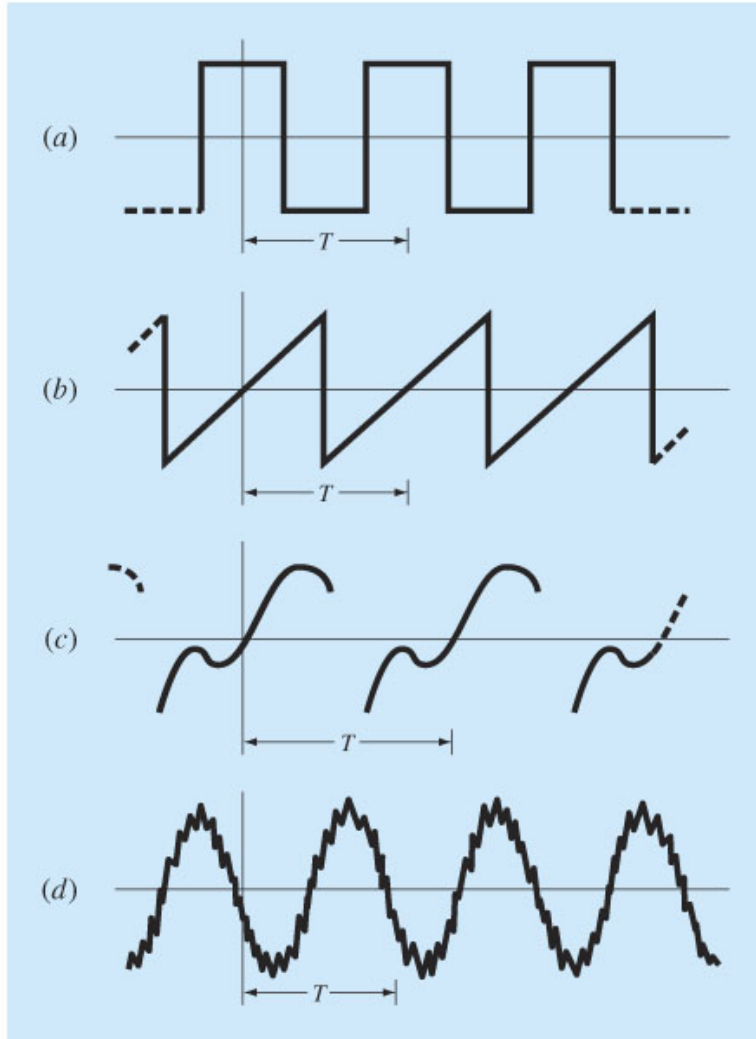
2) Correlation coefficient :

$$r = \sqrt{\frac{S_1 - S_r}{S_1}} \quad S_1 = \sum_{i=1}^n (y_i - \bar{y})^2$$

Fitting periodic functions by Regression (Fourier Approximation)

Periodic functions

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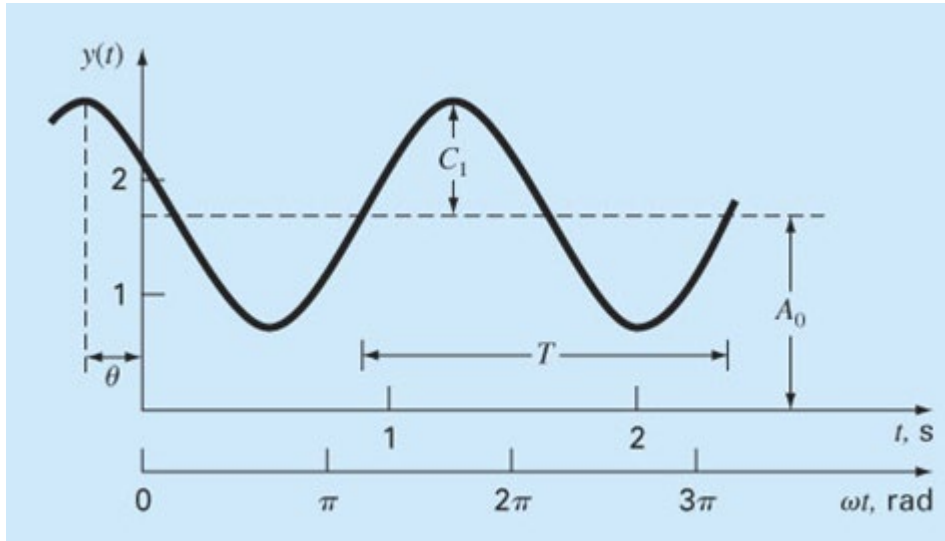


$$f(t) = f(t + T)$$

- The periodic function repeats its values at a regular interval (T).
- T is defined as the period.

Example 1- Sinusoid function

$$f(t) = A_0 + C_1 \cos(\omega_0 t + \theta)$$



$$\omega_0 = \frac{2\pi}{T} = 2\pi f$$

$$f = \frac{1}{T}$$

f = frequency

A_0 = mean value, the average height above the t axis,

C_1 = amplitude, the height of the oscillation,

ω_0 = angular frequency, how often the cycles occur,

θ = phase angle, the extent to which sinusoid is shifted horizontally.

Rewriting the function as...

$$f(t) = A_0 + C_1 \cos(\omega_0 t + \theta)$$



$$f(t) = A_0 + A_1 \cos(\omega_0 t) + B_1 \sin(\omega_0 t)$$

where:

$$A_1 = C_1 \cos(\theta) \qquad B_1 = -C_1 \sin(\theta)$$

Least-squares fit of a sinusoid

Fit the following sinusoid function to the **discrete** data points $(t_1, y_1), (t_2, y_2), \dots, (t_i, y_i), \dots (t_n, y_n)$.

$$f(t) = A_0 + A_1 \cos(\omega_0 t) + B_1 \sin(\omega_0 t)$$

The goal is to determine coefficients values A_0 , A_1 and B_1 that minimize

$$S_r = \sum_{i=1}^n \left(y_i - \left(A_0 + A_1 \cos(\omega_0 t_i) + B_1 \sin(\omega_0 t_i) \right) \right)^2$$

Minimization yields:

$$\begin{pmatrix} n & \sum_{i=1}^n \cos(\omega_0 t_i) & \sum_{i=1}^n \sin(\omega_0 t_i) \\ \sum_{i=1}^n \cos(\omega_0 t_i) & \sum_{i=1}^n \cos^2(\omega_0 t_i) & \sum_{i=1}^n \sin(\omega_0 t_i) \cos(\omega_0 t_i) \\ \sum_{i=1}^n \sin(\omega_0 t_i) & \sum_{i=1}^n \sin(\omega_0 t_i) \cos(\omega_0 t_i) & \sum_{i=1}^n \sin^2(\omega_0 t_i) \end{pmatrix} \begin{pmatrix} A_0 \\ A_1 \\ B_1 \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^n y_i \\ \sum_{i=1}^n y_i \cos(\omega_0 t_i) \\ \sum_{i=1}^n y_i \sin(\omega_0 t_i) \end{pmatrix}$$

$$\begin{pmatrix} n & 0 & 0 \\ 0 & n/2 & 0 \\ 0 & 0 & n/2 \end{pmatrix} \begin{pmatrix} A_0 \\ A_1 \\ B_1 \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^n y_i \\ \sum_{i=1}^n y_i \cos(\omega_0 t_i) \\ \sum_{i=1}^n y_i \sin(\omega_0 t_i) \end{pmatrix}$$

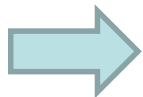
$$A_0 = \frac{\sum_{i=1}^n y_i}{n}$$

$$A_1 = \frac{2}{n} \sum_{i=1}^n y_i \cos(\omega_0 t_i)$$

$$B_1 = \frac{2}{n} \sum_{i=1}^n y_i \sin(\omega_0 t_i)$$

This is familiar!

**Use Gauss
elimination or LU
decomposition, or
Gauss-Seidel
iteration from
week 3.**



Example 2 - Sinusoid function

If the sinusoid function is as follows:

$$f(t) = A_0 + A_1 \cos(\omega_0 t) + B_1 \sin(\omega_0 t) + A_2 \cos(2\omega_0 t) + B_2 \sin(2\omega_0 t) \\ + \dots + A_m \cos(m\omega_0 t) + B_m \sin(m\omega_0 t)$$

...the coefficients can be determined by:

$$\left. \begin{aligned} A_0 &= \frac{\sum_{i=1}^n y_i}{n} \\ A_j &= \frac{2}{n} \sum_{i=1}^n y_i \cos(j\omega_0 t_i) \\ B_j &= \frac{2}{n} \sum_{i=1}^n y_i \sin(j\omega_0 t_i) \end{aligned} \right\} j = 1, 2, \dots, m$$

Example – Continuous Fourier series

For a **continuous** curve function ($F(t)$) with period T , the continuous Fourier series (with infinite terms) can be written:

$$f(t) = a_0 + \sum_{k=1}^{\infty} (a_k \cos(k\omega_0 t) + b_k \sin(k\omega_0 t))$$

The coefficients can be computed via

$$a_k = \frac{2}{T} \int_0^T F(t) \cos(k\omega_0 t) dt$$

$$b_k = \frac{2}{T} \int_0^T F(t) \sin(k\omega_0 t) dt$$

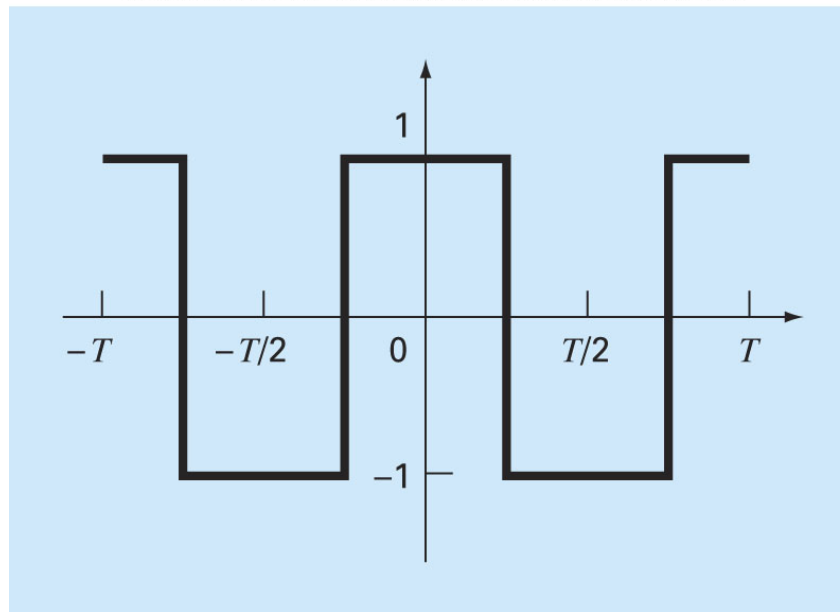
$$a_0 = \frac{1}{T} \int_0^T F(t) dt$$

Continuous Fourier series – Example 2

Use the continuous Fourier series to approximate the square of rectangular wave function.

$$F(t) = \begin{cases} -1 & -T/2 < t < -T/4 \\ 1 & -T/4 < t < T/4 \\ -1 & T/4 < t < T/2 \end{cases}$$

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Continuous Fourier (infinite) series

$$f(t) = \frac{4}{\pi} \cos(\omega_0 t) - \frac{4}{3\pi} \cos(3\omega_0 t) + \frac{4}{5\pi} \cos(5\omega_0 t) - \frac{4}{7\pi} \cos(7\omega_0 t) + \dots$$

$$a_0 = \frac{1}{T} \int_{-T/2}^{T/2} F(t) dt = 0$$

$$\begin{aligned} a_k &= \frac{2}{T} \int_{-T/2}^{T/2} F(t) \cos(k\omega_0 t) dt \\ &= \frac{2}{T} \left(- \int_{-T/2}^{-T/4} \cos(k\omega_0 t) dt + \int_{-T/4}^{T/4} \cos(k\omega_0 t) dt - \int_{T/4}^{T/2} \cos(k\omega_0 t) dt \right) \end{aligned}$$

$$a_k = \begin{cases} 4/(k\pi) & \text{for } k = 1, 5, 9, \dots \\ -4/(k\pi) & \text{for } k = 3, 7, 11, \dots \\ 0 & \text{for } k = 2, 4, 6, \dots \end{cases}$$

$$b_k = \frac{2}{T} \int_{-T/2}^{T/2} F(t) \sin(k\omega_0 t) dt = 0$$

Interpolation

Interpolation

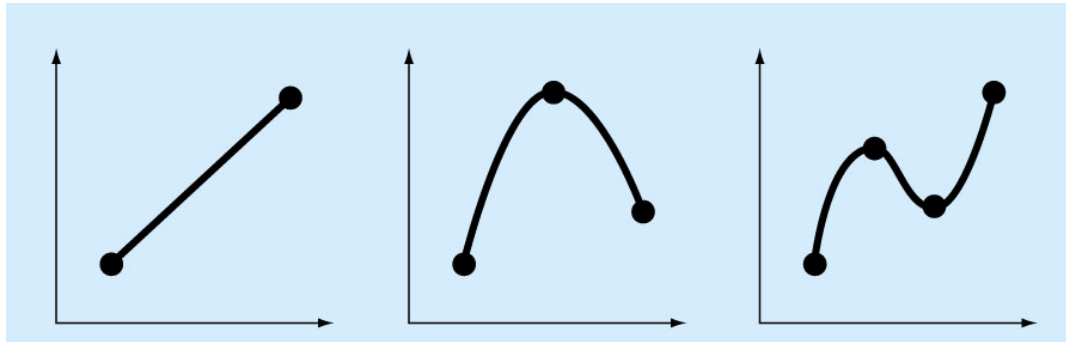
Estimation of intermediate values between precise data points. The most common method is:

$$f(x) = a_0 + a_1x + a_2x^2 + \cdots + a_nx^n$$

Although there is one and only one ***n*th-order polynomial** that fits ***n*+1 points**, there are 2 common mathematical formats the polynomial can be expressed:

The **Newton** or **Lagrange** polynomials

(a)
1st order (linear)
connecting 2
points



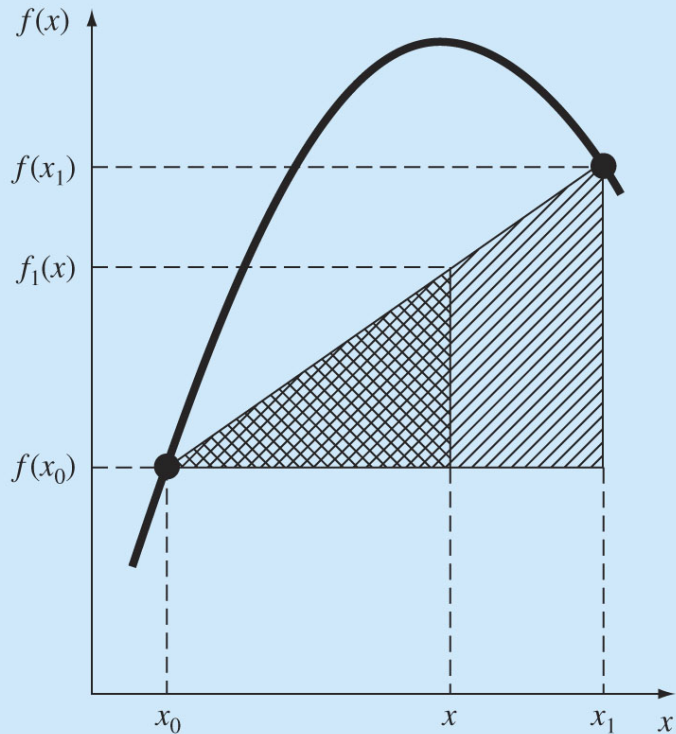
(b)
2nd order (quadratic / parabolic)
connecting 3 points

(c)
3rd order (cubic)
connecting 4
points.

Linear interpolation

If **two** points $(x_0, f(x_0))$ and $(x_1, f(x_1))$ are known, $f(x)$ at x between x_0 and x_1 can be estimated by linear interpolation using **similar triangles**.

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The simplest form of interpolation, connects two data points with a straight line

$$\frac{f(x) - f(x_0)}{x - x_0} = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

$$f(x) = f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0} (x - x_0)$$

Function value
at the starting
data point

Finite-divided difference
approximation for the **first
derivative**

Linear interpolation

Estimate the natural log of 2 by linear interpolation.

1. Interpolate between $\ln(1) = 0$ & $\ln(6) = 1.7918$.
2. Repeat using a smaller interval between $\ln(1) = 0$ & $\ln(4) = 1.3863$.

Solution:

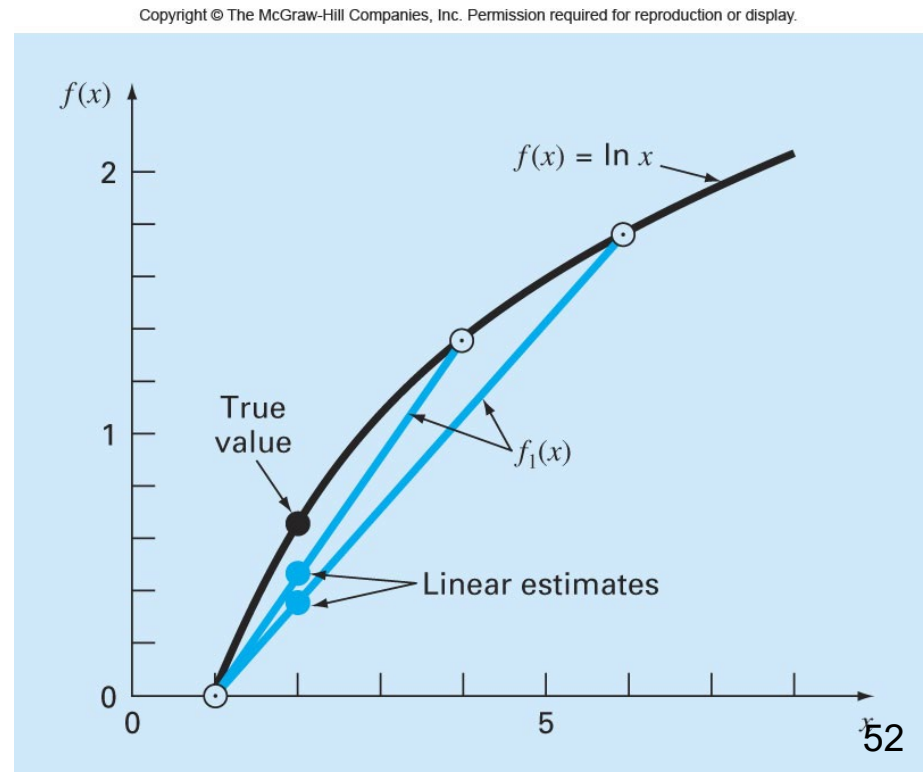
$$(1) x_0 = 1; f(x_0) = 0; x_1 = 6; f(x_1) = 1.791759.$$

$$\begin{aligned} f(x) &= f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0} (x - x_0) \\ &= 0 + \frac{1.791759 - 0}{6 - 1} (2 - 0) \\ &= 0.3584 \end{aligned}$$

(2) $x_0 = 1$; $f(x_0) = 0$; $x_1 = 4$; $f(x_1) = 1.386294$.

$$\begin{aligned} f(x) &= f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0} (x - x_0) \\ &= 0 + \frac{1.386294 - 0}{4 - 1} (2 - 0) \\ &= 0.4621 \end{aligned}$$

**Smaller intervals
improve accuracy!**

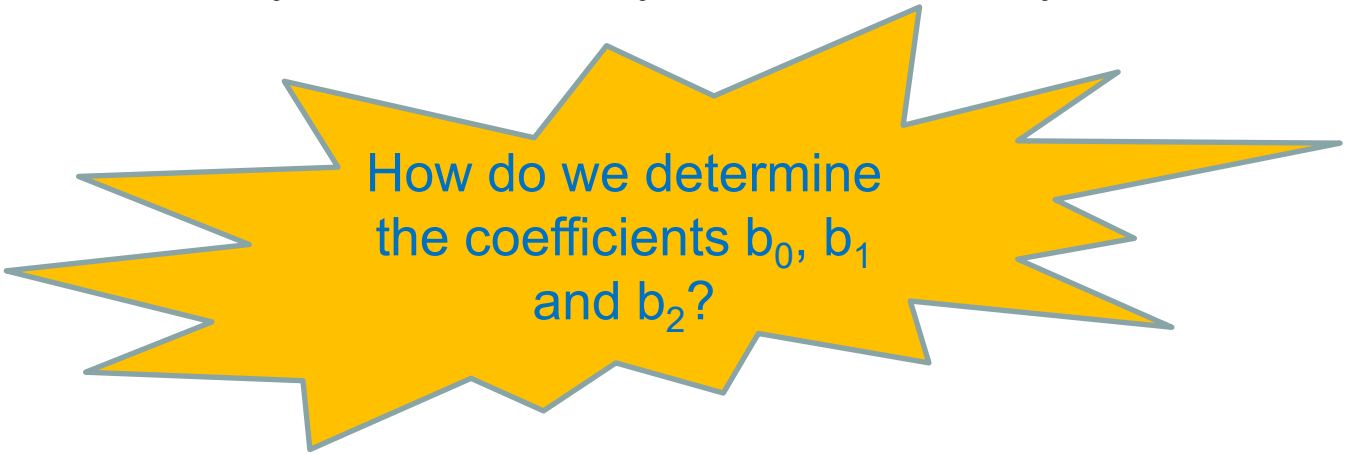


Quadratic interpolation

If **three** points $(x_0, f(x_0))$, $(x_1, f(x_1))$ and $(x_2, f(x_2))$ are known, $f(x)$ at x between x_0 and x_2 can be estimated by quadratic interpolation.

The quadratic formula (Newton equation) can be expressed by:

$$f(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1)$$

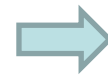


How do we determine
the coefficients b_0 , b_1
and b_2 ?

Quadratic interpolation

$$f(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1)$$

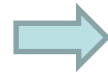
1) At $x = x_0$ $f(x_0) = b_0$



$$b_0 = f(x_0)$$

Function value at starting data point

2) At $x = x_1$ $f(x_1) = b_0 + b_1(x_1 - x_0)$

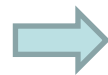


$$b_1 = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

Finite-divided difference approximation for **the first derivative**

3) At $x = x_2$

$f(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1)$



$$b_2 = \frac{\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}}{x_2 - x_0}$$

Finite-divided difference approximation for **the second derivative**

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General form of Newton's (quadratic) interpolating polynomials

If $n+1$ points are available, $f(x)$ can be estimated by polynomial interpolation.

$$f(x) = b_0 + b_1(x - x_0) + \cdots + b_n(x - x_0)(x - x_1) \cdots (x - x_{n-1})$$

The coefficients b_0, b_1, \dots, b_n can be determined by:

$$b_0 = f(x_0)$$

Function value at starting data point

$$b_1 = f[x_1, x_0] = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

Finite-divided difference of the **1st derivative**

$$b_2 = f[x_2, x_1, x_0] = \frac{f[x_2, x_1] - f[x_1, x_0]}{x_2 - x_0}$$

Finite-divided difference of the **2nd derivative**

\vdots

$$b_n = f[x_n, x_{n-1}, \dots, x_1, x_0] = \frac{f[x_n, x_{n-1}, \dots, x_1] - f[x_{n-1}, \dots, x_1, x_0]}{x_n - x_0}$$

Finite-divided difference of the **nth derivative**

Example - Quadratic interpolation

Fit a second-order polynomial to the three points:

$$x_0 = 1, \quad f(x_0) = 0$$

$$x_1 = 4, \quad f(x_1) = 1.386294$$

$$x_2 = 6, \quad f(x_2) = 1.791759$$

Use the polynomial to evaluate $\ln(2)$.

Solution:

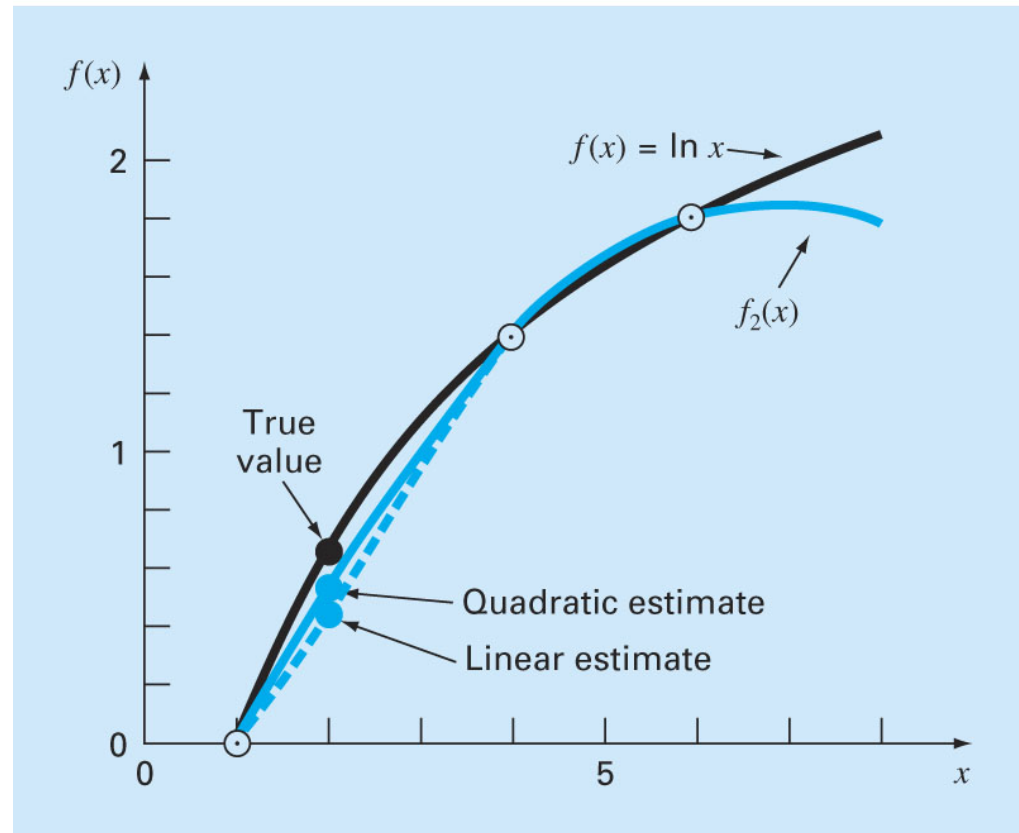
$$b_0 = f(x_0) = 0$$
$$b_1 = \frac{f(x_1) - f(x_0)}{x_1 - x_0} = \frac{1.386294 - 0}{4 - 1} = 0.4621$$
$$b_2 = \frac{\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}}{x_2 - x_0} = -0.05187$$

$$f(x) = 0 + 0.4621(x - 1) - 0.05187(x - 1)(x - 4)$$

At $x = 2$

$$\begin{aligned} f(2) &= 0 + 0.4621((2) - 1) - 0.05187((2) - 1)((2) - 4) \\ &= 0.5658 \end{aligned}$$

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Recursive Nature of Finite Divided Differences

for example, 4 data points, 3 order polynomial (3 derivatives)

i	x_i	$f(x_i)$		First		Second		Third
0	x_0	$f(x_0)$	→	$f[x_1, x_0]$	→	$f[x_2, x_1, x_0]$	→	$f[x_3, x_2, x_1, x_0]$
1	x_1	$f(x_1)$	→	$f[x_2, x_1]$	→	$f[x_3, x_2, x_1]$		
2	x_2	$f(x_2)$	→	$f[x_3, x_2]$				
3	x_3	$f(x_3)$	→					

$$\begin{aligned}
 f(x) = & f(x_0) + f[x_1, x_0](x - x_0) \\
 & + f[x_2, x_1, x_0](x - x_0)(x - x_1) \\
 & + f[x_3, x_2, x_1, x_0](x - x_0)(x - x_1)(x - x_2)
 \end{aligned}$$

Find the solution using a matrix/table as a guide:

Data points (x, f(x)): (1, 0), (4, 1.386294) and (6, 1.791759)

x	$f(x)$	b_0	b_1	b_2
1	0			
4	1.386294	0.4621		
6	1.791759	0.2027	-0.05187	

This matrix/table is computed as follows:

after writing down the x and f(x) values in separate columns, move from left to right while calculating the next column,.

$$\frac{1.386294 - 0}{4 - 1} = 0.4621$$

$$\frac{0.2027 - 0.4621}{6 - 1} = -0.05187$$

$$\frac{1.791759 - 1.386294}{6 - 4} = 0.2027$$

$$f(x) = 0 + 0.4621(x - 1) - 0.05187(x - 1)(x - 4)$$

Lagrange's interpolating polynomials

(a reformulation of Newton's polynomials to **avoid computing divided differences**)

$$f_n(x) = \sum_{i=0}^n L_i(x) f(x_i)$$
$$L_i(x) = \prod_{\substack{j=0 \\ j \neq i}}^n \frac{x - x_j}{x_i - x_j}$$

\prod denotes “the product”.

For the **linear** version:

$$f(x) = \frac{x - x_1}{x_0 - x_1} f(x_0) + \frac{x - x_0}{x_1 - x_0} f(x_1)$$

For the **second-order** version:

$$f(x) = \frac{(x - x_1)(x - x_2)}{(x_0 - x_1)(x_0 - x_2)} f(x_0) + \frac{(x - x_0)(x - x_2)}{(x_1 - x_0)(x_1 - x_2)} f(x_1) + \frac{(x - x_0)(x - x_1)}{(x_2 - x_0)(x_2 - x_1)} f(x_2)$$

While the Lagrange interpolating polynomial is a simple reformulation of the Newton's polynomial, it is computationally EFFICIENT by **avoiding the calculation of divided differences entirely.**

Newton's polynomial

$$f(x) = f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0}(x - x_0)$$

$$f(x) = f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0}(x - x_0) + \frac{\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}}{x_2 - x_0}(x - x_0)(x - x_1)$$

Lagrange's polynomial

$$f(x) = \frac{x - x_1}{x_0 - x_1} f(x_0) + \frac{x - x_0}{x_1 - x_0} f(x_1)$$

$$f(x) = \frac{(x - x_1)(x - x_2)}{(x_0 - x_1)(x_0 - x_2)} f(x_0) + \frac{(x - x_0)(x - x_2)}{(x_1 - x_0)(x_1 - x_2)} f(x_1) + \frac{(x - x_0)(x - x_1)}{(x_2 - x_0)(x_2 - x_1)} f(x_2)$$

Example 1 – Lagrange's interpolating polynomials

Find an **Lagrange** interpolating polynomial for **three** data points:
(0,1), (2,2), and (3,4)

Solution:

$$\begin{aligned} f(x) &= \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)} f(x_0) + \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} f(x_1) + \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)} f(x_2) \\ &= \frac{(x-2)(x-3)}{(0-2)(0-3)} 1 + \frac{(x-0)(x-3)}{(2-0)(2-3)} 2 + \frac{(x-0)(x-2)}{(3-0)(3-2)} 4 \\ &= \frac{1}{2} x^2 - \frac{1}{2} x + 1 \end{aligned}$$

Re-checking the Lagrangian equation of best-fit with the known data points

$$f(0) = \frac{1}{2} * 0^2 - \frac{1}{2} * 0 + 1 = 1$$

$$f(2) = \frac{1}{2} * 2^2 - \frac{1}{2} * 2 + 1 = 2$$

$$f(3) = \frac{1}{2} * 3^2 - \frac{1}{2} * 3 + 1 = 4$$

Example 2 – Lagrange's interpolating polynomials

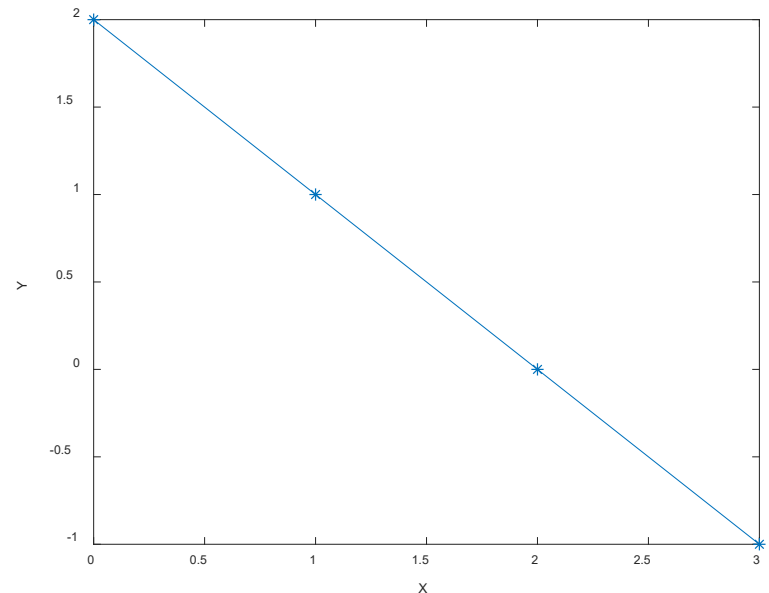
Find an **Lagrange** interpolating polynomial for **four** data points:
((0,2), (1,1), (2,0) and (3,-1))

Solution:

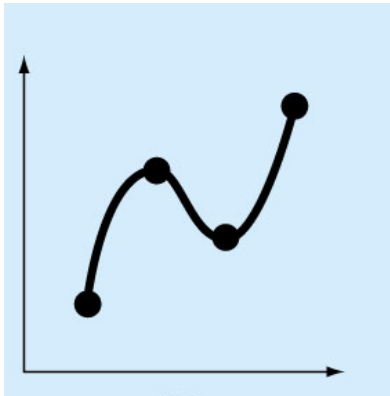
$$\begin{aligned} f(x) &= \frac{(x-1)(x-2)(x-3)}{(0-1)(0-2)(0-3)} 2 + \frac{(x-0)(x-2)(x-3)}{(1-0)(1-2)(1-3)} 1 + \frac{(x-0)(x-1)(x-3)}{(2-0)(2-1)(2-3)} 0 + \frac{(x-0)(x-1)(x-2)}{(3-0)(3-1)(3-2)} \times (-1) \\ &= \frac{1}{3}(x^3 - 6x^2 + 11x - 6) + \frac{1}{2}(x^3 - 5x^2 + 6x) - \frac{1}{6}(x^3 - 3x^2 + 2x) \\ &= -x + 2 \end{aligned}$$

The interpolating polynomials
may be 3 or less.

In this example, the data point are
co-linear, so the interpolating
polynomial degree is 1.

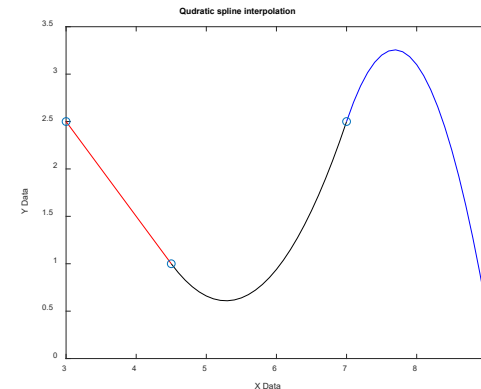


- Newton / Lagrange interpolations comprise **one function** to describe the full range (domain) of data.
- If the data domain (range) shows sub-features, is there a better way to interpolate?



One polynomial equation

$$f(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1) + b_3(x - x_0)(x - x_1)(x - x_2)$$



Data divided into 3 sub-domains.
1 equation describes each subdomain.

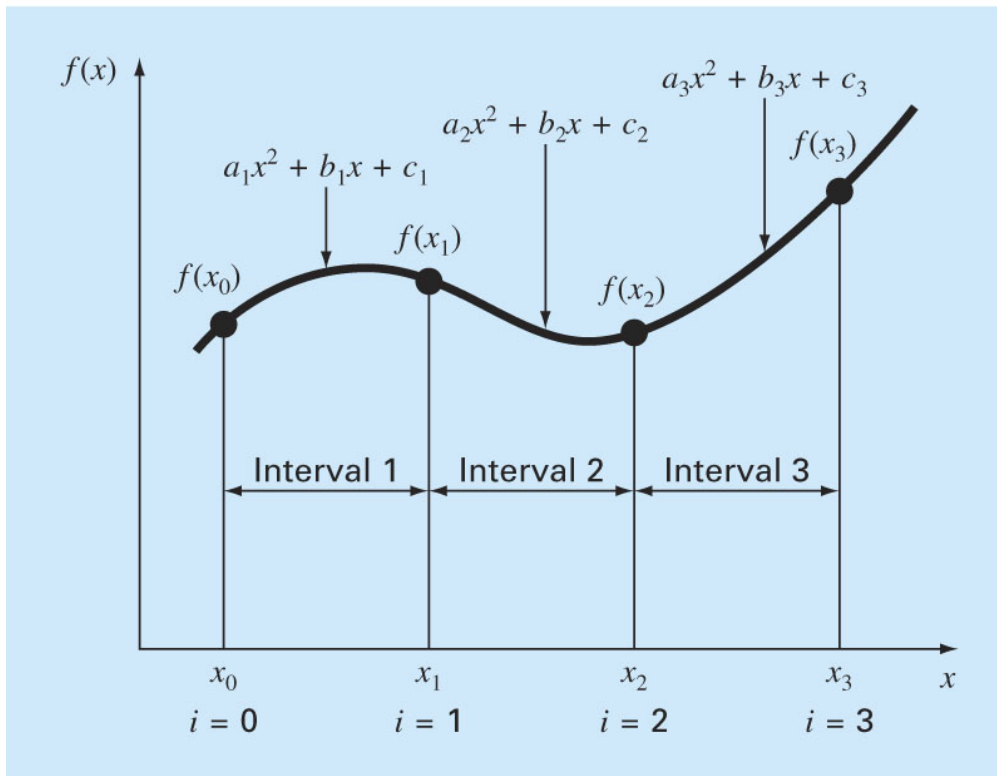
$$f_i(x) = a_i x^2 + b_i x + c_i$$

Quadratic splines interpolation

The objective in quadratic splines is to derive a second-order polynomial for each interval between data points.

The polynomial for each interval is generally represented as:

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$$f_i(x) = a_i x^2 + b_i x + c_i$$

$$f_i(x) = a_i x^2 + b_i x + c_i \quad \Rightarrow$$

Three unknown coefficients (a_i , b_i and c_i) for each interval.

For **$n+1$ data points** ($i = 0, 1, \dots, n$), there are **n intervals**.

Consequently **$3n$ unknown coefficients**.

So **$3n$ equations** are required to evaluate the unknowns.

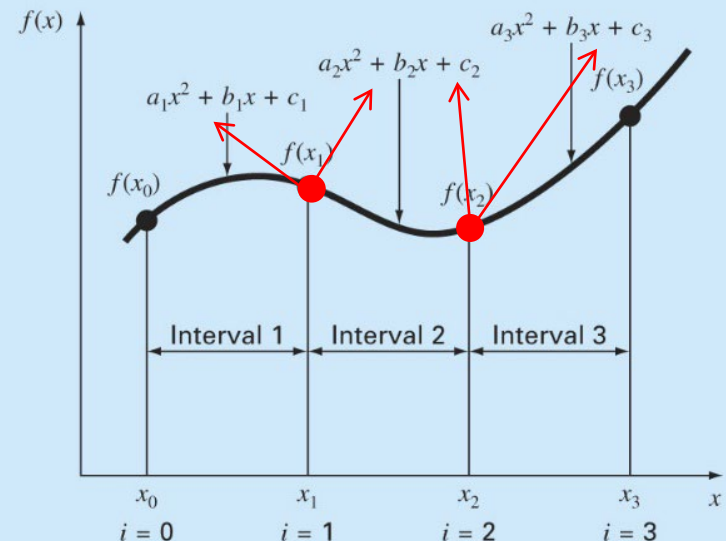
(1) The function values for **internal data points** ($i = 1, 2, \dots, n-1$) are known.
So **$(2n-2)$ equations are now known.**

For point $(i-1)$:

$$a_{i-1}x_{i-1}^2 + b_{i-1}x_{i-1} + c_{i-1} = f_{i-1}(x_{i-1})$$

$$a_i x_{i-1}^2 + b_i x_{i-1} + c_i = f_i(x_{i-1})$$

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(2) The **first derivative** for both equations of **internal data points** are equal.

So (n-1) equations are now known.

$$2a_{i-1}x_{i-1} + b_{i-1} = 2a_ix_{i-1} + b_i$$

(3) The **first and last functions** must pass through the end points.

So 2 equations are now known.

$$a_1x_0^2 + b_1x_0 + c_1 = f_1(x_0)$$

$$a_nx_n^2 + b_nx_n + c_n = f_n(x_n)$$

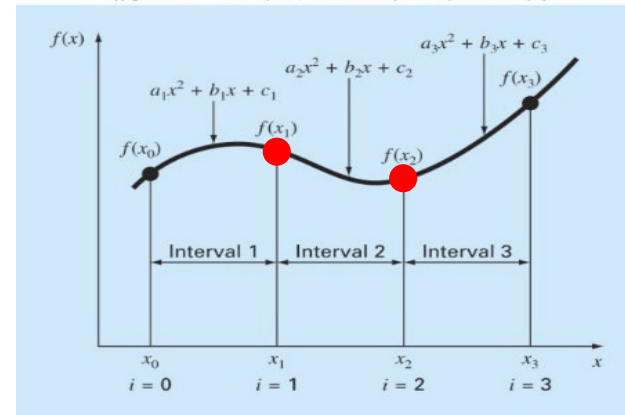
4) **ASSUME** the first point extends to the origin. In this case, the second derivative is zero for the **first point**.

So 1 equation is now known and solved.

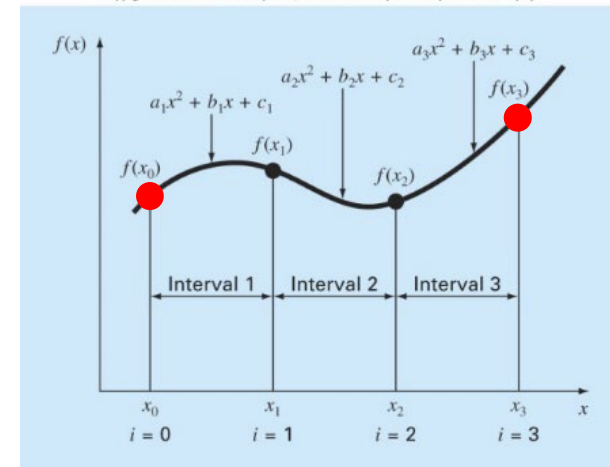
$$a_1 = 0$$

The total number of equations = $(2n - 2) + (n-1) + 2 + 1 = 3n$.

$(3n - 1)$ unknowns with $(3n - 1)$ equations can be solved by spline interpolation!



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Example - Quadratic splines interpolation

Fit quadratic splines to the following data. Use the results to estimate the value at $x = 5$.

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TABLE 18.1

Data to be fit with
spline functions.

x	$f(x)$
3.0	2.5
4.5	1.0
7.0	2.5
9.0	0.5

Solution

- 4 data points; intervals $n = 3$.

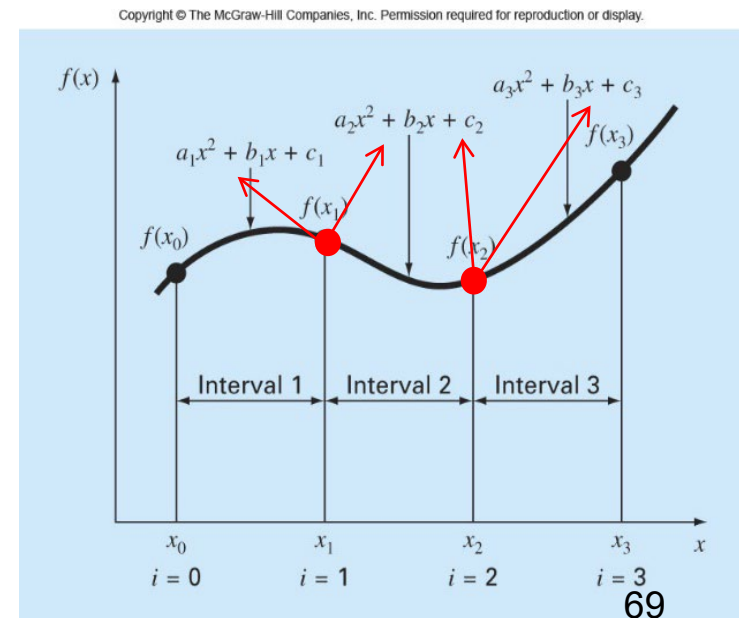
$$f_i(x) = a_i x^2 + b_i x + c_i$$

Hence, there are 3 equations and 9 unknown coefficients ($a_1, b_1, c_1, a_2, b_2, c_2, a_3, b_3, c_3$).

- The equations for the 2 internal points.
(4 equations)

For point (4.5, 1.0) $\begin{cases} 4.5^2 \times a_1 + 4.5b_1 + c_1 = 1.0 \\ 4.5^2 \times a_2 + 4.5b_2 + c_2 = 1.0 \end{cases}$

For point (7.0, 2.5) $\begin{cases} 7.0^2 \times a_2 + 7b_2 + c_2 = 2.5 \\ 7.0^2 \times a_3 + 7b_3 + c_3 = 2.5 \end{cases}$



Solution

- The first derivatives at internal points are also equal.
(2 equations)

$$f_i(x) = a_i x^2 + b_i x + c_i$$

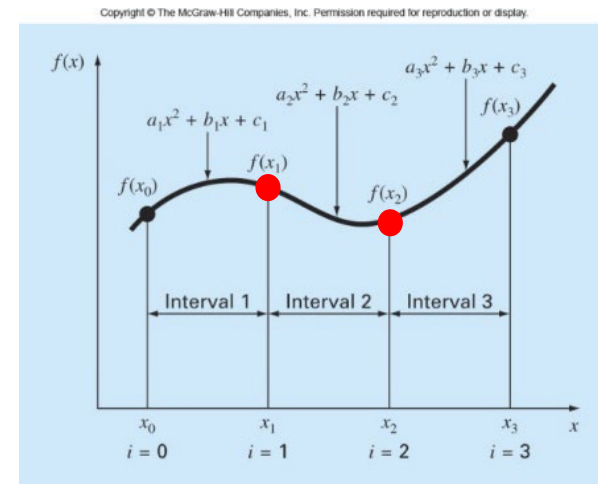


$$\frac{\partial f}{\partial x} = 2a_i x + b_i$$

continuous slopes



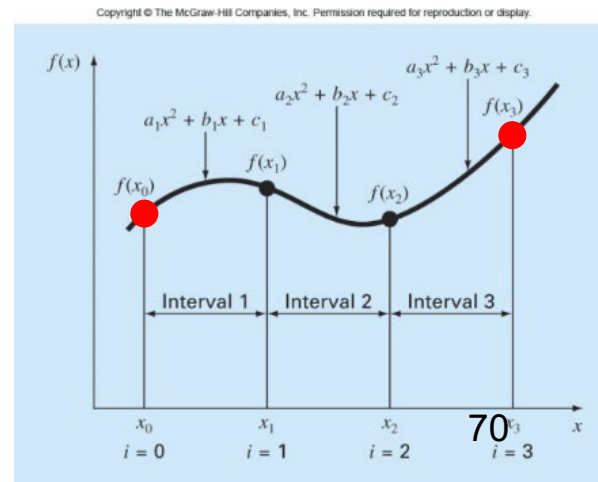
$$2a_{i-1}x + b_{i-1} = 2a_i x + b_i$$



- For point (4.5, 1.0) $2 \times 4.5 \times a_1 + b_1 = 2 \times 4.5 \times a_2 + b_2$
 For point (7.0, 2.5) $2 \times 7 \times a_2 + b_2 = 2 \times 7 \times a_3 + b_3$

- The first and last function must pass through the end points.
(2 equations)

- For point (3.0, 2.5) $3^2 \times a_1 + 3b_1 + c_1 = 2.5$
 For point (9.0, 0.5) $9^2 \times a_3 + 9b_3 + c_3 = 0.5$



Solution

(1) $n = 3$. The function values for interior data points ($i = 1$ and 2) are known (4 equations).

$$20.25a_1 + 4.5b_1 + c_1 = 1.0$$

$$20.25a_2 + 4.5b_2 + c_2 = 1.0$$

$$49a_2 + 7b_2 + c_2 = 2.5$$

$$49a_3 + 7b_3 + c_3 = 2.5$$

2) The first and last functions must pass through the end points ($i = 0$ and $i = 3$) (2 equations).

$$9a_1 + 3b_1 + c_1 = 2.5$$

$$81a_3 + 9b_3 + c_3 = 0.5$$

3) The first derivative at interior data points ($i = 1$ and 2) must be equal (2 equations).

$$9a_1 + b_1 = 9a_2 + b_2$$

$$14a_2 + b_2 = 14a_3 + b_3$$

4) Assume the second derivative is zero at the first point (1 equation).

$$a_1 = 0$$

**Assemble all
equations:**

$$\begin{pmatrix} 4.5 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 20.25 & 4.5 & 1 & 0 & 0 & 0 \\ 0 & 0 & 49 & 7 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 49 & 7 & 1 \\ 3 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 81 & 9 & 1 \\ 1 & 0 & -9 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 14 & 1 & 0 & -14 & -1 & 0 \end{pmatrix} \begin{pmatrix} b_1 \\ c_1 \\ a_2 \\ b_2 \\ c_2 \\ a_3 \\ b_3 \\ c_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 2.5 \\ 2.5 \\ 2.5 \\ 0.5 \\ 0 \\ 0 \end{pmatrix}$$


Solving equations yields:

$$a_1 = 0 \quad b_1 = -1 \quad c_1 = 5.5$$

$$a_2 = 0.64 \quad b_2 = -6.76 \quad c_2 = 18.46$$

$$a_3 = -1.6 \quad b_3 = 24.6 \quad c_3 = -91.3$$

$$f_1(x) = -x + 5.5 \quad 3.0 \leq x \leq 4.5$$


$$f_2(x) = 0.64x^2 - 6.76x + 18.46 \quad 4.5 \leq x \leq 7.0$$

$$f_3(x) = -1.6x^2 + 24.6x - 91.3 \quad 7.0 \leq x \leq 9.0$$

At $x = 5$

$$f_2(x = 5) = 0.64(5)^2 - 6.76(5) + 18.46 = 0.66$$

Cubic splines interpolation

The objective in cubic splines is to derive a third-order polynomial for each interval between data points.

The polynomial for each interval is generally represented as:

$$f_i(x) = a_i x^3 + b_i x^2 + c_i x + d_i$$

For **$n+1$ data points** ($i = 0, 1, \dots, n$), there are **n intervals** and consequently, **$4n$ unknown constants**.

$4n$ equations are required to evaluate the unknown.

Equations for cubic splines interpolation:

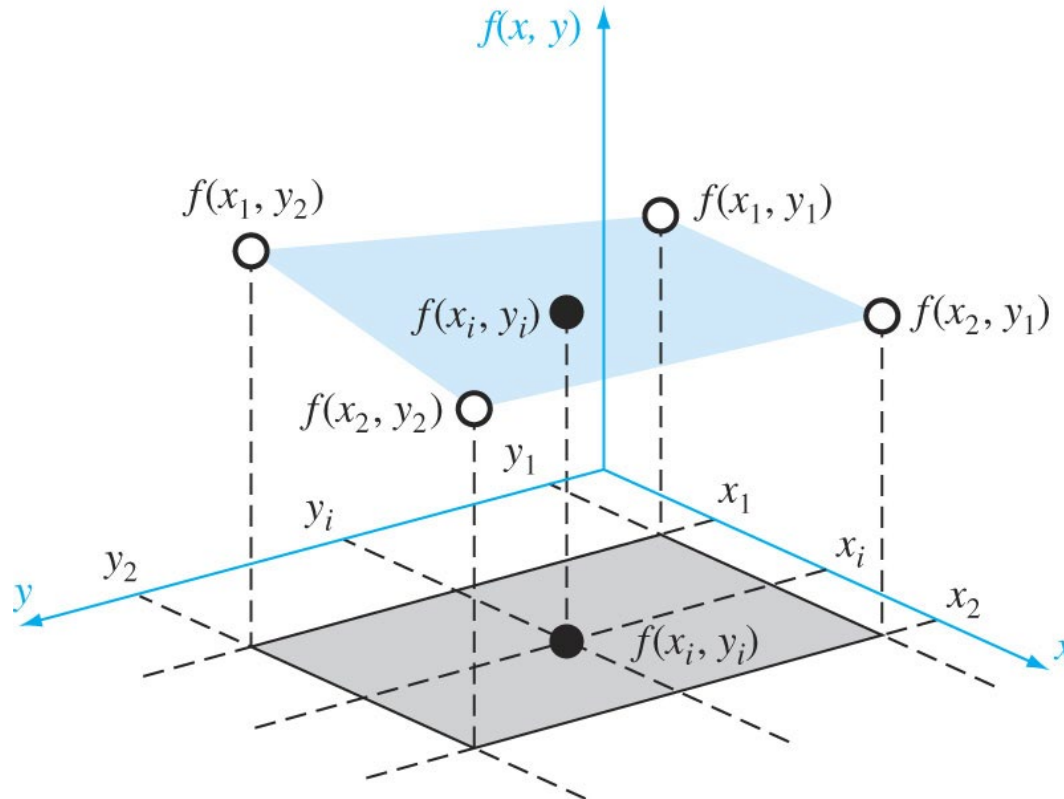
- (1) The function values for interior data points ($i = 1, 2, \dots, n-1$) are known **($2n-2$ equations)**.
- (2) The first derivative for interior data points ($i = 1, 2, \dots, n-1$) are equal **($n-1$ equations)**.
- (3) The second derivative at interior data points ($i = 1, 2, \dots, n-1$) are equal **($n-1$ equations)**.
- (4) The first and last functions must pass through the end points ($i = 0$ and n) **(2 equations)**.
- (5) ASSUME the second derivative is zero for the end points **(2 equations)**.

HOME READING

Two-dimensional bilinear interpolation

We have values at four points $f(x_1, y_1)$, $f(x_1, y_2)$, $f(x_2, y_1)$ and $f(x_2, y_2)$. Estimate the value at an intermediate point $f(x_i, y_i)$.

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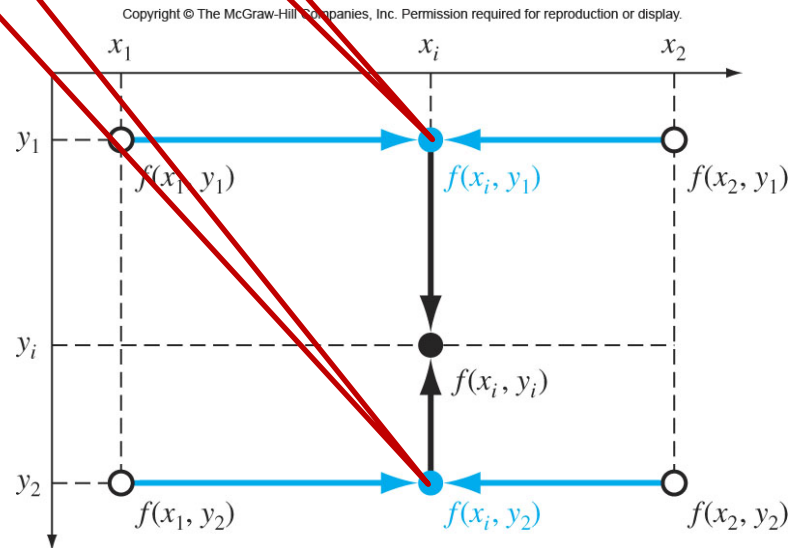


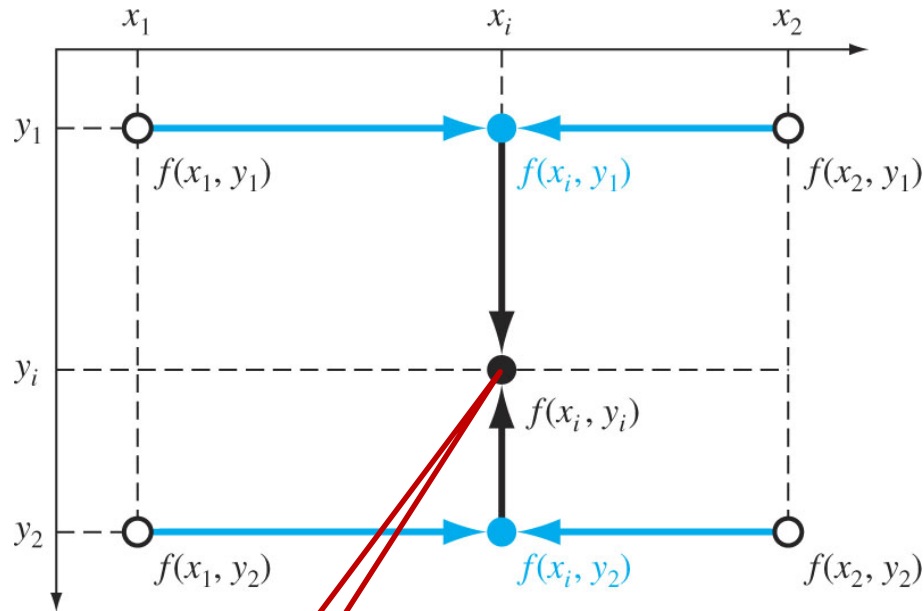
(1) Fix the y-value and apply 1-D linear interpolation in the x-direction. Using the Lagrange form, the result at (x_i, y_1) is...

$$f(x_i, y_1) = \frac{x_i - x_2}{x_1 - x_2} f(x_1, y_1) + \frac{x_i - x_1}{x_2 - x_1} f(x_2, y_1)$$

and at (x_i, y_2) the result is...

$$f(x_i, y_2) = \frac{x_i - x_2}{x_1 - x_2} f(x_1, y_2) + \frac{x_i - x_1}{x_2 - x_1} f(x_2, y_2)$$





(2) (x_i, y_1) and (x_i, y_2) are used to linearly interpolate along the y direction. Using the Lagrange form, the result at (x_i, y_i) is...

$$f(x_i, y_i) = \frac{y_i - y_2}{y_1 - y_2} f(x_i, y_1) + \frac{y_i - y_1}{y_2 - y_1} f(x_i, y_2)$$