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Largenet2: an object-oriented programming library for simulating large adaptive networks

Gerd Zschaler^{1,*} and Thilo Gross²

¹Max-Planck-Institut für Physik komplexer Systeme, 01187 Dresden, Germany and ²Department of Engineering Mathematics, Merchant Venturers Building, University of Bristol, Clifton, Bristol BS81UB, UK

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ABSTRACT

Summary: The largenet2 C++ library provides an infrastructure for the simulation of large dynamic and adaptive networks with discrete node and link states.

Availability: The library is released as free software. It is available at http://biond.github.com/largenet2. Largenet2 is licensed under the Creative Commons Attribution-NonCommercial 3.0 Unported License. Contact: gerd@biond.org.

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The investigation of dynamical processes on networks has become a highly active research field, which addresses questions from a wide range of disciplines (Barrat et al., 2008; Newman, 2010). One of the fundamental tools of 'network science' (Börner et al., 2007) is computer simulation. Prominent examples include the study of the propagation of communicable diseases in networks of social contacts (e.g. Kuperman and Abramson, 2001), the emergence of consensus in networks of interacting agents (Castellano, 2005; Sood and Redner, 2005) or the evolution of cooperation among selfish individuals (Santos and Pacheco, 2005; Nowak, 2006).

During the past decade in particular, adaptive networks have received a lot of attention. In this class of network models, the network structure itself changes dynamically in response to the dynamics of its constituents (Gross and Blasius, 2008; Gross and Sayama, 2009). This creates a feedback loop between the dynamics on the network and the dynamics of the network itself, leading to emergent complex behaviour. For instance, adaptive-network models have been studied for social networks (Skyrms and Pemantle, 2000), opinion formation (Durrett et al., 2012; Nardini et al., 2008; Vazquez et al., 2008), epidemic spreading (Gross et al., 2006; Shaw and Schwartz, 2008) and collective motion (Couzin et al., 2011; Huepe et al., 2011).

Dynamical processes in adaptive networks are typically specified in terms of a set of rules that locally transform a part of the network, e.g. update a node's state according to its neighbourhood or modify the local connectivity of a node (Gorochowski et al., 2012; Zschaler, 2012). An example of such rules for an epidemiological model is shown in Figure 1. The transformation rules can be directly implemented in computer simulations. For stochastic models, they are typically applied asynchronously

*To whom correspondence should be addressed.

using Monte Carlo techniques such as Gillespie's algorithm (Gillespie, 1976).

To apply the transformation rules efficiently in simulations, the network subgraphs involved in a specific rule must be accessible at random, i.e. they must be located directly without resorting to an extensive search in the network. For instance, for the infection rule in Figure 1 (top), efficient access to the links connecting S- and I-nodes in the network must be provided. Thus, appropriate data structures representing the network are required, which provide random access to the network nodes, links and similar subgraphs; store properties such as node and link states and allow for fast changes of the network topology.

Standard data structures used to represent networks (or graphs) in computer science are tailored towards the efficient implementation of certain algorithms, as for instance graph traversal, search or finding shortest paths (Mehlhorn and Näher, 1999; Sedgewick, 2002; Siek et al., 2002). In most cases, these algorithms work on static networks with a fixed topology, and efficient access to node and link states is usually not of major concern. Such data structures are therefore not suitable for the simulation of large adaptive networks, whose structure changes dynamically and depending on the node and link states.

The largenet2 library has been developed specifically for the efficient simulation of dynamic and adaptive networks. It provides data structures for networks with discrete node and link states (represented as integer numbers), allowing for fast random access to nodes and links in any given state, and efficient manipulation of these states and the network topology. Nodes, links and, if required, larger subgraphs are stored in a custom-made, index-based container, which can hold items in different categories (states). It ensures that items in the same category are stored in contingent memory and provides both index-based and category-based access so that selecting a random item in a given category can be achieved in constant time.

The network structure is modelled directly in memory using nodes and links as the basic entities in a double adjacency set representation, in which each node keeps a set of pointers to its incoming and outgoing links. Addition and removal of links is thus achieved in logarithmic time so that efficient simulation is not limited to networks of fixed size. In effect, simulating large adaptive networks with largenet2 is typically of linear complexity, i.e. the required simulation time scales linearly with the number of edges in the network for most applications.

The library is not primarily concerned with simulation algorithms, although also providing a basic stochastic simulation framework implementing Gillespie's algorithm (Gillespie, 1976)

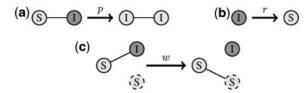


Fig. 1. Diagrammatic representation of the transformation rules for an epidemiological model (Gross *et al.*, 2006). (a) a susceptible node (S) is infected through its link to an infectious neighbour (I) with probability p per S-I-link and unit time; (b) an infectious node (I) recovers with probability r; (c) a susceptible node (S) breaks its connection to an infectious neighbour (I) and rewires to another randomly selected susceptible node (dashed) with probability w. This last rule makes the network adaptive because it changes the topology depending on the node states

and one of its variants (Allen and Dytham, 2009). However, the provided data structures could be used in existing frameworks focusing on particular simulation algorithms for network dynamics, such as the NetEvo package (Gorochowski *et al.*, 2010).

Largenet2 also provides a partial interface to the Boost Graph Library (Siek et al., 2002) so that many of the latter's generic graph algorithms can be used. For implementation details, examples and source code documentation, please refer to the website.

The *largenet2* library and its predecessor *largenet* have been used for the simulations of large adaptive networks in (Böhme and Gross, 2011; Demirel *et al.*, 2011; Zschaler *et al.*, 2010, 2012). To implement more complex transformation rules than depicted in Figure 1, the library can be and has been extended to also track larger network subgraphs involved in such rules, such as node triplets (e.g. Couzin *et al.*, 2011; Huepe *et al.*, 2011).

The open source library *largenet2* is under ongoing development. It is set up as a community effort, and contributions are welcome at http://github.com/biond/largenet2.

Conflict of Interest: none declared.

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